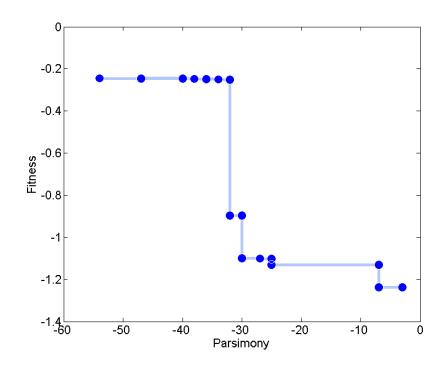
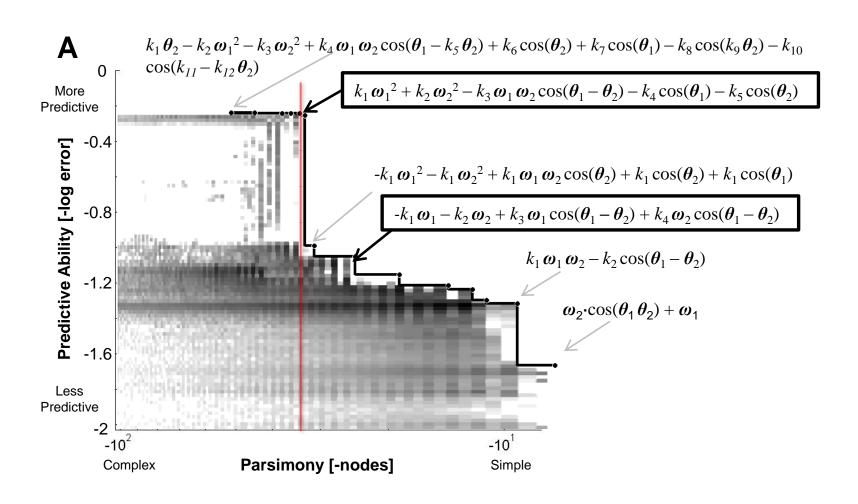
Overfitting

Accuracy Vs. Complexity

- Many hypotheses. How to choose?
- Pareto charts



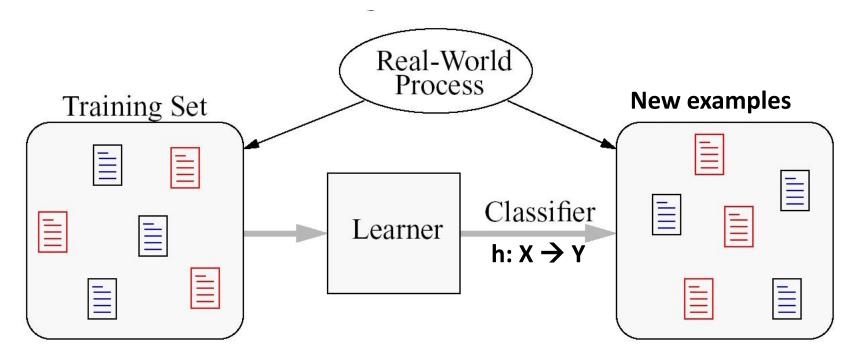
Example



Regularization

- Forcing solutions to be simple
 - Add penalty for complex models
 - E.g. accuracy + size of tree
 - Number of samples in Thin-KNN
 - Sum of weights or number of nonzero weights (number of connections) in NN

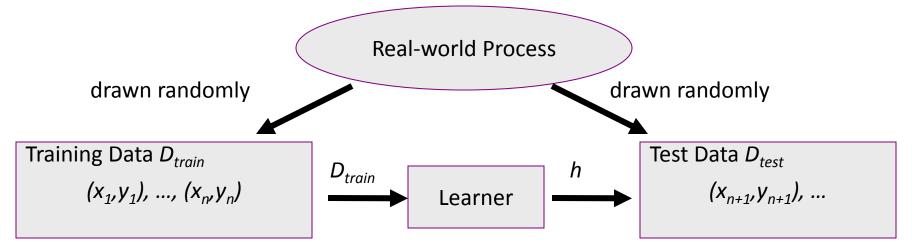
Inductive Learning Setting



Learning as Prediction:

- Learner induces a general rule h from a set of observed examples that classifies new examples accurately.
- Assume source is stationary and samples are representative.

