the gamedesigninitiative at cornell university

#### Lecture 22

# **Strategic Al**

# **Role of AI in Games**

• Autonomous Characters (NPCs)

- Mimics the "personality" of the character
- May be opponent or support character

#### Strategic Opponents

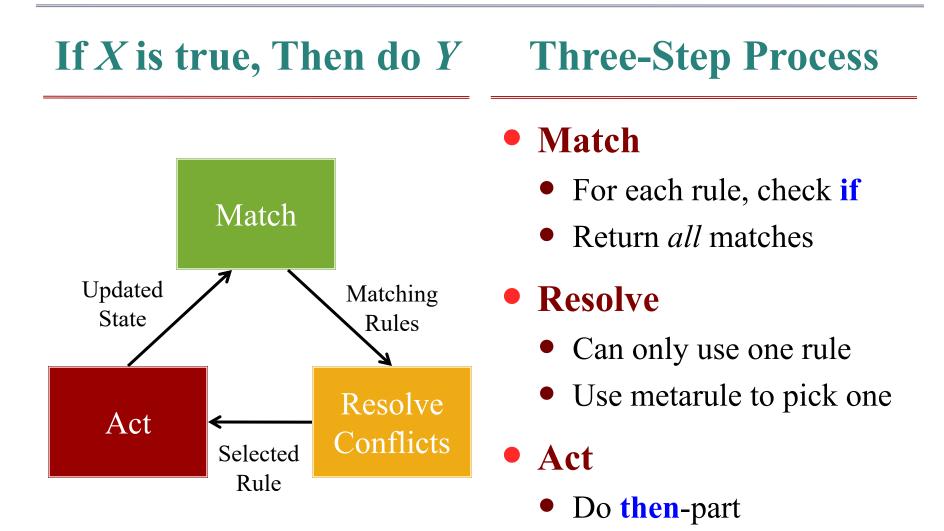
- AI at the "player level"
- Closest to classical AI

#### Character Dialog

- Intelligent commentary
- Narrative management (e.g. Façade)



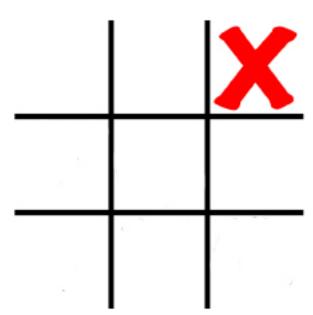
#### **Rule-Based Al**





### Example: Tic-Tac-Toe

- Next move for player O?
  - If have a winning move, make it
  - If opponent can win, block it
  - If the center is available, take it
  - Corners are better than edges
- Very easy to program
  - Just check the board state
  - Tricky part is prioritization





## Example: Microsoft's Age of Kings

; The AI will attack once at 1100 seconds and then again

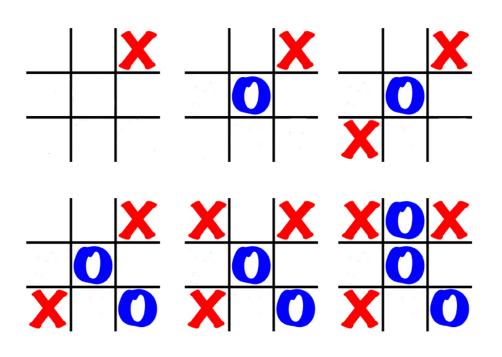
; every 1400 sec, provided it has enough defense soldiers.

```
(defrule
   (game-time > 1100)
   =>
   (attack-now)
   (enable-timer 7 1100))
(defrule
   (timer-triggered 7) (defend-soldier-count \geq 12)
   =>
   (attack-now)
   (disable-timer 7)
   (enable-timer 7 1400)
```



## The Problems with Rules

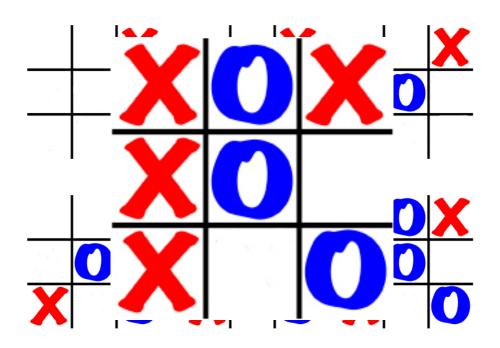
- Rules only do one step
  - May not be best move
  - Could lose long term
- Next move for player O?
  - If can win, then do it
  - If X can win, then block it
  - Take the center if possible
  - Corners > edges
- Need to look ahead





