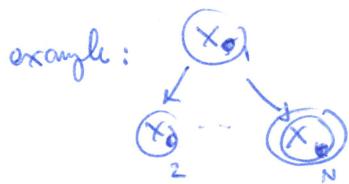


Reviewing variable elimination:
List ← cond; marg. distributions, and pick I an order of elimination

$m_{x_i} \leftarrow \sum_{x_i} \prod_j \text{list}_j[x_i]$, having added all distributions
having removed from List all distr contg X_i and adding them to list!

insert m_{x_i} into list.

Runtime poly in n^2 but not linear.
but actually depends on H of values that each var can take.



And consider $I = x_{n-1} x_{n-2} \dots x_1$ (A)

vs. $I' = x_1 \dots x_{n-1}$ (B)

claim: B is better: b/c:

$$(A) P(x_1, \dots, x_n) = P(x_1) \prod_{j=2}^n P(x_j | x_1)$$

so what would m_{x_1} be? $\sum_{x_1} P(x_1) \prod_{j=2}^n P(x_j | x_1)$

↙
it's a fn of all the vars $x_2 \dots x_N$.

so will get:

$$P(x_N) = \underbrace{\sum_{x_{N-1}} \sum_{x_{N-2}} \dots \sum_{x_2}}_{2^{N-1}} m_{x_1}(x_2 \dots x_N)$$

which is how many possibilities?

$$(B) P(x_1, \dots, x_N) = P(x_N)$$

$$P(x_N) = \sum_{x_1} \sum_{x_2} \dots \sum_{x_{N-1}} P(x_1) \prod_{j=2}^N P(x_j | x_1)$$

but x_{N-1} only shows up in one of the ~~two~~ summations.

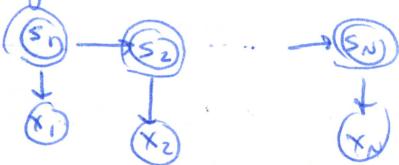
~~so~~ in which case $\sum_{x_{N-1}} P(x_{N-1} | x_1) = 1$.

$$\text{this results in } P(x_N) = \sum_{x_1} P(x_1) P(x_N | x_1)$$

so this is "linear" time.

but picking a good ordering is NP complete.

another exaple: HMMs.



here, it might be less obvious what is the right order.

let's try variable elimination, and assume we're given x_1, \dots, x_n , and what's my g is, what is $P(s_t | x_1, \dots, x_n)$?

Can we get this down to marginal dist? yes: $P(s_t, x_1, \dots, x_n) / P(x_1, \dots, x_n)$

Usually you don't actually need to compute $P(x_1, \dots, x_n)$, but just normalize afterward.

g : which vars should we eliminate? a : all the remaining hidden states.

q : what order?

d : t is distinguished, so we should consider $(1, \dots, t-1)$ and $(N, N-1, \dots, t+1)$

$$\begin{aligned} P(s_t | x_1, \dots, x_T) &= \sum_{s_1, \dots, s_{t-1}, s_{N-t+1}} P(s_1, \dots, s_N, x_1, \dots, x_T) \\ &= \sum_{s_{t-1}} \sum_{s_1} \sum_{s_{N-t+1}} \dots \sum_{s_N} \underbrace{P(s_1, \dots, s_N, x_1, \dots, x_T)}_{\downarrow} \end{aligned}$$

which gives us: $P(s_1) P(x_1 | s_1) P(s_2 | s_1) P(x_2 | s_2) \dots$

If you consider the \sum_{s_N} summation, the only thing that contains it is $\underline{P(s_N | s_{N-1}) P(x_N | s_N)}$.

Let's now introduce forward and backward probs α, β .

$$\beta_N(\underbrace{s_{N-1}, x_N}_{\text{from } \dots}, s_N) = \sum_{s_{N-1}} P(s_N | s_{N-1}) P(x_N | s_N)$$

Similarly, $\beta_{N-1}(s_{N-2}, x_{N-1}, x_N)$
which ~~depends on~~ it
since it depends on β_N .

eventually, this gives us:

$$P(s_t, x_1, \dots, x_n) = \beta_{t+1}(s_{t+1}, x_{t+1}, \dots, x_N) \quad \text{which will be } P(s_t, x_1, \dots,$$

\uparrow
should this be t? yes.

$$\alpha \sum_{s_{t-1}} \dots \sum_{s_1} P(s_t) P(x_1 | s_1) P(x_2 | s_2) \dots P(x_t | s_{t-1})$$

β = sum over s_{n-1}

and you can do the same process, but left to right instead.

that is, have $\alpha_1(x_1) = \sum_{s_1} P(s_1) P(x_1 | s_1) P(s_2 | s_1)$
 i.e., sum over what involves s_1 .

$$\text{similarly, } \alpha_2(x_2, s_3, x_1) = \sum_{s_2} \alpha_1(s_2 | x_1) \underbrace{P(s_3 | s_2)}_{\substack{\text{I guess this, too} \\ \text{Lillian will do step similar}}} \underbrace{P(x_2 | s_2)}_{\substack{\text{but not quite variable etc!} \\ t}}$$

$$\text{will then get: } P(s_t, x_1, \dots, x_n) = \beta_{t+1}(s_t, \dots, x_n - x_{t+1}) \alpha_{t+1}(s_t, x_1 - x_{t+1}) P(x_{t+1} | s_t)$$

so... this was meant to be an example of variable elimination
 → note that you can think of this as if neighbors are passing msgs to each other.

Now, generally: what if we need more than one variable's marginals?
 each node is doing additn / multiplicatn .

so: belief propagation:

supse we have observation $X_j = x_j$, let the evidence vector (f_i): $E_{X_j}(x) = \mathbb{1}\{x_j = x\}$

for unobserved vars, set $E_X(x) = 1$. for all x .

At round 0, all msgs btwn nodes are 1.

(he wants us to do this next for HMMs)

• in during nrs, we have incoming / outgoing msgs from parents / children.

ex: incoming msg to node from children:

$$\lambda(x) = E_{X_j}(x) \prod_{j \in \text{children}(x_i)} \lambda_{X_j}(x)$$

$\downarrow \beta \text{ for HMMs.}$ $\downarrow \text{for HMMs: } s_{t+1}, x_{t+1}$

slides: for HMM,
 $\pi \rightarrow \alpha$.

can show that you get convergence of this for trees.

(for next lecture:
 inference for setting)
 inference from sampling)