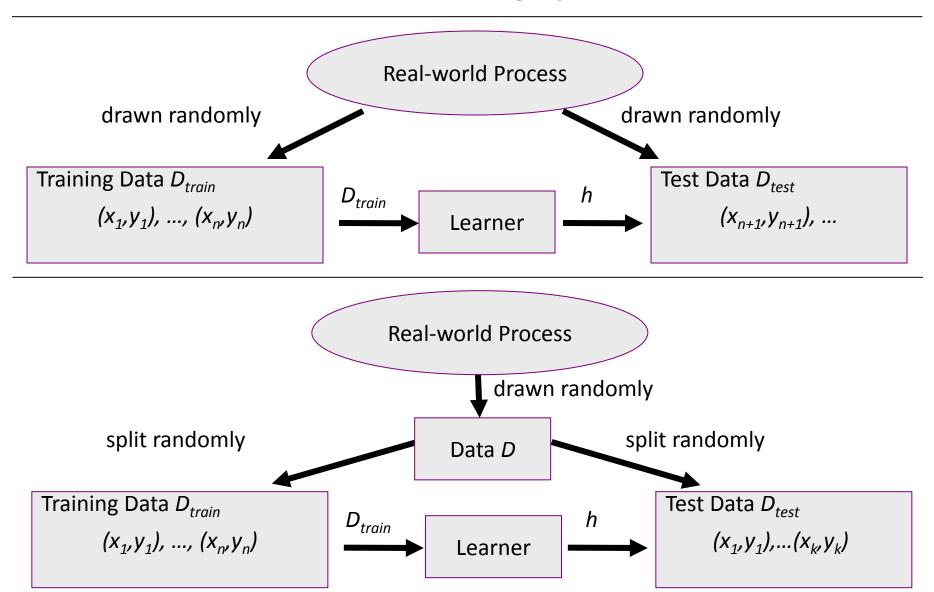
Testing Machine Learning Algorithms



Machine Learning Experiment:

- Gather training examples D_{train}
- Run learning algorithm on D_{train} to produce h
- Gather Test Examples D_{test}
- Apply h to D_{test} and measure how many test examples are predicted correctly by h

Test/Training Split



Measuring Prediction Performance

Definition: The training error $Err_{D_{train}}(h)$ on training data $D_{train} = ((\vec{x}_1, y_1), ..., (\vec{x}_n, y_n))$ of a hypothesis h is $Err_{D_{train}}(h) = \frac{1}{n} \sum_{i=1}^{n} \Delta(h(\vec{x}_i), y_i)$.

Definition: The **test error** $Err_{D_{test}}(h)$ on test data $D_{test} = ((\vec{x}_1, y_1), ..., (\vec{x}_k, y_k))$ of a hypothesis h is $Err_{D_{test}}(h) = \frac{1}{n} \sum_{i=1}^{k} \Delta(h(\vec{x}_i), y_i)$.

Definition: The prediction/generalization/true error $Err_P(h)$ of a hypothesis h for a learning task P(X,Y) is

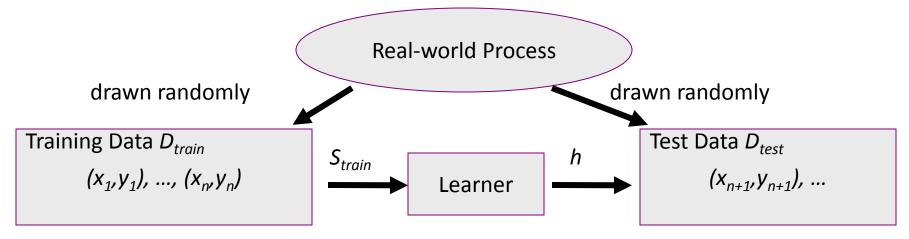
$$Err_P(h) = \sum_{\vec{x} \in X, y \in Y} \Delta(h(\vec{x}), y) P(X = \vec{x}, Y = y).$$

Definition: The zero/one-loss function $\Delta(a,b)$ returns 1 if $a \neq b$ and 0 otherwise.