## The Problems with Rules

- Rules only do one step
  - May not be best move
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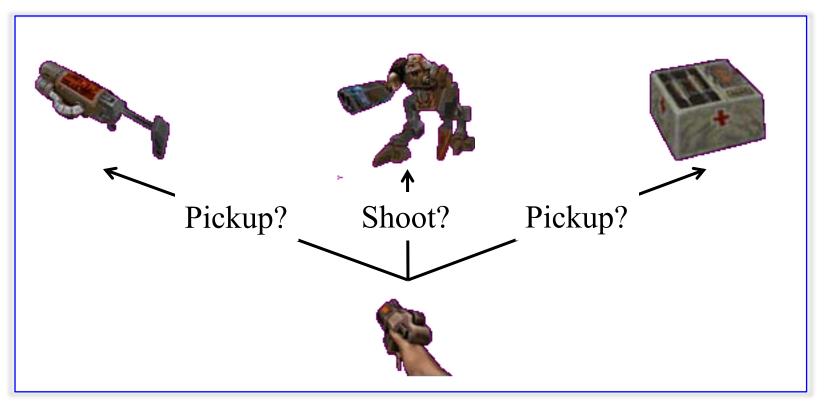
# **Multiple Steps: Planning**

- Plan: actions necessary to reach a goal
  - Goal is a (pseudo) specific game state
  - Actions change game state (e.g. verbs)
- **Planning**: steps to generate a plan
  - Initial State: state the game is currently in
  - Goal Test: determines if state meets goal
  - **Operators**: action the NPC can perform



### What Should We Do?

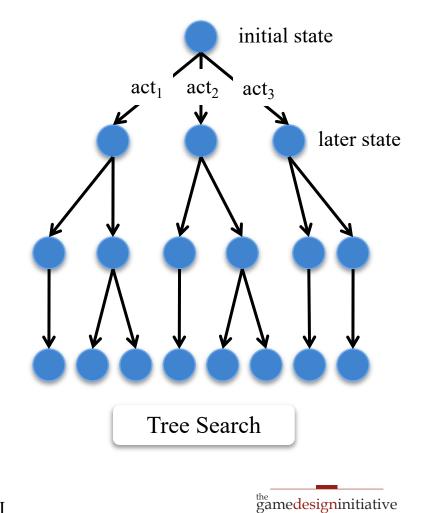
Slide courtesy of John Laird





# Simplification: No Opponent

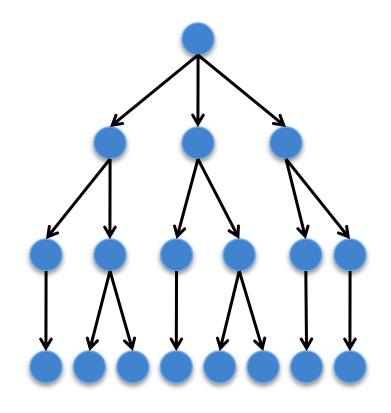
- Identify desired goal
  - Ex: Kill enemy, get gold
  - Design appropriate test
- List all relevant actions
  - **Ex**: Build, send troops
- Look-ahead Search
  - Start with initial state
  - Try all actions (look-ahead)
  - Stop if reached goal
  - Continue if not at goal



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# **Planning Issues**

- Exponential choices
  - Search action *sequences*
  - How far are we searching?
  - Cannot do this in real life!
- Game state is **complex** 
  - Do we look at entire state?
  - Faster to "do" than to plan
- Must limit search
  - Reduce actions examined
  - Simplify game state





## **Internal State Representation**

#### **Simplified World Model**

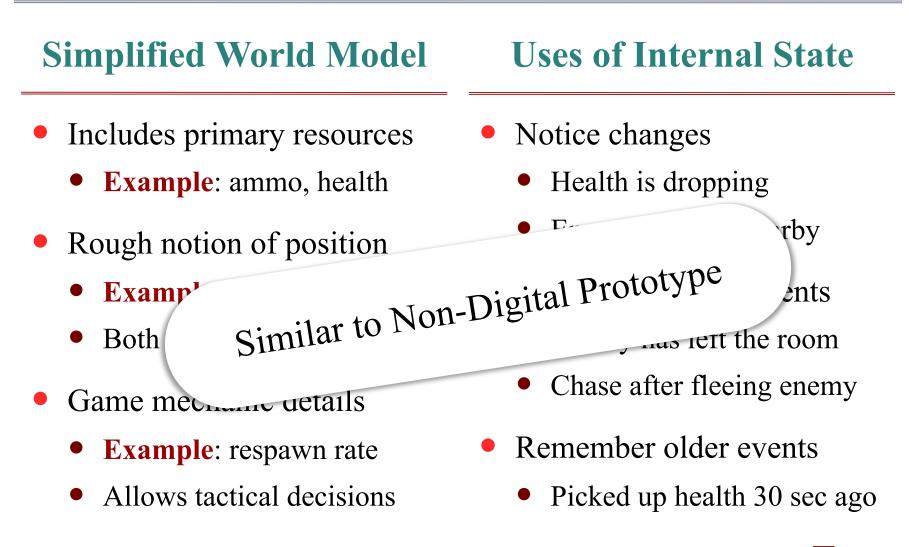
- Includes primary resources
  - **Example**: ammo, health
- Rough notion of position
  - **Example**: in/outside room
  - Both characters and items
- Game mechanic details
  - **Example**: respawn rate
  - Allows tactical decisions

