gamedesigninitiative at cornell university

Lecture 19

Character Behavior

Classical AI vs. Game AI

- Classical: Design of intelligent agents
 - Perceives environment, maximizes its success
 - Established area of computer science
 - Subtopics: planning, machine learning
- Game: Design of rational behavior
 - Does not need to optimize (and often will not)
 - Often about "scripting" a personality
 - More akin to cognitive science



Take Away for This Lecture

- Review the sense-think-act cycle
 - How do we separate actions and thinking?
 - Delay the sensing problem to next time
- What is **rule-based** character AI?
 - How does it relate to sense-think-act?
 - What are its advantages and disadvantages?
- What **alternatives** are there to rule-based AI?
 - What is our motivation for using them?
 - How do they affect the game architecture?



Role of AI in Games

- Autonomous Characters (NPCs)
 - Mimics the "personality" of the character
 - May be opponent or support character

Strategic Opponents

- AI at the "player level"
- Closest to classical AI

Character Dialog

- Intelligent commentary
- Narrative management (e.g. Façade)



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Review: Sense-Think-Act

Sense:

- Perceive the world
- Reading the game state
- Example: enemy near?

Think:

- Choose an action
- Often merged with sense
- Example: fight or flee

• Act:

- Update the state
- Simple and fast
- Example: reduce health





S-T-A: Separation of Logic

- Loops = sensing
 - Read other objects
 - *Aggregate* for thinking
 - **Example**: nearest enemy
- Conditionals = thinking
 - Use results of sensing
 - Switch between possibilities
 - Example: attack or flee
- Assignments = actions
 - Rarely need loops
 - Avoid conditionals

```
move(int direction) {
 switch (direction) {
 case NORTH:
   y -= 1;
   break;
 case EAST:
   x += 1;
   break;
 case SOUTH:
   y += 1;
   break;
 case WEST:
   x = 1;
   break;
```

S-T-A: Separation of Logic

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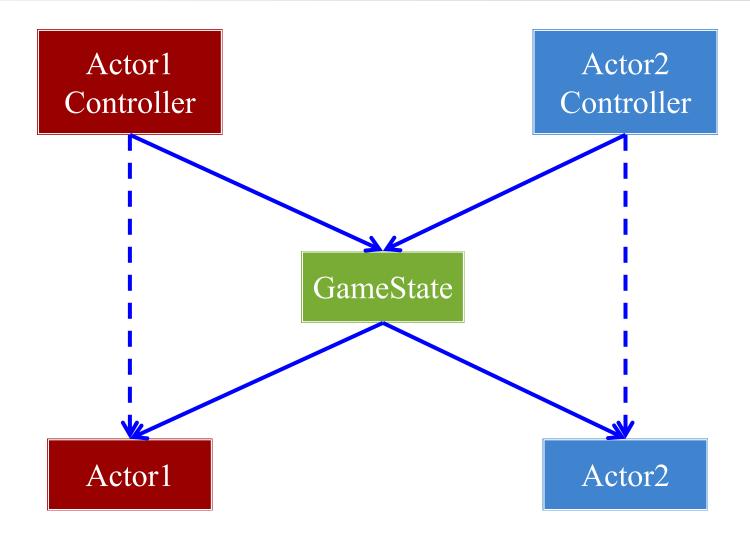
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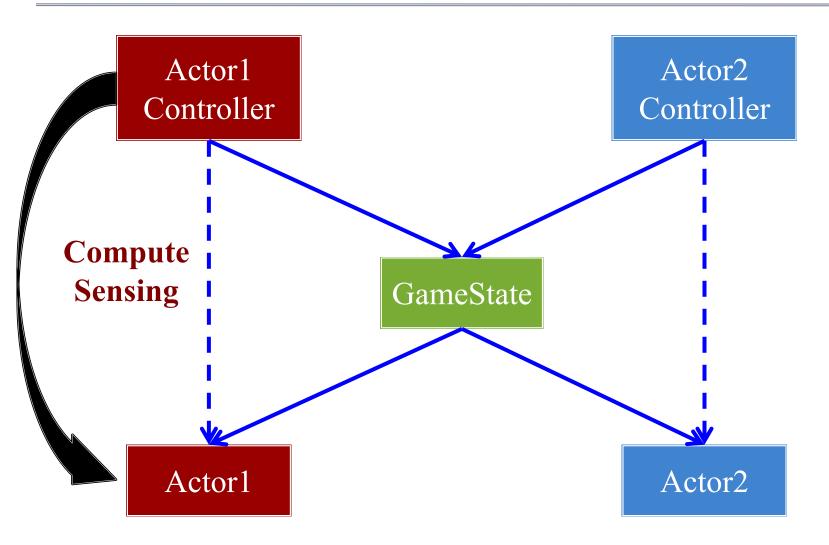
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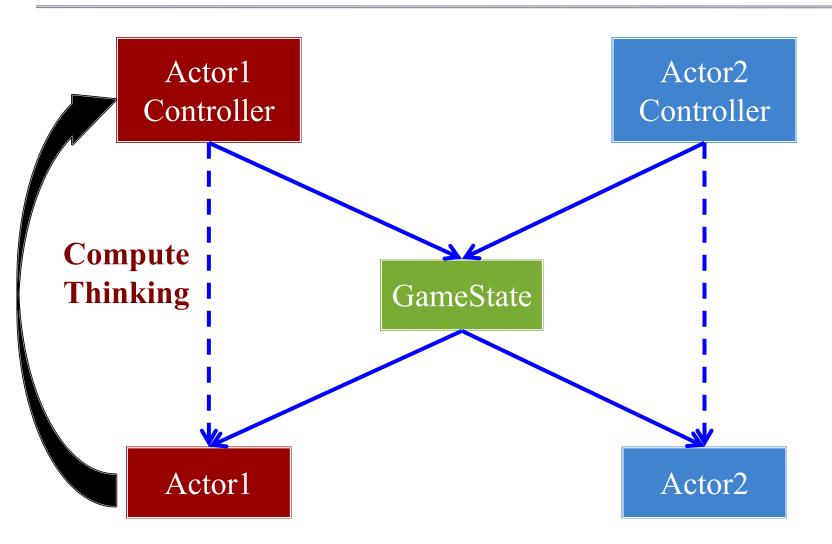
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 switch (direction) {
 case NORTH:
   break;
 case EAST:
  move(int dx, int dy) {
     x += dx:
     y += dy;
 case WEST:
```



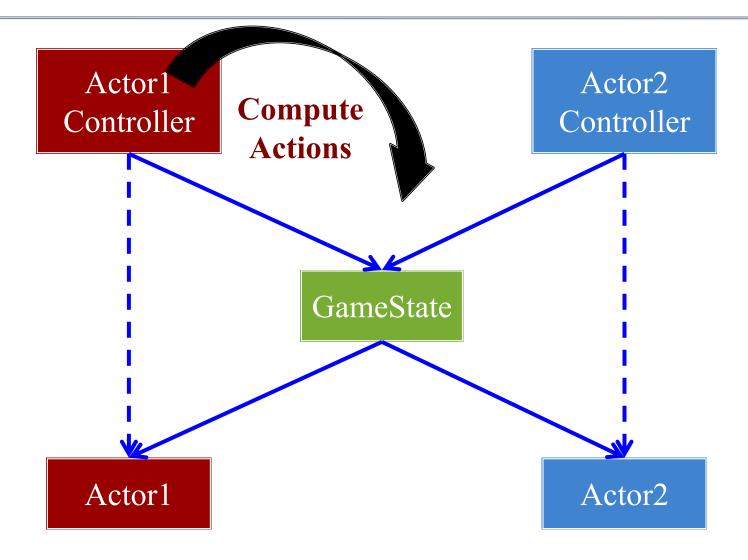














Review: Sense-Think-Act

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• Act:

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Actions: Short and Simple

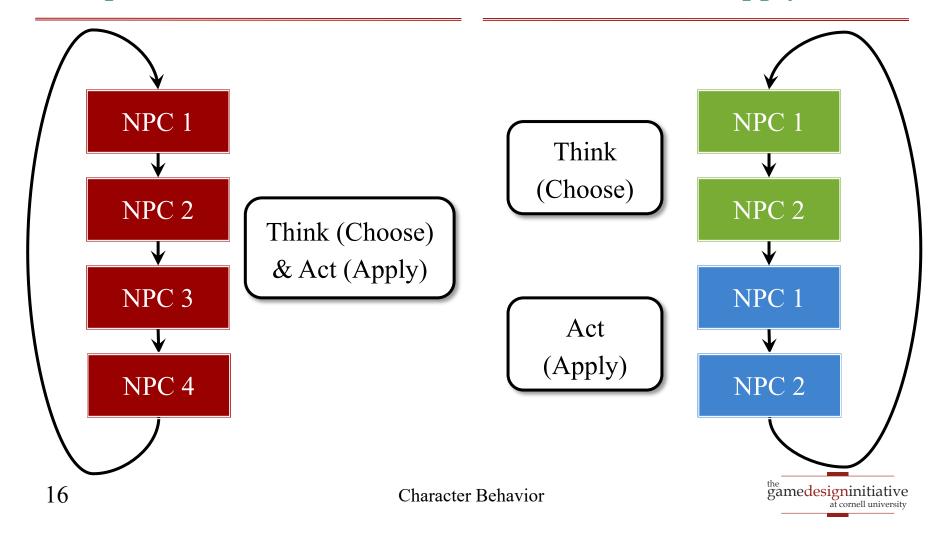
- Mainly use assignments
 - Avoid loops, conditionals
 - Similar to getters/setters
 - Complex code in thinking
- Helps with serializability
 - Record and undo actions
- Helps with networking
 - Keep doing last action
 - Recall: *dead reckoning*