Performance Measures

- Error Rate
 - Fraction (or percentage) of false predictions
- Accuracy
 - Fraction (or percentage) of correct predictions
- Precision/Recall
 - Applies only to binary classification problems (classes pos/neg)
 - Precision: Fraction (or percentage) of correct predictions among all examples predicted to be positive
 - Recall: Fraction (or percentage) of correct predictions among all positive examples

Learning as Prediction Task

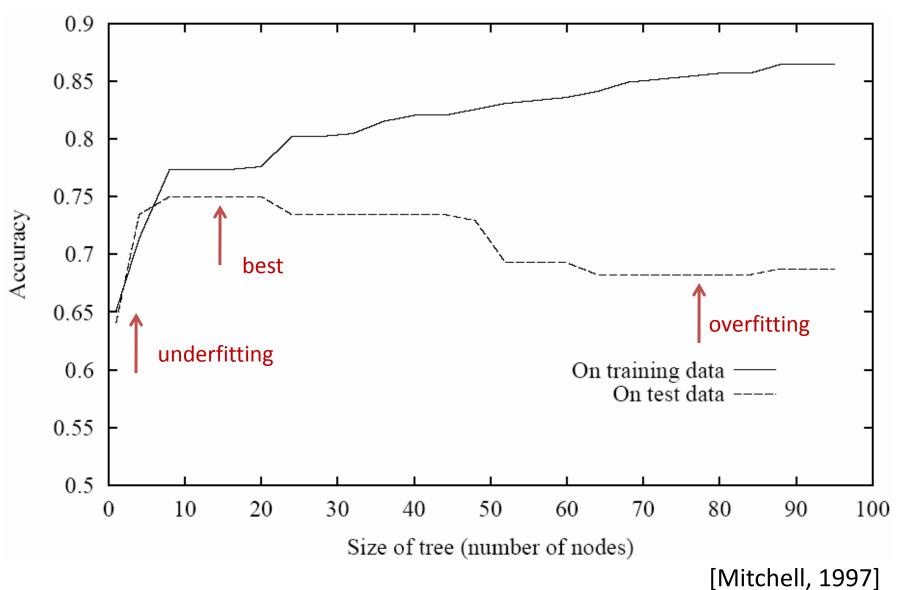


- Goal: Find h with small prediction error $Err_p(h)$.
- Strategy: Find (any?) h with small error $Err_{D_{train}}(h)$ on D_{train} .

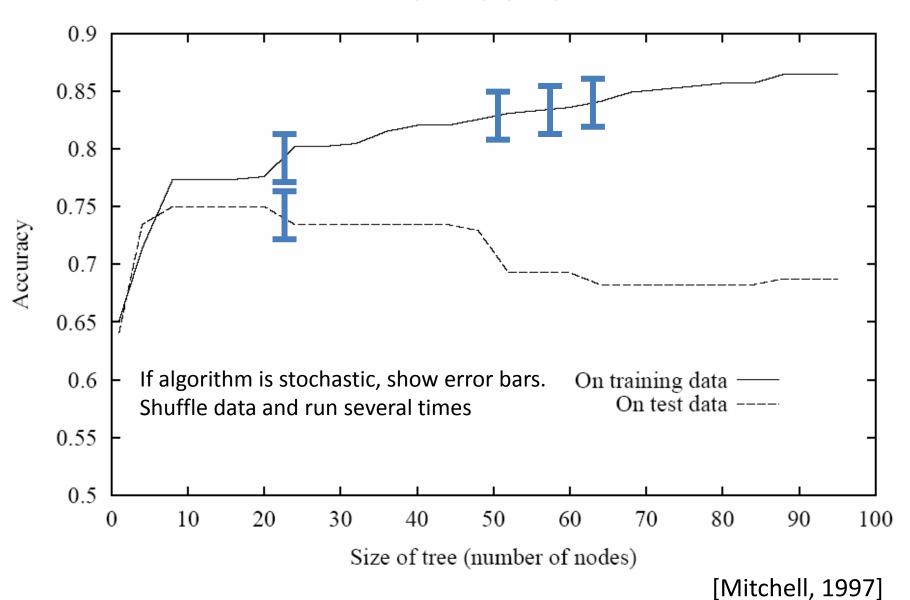
Inductive Learning Hypothesis: Any hypothesis found to approximate the target function well over a sufficiently large set of training examples will also approximate the target function well over any other unobserved examples.

