Bias-Variance Tradeoff

Announcements

Overview of the second half the semester

1. A little bit Learning Theory

2. Make our linear models nonlinear (Kernel)

3. How to combine multiple classifiers into a stronger one (Bagging & Boosting)?

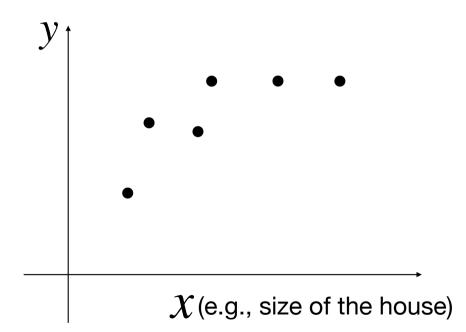
4. Intro of Neural Networks (old and new)

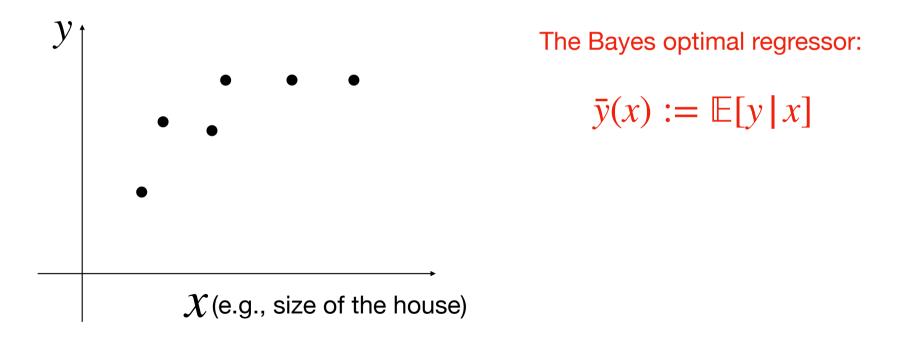
Outline of Today

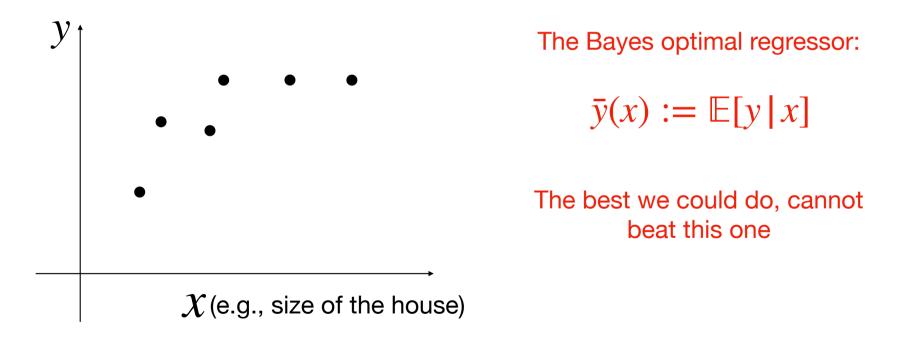
1. Intro on Underfitting/Overfitting and Bias/Variance

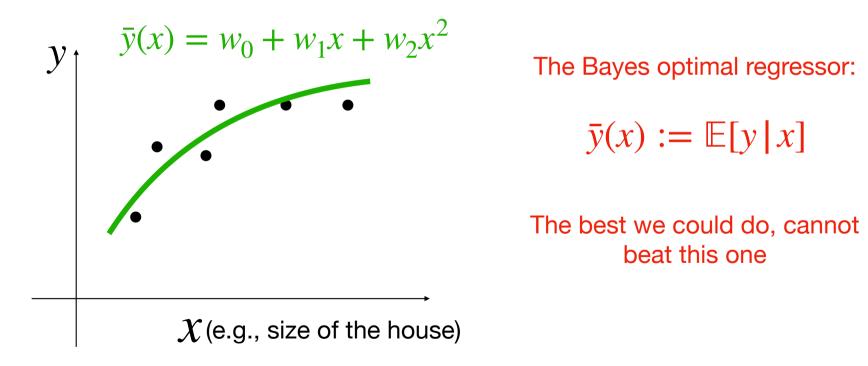
2. Derivation of the Bias-Variance Decomposition

