### **CS5670: Computer Vision**

Image Resampling & Interpolation





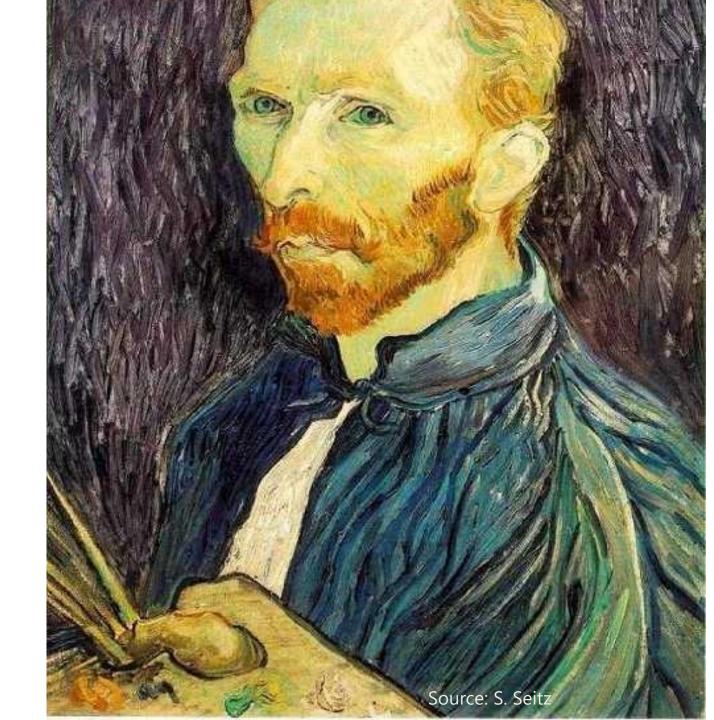


#### **Announcements**

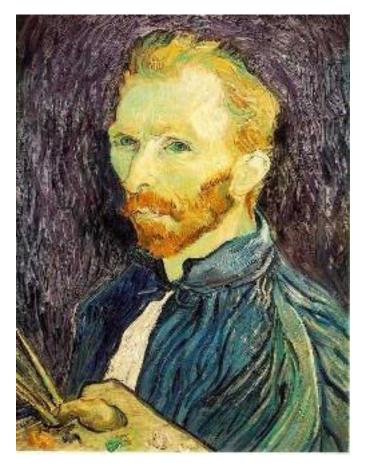
- Project 1 released, due Thursday, February 25 by 11:59pm
  - Project to be done solo (teams of one)
  - Artifact due Monday, March 1 by 11:59pm
- First quiz next week, TBA. Will accommodate other time zones.

## **Image scaling**

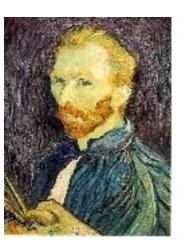
This image is too big to fit on the screen. How can we generate a half-sized version?



### Image sub-sampling



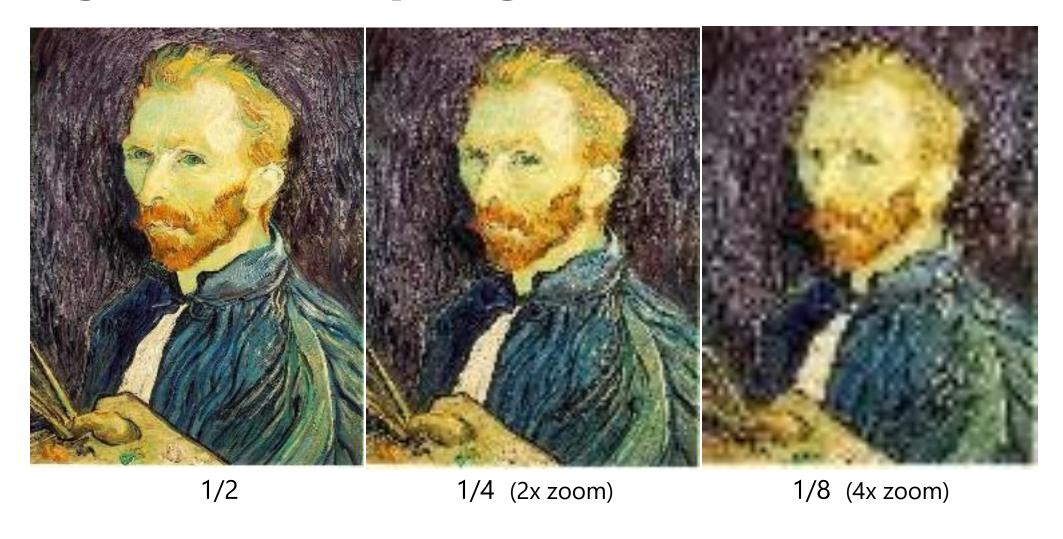
Throw away every other row and column to create a 1/2 size image - called *image sub-sampling* 





