

CS 4110

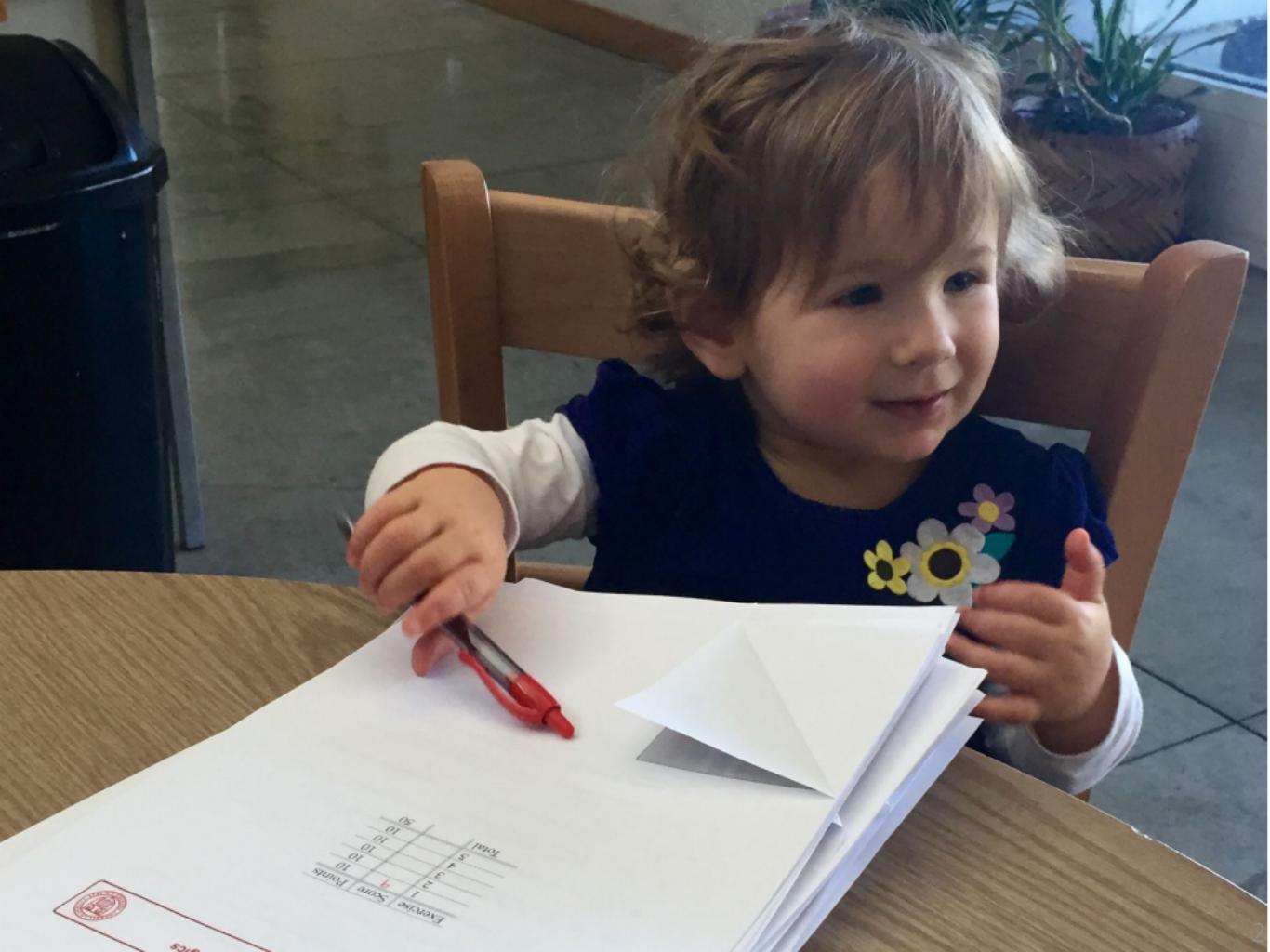
# Programming Languages & Logics

Lecture 31

Featherweight Java and Object Encodings

17 November 2014

- Foster Office Hours today 4-5pm
- HW 9 out Wednesday
- Prelim II debrief Wednesday



| Pencils | Score | Points |
|---------|-------|--------|
| 1       | 9     | 10     |
| 2       | 8     | 10     |
| 3       | 7     | 10     |
| 4       | 6     | 10     |
| 5       | 5     | 10     |
| 6       | 4     | 10     |
| 7       | 3     | 10     |
| 8       | 2     | 10     |
| 9       | 1     | 10     |
| 10      | 0     | 10     |

# Properties

## Lemma (Preservation)

If  $\Gamma \vdash e : C$  and  $e \rightarrow e'$  then there exists a type  $C'$  such that  $\Gamma \vdash e' : C'$  and  $C' \leq C$ .

