## 1 Denotational Semantics for REC

So far the most interesting thing we have given a denotational semantics for is the while loop. What about functions? We now have enough machinery to capture some of their semantics, even for mutually recursive functions. We show how to give a semantics for the language REC [Win93, Chp. 9].

### 1.1 REC Syntax

$$
\begin{aligned}
p & ::=\text { let } d \text { in } e \\
d & ::=f\left(x_{1}, \ldots, x_{n}\right)=e \mid f\left(x_{1}, \ldots, x_{n}\right)=e \text { and } d \\
e & ::=n|x| e_{1} \oplus e_{2} \mid \text { let } x=e_{1} \text { in } e_{2} \mid \text { ifp } e_{0} \text { then } e_{1} \text { else } e_{2} \mid f_{i}\left(e_{1}, \ldots, e_{a_{i}}\right)
\end{aligned}
$$

The expressions $d$ are function declarations. The functions can be mutually recursive. It is reasonable to expect that under most semantics, let $f(x)=f(x)$ in $f(0)$ will loop infinitely, but let $f(x)=f(x)$ in 0 will halt and return 0 .

For example,

$$
\begin{aligned}
& \text { let } f_{1}(n, m)=\text { ifp } m^{2}-n \text { then } 1 \text { else }(n \bmod m) \cdot f_{1}(n, m+1) \\
& \text { and } f_{2}(n)=\operatorname{ifp} f_{1}(n, 2) \text { then } n \text { else } f_{2}(n+1) \\
& \text { in } f_{2}(1000)
\end{aligned}
$$

In this REC program, $f_{2}(n)$ finds the first prime number $p \geq n$. The value of $n \bmod m$ is positive iff $m$ does not divide $n$.

### 1.2 CBV Denotational Semantics for REC

The meaning function is $\llbracket e \rrbracket \in F E n v \rightarrow E n v \rightarrow \mathbb{Z}_{\perp}$, where Env and FEnv denote the sets of variable environments and function environments, respectively, as used in REC.

$$
\begin{aligned}
\rho & \in \operatorname{Env}=\operatorname{Var} \rightarrow \mathbb{Z} \\
\varphi & \in \text { FEnv }=\left(\mathbb{Z}^{a_{1}} \rightarrow \mathbb{Z}_{\perp}\right) \times \cdots \times\left(\mathbb{Z}^{a_{n}} \rightarrow \mathbb{Z}_{\perp}\right)
\end{aligned}
$$

Here Var is a countable set of variables, $\mathbb{Z}$ is the set of integers, which are the values that can be bound to a variable in an environment, and $\mathbb{Z}^{m}=\underbrace{\mathbb{Z} \times \mathbb{Z} \times \cdots \times \mathbb{Z}}_{m \text { times }}$.

$$
\begin{aligned}
\llbracket n \rrbracket \varphi \rho \triangleq & n \\
\llbracket x \rrbracket \varphi \rho \triangleq & \rho(x) \\
\llbracket e_{1} \oplus e_{2} \rrbracket \varphi \rho \triangleq & \text { let } v_{1} \in \mathbb{Z}=\llbracket e_{1} \rrbracket \varphi \rho \text { in } \\
& \text { let } v_{2} \in \mathbb{Z}=\llbracket e_{2} \rrbracket \varphi \rho \text { in } \\
& v_{1} \oplus v_{2} \\
= & \llbracket e_{1} \rrbracket \varphi \rho \oplus \perp \llbracket e_{2} \rrbracket \varphi \rho \\
\llbracket \text { let } x=e_{1} \text { in } e_{2} \rrbracket \varphi \rho \triangleq & \text { let } y \in \mathbb{Z}=\llbracket e_{1} \rrbracket \varphi \rho \text { in } \\
& \llbracket e_{2} \rrbracket \varphi \rho[y / x \rrbracket \\
\llbracket \text { ifp } e_{0} \text { then } e_{1} \text { else } e_{2} \rrbracket \varphi \rho \triangleq & \text { let } v_{0} \in \mathbb{Z}=\llbracket e_{0} \rrbracket \varphi \rho \text { in } \\
& \text { if } v_{0}>0 \text { then } \llbracket e_{1} \rrbracket \varphi \rho \text { else } \llbracket e_{2} \rrbracket \varphi \rho \\
\llbracket f_{i}\left(e_{1}, \ldots, e_{a_{i}}\right) \rrbracket \varphi \rho \triangleq & \text { let } v_{1} \in \mathbb{Z}=\llbracket e_{1} \rrbracket \varphi \rho \text { in } \\
& \vdots \\
& \text { let } v_{a_{i}} \in \mathbb{Z}=\llbracket e_{a_{i}} \rrbracket \varphi \rho \text { in } \\
& \left(\pi_{i} \varphi\right)\left(v_{1}, \ldots, v_{a_{i}}\right)
\end{aligned}
$$