1/4

### Image sub-sampling



Why does this look so crufty?

Source: S. Seitz

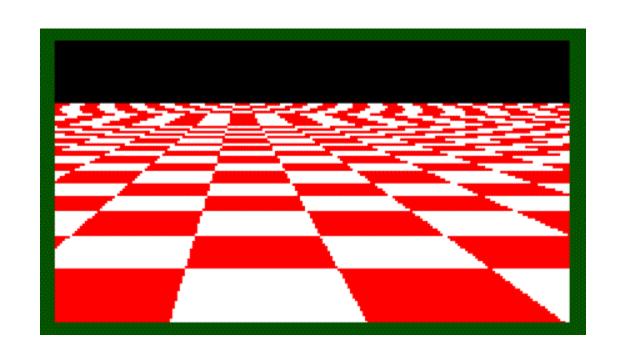
### Image sub-sampling – another example



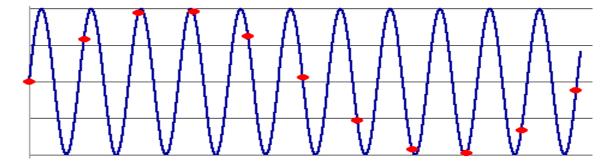


Source: F.

# Even worse for synthetic images



## Aliasing



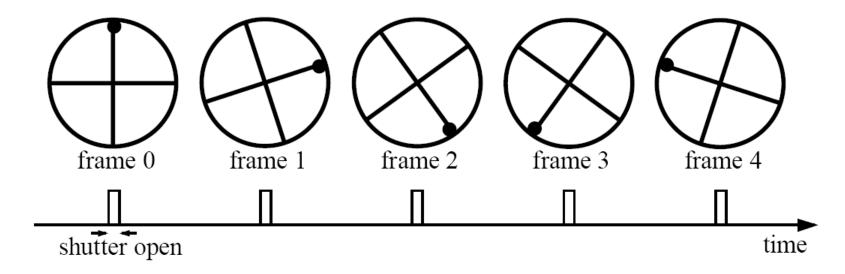
- Occurs when your sampling rate is not high enough to capture the amount of detail in your image
- Can give you the wrong signal/image—an alias
- To do sampling right, need to understand the structure of your signal/image
- Enter Monsieur Fourier...
  - "But what is the Fourier Transform? A visual introduction." <a href="https://www.youtube.com/watch?v=spUNpyF58BY">https://www.youtube.com/watch?v=spUNpyF58BY</a>
- To avoid aliasing:
  - sampling rate ≥ 2 \* max frequency in the image
    - said another way: ≥ two samples per cycle
  - This minimum sampling rate is called the Nyquist rate

Source: L. Zhang

### Wagon-wheel effect

Imagine a spoked wheel moving to the right (rotating clockwise). Mark wheel with dot so we can see what's happening.

If camera shutter is only open for a fraction of a frame time (frame time = 1/30 sec. for video, 1/24 sec. for film):