## Lemma (Progress)

Let  $e$  be an expression such that  $\vdash e : C$ . Then either:

1.  $e$  is a value,
2. there exists an expression  $e'$  such that  $e \rightarrow e'$ , or
3.  $e = E[(B) (\text{new } A(\bar{v}))]$  with  $A \not\leq B$ .

# Lemmas

## Lemma (Method Typing)

If  $mtype(m, C) = \bar{D} \rightarrow D$  and  $mbody(m, C) = (\bar{x}, e)$  then there exists types  $C'$  and  $D'$  such that  $\bar{x} : \bar{D}$ ,  $this : C' \vdash e : D'$  and  $D' \leq D$ .

# Lemmas

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## Lemma (Substitution)

If  $\Gamma, \bar{x} : \bar{B} \vdash e : C$  and  $\Gamma \vdash \bar{u} : \bar{B}'$  with  $\bar{B}' \leq \bar{B}$  then there exists  $C'$  such that  $\Gamma \vdash [\bar{x} \mapsto \bar{u}]e : C'$  and  $C' \leq C$ .

# Lemmas

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## Lemma (Weakening)

If  $\Gamma \vdash e : C$  then  $\Gamma, x : B \vdash e : C$ .

# Lemmas

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## Lemma (Decomposition)

*If  $\Gamma \vdash E[e] : C$  then there exists a type  $B$  such that  $\Gamma \vdash e : B$*

# Lemmas

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If  $\Gamma \vdash E[e] : C$  then there exists a type  $B$  such that  $\Gamma \vdash e : B$

## Lemma (Context)

If  $\Gamma \vdash E[e] : C$  and  $\Gamma \vdash e : B$  and  $\Gamma \vdash e' : B'$  with  $B' \leq B$  then there exists a type  $C'$  such that  $\Gamma \vdash E[e'] : C'$  and  $C' \leq C$ .

# Operational Semantics

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$$E ::= [\cdot] \mid E.f \mid E.m(\bar{e}) \mid v.m(\bar{v}, E, \bar{e}) \mid \text{new } C(\bar{v}, E, \bar{e}) \mid (C) E$$

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$$\frac{mbody(m, C) = (\bar{x}, e)}{\text{new } C(\bar{v}).m(\bar{u}) \rightarrow [\bar{x} \mapsto \bar{u}, \text{this} \mapsto \text{new } C(\bar{v})]e} \text{ E-Invk}$$

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$$\frac{C \leq D}{(D) \text{ new } C(\bar{v}) \rightarrow \text{new } C(\bar{v})} \text{ E-Cast}$$

# Lemmas

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## Lemma (Canonical Forms)

If  $\vdash v : C$  then  $v = \text{new } C(\bar{v})$ .

# Lemmas

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If  $\vdash v : C$  then  $v = \text{new } C(\bar{v})$ .

## Lemma (Inversion)

1. If  $\vdash (\text{new } C(\bar{v})).f_i : C_i$  then  $\text{fields}(C) = \bar{C}f$  and  $f_i \in \bar{f}$ .
2. If  $\vdash (\text{new } C(\bar{v})).m(\bar{u}) : C$  then  $\text{mbody}(m, C) = (\bar{x}, e)$  and  $|\bar{u}| = |\bar{e}|$ .

# Typing Rules

$$\frac{\Gamma(x) = C}{\Gamma \vdash x : C} \text{ T-Var}$$

$$\frac{\Gamma \vdash e : C \quad \text{fields}(C) = \overline{Cf}}{\Gamma \vdash e.f_i : C_i} \text{ T-Field}$$

$$\frac{\Gamma \vdash e : C \quad mtype(m, C) = \overline{B} \rightarrow B \quad \Gamma \vdash \bar{e} : \overline{A} \quad \overline{A} \leq \overline{B}}{\Gamma \vdash e.m(\bar{e}) : B} \text{ T-Invk}$$

$$\frac{\text{fields}(C) = \overline{Cf} \quad \Gamma \vdash \bar{e} : \overline{B} \quad \overline{B} \leq \overline{C}}{\Gamma \vdash \text{new } C(\bar{e}) : C} \text{ T-New}$$

$$\frac{\Gamma \vdash e : D \quad D \leq C}{\Gamma \vdash (C)e : C} \text{ T-UCast}$$

$$\frac{\Gamma \vdash e : D \quad C \leq D \quad C \neq D}{\Gamma \vdash (C)e : C} \text{ T-DCast}$$

$$\frac{\Gamma \vdash e : D \quad C \not\leq D \quad D \not\leq C \quad \text{stupid warning}}{\Gamma \vdash (C)e : C} \text{ T-SCast}$$

# Object Encodings

# Object-Oriented Features

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- Dynamic dispatch
- Encapsulation
- Subtyping
- Inheritance
- Open recursion

