

CS 4110

Programming Languages & Logics

Lecture 18

Definitional Translation and Continuations

15 October 2014



Announcements

- Today: PS 5 out
- Friday: no Foster office hours
- Friday: guest lecture by Clarkson

Products and Let

Syntax

$$\begin{aligned} e ::= & x \\ & | \lambda x. e \\ & | e_1 e_2 \\ & | (e_1, e_2) \\ & | \#1 e \\ & | \#2 e \\ & | \text{let } x = e_1 \text{ in } e_2 \end{aligned}$$
$$\begin{aligned} v ::= & \lambda x. e \\ & | (v_1, v_2) \end{aligned}$$

Products and Let

Evaluation Contexts

$$\begin{aligned} E ::= & [\cdot] \\ & | E e \\ & | v E \\ & | (E, e) \\ & | (v, E) \\ & | \#1 E \\ & | \#2 E \\ & | \text{let } x = E \text{ in } e_2 \end{aligned}$$

Products and Let

Semantics

$$\frac{e \rightarrow e'}{E[e] \rightarrow E[e']}$$

$$\overline{(\lambda x. e) v \rightarrow e\{v/x\}}^{\beta}$$

$$\overline{\#1 (v_1, v_2) \rightarrow v_1}$$

$$\overline{\#2 (v_1, v_2) \rightarrow v_2}$$

$$\overline{\text{let } x = v \text{ in } e \rightarrow e\{v/x\}}$$

Products and Let

Translation

$$\mathcal{T}[[x]] = x$$

$$\mathcal{T}[[\lambda x. e]] = \lambda x. \mathcal{T}[[e]]$$

$$\mathcal{T}[[e_1 e_2]] = \mathcal{T}[[e_1]] \mathcal{T}[[e_2]]$$

$$\mathcal{T}[[\lambda x. \lambda y. \lambda f. f x y]] = (\lambda x. \lambda y. \lambda f. f x y) \mathcal{T}[[e_1]] \mathcal{T}[[e_2]]$$

$$\mathcal{T}[[\#1 e]] = \mathcal{T}[[e]] (\lambda x. \lambda y. x)$$

$$\mathcal{T}[[\#2 e]] = \mathcal{T}[[e]] (\lambda x. \lambda y. y)$$

$$\mathcal{T}[[\text{let } x = e_1 \text{ in } e_2]] = (\lambda x. \mathcal{T}[[e_2]]) \mathcal{T}[[e_1]]$$

Laziness

Consider the call-by-name λ -calculus...

Syntax

$$\begin{aligned} e ::= & x \\ & | e_1 e_2 \\ & | \lambda x. e \\ v ::= & \lambda x. e \end{aligned}$$

Semantics

$$\frac{e_1 \rightarrow e'_1}{e_1 e_2 \rightarrow e'_1 e_2} \qquad \frac{}{(\lambda x. e_1) e_2 \rightarrow e_1 \{e_2/x\}} \beta$$

Laziness

Translation

$$\mathcal{T}[[x]] = x (\lambda y. y)$$

$$\mathcal{T}[[\lambda x. e]] = \lambda x. \mathcal{T}[[e]]$$

$$\mathcal{T}[[e_1 e_2]] = \mathcal{T}[[e_1]] (\lambda z. \mathcal{T}[[e_2]]) \quad z \text{ is not a free variable of } e_2$$

References

Syntax

$$e ::= x$$
$$| \lambda x. e$$
$$| e_0 e_1$$
$$v ::= \lambda x. e$$

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$$\begin{aligned} e ::= & x \\ & | \lambda x. e \\ & | e_0 e_1 \\ & | \text{ref } e \end{aligned}$$
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Syntax

$$\begin{aligned} e ::= & x \\ & | \lambda x. e \\ & | e_0 e_1 \\ & | \text{ref } e \\ & | !e \\ & | e_1 := e_2 \end{aligned}$$
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Semantics

$$\frac{\langle \sigma, e \rangle \rightarrow \langle \sigma', e' \rangle}{\langle \sigma, E[e] \rangle \rightarrow \langle \sigma', E[e'] \rangle} \qquad \frac{}{\langle \sigma, (\lambda x. e) v \rangle \rightarrow \langle \sigma, e\{v/x\} \rangle} \beta$$

$$\frac{l \notin \text{dom}(\sigma)}{\langle \sigma, \text{ref } v \rangle \rightarrow \langle \sigma[l \mapsto v], l \rangle} \qquad \frac{\sigma(l) = v}{\langle \sigma, !l \rangle \rightarrow \langle \sigma, v \rangle}$$

$$\frac{}{\langle \sigma, l := v \rangle \rightarrow \langle \sigma[l \mapsto v], v \rangle}$$

References

Translation

...left as an exercise to the reader ;-)

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Every target evaluation should represent a source evaluation...