```
move(int direction) {
 switch (direction) {
 case NORTH:
   break:
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  move(int dx, int dy) {
     x += dx:
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 case WEST:
```

Delaying Actions

Sequential Actions are Bad

Choose Action; Apply Later



Thinking: Primary Challenge

- A mess of conditionals
 - "Spaghetti" code
 - Difficult to modify
- Abstraction requirements:
 - Easy to visualize models
 - Mirror "cognitive thought"
- Want to separate talent
 - **Sensing**: Programmers
 - Thinking: Designers
 - Actions: Programmers

```
if (sense<sub>1</sub>) {
   if (sense_{11}) { ...
    else if (sense_{12}) \{ ... \}
    \} else if (sense<sub>13</sub>)\{ ... \}
    } else {...
} else if (sense<sub>2</sub>) {
   if (sense_{21}) \{ \dots \}
    \} else if (sense<sub>22</sub>)\{ ... \}
    } else {...
ext{less if (sense_3) { ... }}
```

Thinking: Primary Challenge

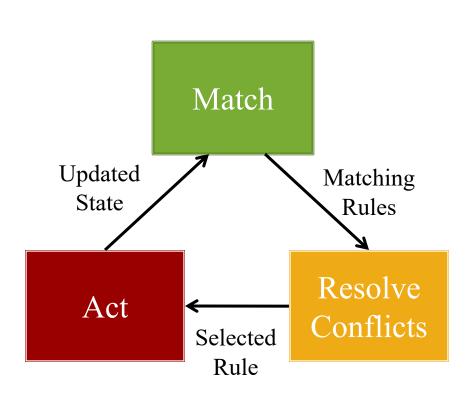
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   if (sense<sub>21</sub>)
    } else if (sense<sub>22</sub>)
    } else { ...
\} self (sense<sub>3</sub>) { ...
```

Rule-Based Al

If X is true, Then do Y

Three-Step Process



Match

- For each rule, check if
- Return *all* matches

Resolve

- Can only use one rule
- Use metarule to pick one

Act

Do then-part



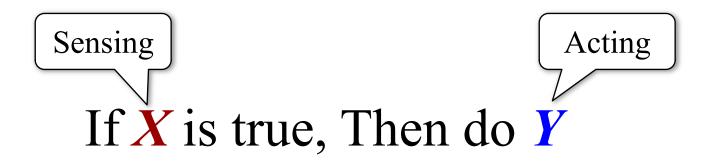
Rule-Based Al

If X is true, Then do Y

- Thinking: Providing a list of several rules
 - But what happens if there is more than one rule?
 - Which rule do we choose?