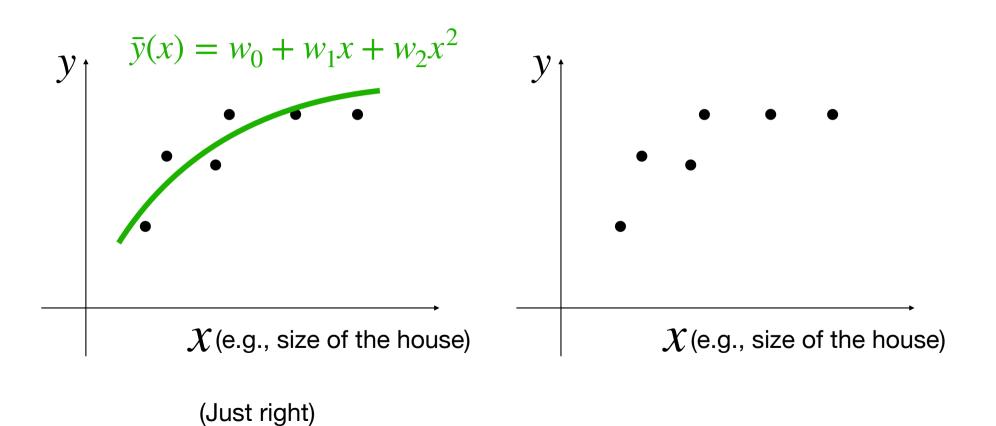
3. Example on Ridge Linear Regression

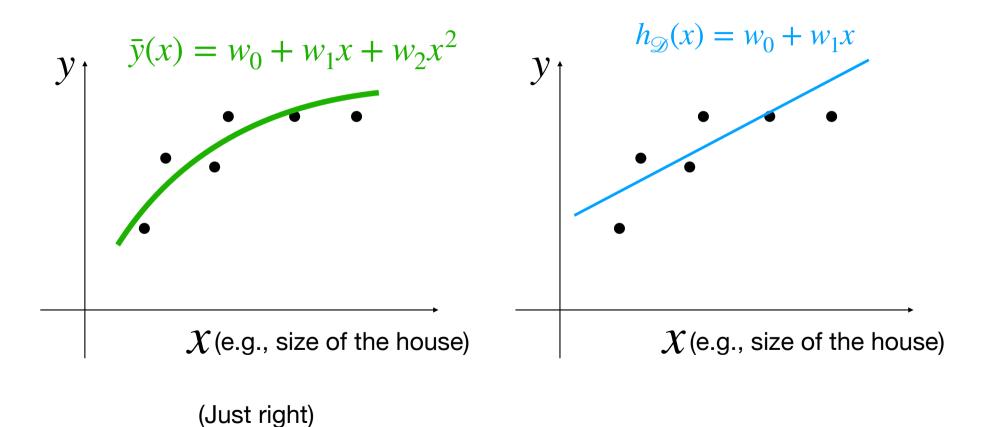


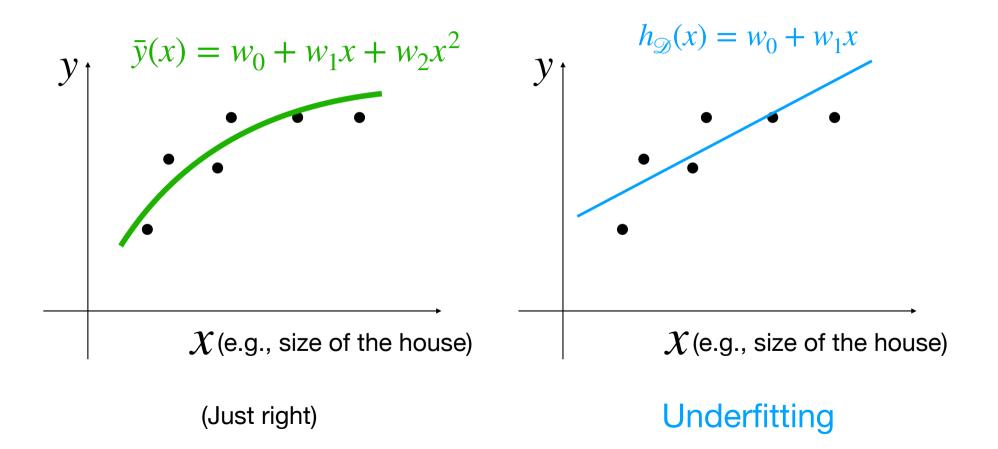




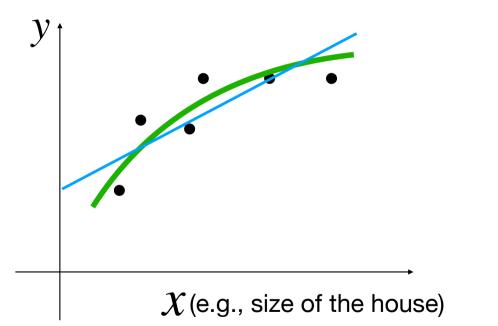








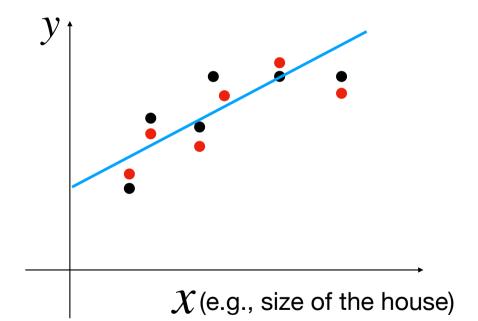
Just right versus Underfitting



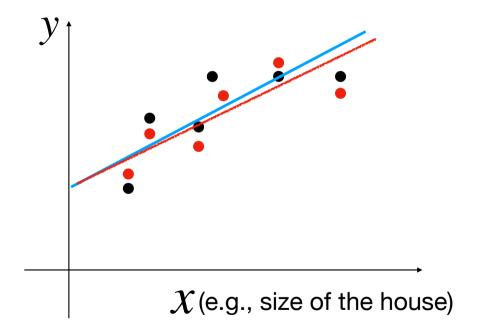


Bias towards to linear models

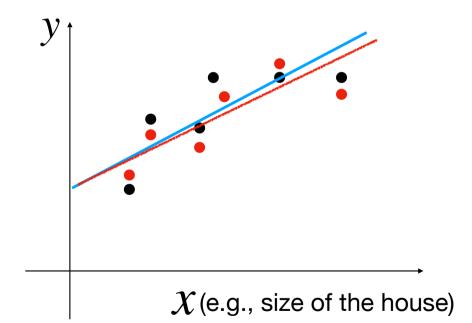
Now let's redo linear regression on a different dataset \mathcal{D}' , but from the same distribution