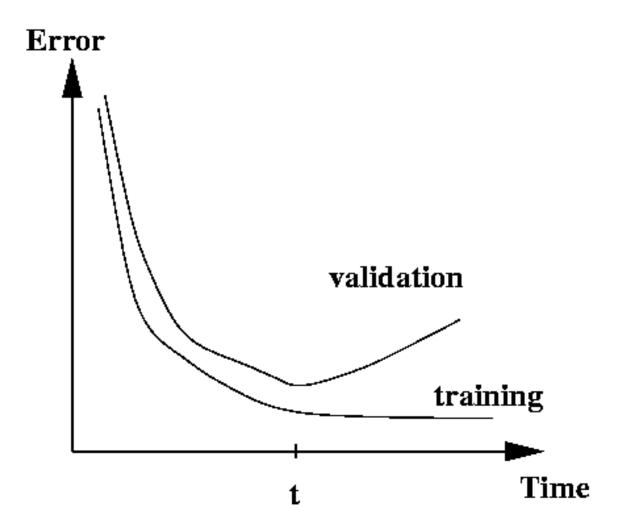
→ Is Inductive Learning Hypothesis really true?

Overfitting vs. Underfitting



Error bars





Example: Text Classification

- Task: Learn rule that classifies Reuters Business News
 - Class +: "Corporate Acquisitions"
 - Class -: Other articles
 - 2000 training instances
- Representation:
 - Boolean attributes, indicating presence of a keyword in article
 - 9947 such keywords (more accurately, word "stems")

LAROCHE STARTS BID FOR NECO SHARES



Investor David F. La Roche of North Kingstown, R.I., said he is offering to purchase 170,000 common shares of NECO Enterprises Inc at 26 dlrs each. He said the successful completion of the offer, plus shares he already owns, would give him 50.5 pct of NECO's 962,016 common shares. La Roche said he may buy more, and possible all NECO shares. He said the offer and withdrawal rights will expire at 1630 EST/2130 gmt, March 30, 1987.