#### **Uses of Internal State**

- Notice changes
  - Health is dropping
  - Enemy must be nearby
- Remember recent events
  - Enemy has left the room
  - Chase after fleeing enemy
- Remember older events
  - Picked up health 30 sec ago



## **Internal State Representation**





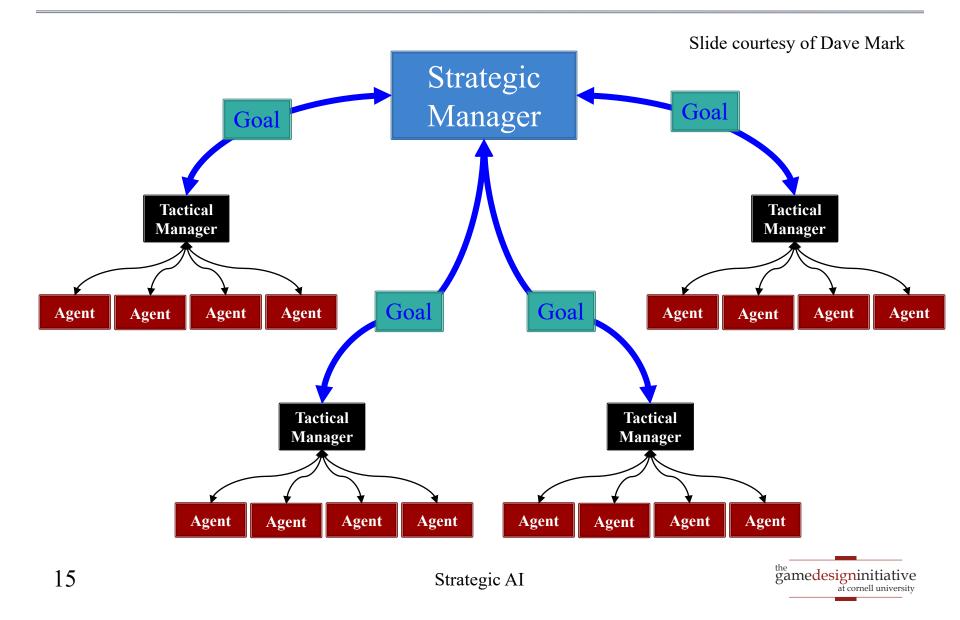
#### **Internal State and Memory**

- Each NPC has own state
  - Represents NPC *memory*
  - Might not be consistent
- Useful for character AI
  - Models sensory data
  - Models communication
- Isolates planning
  - Each NPC plans separately
  - Coordinate planning with a *strategic manager*





## **Strategy versus Tactics**



# **Internal State for Quake II**

- Self
  - Current-health
    - Last-health
  - Current-weapon
    - Ammo-left
  - Current-room
    - Last-room
  - Current-armor
    - Last-armor
  - Available-weapons
- Enemy
  - Current-weapon
  - Current-room
  - Last-seen-time
  - Estimated-health
- Current-time

- Random-number
- Powerup
  - Type
  - Room
  - Available
  - Estimated-spawn-time
- Map
  - Rooms
  - Halls
  - Paths
- Parameters
  - Full-health
  - Health-powerup-amount
  - Ammo-powerup-amount
  - Respawn-rate



# **Internal Action Representation**

#### **Simplified Action Model**

- Internal Actions = *operators* 
  - Just mathematical functions
  - Operators alter internal state

#### Pre-conditions

- What is required for action
- Often resource requirement
- Effects
  - How action changes state
  - Both global and for NPC

#### **Designing Actions**

- Extrapolate from gameplay
  - Start with an internal state
  - Pick "canonical" game state
  - Apply game action to state
  - Back to internal state
- Remove any uncertainty
  - Deterministic NPC behavior
  - "Average" random results
  - Or pick worse case scenario