Rule-Based Al



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Simplicity of Rule-Based Al



Conflict Resolution

Often resolve by order

- Each rule has a priority
- Higher priorities go first
- "Flattening" conditionals

Problems:

- PredictableSame events = same rules
- Total order
 Sometimes no preference
- PerformanceOn average, go far down list

```
R_1: if event<sub>1</sub> then act<sub>1</sub>
R_2: if event<sub>2</sub> then act<sub>2</sub>
R_3: if event<sub>3</sub> then act<sub>3</sub>
R_4: if event<sub>4</sub> then act<sub>4</sub>
R_5: if event<sub>5</sub> then act<sub>5</sub>
R_6: if event<sub>6</sub> then act<sub>6</sub>
R_7: if event<sub>7</sub> then act<sub>7</sub>
```



Conflict Resolution

Specificity:

Rule w/ most "components"

• Random:

- Select randomly from list
- May "weight" probabilities

• Refractory Inhibition:

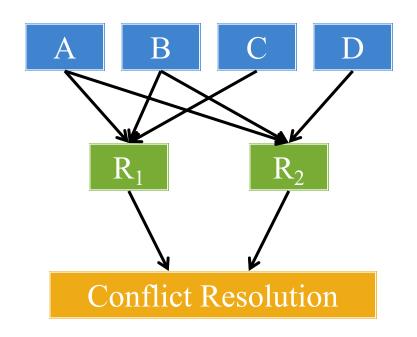
- Do not repeat recent rule
- Can combine with ordering

• Data Recency:

Select most recent update

 R_1 : if A, B, C, then

 R_2 : if A, B, D, then





Impulses

- Correspond to certain events
 - Global: not tied to NPC
 - Must also have duration
- Used to reorder rules
 - Event makes rule important
 - Temporarily up the priority
 - Restore when event is over
- Preferred conflict resolution
 - Simple but flexible
 - Used in *Halo* 3 AI.

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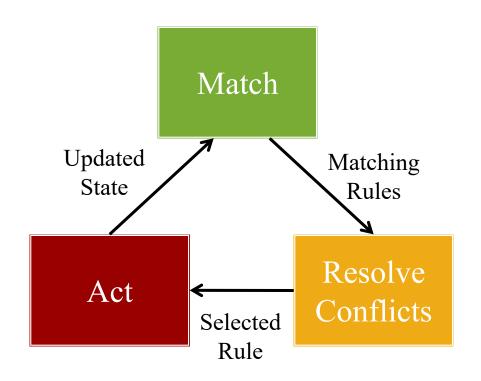
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Rule-Based AI: Performance

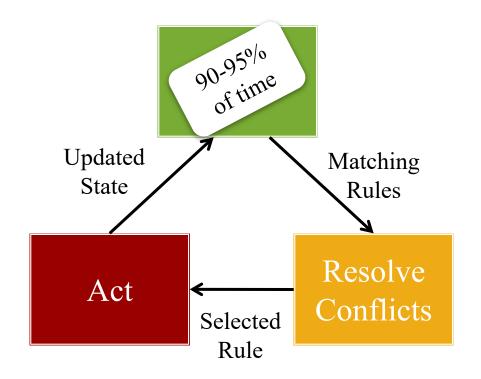
- Matching = sensing
 - If-part is expensive
 - Test *every* condition
 - Many unmatched rules
- Improving performance
 - Optimize sensing (make if-part cheap)
 - Limit number of rules
 - Other solutions?
- Most games limit rules
 - Reason for *state machines*





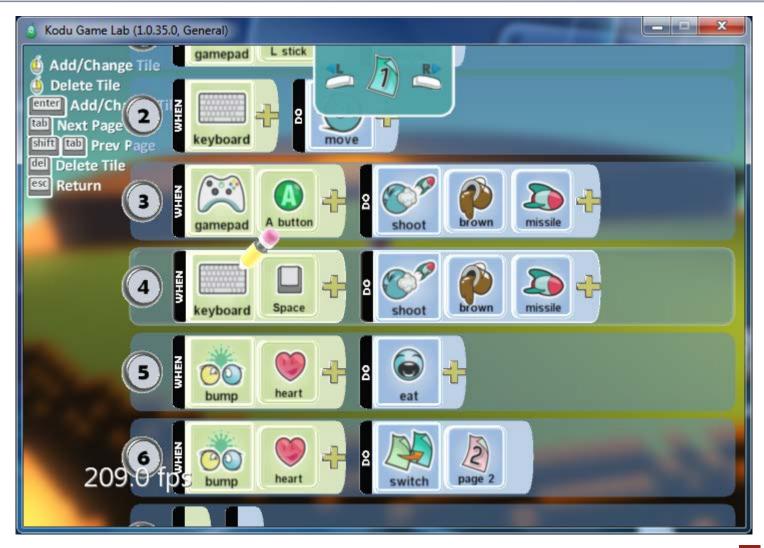
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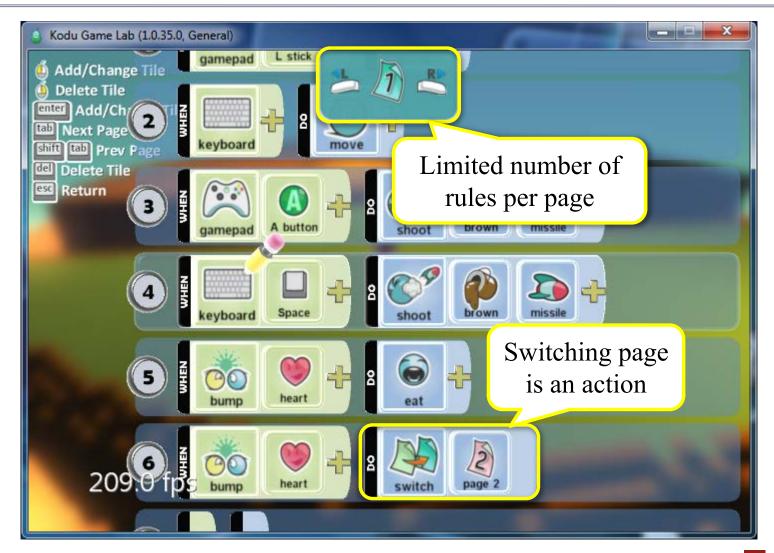