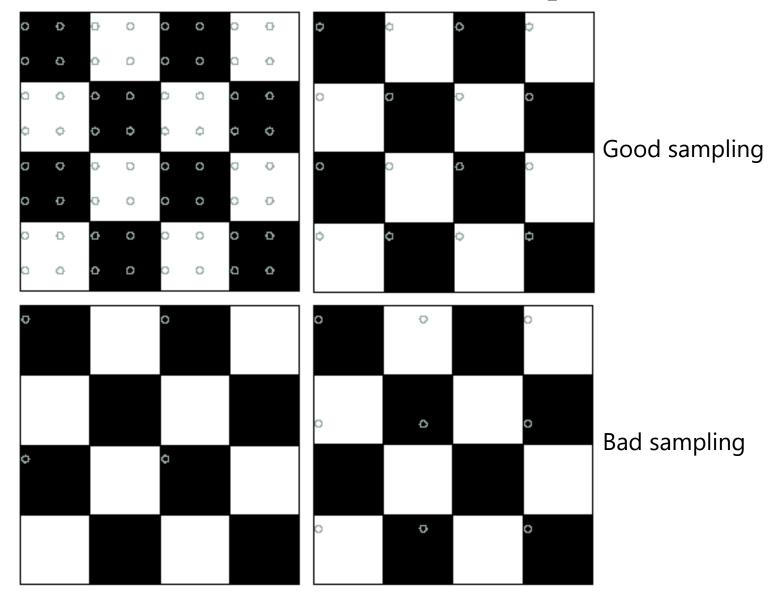
Without dot, wheel appears to be rotating slowly backwards! (counterclockwise)

### Wagon-wheel effect



https://en.wikipedia.org/wiki/Wagon-wheel effect

### Nyquist limit – 2D example

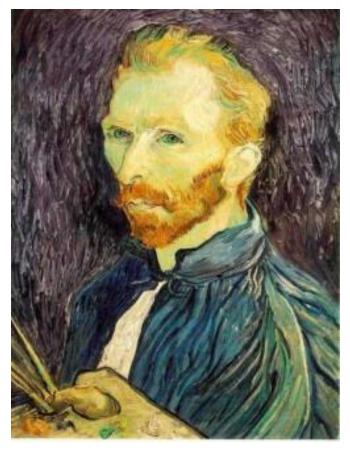


## Aliasing

- When downsampling by a factor of two
  - Original image has frequencies that are too high

How can we fix this?

### Gaussian pre-filtering



Gaussian 1/2







G 1/8

• Solution: filter the image, then subsample

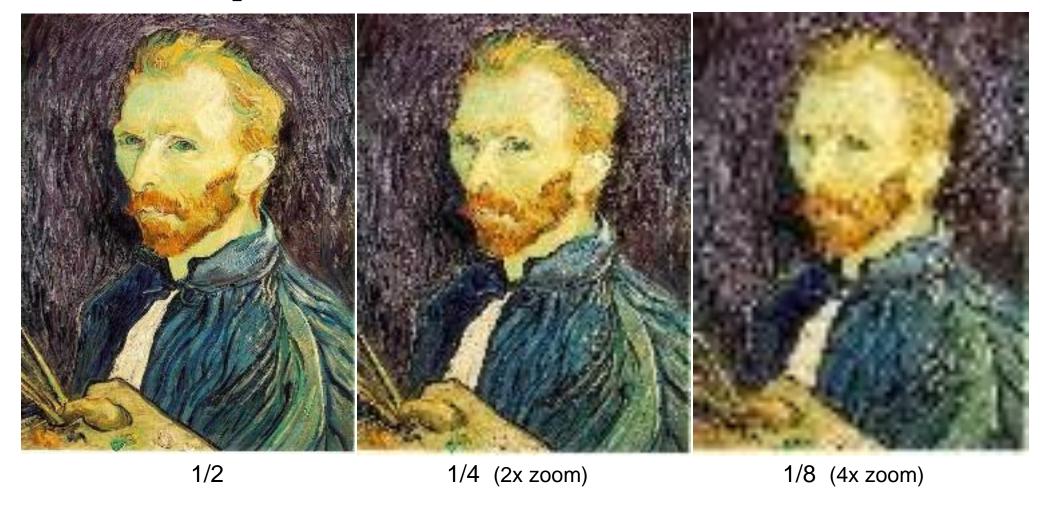
### Subsampling with Gaussian pre-filtering