## **Internal Action Representation**

| Simplified Action Model   | <b>Designing Actions</b>  |
|---|---|
| <ul> <li>Internal Actions = operators</li> <li>Just mathematical functions</li> <li>Operators alter internal state</li> </ul> | <ul> <li>Extrapolate from gameplay</li> <li>Start with an internal state</li> <li>Pick "comparing a state</li> </ul>  |
| <ul> <li>Pre-cond</li> <li>What Like Gamepla</li> <li>Often but actions, interview</li> </ul>                                 | ay Specification, o state<br>eractions combined e<br>Kemove any uncertainty   |
| <ul> <li>Effects</li> <li>How action changes state</li> <li>Both global and for NPC</li> </ul>                                | <ul> <li>Deterministic NPC behavior</li> <li>"Average" random results</li> <li>Or pick worse case scenario</li> </ul> |



### Example: Pick-Up Health Op

#### • **Preconditions**:

- Self.current-room = Powerup.current-room
- Self.current-health < full-health
- Powerup.type = health
- Powerup.available = yes
- Effects:
  - Self.last-health = self.current-health
  - Self.current-health = current-health + health-powerup-amount
  - Powerup.available = no
  - Powerup.estimated-spawn-time = current-time + respawn-rate



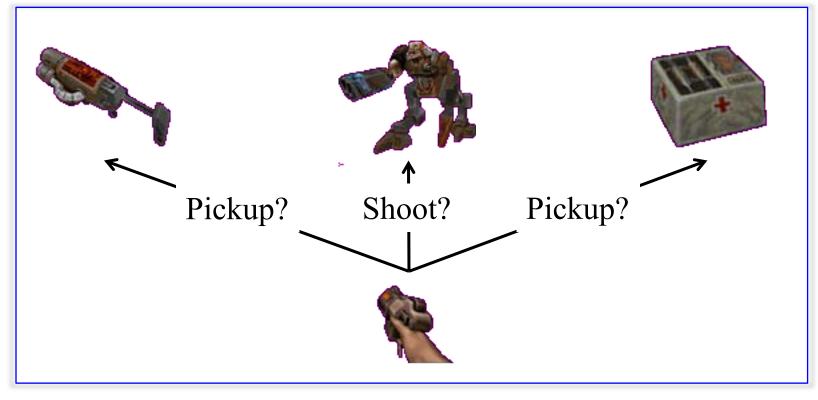
# **Building Internal Models**

- Planning is only as accurate as model
  - Bad models  $\rightarrow$  bad plans
  - But complex models  $\rightarrow$  slow planning
- Look at your nondigital prototype!
  - Heavily simplified for playability
  - Resources determine internal state
  - Nondigital verbs are internal actions
- One of many reasons for this exercise



#### What Should We Do?

Slide courtesy of John Laird



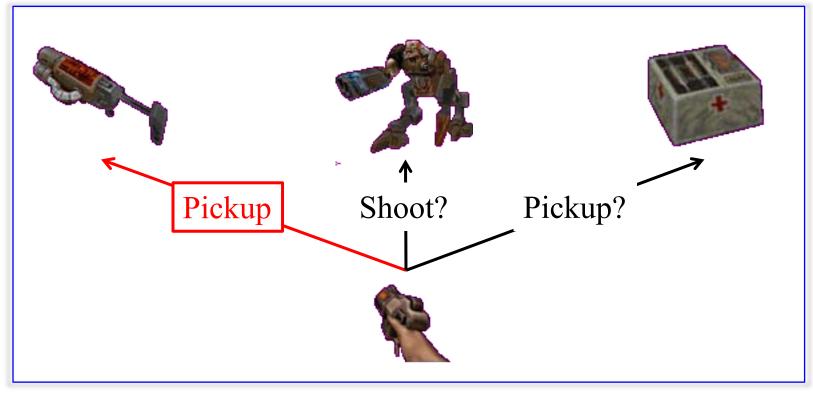
Self.current-health = 20 Self.current-weapon = blaster Enemy.estimated-health = 50

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = yes



#### **One Step: Pick-up Railgun**

Slide courtesy of John Laird



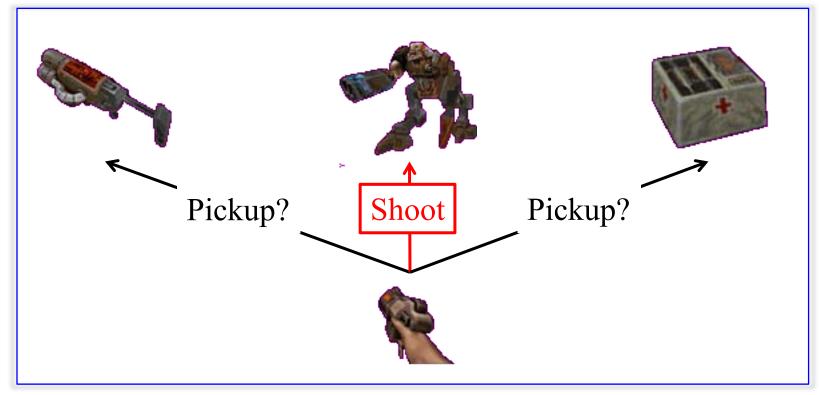
Self.current-health = 10 Self.current-weapon = railgun Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun **Powerup.available = no** 