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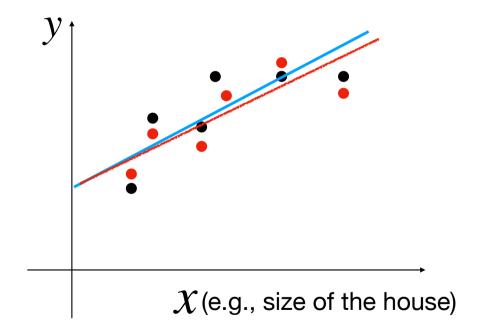


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The new linear function does not differ too much from the old one

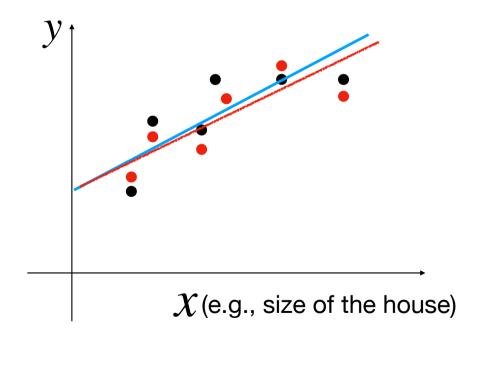
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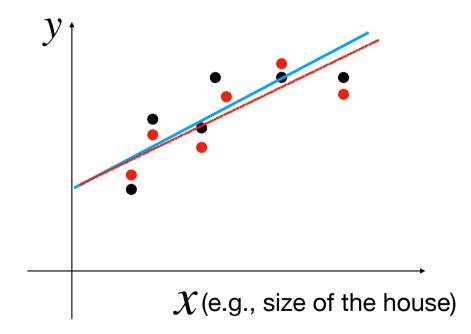
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Q: what happens when our linear predictor is $h(x) = w_0$?

min Z (yi-w

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Q: what happens when our linear predictor is $h(x) = w_0$?