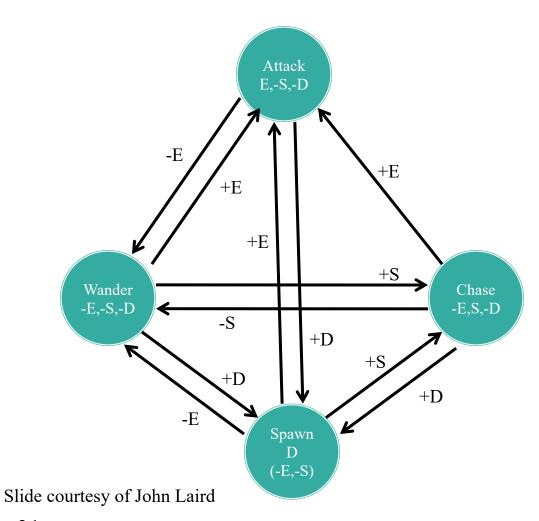
Making the Rules Manageable



Making the Rules Manageable



Finite State Machines

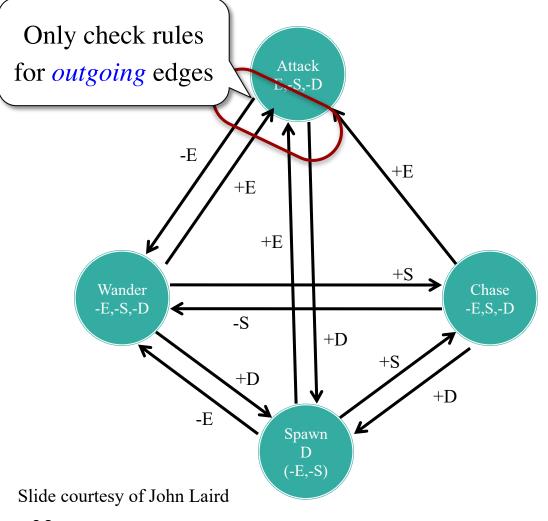


Events

- E=Enemy Seen
- S=Sound Heard
- **D**=Die



Finite State Machines



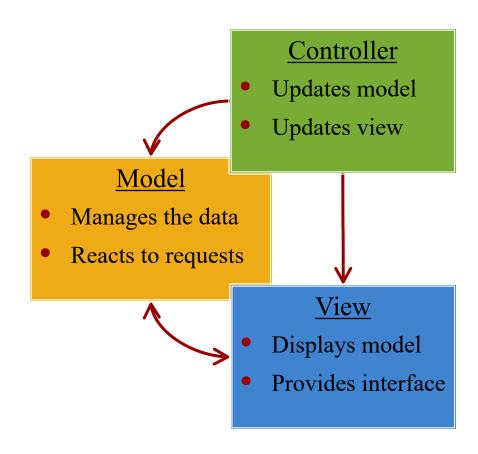
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Implementation: Model-View-Controller

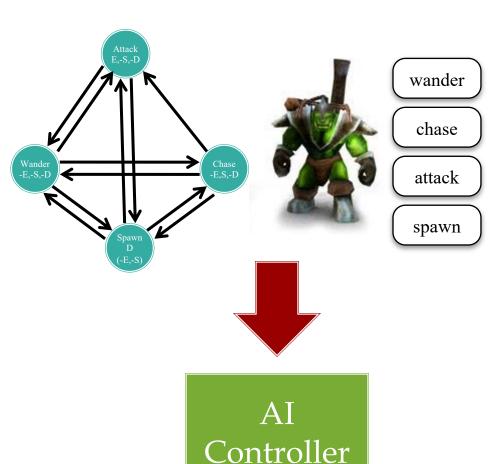
- Games have thin models
 - Methods = get/set/update
 - Controllers are heavyweight
- AI is a controller
 - Uniform process over NPCs
- But behavior is personal
 - Diff. NPCs = diff. behavior
 - Do not want unique code
- What can we do?
 - Data-Driven Design





Implementation: Model-View-Controller

- Actions go in the model
 - Lightweight updates
 - Specific to model or role
- Controller is framework for general sensing, thinking
 - Standard FSM engine
 - Or FSM alternatives (later)
- Process stored in a model
 - Represent thinking as *graph*
 - Controller processes graph





An Aside: Animations

Landing Animation



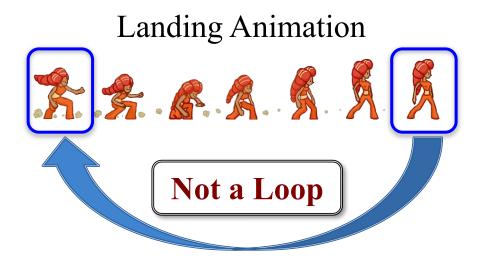
- AI may need many actions
 - Run, jump, duck, slide
 - Fire weapons, cast spells
 - Fidget while idling
- Want animations for all
 - Is loop appropriate for each?
 - How do we transition?
- Idea: shared boundaries
 - End of loop = start of another
 - Treat like advancing a frame



