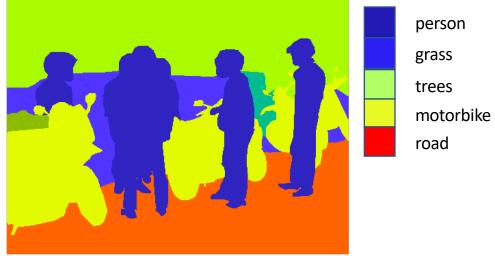
## Semantic Segmentation

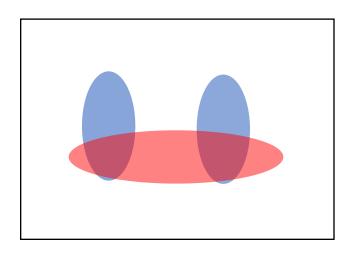
### The Task





#### Evaluation metric

- Pixel classification!
- Accuracy?
  - Heavily unbalanced
  - Common classes are overemphasized
- Intersection over Union
  - Average across classes and images
- Per-class accuracy
  - Compute accuracy for every class and then average



### Things vs Stuff

#### **THINGS**

- Person, cat, horse, etc
- Constrained shape
- Individual instances with separate identity
- May need to look at objects



#### STUFF

- Road, grass, sky etc
- Amorphous, no shape
- No notion of instances
- Can be done at pixel level
- "texture"

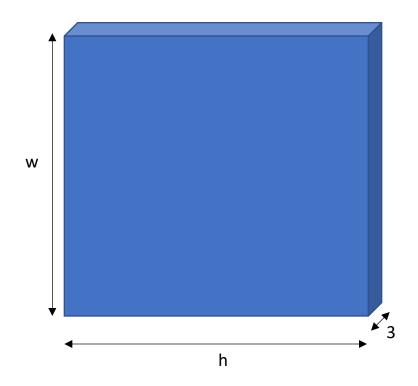


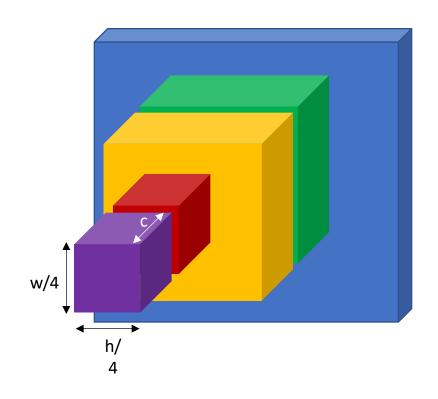
### Challenges in data collection

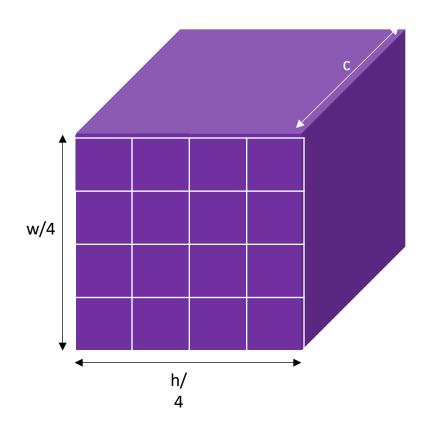
- Precise localization is hard to annotate
- Annotating every pixel leads to heavy tails
- Common solution: annotate few classes (often things), mark rest as "Other"
- Common datasets: PASCAL VOC 2012 (~1500 images, 20 categories), COCO (~100k images, 20 categories)