A: in this case, w_0 models the mean of the y in data

Summary on underfitting

1. Often our model is too simple, i.e.., we bias towards too simple models

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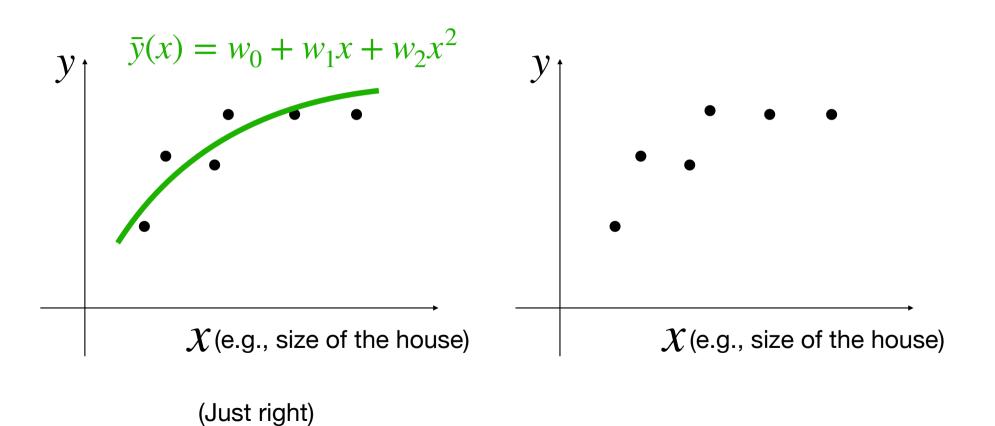
2. This causes underfitting, i.e., we cannot capture the trend in the data

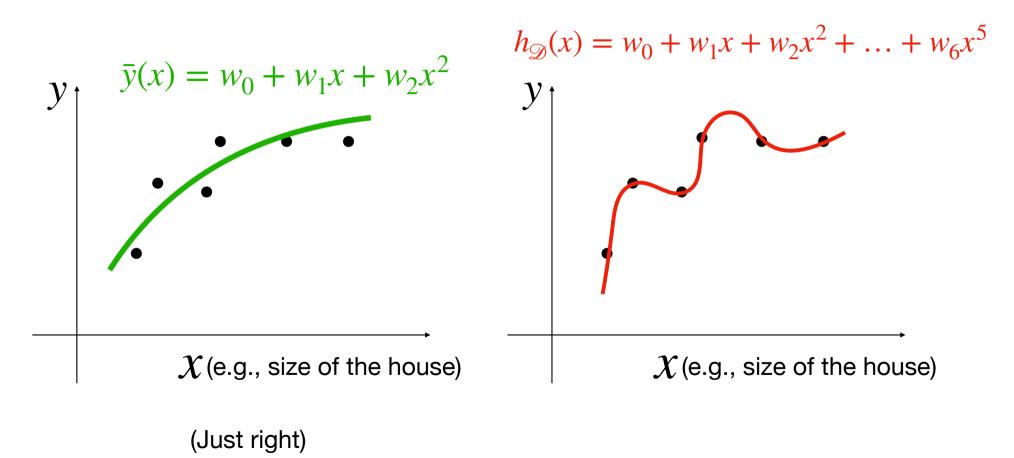
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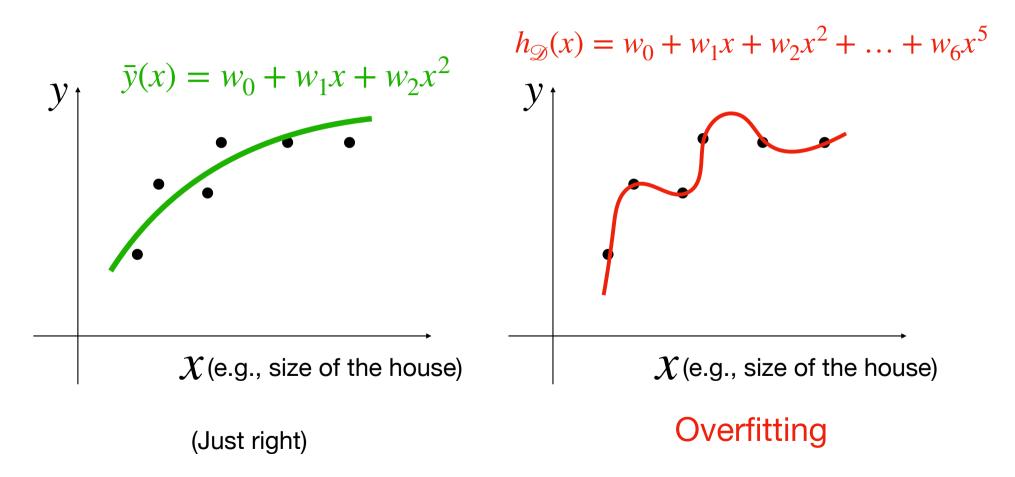
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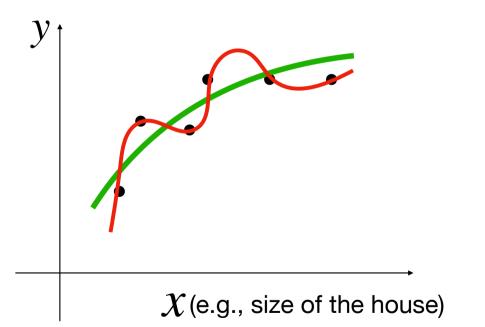
3. In this case, we have large bias, but low variance (think about the $h(x) = w_0$ case)