Idling Animation



An Aside: Animations



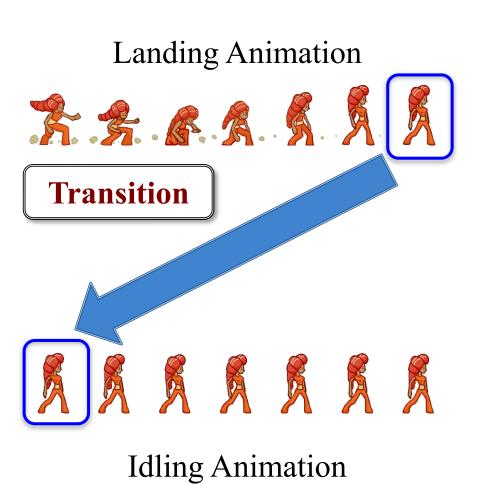
A A A A A A A

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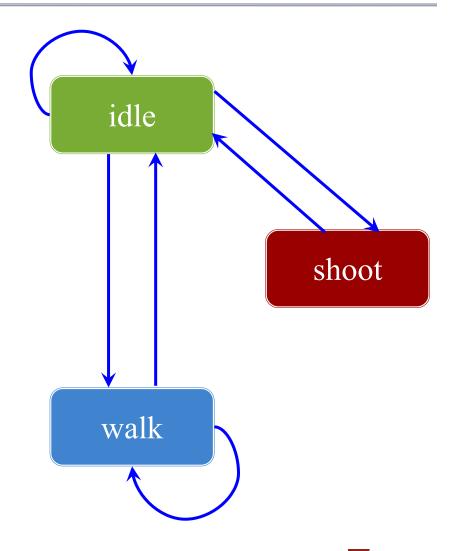


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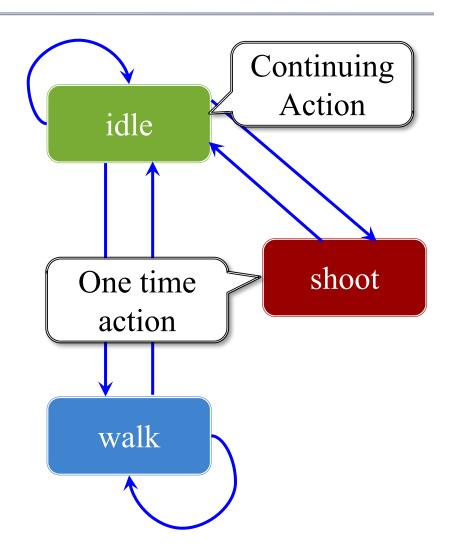
Animation and State Machines

- Idea: Each sequence a state
 - Do sequence while in state
 - Transition when at end
 - Only loop if loop in graph
- A graph edge means...
 - Boundaries match up
 - Transition is allowable
- Similar to data driven AI
 - Created by the designer
 - Implemented by programmer
 - Modern engines have tools



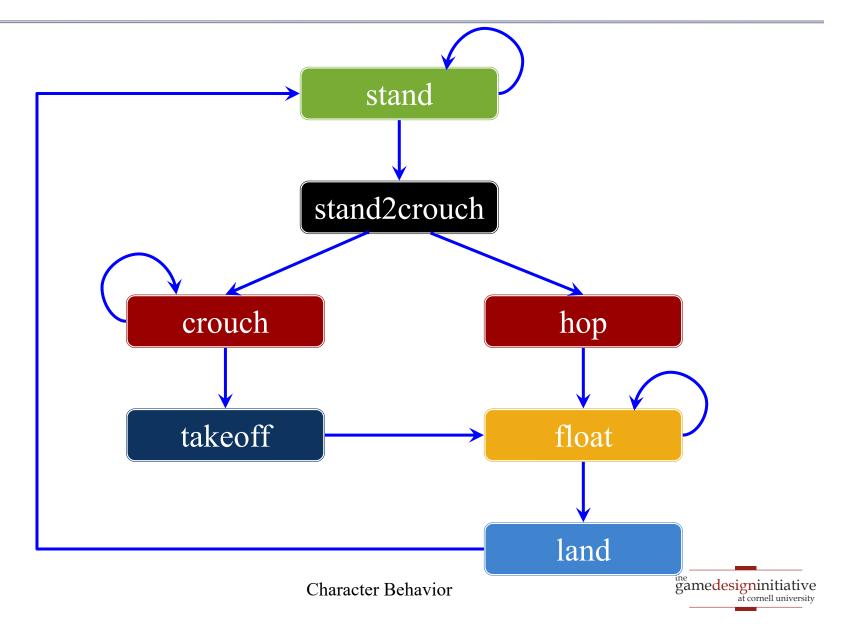
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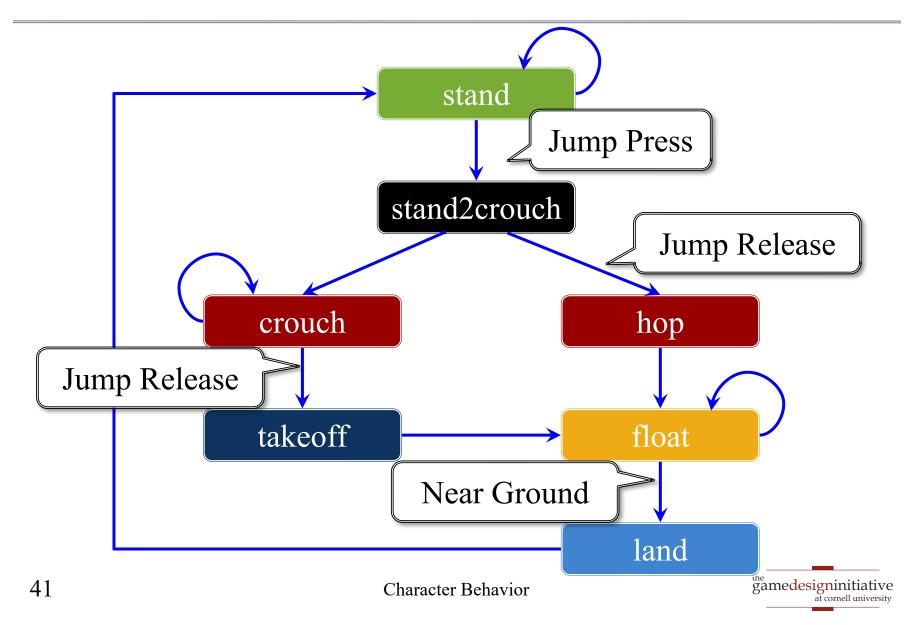