# Dynamic Dispatch

```
interface Shape {  
    ...  
    void draw() { ... }  
}  
  
class Circle extends Shape {  
    ...  
    void draw() { ... }  
}  
  
class Square extends Shape {  
    ...  
    void draw() { ... }  
}  
  
/*could be a circle, square, or something else */  
Shape s = ...;  
s.draw();
```

# Encapsulation

```
class Circle extends Shape {  
    private Point center;  
    private int radius;  
    ...  
    public Point getX() { return center.x }  
    public Point getY() { return center.y }  
}
```

# Subtyping

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Subtyping fits naturally with object-oriented languages because (ignoring languages such as Java that allow certain objects to manipulate instance variables directly) the only way to interact with an object is to invoke a method

As a result, an object that supports the same methods as another object can be used wherever the second is expected

**Example:** a method that takes an object of type **Shape** can be passed a **Circle**, **Square**, or any other subtype of **Shape**, because they each support the methods listed in the **Shape** interface

# Inheritance

```
class A {  
    public int f(...) { ... g(...) ... }  
    public bool g(...) { ... }  
}  
  
class B extends A {  
    public bool g(...) { ... }  
}  
  
...  
new B.f(...)
```

# Open Recursion

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Many object-oriented languages allow objects to invoke their own methods using the special keyword **this** (or **self**)

Implementing **this** in the presence of inheritance requires deferring the binding of **this** until the object is actually created

We will see an example of this next...

# Record Encoding

```
type pointRep = { x:int ref; y:int ref }
```

# Record Encoding

```
type pointRep = { x:int ref; y:int ref }

type point = { movex:int -> unit;
               movey:int -> unit }
```

# Record Encoding

```
type pointRep = { x:int ref; y:int ref }

type point = { movex:int -> unit;
               movey:int -> unit }

let pointClass : pointRep -> point =
  (fun (r:pointRep) ->
    { movex = (fun d -> r.x := !(r.x) + d);
      movey = (fun d -> r.y := !(r.x) + d) })
```

# Record Encoding

```
type pointRep = { x:int ref; y:int ref }

type point = { movex:int -> unit;
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    { movex = (fun d -> r.x := !(r.x) + d);
      movey = (fun d -> r.y := !(r.x) + d) })

let newPoint : int -> int -> point =
  (fun (x:int) ->
    (fun (y:int) ->
      pointClass { x=ref x; y = ref y }))
```

# Inheritance

---

```
type point3D = { movex:int -> unit;  
                 movey:int -> unit;  
                 movez:int -> unit }
```

# Inheritance

```
type point3D = { movex:int -> unit;
                  movey:int -> unit;
                  movez:int -> unit }

let point3DClass : point3DRep -> point3D =
  (fun (r:point3DRep) ->
    let super = pointClass r in
    { movex = super.movex;
      movey = super.movey;
      movez = (fun d -> r.z := !(r.x) + d) } )
```

# Inheritance

```
type point3D = { movex:int -> unit;
                  movey:int -> unit;
                  movez:int -> unit }

let point3DClass : point3DRep -> point3D =
  (fun (r:point3DRep) ->
    let super = pointClass r in
    { movex = super.movex;
      movey = super.movey;
      movez = (fun d -> r.z := !(r.x) + d) } )

let newPoint3D : int -> int -> int -> point3D =
  (fun (x:int) ->
    (fun (y:int) ->
      (fun (z:int) ->
        point3DClass { x=ref x; y = ref y; z = ref z })))
```

# Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }
```

# Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }

type altPoint = { movex:int -> unit;
                  movey:int -> unit;
                  move: int -> int -> unit }
```

# Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }

type altPoint = { movex:int -> unit;
                  movey:int -> unit;
                  move: int -> int -> unit }

let altPointClass : altPointRep -> altPoint ref -> altPoint =
  (fun (r:altPointRep) ->
    (fun (self:altPoint ref) ->
      { movex = (fun d -> r.x := !(r.x) + d);
        movey = (fun d -> r.y := !(r.y) + d);
        move = (fun dx dy -> (!self.movex) dx;
                  (!self.movey) dy) })))
```

# Open Recursion with Self

```
let dummyAltPoint : altPoint =  
{ movex = (fun d -> ());  
movey = (fun d -> ());  
move = (fun dx dy -> ()) }
```

# Open Recursion with Self

```
let dummyAltPoint : altPoint =
  { movex = (fun d -> ());
    movey = (fun d -> ());
    move = (fun dx dy -> ()) }

let newAltPoint : int -> int -> altPoint =
  (fun (x:int) ->
    (fun (y:int) ->
      let r = { x=ref x; y = ref y } in
      let cref = ref dummyAltPoint in
      cref := altPointClass r cref;
      !cref )))
```