Just right versus Overfitting

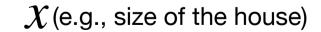




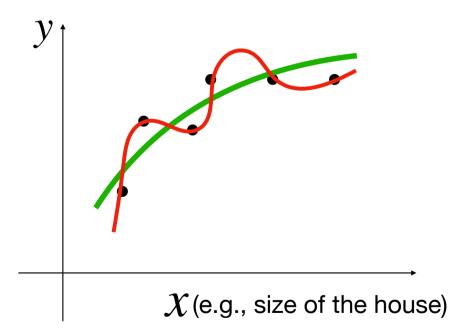
y



Our hypothesis class is all polynomials up to 5-th order



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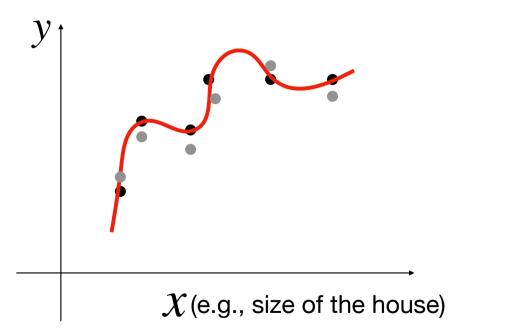


No strong bias:

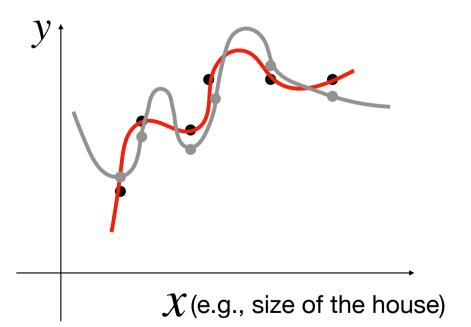
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i.e., in a priori, no strong bias towards linear or quadratic, or cubic, etc