Definition (Soundness)

$\forall e \in \mathbf{Exp}_{\text{src}}. \text{ if } \mathcal{T}[[e]] \rightarrow_{\text{trg}}^* v' \text{ then } \exists v. e \rightarrow_{\text{src}}^* v \text{ and } v' \text{ equivalent to } v$

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...and every source evaluation should have a target evaluation:

Definition (Completeness)

$\forall e \in \mathbf{Exp}_{\text{src}}. \text{ if } e \rightarrow_{\text{src}}^* v \text{ then } \exists v'. \mathcal{T}[[e]] \rightarrow_{\text{trg}}^* v' \text{ and } v' \text{ equivalent to } v$

Continuations

In the preceding translations, the control structure of the source language was translated directly into the corresponding control structure in the target language.

For example:

$$\begin{aligned}\mathcal{T}[\lambda x. e] &= \lambda x. \mathcal{T}[e] \\ \mathcal{T}[e_1 e_2] &= \mathcal{T}[e_1] \mathcal{T}[e_2]\end{aligned}$$

What can go wrong with this approach?

Continuations

- A snippet of code that represents “the rest of the program”
- Can be used directly by programmers...
- ...or in program transformations by a compiler
- Make the control flow of the program explicit
- Also useful for defining the meaning of features like exceptions

Example

Consider the following expression:

$$(\lambda x. x) ((1 + 2) + 3) + 4$$

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$$k_1 = \lambda a. k_0 (a + 4)$$

$$k_2 = \lambda b. k_1 (b + 3)$$

$$k_3 = \lambda c. k_2 (c + 2)$$

The original expression is equivalent to $k_3 \ 1$, which is just:

$$(\lambda c. (\lambda b. (\lambda a. (\lambda v. (\lambda x. x) v) (a + 4)) (b + 3)) (c + 2)) 1$$

Example (Continued)

Recall that $\text{let } x = e \text{ in } e'$ is syntactic sugar for $(\lambda x. e') e$.

Hence, we can rewrite the expression with continuations more succinctly as

let $c = 1$ in
let $b = c + 2$ in
let $a = b + 3$ in
let $v = a + 4$ in
 $(\lambda x. x) v$

CPS Transformation

We write $\mathit{CPS}[e] k = \dots$ instead of $\mathit{CPS}[e] = \lambda k. \dots$

We assume that the new variables introduced are “fresh”.

CPS Transformation

$$\mathit{CPS}\llbracket n \rrbracket k = k n$$

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$$\mathit{CPS}\llbracket n \rrbracket k = k n$$

$$\mathit{CPS}\llbracket e_1 + e_2 \rrbracket k = \mathit{CPS}\llbracket e_1 \rrbracket (\lambda n. \mathit{CPS}\llbracket e_2 \rrbracket (\lambda m. k (n + m)))$$

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$$\mathcal{CPS}[(e_1, e_2)] k = \mathcal{CPS}[e_1] (\lambda v. \mathcal{CPS}[e_2] (\lambda w. k (v, w)))$$

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$$\mathcal{CPS}[x] k = k x$$

$$\mathcal{CPS}[\lambda x. e] k = k (\lambda x. \lambda k'. \mathcal{CPS}[e] k')$$

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$$\mathcal{CPS}[x] k = k x$$

$$\mathcal{CPS}[\lambda x. e] k = k (\lambda x. \lambda k'. \mathcal{CPS}[e] k')$$

$$\mathcal{CPS}[e_1 e_2] k = \mathcal{CPS}[e_1] (\lambda f. \mathcal{CPS}[e_2] (\lambda v. f v k))$$

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