The meaning of a program let $d$ in $e$ is

$$
\llbracket \text { let } d \text { in } e \rrbracket \triangleq \llbracket e \rrbracket \varphi \rho_{0},
$$

where $\rho_{0}$ is some initial environment containing default values for the variables (say 0 ), and if the function declarations $d$ are

$$
f_{1}\left(x_{1}, \ldots, x_{a_{1}}\right)=e_{1} \text { and } \ldots \text { and } f_{n}\left(x_{1}, \ldots, x_{a_{n}}\right)=e_{n}
$$

then

$$
\begin{gathered}
\varphi=\text { fix } \lambda \psi \in \text { FEnv. }\left(\lambda v_{1} \in \mathbb{Z}, \ldots, v_{a_{1}} \in \mathbb{Z} \cdot \llbracket e_{1} \rrbracket \psi \rho_{0}\left[v_{1} / x_{1}, \ldots, v_{a_{1}} / x_{a_{1}}\right],\right. \\
\vdots \\
\left.\lambda v_{1} \in \mathbb{Z}, \ldots, v_{a_{n}} \in \mathbb{Z} \cdot \llbracket e_{n} \rrbracket \psi \rho_{0}\left[v_{1} / x_{1}, \ldots, v_{a_{n}} / x_{a_{n}}\right]\right),
\end{gathered}
$$

or more accurately,

$$
\begin{aligned}
& \varphi=\text { fix } \lambda \psi \in \text { FEnv. }(\lambda v \in \mathbb{Z}^{a_{1}} \cdot \llbracket e_{1} \rrbracket \psi \rho_{0}\left[\pi_{1}(v) / x_{1}, \ldots, \pi_{a_{1}}(v) / x_{a_{1}}\right], \\
& \vdots \\
& \lambda v\left.\in \mathbb{Z}^{a_{n}} \cdot \llbracket e_{n} \rrbracket \psi \rho_{0}\left[\pi_{1}(v) / x_{1}, \ldots, \pi_{a_{n}}(v) / x_{a_{n}}\right]\right) .
\end{aligned}
$$

For this fixpoint to exist, we need to know that FEnv a pointed CPO and that the function FEnv $\rightarrow$ FEnv to which we are applying fix is continuous. The domain FEnv is a product, and a product is a pointed CPO when each factor is a pointed CPO. Each factor $\mathbb{Z}^{a_{i}} \rightarrow \mathbb{Z}_{\perp}$ is a pointed CPO, since a function is a pointed CPO when the codomain of that function is a pointed CPO , and $\mathbb{Z}_{\perp}$ is a pointed CPO. Therefore, FEnv is a pointed CPO.

The function $\tau: F E n v \rightarrow$ FEnv to which we are applying fix is continuous, because it can be written using the metalanguage. Here is the argument. We illustrate with $n=2$ and $a_{1}=a_{2}=1$ for simplicity, thus we assume the declaration $d$ is

$$
f_{1}(x)=e_{1} \text { and } f_{2}(x)=e_{2}
$$

Then

$$
\varphi=\operatorname{fix} \lambda \psi \in F E n v .\left(\lambda v \in \mathbb{Z} . \llbracket e_{1} \rrbracket \psi \rho_{0}[v / x], \lambda v \in \mathbb{Z} . \llbracket e_{2} \rrbracket \psi \rho_{0}[v / x \rrbracket)\right.
$$

This gives the least fixpoint of the operator

$$
\tau=\lambda \psi \in F E n v .\left(\lambda v \in \mathbb{Z} . \llbracket e_{1} \rrbracket \psi \rho_{0}[v / x], \lambda v \in \mathbb{Z} . \llbracket e_{2} \rrbracket \psi \rho_{0}[v / x]\right)
$$

provided we can show that $\tau$ is continuous. We can write

$$
\begin{aligned}
\tau & =\lambda \psi \in \text { FEnv. }\left(\lambda v \in \mathbb{Z} \cdot \llbracket e_{1} \rrbracket \psi \rho_{0}[v / x], \lambda v \in \mathbb{Z} \cdot \llbracket e_{2} \rrbracket \psi \rho_{0}[v / x]\right) \\
& =\lambda \psi \in \text { FEnv. }\left(\tau_{1}(\psi), \tau_{2}(\psi)\right) \\
& =\lambda \psi \in \text { FEnv. }\left\langle\tau_{1}, \tau_{2}\right\rangle(\psi) \\
& =\left\langle\tau_{1}, \tau_{2}\right\rangle
\end{aligned}
$$

where $\tau_{i}:$ FEnv $\rightarrow$ FEnv is

$$
\tau_{i}=\lambda \psi \in F E n v . \lambda v \in \mathbb{Z} . \llbracket e_{i} \rrbracket \psi \rho_{0}[v / x]
$$