• Solution: filter the image, then subsample

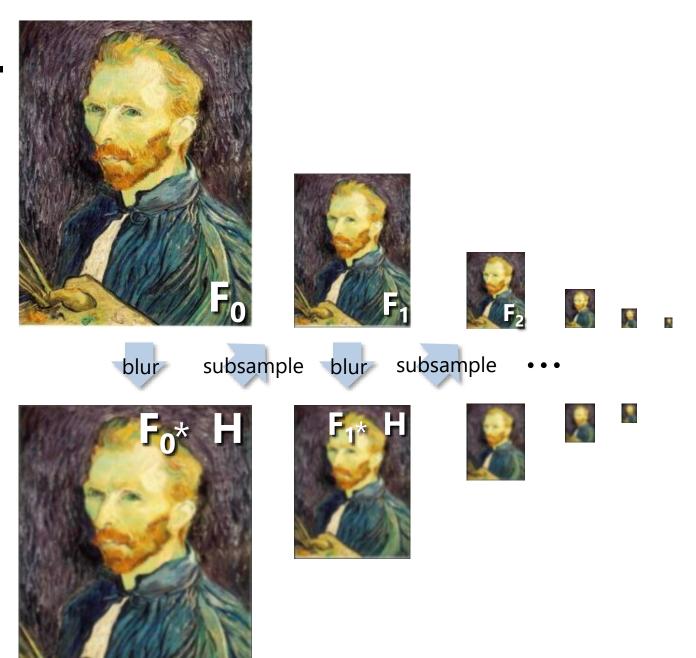
Source: S. Seitz

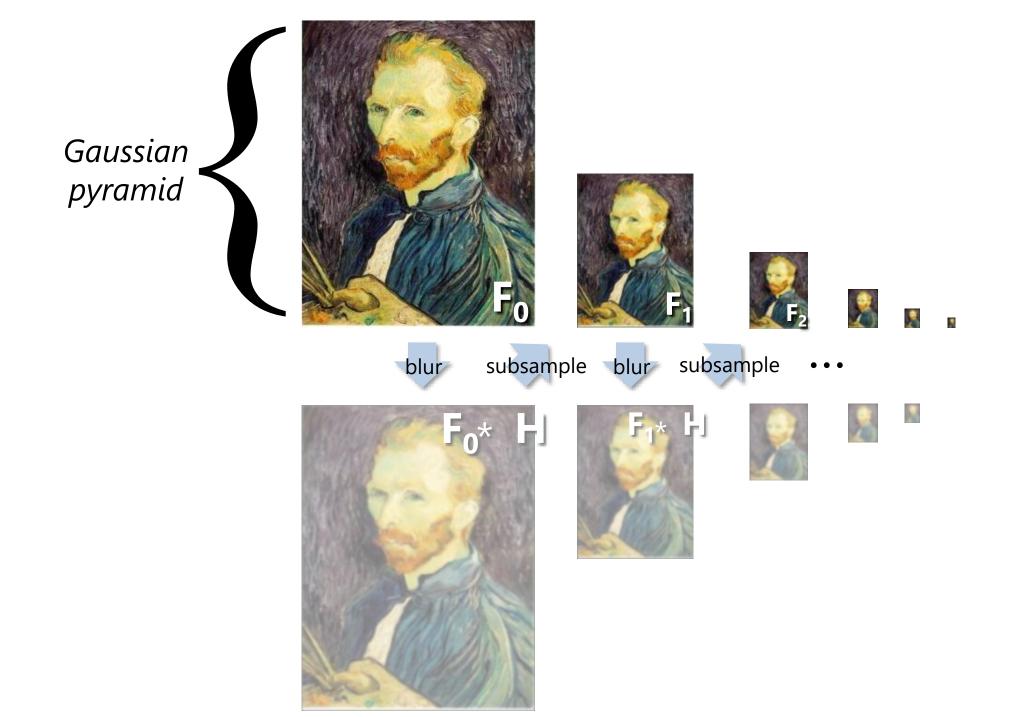
# **Compare with...**

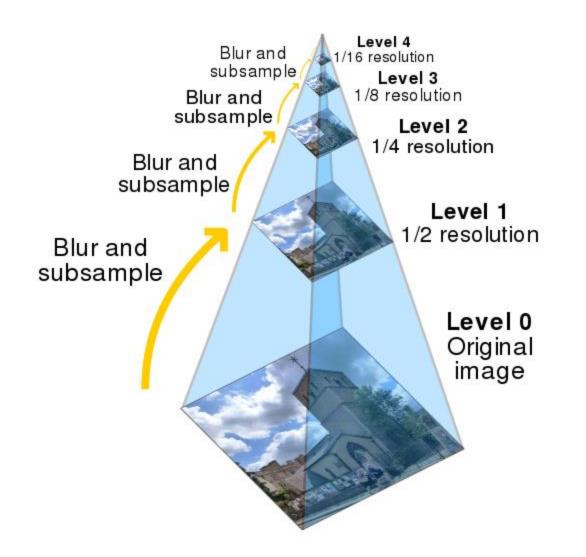


# Gaussian prefiltering

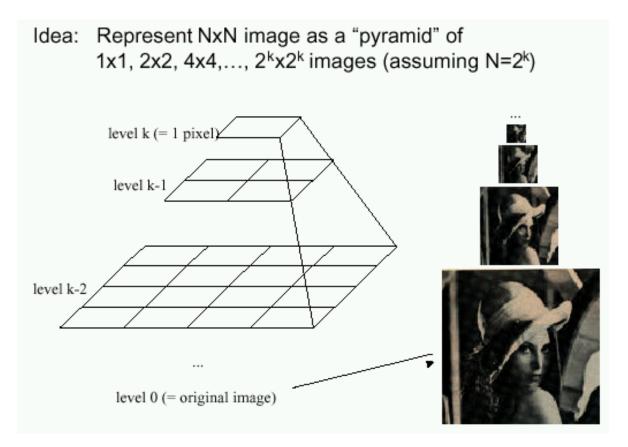
• Solution: filter the image, *then* subsample







### Gaussian pyramids [Burt and Adelson, 1983]

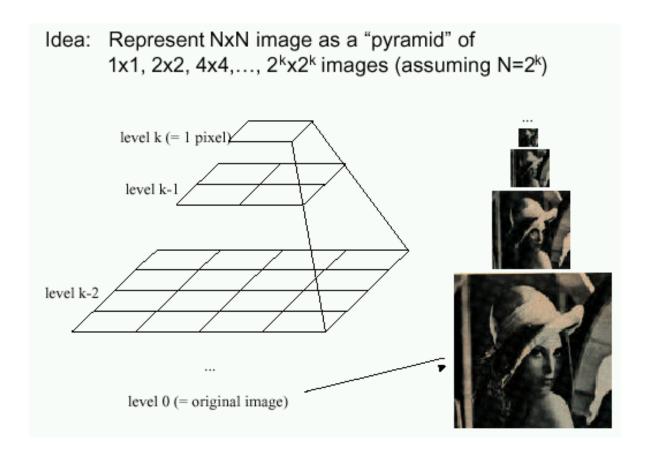


- In computer graphics, a mip map [Williams, 1983]
- A precursor to wavelet transform