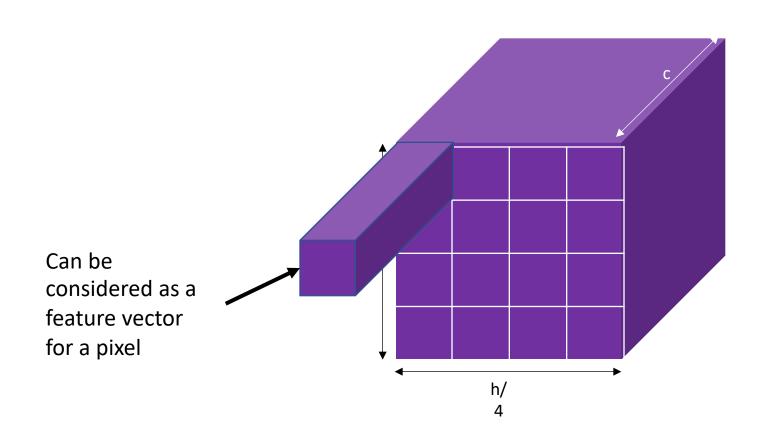
### Pre-convnet semantic segmentation

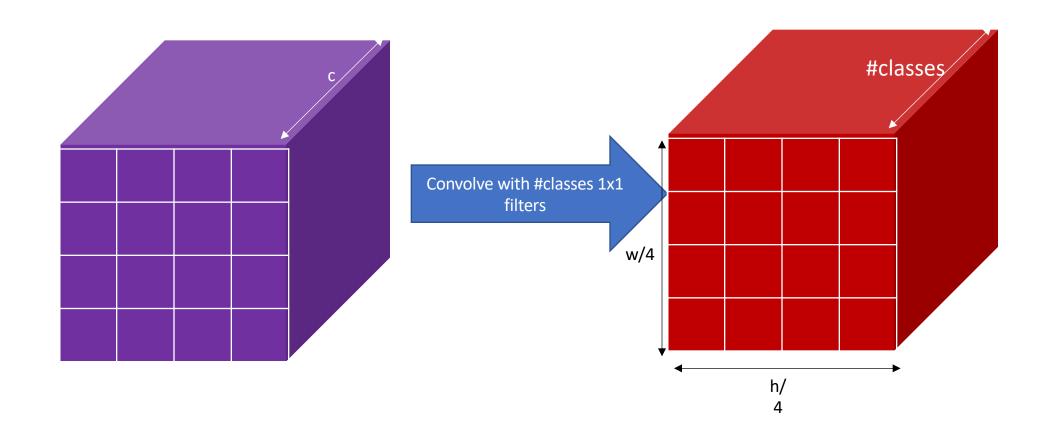
- Things
  - Do object detection, then segment out detected objects
- Stuff
  - "Texture classification"
  - Compute histograms of filter responses
  - Classify local image patches



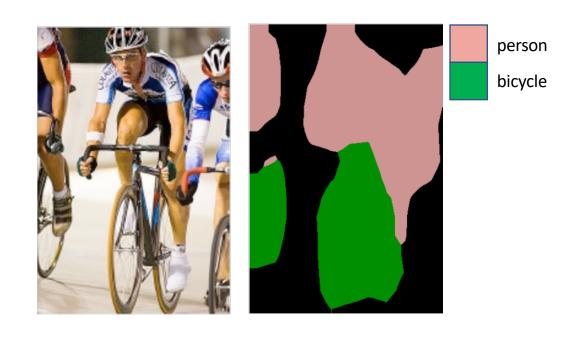








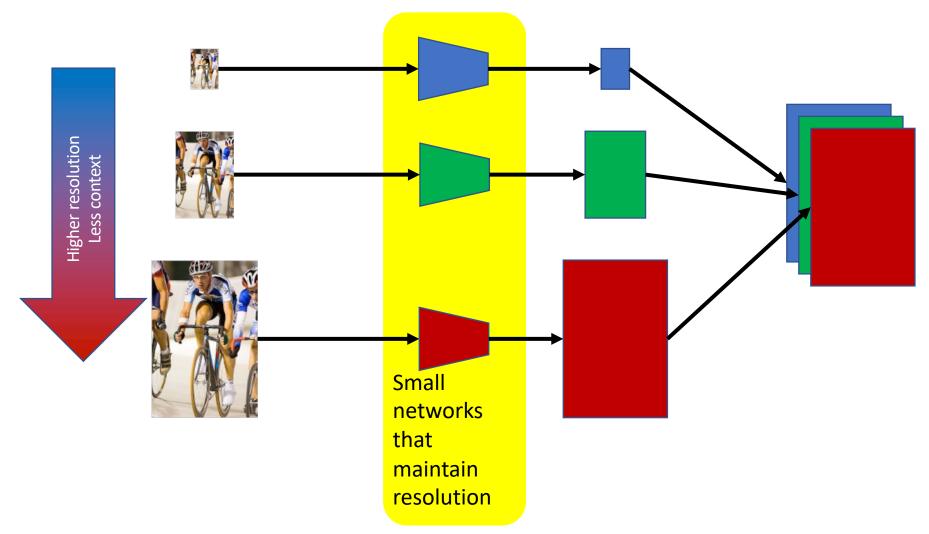
- Pass image through convolution and subsampling layers
- Final convolution with #classes outputs
- Get scores for *subsampled* image
- Upsample back to original size



#### The resolution issue

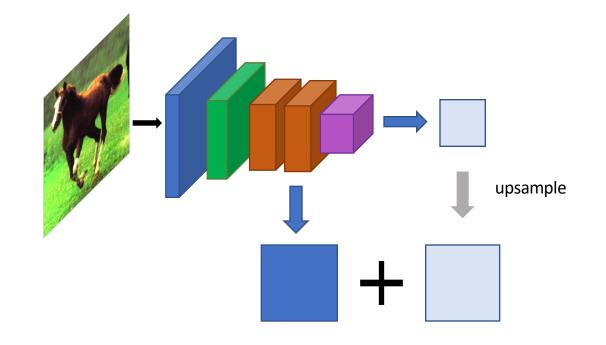
- Problem: Need fine details!
- Shallower network / earlier layers?
  - Deeper networks work better: more abstract concepts
  - Shallower network => Not very semantic!
- Remove subsampling?
  - Subsampling allows later layers to capture larger and larger patterns
  - Without subsampling => Looks at only a small window!

