

# Machine Learning for Intelligent Systems

Lecture 19: Statistical Learning Theory 3

Reading: UML 6

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## Growth Function & VC Dimension

**Growth function**

The set of all  $m$ -tuples produced by hypotheses in  $H$  on the sample set  $S$

$$H[S] = \{ (h(x_1), h(x_2), h(x_3), \dots, h(x_m)) \}_{h \in H}$$

**Growth function:**  $H[m] = \max_{|S|=m} |H[S]|$  is the largest number of unique rows that  $H$  can produce on any set of  $m$  elements.

**Recall: Shattering and VC Dimension**

$H$  **shatters** a sample set  $S$  if  $|H[S]| = 2^{|S|}$ .

**VC Dimension** of  $H$  is the size of the largest set  $S$  that can be shattered by  $H$ .  $\leftarrow$   $\text{VCDim}(H)$ : Largest  $m$  for which  $H[m] = 2^m$ .

To show that  $\text{VCDim}(H) = d$  we need to show

1. There **exists a set** of  $d$  points that can be shattered.
2. There is **no set** of  $d + 1$  points that can be shattered.

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## VC Dimension of Linear Threshold

**Theorem: VC Dimension of Linear thresholds in  $\mathbb{R}^d$**

Let  $H$  be the set of all homogenous linear thresholds in  $\mathbb{R}^d$ . We have  $\text{VCDim}(H) = d$ .

Let  $H$  be the set of all linear thresholds (possibly non-homogenous) in  $\mathbb{R}^d$ . We have  $\text{VCDim}(H) = d + 1$ .

- $\rightarrow$  You can shatter the set  $\{\vec{0}, \vec{e}_1, \dots, \vec{e}_d\}$ , where  $\vec{e}_i = (0, \dots, 0, 1, 0, \dots, 0)$  has 1 only at coordinate  $i$ .  $\rightarrow$   $\text{VCDim}(H) \geq d + 1$ . (Try at home)
- $\rightarrow$  Showing that we cannot shatter a set of  $d + 2$  points requires more work (we won't cover it).

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## VC Dimension & Learnability

VC Dimension is roughly the point where the growth function stops being exponential and becomes polynomial.

**When is learning from samples possible?**

- If  $\text{VCDim}(H) = \infty$  then  $H[m] = 2^m$  for all  $m$   
 $\rightarrow$  **It would be impossible to learn!**
- If  $\text{VCDim}(H) = d$  then  $H[m] < O(m^d)$  for all  $m$   
 $\rightarrow$  **We can learn!**

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## PAC Learnability

**Probably Approximately Correct Learnability**

A hypothesis class  $H$  is **PAC learnable** if there is a function  $m_H(\epsilon, \delta)$  and a learning algorithm such that:

For any  $\epsilon, \delta \in (0, 1)$  and any distribution  $P$  over  $X \times Y$  such that all samples are labeled by one hypothesis  $h^* \in H$ , running the learning algorithm on  $m \geq m_H(\epsilon, \delta)$  i.i.d. samples generated from  $P$ , the algorithm returns  $h \in H$  such that with probability  $1 - \delta$  over the choice of the samples,  $\text{err}_P(h) \leq \epsilon$ .

**Often called "realizable" PAC:** There is a hypothesis  $\text{err}_P(h^*) = 0$

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## Agnostic PAC Learnability

**Probably Approximately Correct Learnability**

A hypothesis class  $H$  is **PAC learnable** if there is a function  $m_H(\epsilon, \delta)$  and a learning algorithm such that:

For any  $\epsilon, \delta \in (0, 1)$  and any distribution  $P$  over  $X \times Y$  running the learning algorithm on  $m \geq m_H(\epsilon, \delta)$  i.i.d. samples generated from  $P$ , the algorithm returns  $h \in H$  such that with probability  $1 - \delta$  over the choice of the samples  $\text{err}_P(h) \leq \min_{h \in H} \text{err}_P(h) + \epsilon$

**Often called "agnostic" PAC:** No assumption on  $\min_{h \in H} \text{err}_P(h)$

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**Theorem: Sample Complexity Infinite Hypothesis Class (zero empirical error)**

Let  $m \geq \frac{c_0}{\epsilon} \left( VCdim(H) \ln\left(\frac{1}{\epsilon}\right) + \ln\left(\frac{1}{\delta}\right) \right)$ . For any  $X, Y = \{-1, 1\}$ , and distribution  $P$  on  $X \times Y$ , with probability  $1 - \delta$  over i.i.d draws of set  $S$  of  $m$  samples, any  $h \in H$  such that  $err_S(h) = 0$ , also has  $err_P(h) < \epsilon$ .

**Probably Approximately Correct (PAC)**  
(Belief that  $err_P(h^*) = 0$ )

**Agnostic Probably Approximately Correct**  
(No belief about value of  $err_P(h^*)$ )

**Theorem: Sample Complexity infinite Hypothesis Class (Non-zero empirical error)**

Let  $m \geq \frac{c_0}{\epsilon^2} \left( VCdim(H) + \ln\left(\frac{1}{\delta}\right) \right)$ . For any  $X, Y = \{-1, 1\}$ , and distribution  $P$  on  $X \times Y$ , with probability  $1 - \delta$  over i.i.d draws of set  $S$  of  $m$  samples,  $h_S = \text{argmin}_{h \in H} err_S(H)$  has  $err_P(h_S) \leq err_P(h^*) + \epsilon$ .

**Algorithm: Empirical Risk Minimization (ERM)**

**Empirical Risk Minimization alg:** Return  $h_S = \text{argmin}_{h \in H} err_S(H)$

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## VC Dimension & Learnability

When is learning from samples possible?

All the following are equivalent:

- $H$  has finite VC dimension.
- $H$  is (realizable) PAC learnable
- $H$  is agnostically PAC learnable
- The Empirical Risk Minimization algorithm PAC learns  $H$ .
- The Empirical Risk Minimization algorithm agnostically PAC learns  $H$ .

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