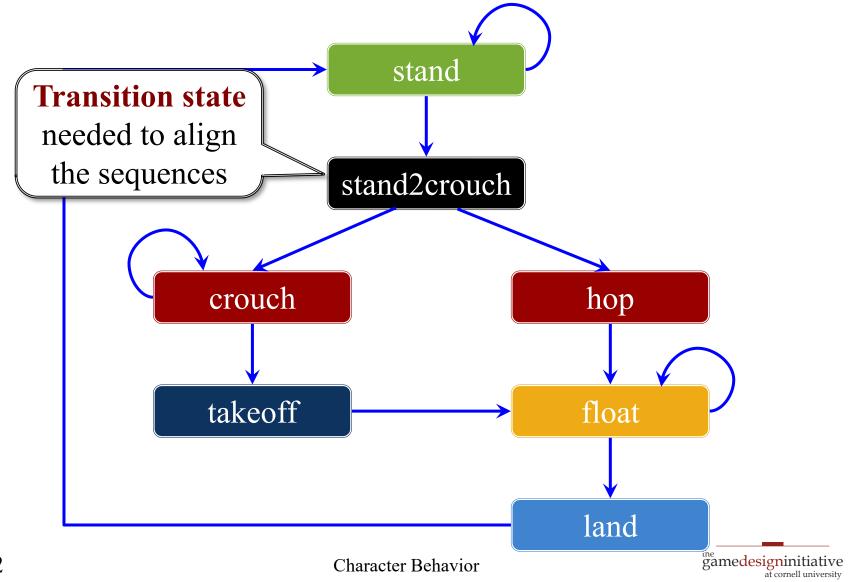
Complex Example: Jumping



Complex Example: Jumping



Complex Example: Jumping



LibGDX Interfaces

StateMachine<E>

- Attached to an entity
 - Set the entity in constructor
 - New entity, new state machine
- Must implement methods
 - update()
 - changeState(State<A> state)
 - revertToPreviousState()
 - getCurrentState()
 - isInState(State<A> state)
- DefaultStateMachine provided

State<E>

- Not attached to an entity
 - StateMachine sets state
 - StateMachine passes entity
- Must implement methods
 - enter(E entity)When machine enters state
 - exit(E entity)
 When machine enters state
 - update(E entity)When machine stays in state



LibGDX Interfaces

StateMachine < E >

State<E>

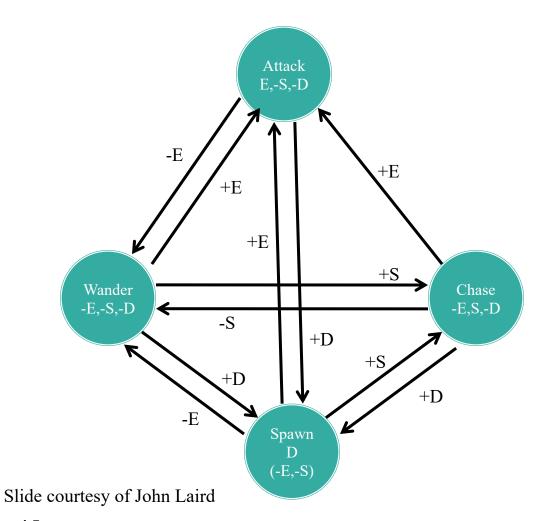
- Attached to an entity
 Updates current state. ructor
 - Does not transition!
- Me implement method
 - update()
 - changeState(State<A> state)

ma

- revertToPreviousState()
- getCurrentState()
- isInState(State<A> state)
- DefaultStateMachine provided

- Not attached to an entity
- Transition logic external to the state machine.
 - When machine enters state
 - exit(E entity)When machine enters state
 - update(E entity)When machine stays in state