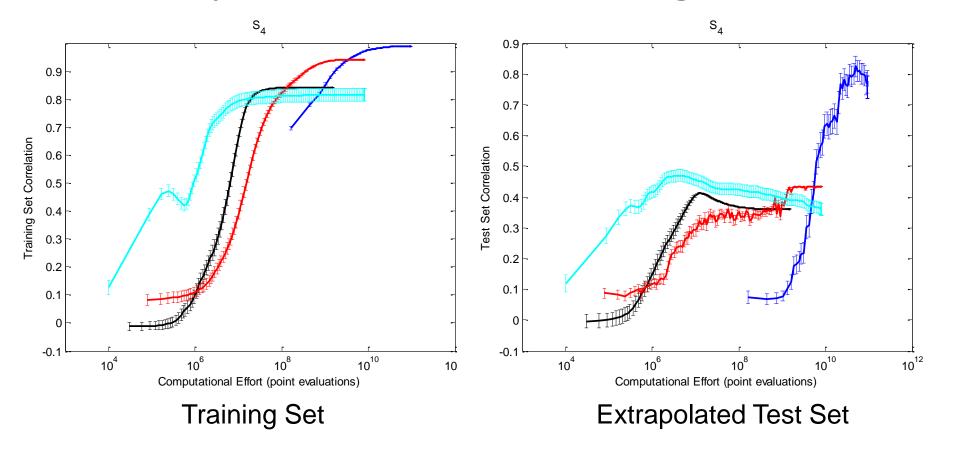
SALANT CORP 1ST QTR FEB 28 NET

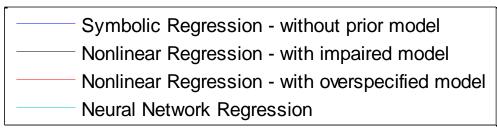
Oper shr profit seven cts vs loss 12 cts. Oper net profit 216,000 vs loss 401,000. Sales 21.4 mln vs 24.9 mln. NOTE: Current year net excludes 142,000 dlr tax credit. Company operating in Chapter 11 bankruptcy.

Text Classification Example: Results

- Data
 - Training Sample: 2000 examples
 - Test Sample: 600 examples
- Full Decision Tree:
 - Size: 437 nodes Training Error: 0.0%
 - Test Error: 11.0%
- Early Stopping Tree:
 - Size: 299 nodes Training Error: 2.6%
 - Test Error: 9.8%

Comparison to NN and Regression



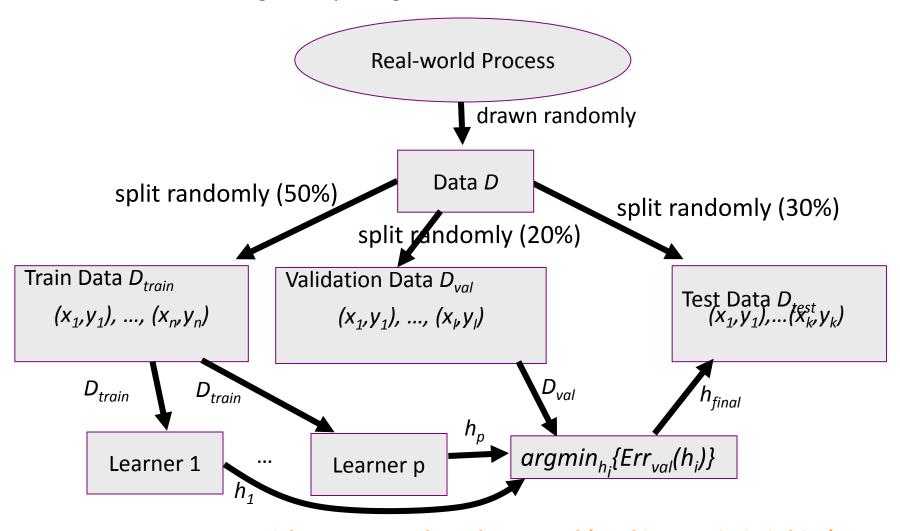


Averaged over 100 independent runs

Selecting Algorithm Parameters

Optimal choice of algorithm parameters depends on learning task:

• k in k-nearest neighbor, splitting criterion in decision trees



DANGER: Never pick parameters based on Dtest! (peeking, optimistic bias)

K-fold Cross Validation

Given

- Sample of labeled instances D (after putting aside D_{test})
- Learning Algorithms $A_1 \dots A_p$ (e.g. k-NN with different k)

Compute

- Randomly partition D into k equally sized subsets $D_1 \dots D_k$
- For *i* from 1 to *k*
 - Train $A_1 \dots A_p$ on $\{D_1 \dots D_{i-1} D_{i+1} \dots D_k\}$ and get $h_1 \dots h_p$.
 - Apply $h_1 \dots h_p$ to D_i and compute $Err_{D_i}(h_1) \dots Err_{D_i}(h_p)$.