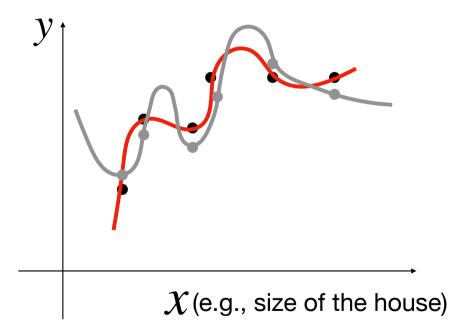
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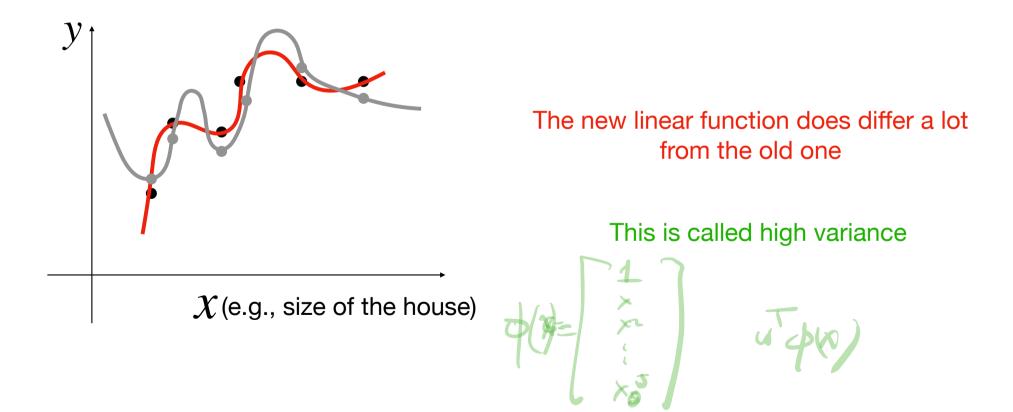


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1. Often our model is too complex (e.g., can fit noise perfectly to achieve zero training error)

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3. In this case, we have small bias, but large variance (tiny change on the dataset cause large change in the fitted functions)

Outline of Today

1. Intro on Underfitting/Overfitting and Bias/Variance

2. Derivation of the Bias-Variance Decomposition

3. Example on Ridge Linear Regression

Generalization error

Given dataset \mathcal{D} , a hypothesis class \mathcal{H} , squared loss $\ell(h, x, y) = (h(x) - y)^2$, denote $h_{\mathcal{D}}$ as the ERM solution $h_{\mathcal{D}} = \text{ERM}(\mathcal{P}, \ell)$ = arguin $\frac{1}{n} \overset{\mathcal{D}}{\underset{\mathcal{H}}{\underset{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}}{\underset{\mathcal{H}{$

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We are interested in the generalization bound of $h_{\mathcal{D}}$:

$$\mathbb{E}_{\mathcal{D}}\mathbb{E}_{x,y\sim P}(h_{\mathcal{D}}(x)-y)^2$$

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Q: how to estimate this in practice?

Since $h_{\mathcal{D}}$ is random, we consider its expected behavior:

$$\bar{h} := \mathbb{E}_{\mathscr{D}}\left[h_{\mathscr{D}}\right]$$

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A: $\bar{h}(x) = \mathbb{E}_{y}[y]$

$$\bar{h} := \mathbb{E}_{\mathscr{D}} \left[h_{\mathscr{D}} \right] \qquad \bar{y}(x) := \mathbb{E}[y \,|\, x]$$

Bias: difference between \bar{h} and the best $\bar{y}(x)$, i.e., $\mathbb{E}_{x}(\bar{y}(x) - \bar{h}(x))^{2}$

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Difference between our mean and the best

Variance: difference from
$$\bar{h}$$
 and $h_{\mathcal{D}}$, i.e., $\mathbb{E}_{\mathcal{D}}\mathbb{E}_{x}\left(h_{\mathcal{D}}(x) - \bar{h}(x)\right)^{2}$

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Difference between our mean and the best

Mean

Variance: difference from \overline{h} and $h_{\mathcal{D}}$, i.e., $\mathbb{E}_{\mathcal{D}}\mathbb{E}_{x}\left(h_{\mathcal{D}}(x)-\overline{h}(x)\right)^{2}$

Fluctuation of our random model around its mean

ERM From D

Generalization error decomposition

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What we gonna show now:

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$$\mathbb{E}_{\mathscr{D}}\mathbb{E}_{x,y\sim P}(h_{\mathscr{D}}(x)-y)^2$$