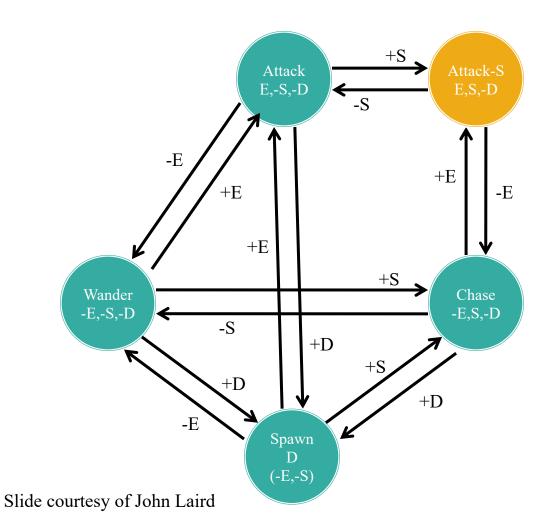


Events

- **E**=Enemy Seen
- S=Sound Heard
- **D**=Die

No edge from Attack to Chase



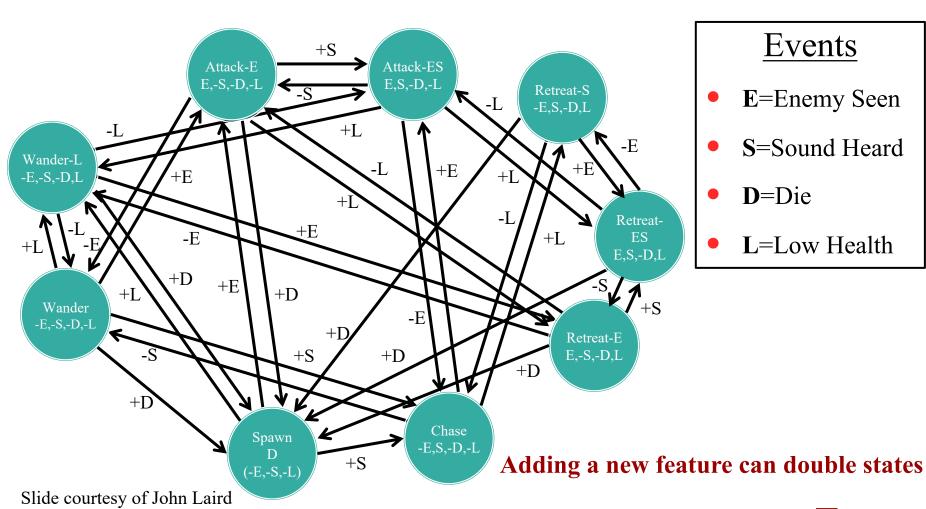


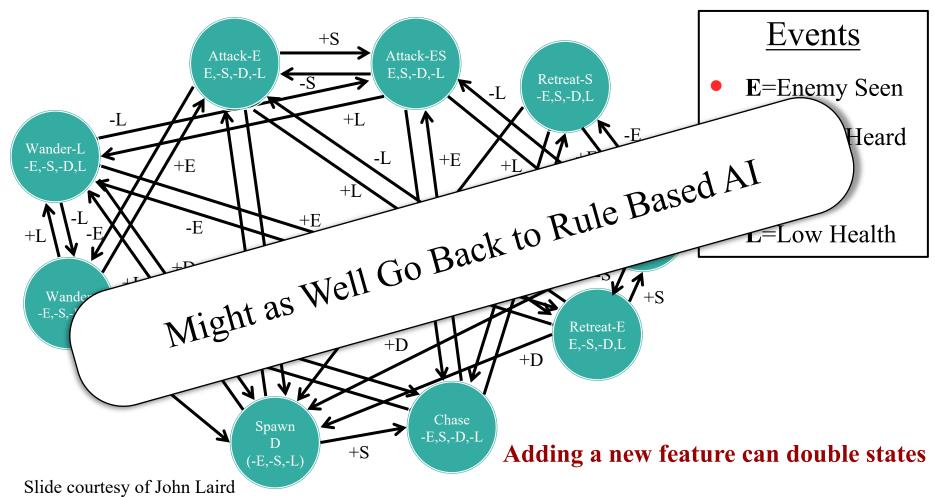
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Requires a redundant state







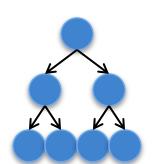
An Observation

- Each state has a set of global attributes
 - Different attributes may have same actions
 - Reason for redundant behavior
- Currently just cared about attributes
 - Not really using the full power of a FSM
 - Why don't we just check attributes directly?
- Attribute-based selection: *decision trees*



Decision Trees

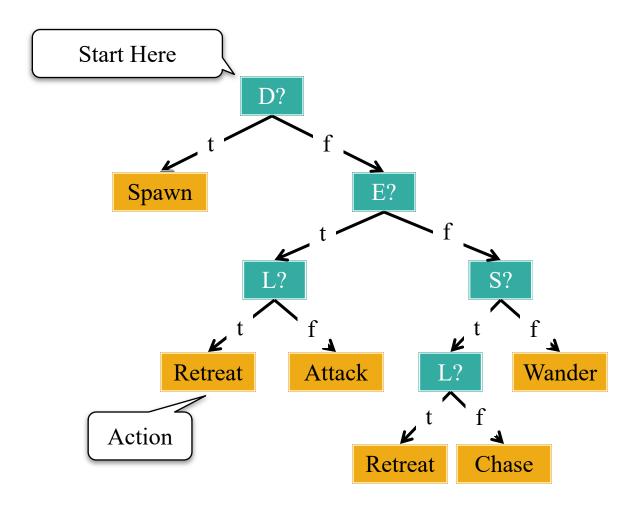
- Thinking encoded as a tree
 - Attributes = tree nodes
 - Left = true, right = false
 - Actions = leaves (reach from the root)



- Classify by descending from root to a leaf
 - Start with the test at the root
 - Descend the branch according to the test
 - Repeat until a leaf is reached

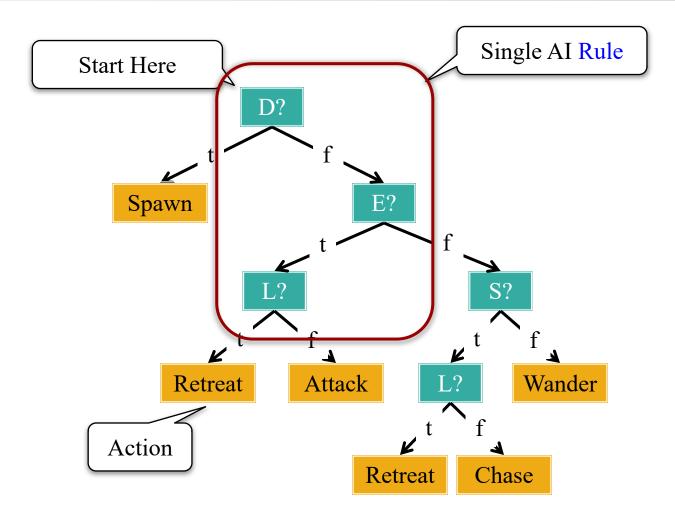


Decision Tree Example



Slide courtesy of John Laird

Decision Tree Example

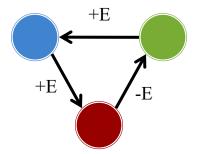


Slide courtesy of John Laird

FSMs vs. Decision Trees

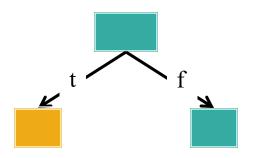
Finite State Machines

- Not limited to attributes
- Allow "arbitrary" behavior
- Explode in size very fast