Gaussian Pyramids have all sorts of applications in computer vision

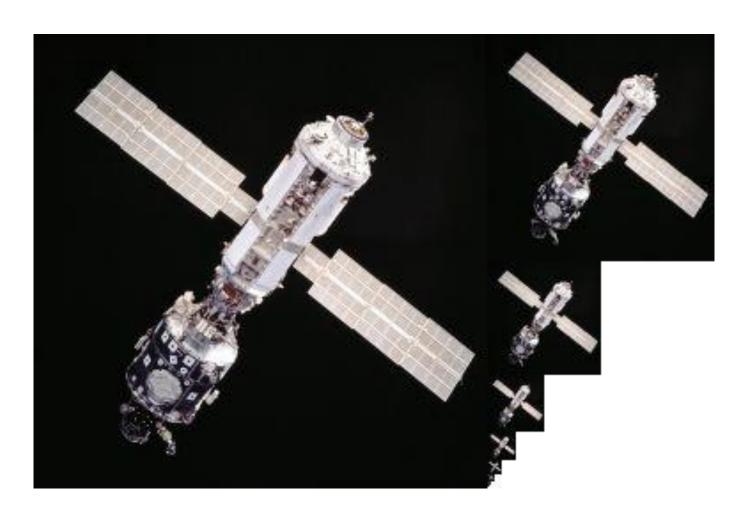
Source: S. Seitz

### Gaussian pyramids [Burt and Adelson, 1983]

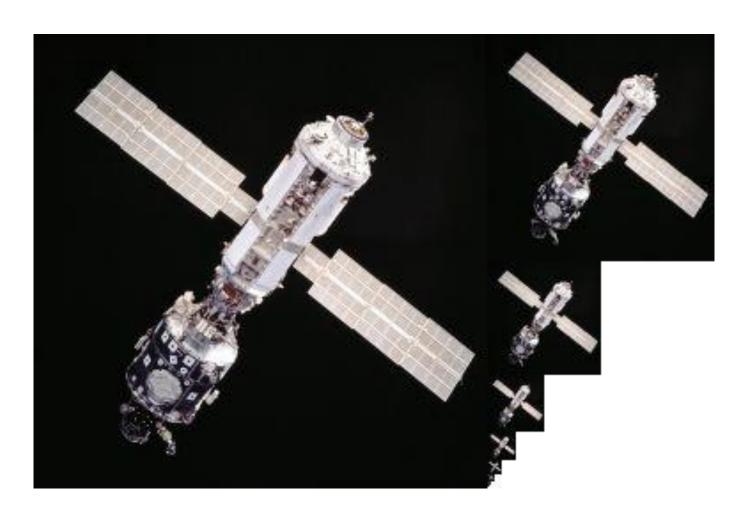


How much space does a Gaussian pyramid take compared to the original image?

# Gaussian pyramid

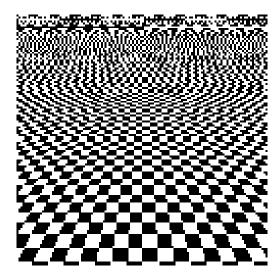


# Gaussian pyramid

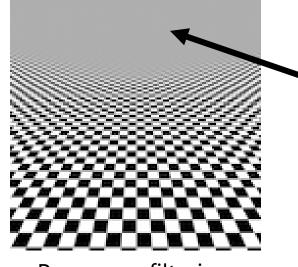


#### **Back to the checkerboard**

 What should happen when you make the checkerboard smaller and smaller?



Naïve subsampling



Proper prefiltering ("antialiasing")

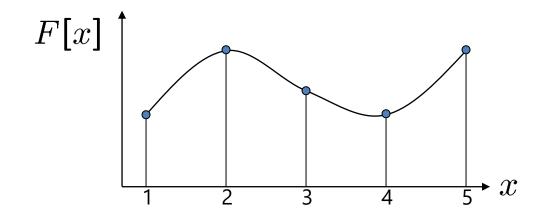
Image turns grey! (Average of black and white squares, because each pixel contains both.)

### **Questions?**

### Upsampling

- This image is too small for this screen:
- How can we make it 10 times as big?
- Simplest approach:
   repeat each row
   and column 10 times
- ("Nearest neighbor interpolation")



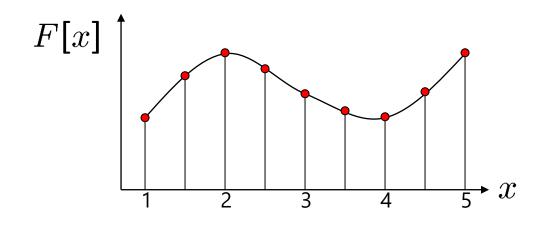


d = 1 in this example

Recall that a digital images is formed as follows:

$$F[x, y] = quantize\{f(xd, yd)\}$$

- It is a discrete point-sampling of a continuous function
- If we could somehow reconstruct the original function, any new image could be generated, at any resolution and scale

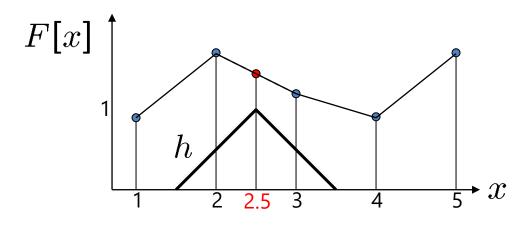


d = 1 in this example

Recall that a digital images is formed as follows:

$$F[x, y] = quantize\{f(xd, yd)\}$$

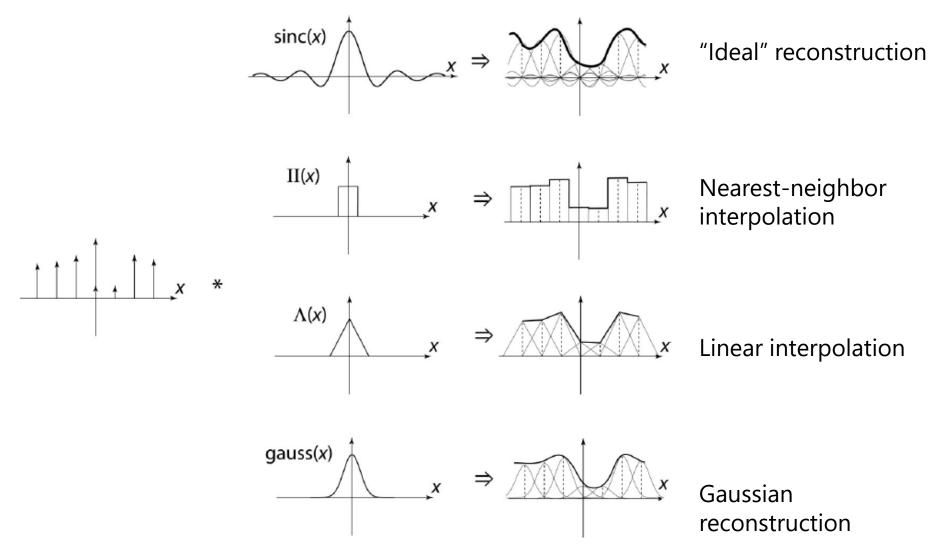
- It is a discrete point-sampling of a continuous function
- If we could somehow reconstruct the original function, any new image could be generated, at any resolution and scale



d = 1 in this example

- What if we don't know f?
  - Guess an approximation:  $\tilde{f}$
  - Can be done in a principled way: filtering
  - Convert F to a continuous function:  $f_F(x) = F(\frac{x}{d}) \text{ when } \frac{x}{d} \text{ is an integer, 0 otherwise}$
  - Reconstruct by convolution with a reconstruction filter, h

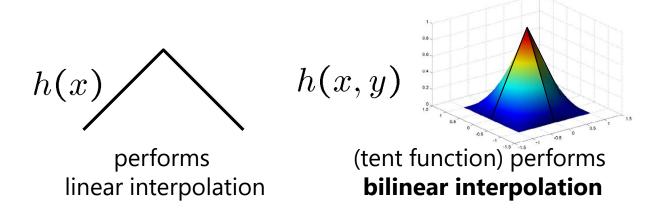
$$\tilde{f} = h * f_F$$



Source: B. Curless

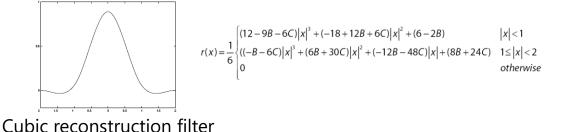
#### **Reconstruction filters**

What does the 2D version of this hat function look like?



Often implemented without cross-correlation

- E.g., <a href="http://en.wikipedia.org/wiki/Bilinear\_interpolation">http://en.wikipedia.org/wiki/Bilinear\_interpolation</a>
  Better filters give better resampled images
  - **Bicubic** is common choice



