

**HW for 2019-11-04**

(due: 2019-11-18)

You may (and should) talk about problems with each other and with me, providing attribution for any good ideas you might get. Your final write-up should be your own.

Consider  $A \in \mathbb{R}^{n \times n}$ ,  $b \in \mathbb{R}^n$  with  $A$  symmetric and  $b$  not an eigenvector, and define

$$\phi(x) = \frac{1}{2}x^T Ax - x^T b.$$

We wish to minimize  $\phi$  subject to the constraint  $x^T x = 1$ , via the Lagrangian

$$L(x, \mu) = \frac{1}{2}x^T Ax - x^T b - \frac{\mu}{2}(x^T x - 1).$$

1. Express  $x$  at a stationary point in terms of  $A$ ,  $b$ , and  $\mu$ .
2. Argue that the condition  $\|x\|^2 = 1$ , given the expression from the previous step, implies singularity of the matrix

$$\begin{bmatrix} (A - \mu I)^2 & b \\ b^T & 1 \end{bmatrix}$$

3. Eliminating the  $z$  variable in

$$\begin{bmatrix} (A - \mu I)^2 & b \\ b^T & 1 \end{bmatrix} \begin{bmatrix} y \\ z \end{bmatrix} = 0,$$

show that  $\mu$  satisfies the quadratic eigenvalue problem

$$[(A^2 - bb^T) - 2\mu A + \mu^2 I] y = 0.$$

Solving via polyeig gives us all possible  $\mu$  in  $O(n^3)$  time.

4. At the constrained minimizer, we must satisfy that  $v^T(A - \mu I)v$  is positive for all  $v$  s.t.  $v^T x = 0$ . Argue that this implies  $\mu < \lambda_2(A)$ , where  $\lambda_2(A)$  is the second smallest eigenvalue of  $A$ .
5. Following the divide-and-conquer idea and the argument from the previous step, argue that  $\phi$  has no more than three constrained minimizers.
6. Write a code to solve the problem, with the interface `hw6solve(A, b)` (returning the vector `x`). Please also write a test case to sanity check your solver!