Enemy.estimated-health = 50

#### **One Step: Shoot Enemy**

Slide courtesy of John Laird



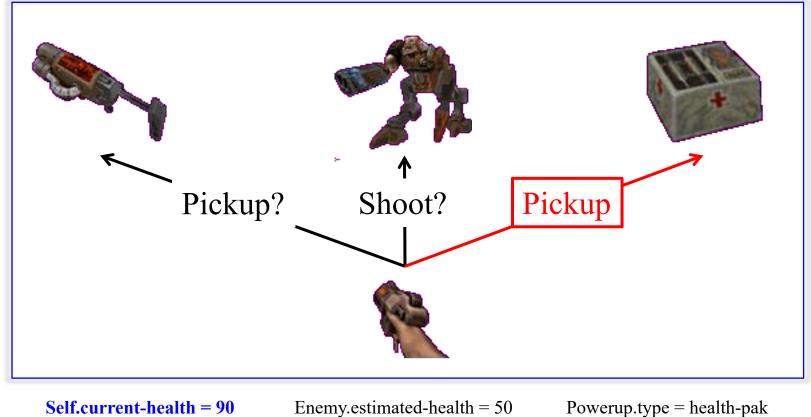
**Self.current-health = 10** Self.current-weapon = blaster **Enemy.estimated-health = 40** 

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = yes



#### **One Step: Pick-up Health-Pak**

Slide courtesy of John Laird



Self.current-weapon = blaster

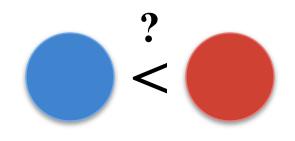
ted-health = 50 Power Power

Powerup.type = health-pak **Powerup.available = no** Powerup.type = Railgun Powerup.available = yes



## **State Evaluation Function**

- Need to **compare** states
  - Is either state better?
  - How far away is goal?
- Might be **partial order** 
  - Some states incomparable
  - If not goal, just continue
- Purpose of planning
  - Find good states
  - Avoid bad states





## State Evaluation: Quake II

- **Example 1**: Prefer higher self.current-health
  - Always pick up health powerup
  - Counter example:
    - Self.current-health = 99%
    - Enemy.current-health = 1%
- **Example 2**: Prefer lower enemy.current-health
  - Always shoot enemy
  - Counter example:
    - Self.current-health = 1%
    - Enemy.current- health = 99%



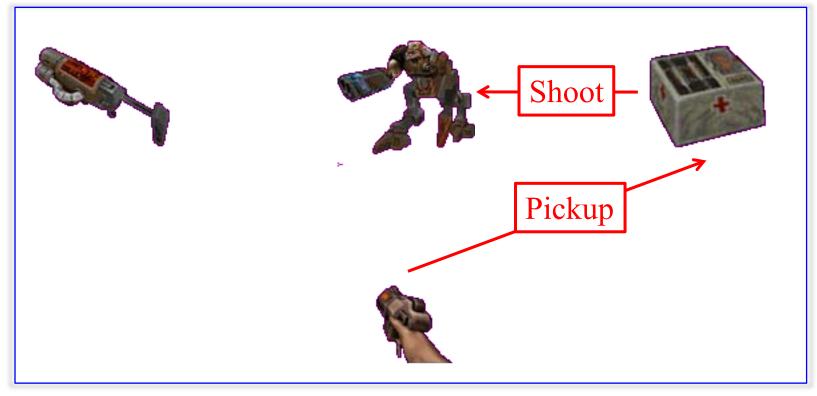
## State Evaluation: Quake II

- **Example 3**: Prefer higher self.health enemy.health
  - Shoot enemy if I have health to spare
  - Otherwise pick up a health pack
  - Counter examples?
- Examples of more complex evaluations
  - If self.health > 50% prefer lower enemy.health
    - Otherwise, want higher self.health
  - If self.health > low-health prefer lower enemy.health
    - Otherwise, want higher self.health