Original image: X 10

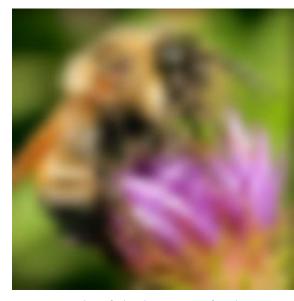




Nearest-neighbor interpolation



Bilinear interpolation



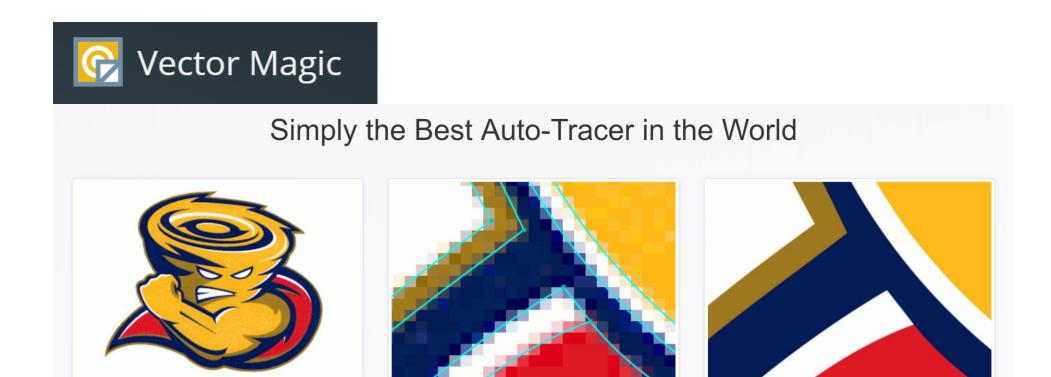
Bicubic interpolation

Also used for *resampling* 

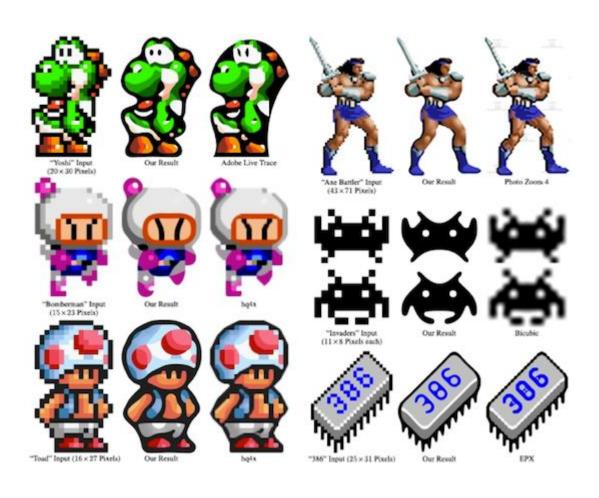




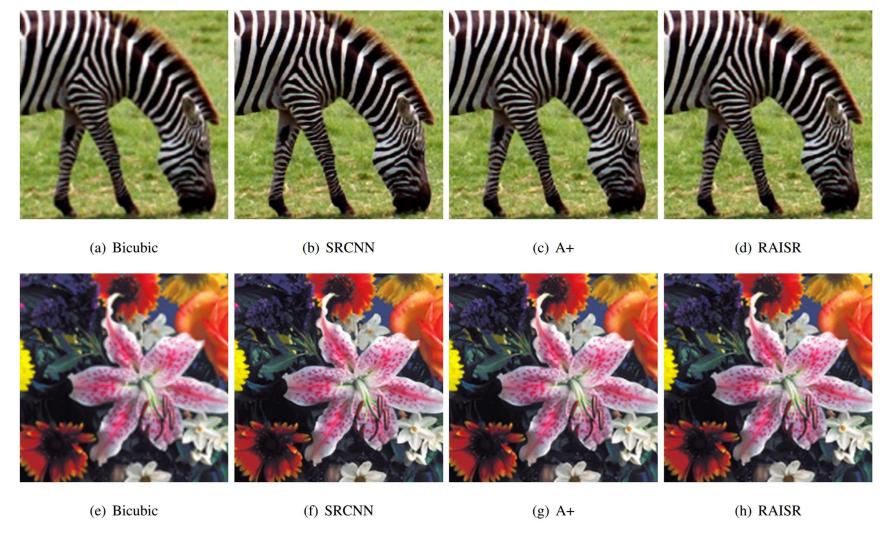
### Raster-to-vector graphics



# **Depixelating Pixel Art**



#### **Modern methods**



From Romano, et al: RAISR: Rapid and Accurate Image Super Resolution, <a href="https://arxiv.org/abs/1606.01299">https://arxiv.org/abs/1606.01299</a>

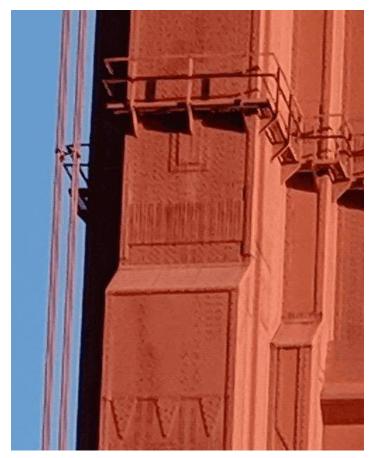
### Super-resolution with multiple images

- Can do better upsampling if you have multiple images of the scene taken with small (subpixel) shifts
- Some cellphone cameras (like the Google Pixel line) capture a burst of photos
- Can we use that burst for upsampling?

### Google Pixel 3 Super Res Zoom



Effect of hand tremor as seen in a cropped burst of photos, after global alignment



Example photo with and without super res zoom (smart burst align and merge)

https://ai.googleblog.com/2018/10/see-better-and-further-with-super-res.html

### **Questions?**