= **Bias** + **Variance** + Noise (unavoidable, independent of Algs/models)

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We will use the following trick twice: $(x - y)^2 = (x - z)^2 + (z - y)^2 + 2(x - z)(z - y)$

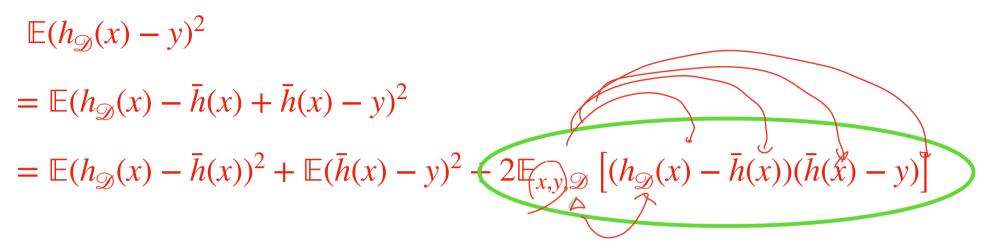
 $E(h_{\mathcal{D}}(x) - y)^2$ $= \mathbb{E}(h_{\mathcal{D}}(x) - \bar{h}(x) + \bar{h}(x) - y)^2$

 $= \mathbb{E}(h_{\mathcal{D}}(x) - \bar{h}(x))^2 + \mathbb{E}(\bar{h}(x) - y)^2 + 2\mathbb{E}_{x,y,\mathcal{D}}\left[(h_{\mathcal{D}}(x) - \bar{h}(x))(\bar{h}(x) - y)\right]$

$$\mathbb{E}(h_{\mathscr{D}}(x) - y)^{2}$$

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$$\mathbb{E}\left[(h_{\mathcal{D}}(x) - \bar{h}(x))(\bar{h}(x) - y)\right]$$

= $\mathbb{E}_{x,y}\left[\mathbb{E}_{\mathcal{D}}(h_{\mathcal{D}}(x) - \bar{h}(x)) \cdot (\bar{h}(x) - y)\right]$
= $h_{\mathcal{D}}(x) = h(x)$

$$\mathbb{E}(h_{\mathscr{D}}(x) - y)^{2}$$

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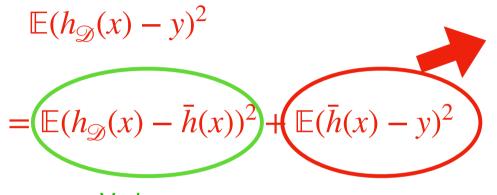
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$$\mathbb{E}(h_{\mathscr{D}}(x) - y)^2$$

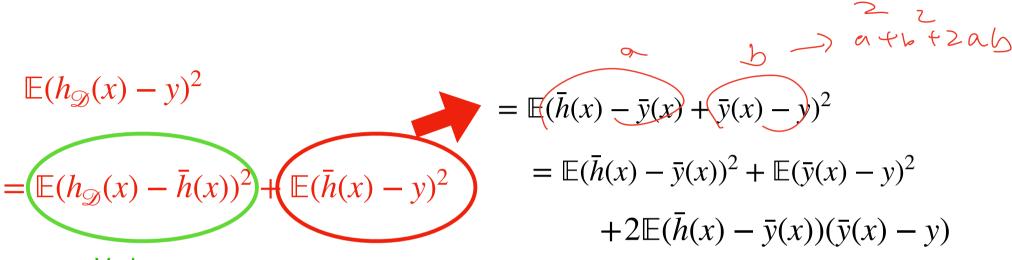
$$= \mathbb{E}(h_{\mathcal{D}}(x) - \bar{h}(x))^2 + \mathbb{E}(\bar{h}(x) - y)^2$$