#### **Two Step Look-Ahead**

Slide courtesy of John Laird



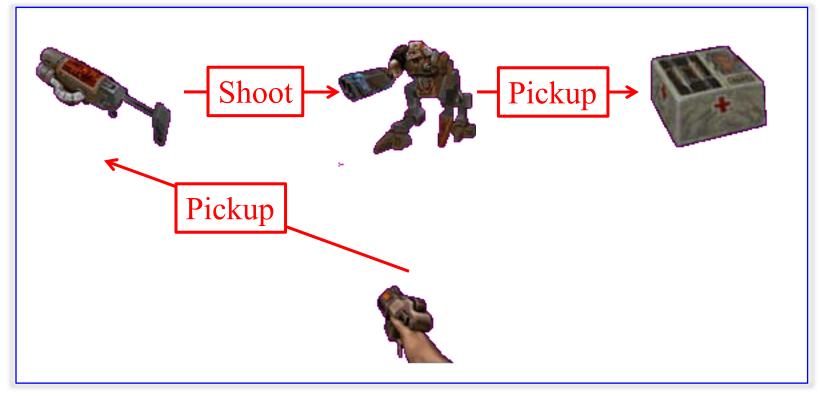
**Self.current-health = 80** Self.current-weapon = blaster **Enemy.estimated-health = 40** 

Powerup.type = health-pak **Powerup.available = no** Powerup.type = Railgun Powerup.available = yes



#### **Three Step Look-Ahead**

Slide courtesy of John Laird



Self.current-health = 100 Self.current-weapon = railgun

Enemy.estimated-health = 0 Powerup.type = health-pak Powerup.available = no Powerup.type = Railgun

**Powerup.available = no** 



## Look-Ahead Search

#### **One-Step Lookahead**

```
op pickBest(state) {
```

```
foreach op satisfying precond {
```

```
newstate = op(state)
```

```
evaluate newstate
```

```
return op with best evaluation
```

#### **Multistep Tree Search**

```
[op] bestPath(&state,depth) {
  if depth == 0 { return [] }
  foreach op satisfying precond {
     newstate = op(state)
     [nop]=bestPath(newstate,depth-1)
     evaluate newstate
  pick op+[nop] with best state
  modify state to reflect op+[nop]
  return op+[nop]
```



}

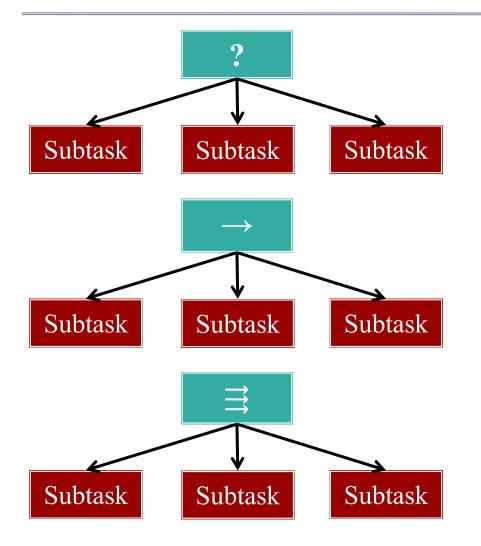
}

#### Look-Ahead Search

- Are more steps better?
  - Longer, more elaborate plans
  - More time & space consuming
  - Opponent or environment can mess up plan
  - Simplicity of internal model causes problems
- In this class, limit three or four steps
  - Anything more, and AI is too complicated
  - Purpose is to be challenging, not to win



# **Recall:** LibGDX Behavior Trees



#### Selector rules

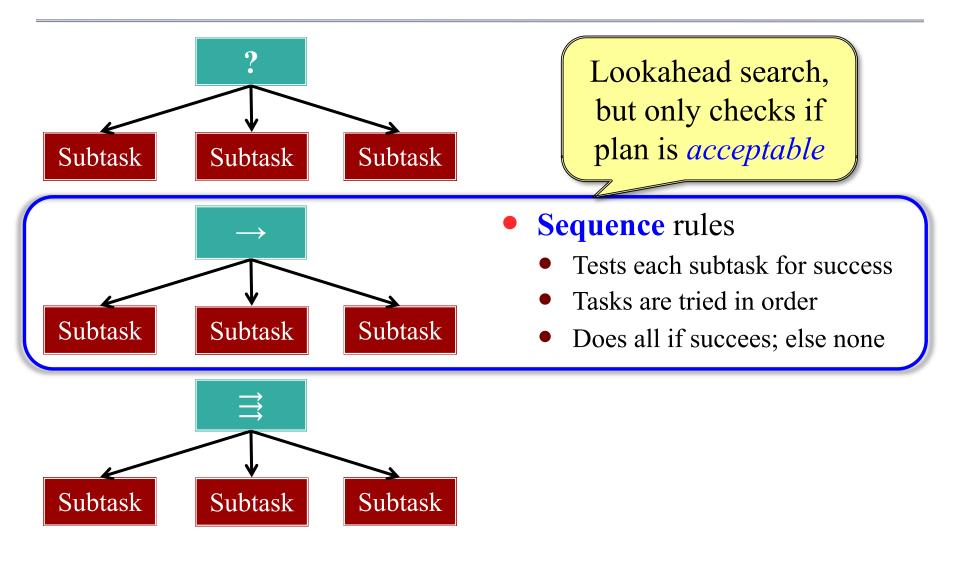
- Tests each subtask for success
- Tasks are tried independently
- Chooses first one to succeed
- Sequence rules
  - Tests each subtask for success
  - Tasks are tried in order
  - Does all if succees; else none