Because $\left\langle\tau_{1}, \tau_{2}\right\rangle$ is continuous iff $\tau_{1}$ and $\tau_{2}$ are, it suffices to show that each $\tau_{i}$ is continuous. Now we can write $\tau_{i}$ in our metalanguage.

$$
\begin{aligned}
\tau_{i} & =\lambda \psi \in F E n v \cdot \lambda v \in \mathbb{Z} \cdot \llbracket e_{i} \rrbracket \psi \rho_{0}[v / x] \\
& =\lambda \psi \in F E n v \cdot \lambda v \in \mathbb{Z} \cdot \llbracket e_{i} \rrbracket \psi\left(\text { subst } \rho_{0} x v\right) \\
& =\lambda \psi \in F E n v \cdot \lambda v \in \mathbb{Z} \cdot\left(\llbracket e_{i} \rrbracket \psi\right)\left(\left(\text { subst } \rho_{0} x\right) v\right) \\
& =\lambda \psi \in F E n v \cdot \lambda v \in \mathbb{Z} \cdot\left(\left(\llbracket e_{i} \rrbracket \psi\right) \circ\left(\text { subst } \rho_{0} x\right)\right) v \\
& =\lambda \psi \in F E n v \cdot\left(\left(\llbracket e_{i} \rrbracket \psi\right) \circ\left(\text { subst } \rho_{0} x\right)\right) \\
& =\lambda \psi \in \text { FEnv. compose }\left(\llbracket e_{i} \rrbracket \psi, \text { subst } \rho_{0} x\right) \\
& =\lambda \psi \in \text { FEnv. compose }\left(\llbracket e_{i} \rrbracket \psi, \text { const }\left(\text { subst } \rho_{0} x\right) \psi\right) \\
& =\lambda \psi \in F E n v \cdot \operatorname{compose}\left(\left\langle\llbracket e_{i} \rrbracket, \text { const }\left(\text { subst } \rho_{0} x\right)\right\rangle \psi\right) \\
& =\lambda \psi \in \text { FEnv. }\left(\text { compose } \circ\left\langle\llbracket e_{i} \rrbracket, \text { const }\left(\text { subst } \rho_{0} x\right)\right\rangle\right) \psi \\
& =\text { compose } \circ\left\langle\llbracket e_{i} \rrbracket, \text { const }\left(\text { subst } \rho_{0} x\right)\right\rangle \\
& =\text { compose }\left(\text { compose },\left\langle\llbracket e_{i} \rrbracket, \text { const }\left(\text { subst } \rho_{0} x\right)\right\rangle\right) .
\end{aligned}
$$

Now we can argue that $\tau_{i}$ is continuous. The composition of two continuous functions is continuous, so it suffices to know that compose and $\left\langle\llbracket e_{i} \rrbracket\right.$, const (subst $\left.\left.\rho_{0} x\right)\right\rangle$ are continuous. We argued last time that compose is continuous. To show $\left\langle\llbracket e_{i} \rrbracket\right.$, const (subst $\left.\left.\rho_{0} x\right)\right\rangle$ is continuous as a function, it suffices to show that both $\llbracket e_{i} \rrbracket$ and const (subst $\left.\rho_{0} x\right)$ are continuous as functions. The former is continuous by the induction hypothesis (structural induction on $e$ ). The latter is a constant function on a discrete domain and is therefore continuous.

### 1.3 CBN Denotational Semantics

The denotational semantics for CBN is the same as for CBV with two exceptions:

$$
\begin{aligned}
\llbracket \text { let } x=e_{1} \text { in } e_{2} \rrbracket \varphi \rho & \triangleq \llbracket e_{2} \rrbracket \varphi \rho\left[\llbracket e_{1} \rrbracket \varphi \rho / x\right] \\
\llbracket f_{i}\left(e_{1}, \ldots, e_{a_{i}}\right) \rrbracket \varphi \rho & \triangleq\left(\pi_{i} \varphi\right)\left(\llbracket e_{1} \rrbracket \varphi \rho, \ldots, \llbracket e_{a_{i}} \rrbracket \varphi \rho\right) .
\end{aligned}
$$

We must extend Env $=\operatorname{Var} \rightarrow \mathbb{Z}_{\perp}$ and $F E n v=\left(\mathbb{Z}_{\perp}^{a_{1}} \rightarrow \mathbb{Z}_{\perp}\right) \times \cdots \times\left(\mathbb{Z}_{\perp}^{a_{n}} \rightarrow \mathbb{Z}_{\perp}\right)$.

## References

[Win93] Glynn Winskel. The Formal Semantics of Programming Languages. MIT Press, 1993.

