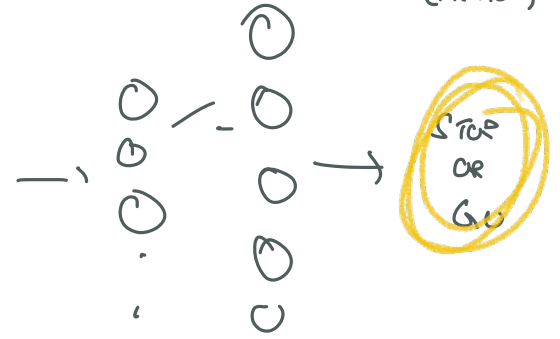


INPUT  
(STATE)

- SPEED
- POSITION OF THE CAR
- STATE OF THE LIGHT
- POSITION OF OTHER ACTOR

• PREVIOUS ACTION

OUTPUT  
(ACTION)



(x,y) are in Q