### Solution 1: Image pyramids



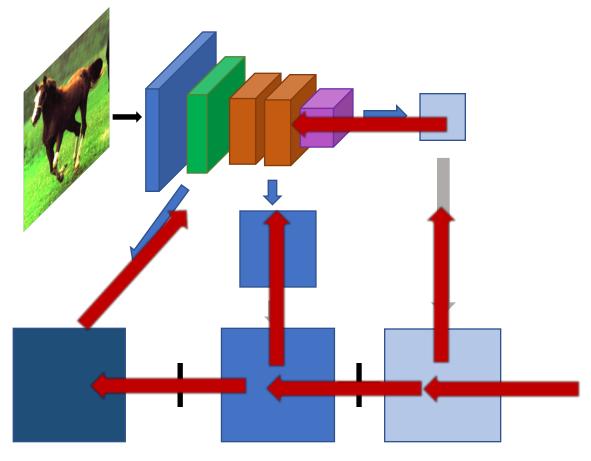
Learning Hierarchical Features for Scene Labeling. Clement Farabet, Camille Couprie, Laurent Najman, Yann LeCun. In *TPAMI*,

### Solution 2: Skip connections



Compute class scores at multiple layers, then upsample and add

### Solution 2: Skip connections



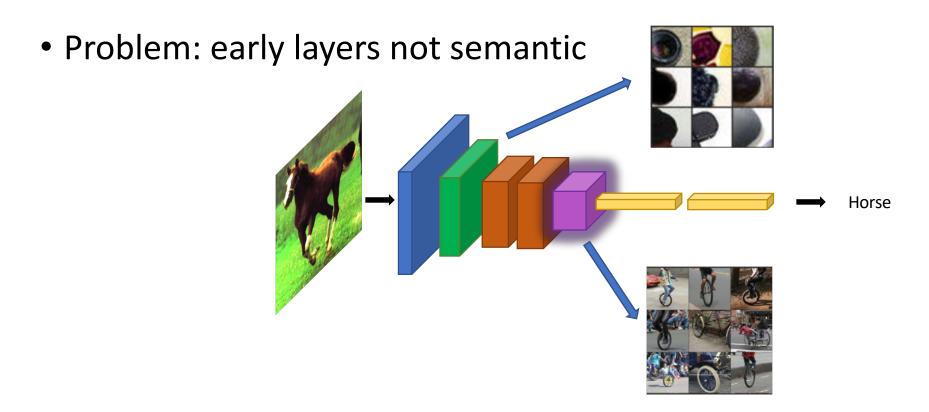
Red arrows indicate backpropagation

### Skip connections



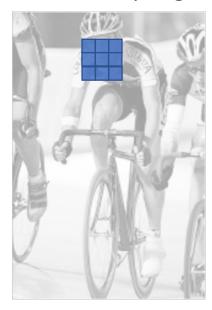
Fully convolutional networks for semantic segmentation. Evan Shelhamer, Jon Long, Trevor Darrell. In CVPR 2015

### Skip connections



Visualizations from: M. Zeiler and R. Fergus. Visualizing and Understanding Convolutional Networks. In ECCV 2014.

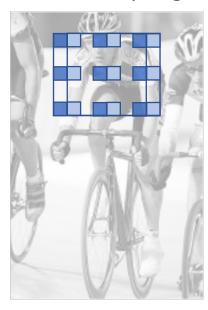
- Need subsampling to allow convolutional layers to capture large regions with small filters
  - Can we do this without subsampling?



- Need subsampling to allow convolutional layers to capture large regions with small filters
  - Can we do this without subsampling?

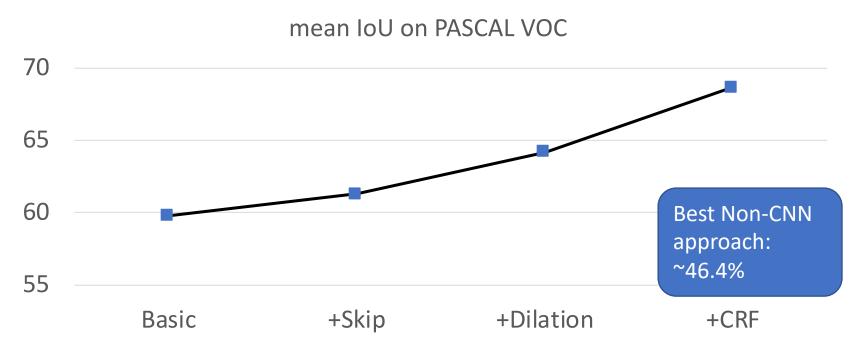


- Need subsampling to allow convolutional layers to capture large regions with small filters
  - Can we do this without subsampling?



- Instead of subsampling by factor of 2: dilate by factor of 2
- Dilation can be seen as:
  - Using a much larger filter, but with most entries set to 0
  - Taking a small filter and "exploding"/ "dilating" it
- Not panacea: without subsampling, feature maps are much larger: memory issues

### Putting it all together



Semantic Image Segmentation with Deep Convolutional Nets and Fully Connected CRFs. Liang-Chieh Chen, George Papandreou, Iasonas Kokkinos, Kevin Murphy, Alan Yuille. In *ICLR*, 2015.