Visualizing convolutional networks

• Which input pixels does a particular unit in a feature map depends on









Visualizing convolutional networks

- Take images for which a given unit in a feature map scores high
- Identify the receptive field for each.



Rich feature hierarchies for accurate object detection and semantic segmentation. R. Girshick, J. Donahue, T. Darrell, J. Malik. In *CVPR*, 2014.

Visualizing convolutional networks II

• Block regions of the image and classify



Visualizing and Understanding Convolutional Networks. M. Zeiler and R. Fergus. In ECCV 2014.

Visualizing convolutional networks II

 Image pixels important for classification = pixels when blocked cause misclassification





Visualizing and Understanding Convolutional Networks. M. Zeiler and R. Fergus. In ECCV 2014.

Semantic Segmentation

The Task



Evaluation metric

- Pixel classification!
- Accuracy?
 - Heavily unbalanced
 - Common classes are overemphasized
- Intersection over Union
 - Average across classes and images
- Per-class accuracy
 - Compute accuracy for every class and then average



Things vs Stuff

THINGS

- Person, cat, horse, etc
- Constrained shape
- Individual instances with separate identity
- May need to look at objects

STUFF

- Road, grass, sky etc
- Amorphous, no shape
- No notion of instances
- Can be done at pixel level
- "texture"





Challenges in data collection

- Precise localization is hard to annotate
- Annotating every pixel leads to heavy tails
- Common solution: annotate few classes (often things), mark rest as "Other"
- Common datasets: PASCAL VOC 2012 (~1500 images, 20 categories), COCO (~100k images, 20 categories)

Pre-convnet semantic segmentation

- Things
 - Do object detection, then segment out detected objects
- Stuff
 - "Texture classification"
 - Compute histograms of filter responses
 - Classify local image patches











- Pass image through convolution and subsampling layers
- Final convolution with #classes outputs
- Get scores for *subsampled* image
- Upsample back to original size



The resolution issue

- Problem: Need fine details!
- Shallower network / earlier layers?
 - Deeper networks work better: more abstract concepts
 - Shallower network => Not very semantic!
- Remove subsampling?
 - Subsampling allows later layers to capture larger and larger patterns
 - Without subsampling => Looks at only a small window!

Solution 1: Image pyramids



Learning Hierarchical Features for Scene Labeling. Clement Farabet, Camille Couprie, Laurent Najman, Yann LeCun. In *TPAMI*, 2013

Solution 2: Skip connections



Visualizations from : M. Zeiler and R. Fergus. Visualizing and Understanding Convolutional Networks. In ECCV 2014.

Solution 2: Skip connections



Compute class scores at multiple layers, then upsample and add

Solution 2: Skip connections



Red arrows indicate backpropagation

Skip connections



Fully convolutional networks for semantic segmentation. Evan Shelhamer, Jon Long, Trevor Darrell. In CVPR 2015

- Need subsampling to allow convolutional layers to capture large regions with small filters
 - Can we do this without subsampling?



- Need subsampling to allow convolutional layers to capture large regions with small filters
 - Can we do this without subsampling?



- Need subsampling to allow convolutional layers to capture large regions with small filters
 - Can we do this without subsampling?



- Instead of subsampling by factor of 2: dilate by factor of 2
- Dilation can be seen as:
 - Using a much larger filter, but with most entries set to 0
 - Taking a small filter and "exploding" / "dilating" it
- Not panacea: without subsampling, feature maps are much larger: memory issues

Putting it all together



Semantic Image Segmentation with Deep Convolutional Nets and Fully Connected CRFs. Liang-Chieh Chen, George Papandreou, Iasonas Kokkinos, Kevin Murphy, Alan Yuille. In *ICLR*, 2015.