#### • Parallel rules

- Tests each subtask for success
- Tasks are tried simultaneously
- Does all if succees; else none



## **Recall:** LibGDX Behavior Trees

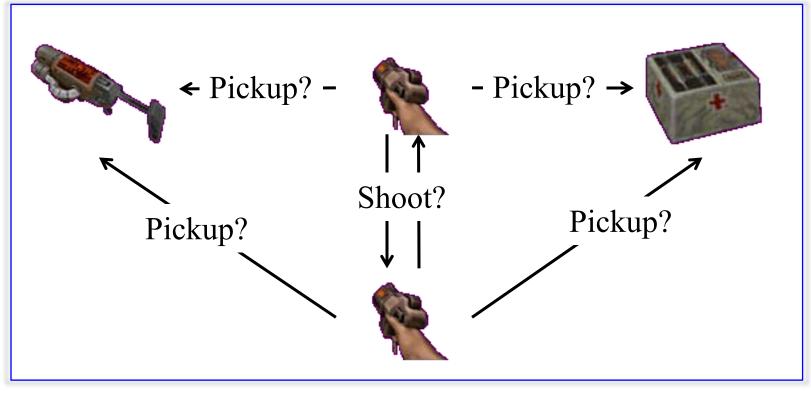




Thinking and Acting

### **Opponent: New Problems**

Slide courtesy of John Laird



Self.current-health = 20 Self.current-weapon = blaster Enemy.estimated-health = 50

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = yes



# **Opponent Model**

- Solution 1: Assume the worst
  - Opponent does what would be worst for you
  - Full game tree search; exponential
- **Solution 2**: What would I do?
  - Opponent does what you would in same situation
- Solution 3: Internal opponent model
  - Remember what did last time
  - Or remember what they like to do

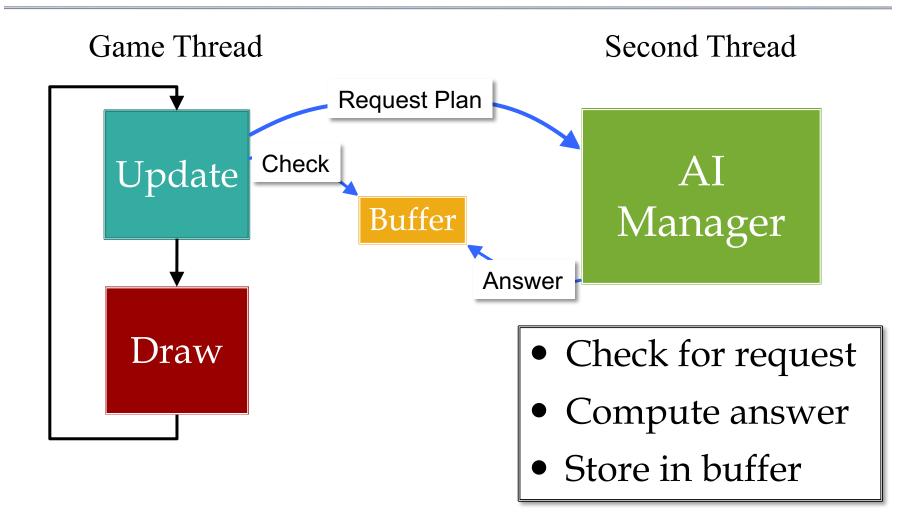


# **Opponent Interference**

- Opponent actions may prevent yours
  - **Example**: Opponent grabs railgun first
  - Need to take into account in your plan
- Solution: Iteration
  - Plan once with no interference
  - Run again, assuming best plans of the opponent
  - Keep iterating until happy (or run out of time)
- Planning is very *expensive*!