Estimate

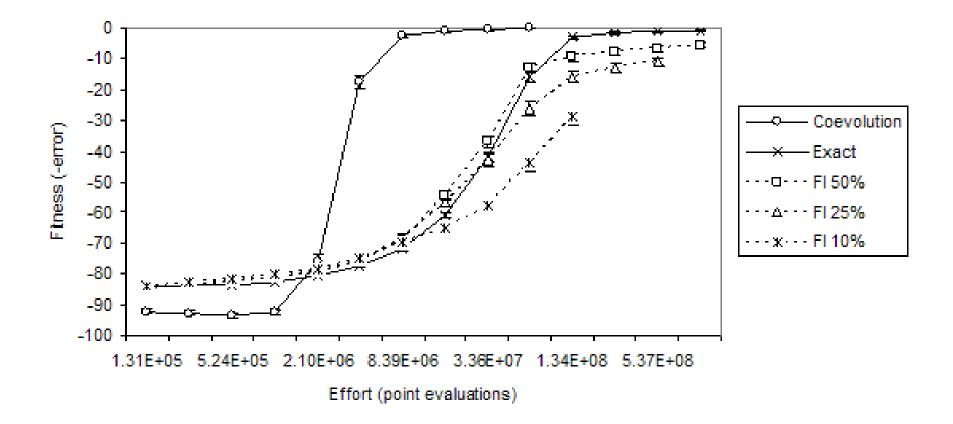
- $Err_{CV}(A_i)$ $\leftarrow 1/k \sum_{i \in \{1...k\}} Err_{D_i}(h_1)$ is estimate of the prediction error of A_i
- Pick algorithm A_{best} with lowest $Err_{CV}(A_i)$
- Train A_{hest} on D and output resulting h

Active learning

 Use uncertainty in h to guide the creation of training/validation set

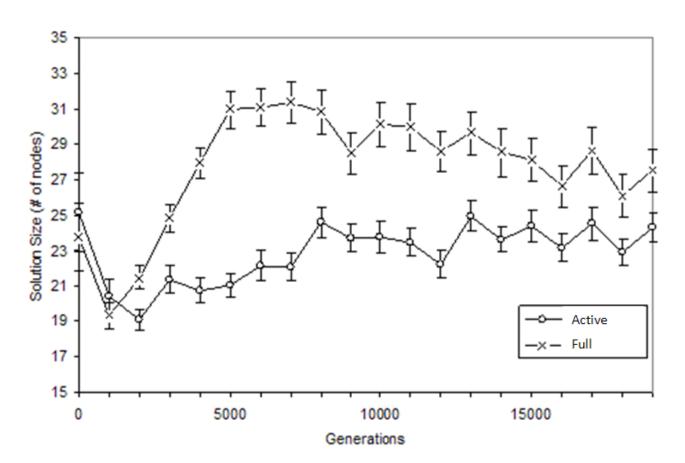
Active learning

 Use uncertainty in h to guide the creation of training/validation set



Active learning

Reduces complexity (hypothesis size) for same accuracy



Why learning doesn't always work

- Unrealizability
 - f may not be in H or not easily represented in H
- Variance
 - There may be many ways to represent f
 - depends on the specific training set
- Noise/stochasticity
 - Elements that cannot be predicted: Missing attributes or stochastic process
- Complexity
 - Finding f may be intractable

Example: Smart Investing

Task: Pick stock analyst based on past performance. Experiment:

- Have analyst predict "next day up/down" for 10 days.
- Pick analyst that makes the fewest errors.

Situation 1:

1 stock analyst {A1}, A1 makes 5 errors

Situation 2:

3 stock analysts {A1,B1,B2}, B2 best with 1 error

Situation 3:

1003 stock analysts {A1,B1,B2,C1,...,C1000},
C543 best with 0 errors

Which analysts are you most confident in, A1, B2, or C543?