Variance

$$\mathbb{E}(h_{\mathcal{D}}(x) - y)^{2} = \mathbb{E}(\bar{h}(x) - \bar{y}(x) + \bar{y}(x) - y)^{2}$$

$$= \mathbb{E}(h_{\mathcal{D}}(x) - \bar{h}(x))^{2} + \mathbb{E}(\bar{h}(x) - y)^{2}$$
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$$= \mathbb{E}(\bar{h}(x) - \bar{y}(x))^{2} + \mathbb{E}(\bar{y}(x) - y)^{2}$$

$$+ 2\mathbb{E}(\bar{h}(x) - \bar{y}(x))(\bar{y}(x) - y)$$
This term is zero since:
$$\mathbb{E}_{y} = \mathbb{E}(\bar{h}(x) - \bar{y}(x))(\bar{y}(x) - y)$$

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Variance

$$= \mathbb{E}_{\mathscr{D}} \mathbb{E}_{x}(\bar{h}(x) - \bar{y}(x)) \cdot \mathbb{E}_{y|x}(\bar{y}(x) - y)$$

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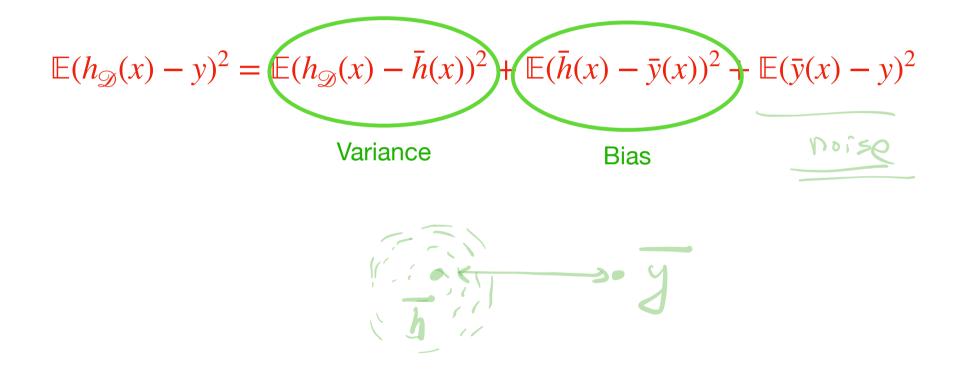
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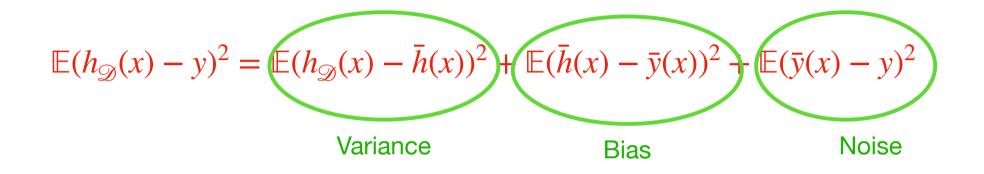
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$$= \mathbb{E}_{\mathfrak{D}}\mathbb{E}_{x}(\bar{h}(x) - \bar{y}(x)) \cdot (\bar{y}(x) - \mathbb{E}_{y|x}[y])$$

Putting the derivations together, we arrive at:



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 $\mathbb{E}(h_{\mathcal{D}}(x) - y)^2 = \mathbb{E}(h_{\mathcal{D}}(x) - \bar{h}(x))^2 + \mathbb{E}(\bar{h}(x) - \bar{y}(x))^2 - \mathbb{E}(\bar{y}(x) - y)^2$ Noise Variance Bias Note that the noise term is independent of training algorithms / models > Var at y conditioned on x

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Let us consider the case where features are fixed, i.e., x_1, \ldots, x_n fixed (no randomness)

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But
$$y_i \sim (w^*)^T x_i + \epsilon_i, \epsilon_i \sim \mathcal{N}(0,1)$$

T
GT Linear predictor

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(This is called LR w/ fixed design)

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(This is called LR w/ fixed design)

(So the only randomness of our dataset $\mathcal{D} = \{x_i, y_i\}$ is coming from the noises ϵ_i)

Ridge Linear Regression formulation

$$\hat{w} = \arg\min_{w} \sum_{i=1}^{n} (w^{\top} x_i - y_i)^2 + \lambda ||w||_2^2$$

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What we will show now:

Larger λ (model becomes "simpler") => larger bias, but smaller variance

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(Q: think about the case where $\lambda \to \infty$, what happens to \hat{w} ?)