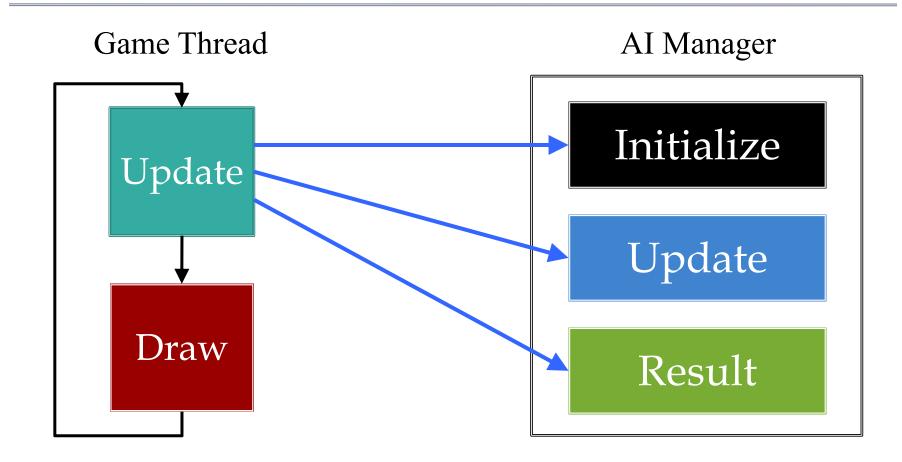


#### **Asynchronous Al**



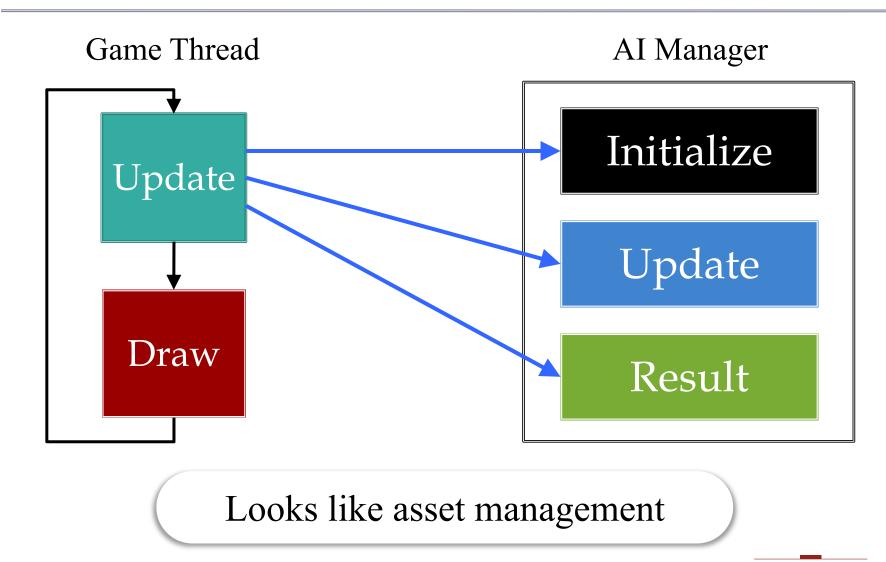


#### **Alternative:** Iterative Al





#### **Alternative:** Iterative Al



Game Architecture

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# Using Asynchronous AI

- Give AI a time budget
  - If planning takes too long, abort it
  - Use counter in update loop to track time
- Beware of stale plans
  - Actual game state has probably changed
  - When find a plan, make sure it is still good
  - Evaluate (quickly) with new internal state
  - Make sure result is "close" to what thought



# **Planning: Optimization**

- Backwards Planning
  - Idea: few operators achieve goal conditions
  - Implementation:
    - For each operator, reverse the effect
    - Check reversed effect satisfies pre-conditions
- Possible to use backwards **and** forwards
  - Start on each end, and check for meets
  - Does not work well with numerical resources

## To Plan or Not to Plan

#### • Advantages

- Less predictable behavior
- Can handle unexpected situations
- More accurate than rule-based AI

#### Disadvantages

- Less predictable behavior (harder to debug)
- Planning takes a lot of processor time
- Planning takes memory
- Need simple but accurate internal representations



## **Other Possibilities**

- There are many more options available
  - Neural nets
  - Decision trees
  - General machine learning
  - Take **CS 4700** if want to learn more
- Quality is a matter of heated debate
  - Better to spend time on internal state design
  - Most AI is focused on perception modeling



# Summary

- Rule-based AI is simplest form of strategic AI
  - Only limited to one-step at a time
  - Can easily make decisions that lose in long term
- More complicated behavior requires **planning** 
  - Simplify the game to turn-based format
  - Use classic AI search techniques
- Planning has advantages and disadvantages
  - Remember, the desire is to challenge, not to win

