## **Prediction and Overfitting**

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Reading: Mitchell Sections 3.6 – 3.7

### Learning as Prediction

**Definition:** A particular instance of a learning problem is described by a probability distribution P(X, Y).

**Definition:** A sample  $S = ((\vec{x}_1, y_1), ..., (\vec{x}_n, y_n))$  is independently identically distributed (i.i.d.) according to P(X, Y) if

 $P(S = ((\vec{x}_1, y_1), ..., (\vec{x}_n, y_n))) = \prod_{i=1}^n P(X = \vec{x}_i, Y = y_i)$ 

# Sample Error and Generalization Error

**Definition:** The error on sample  $S \ Err_S(h)$  of a hypothesis h is  $Err_S(h) = \frac{1}{n} \sum_{i=1}^{n} \Delta(h(\vec{x_i}), y_i).$ 

**Definition:**  $\Delta(a,b)$  is the 0/1-loss function

$$\Delta(a,b) = \begin{cases} 0 & if(a == b) \\ 1 & else \end{cases}$$

**Definition:** The prediction/generalization/true error  $Err_P(h)$  of a hypothesis h for a learning task P(X,Y) is

$$Err_P(h) = \sum_{\vec{x} \in X, y \in Y} \Delta(h(\vec{x}), y) P(X = \vec{x}, Y = y).$$



- Goal: Find h with small prediction error Err<sub>P</sub>(h) over P(X,Y).
  Strategy: Find (any?) h with small error Err<sub>Strain</sub>(h) on training sample S<sub>train</sub>.
- Training Error: Error *Err<sub>Strain</sub>(h)* on training sample.
- Test Error: Error  $Err_{S_{test}}(h)$  on test sample is an estimate of  $Err_{P}(h)$ .

### Overfitting



• Note: Accuracy = 1.0-Error

#### **Decision Tree Example: revisited**



 $\vec{x}_{10} = (c, y, c) y_{10}$ 

#### **Reduced-Error Pruning**



# Text Classification Example Results

- Unpruned Tree:
  - Size: 437 nodes Training Error: 0.0% Test Error: 11.0%
- Early Stopping Tree:
  - Size: 299 nodes Training Error: 2.6% Test Error: 9.8%
- Post-Pruned Tree:
  - Size: 167 nodes Training Error: 4.0% Test Error: 10.8%
- Rule Post-Pruning:
  - Size: 164 tests Training Error: 3.1% Test Error: 10.3%
  - Examples of rules
    - IF vs = 1 THEN [99.4%]
    - IF vs = 0 & export = 0 & takeover = 1 THEN + [93.6%]