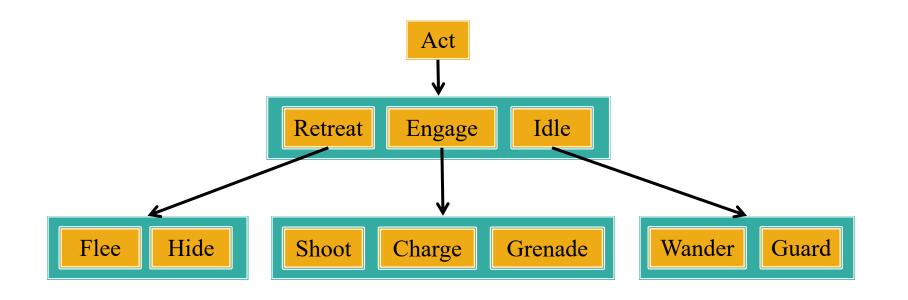
Decision Trees

- Only attribute selection
- Much more manageable
- Mixes w/ machine learning





Behavior Trees

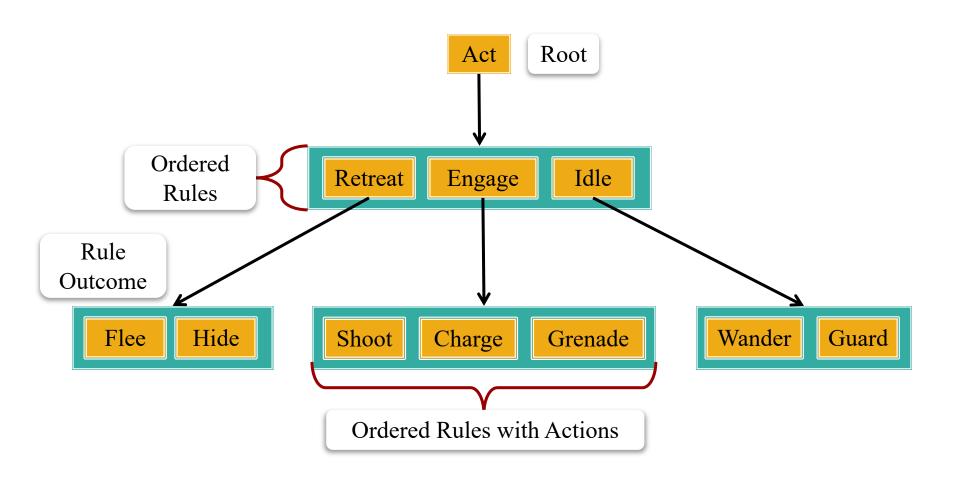


- Part rule-based
- Part decision tree
- Freedom of FSM (almost)

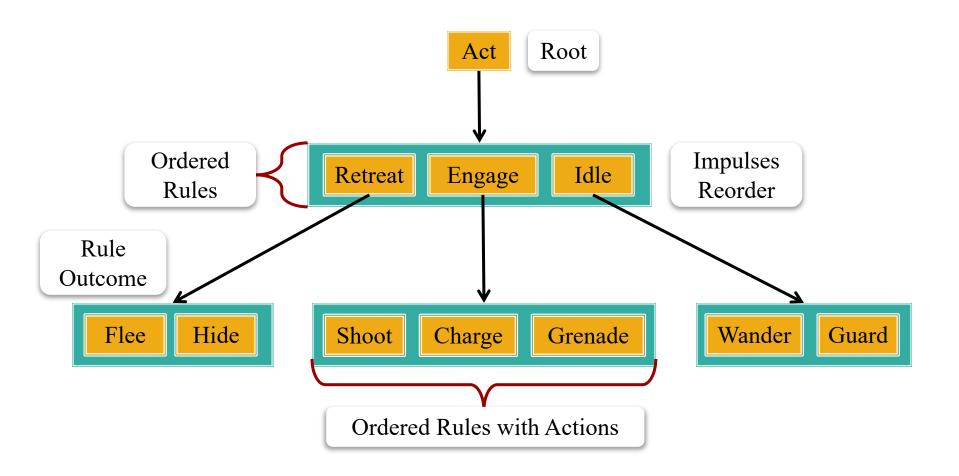
- Node is a list of *actions*
- Select action using *rules*
- Action leads to *subactions*



Behavior Trees



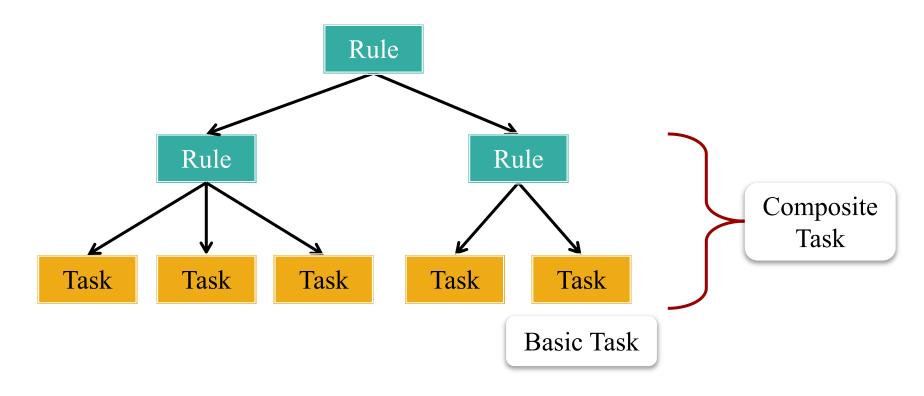
Behavior Trees





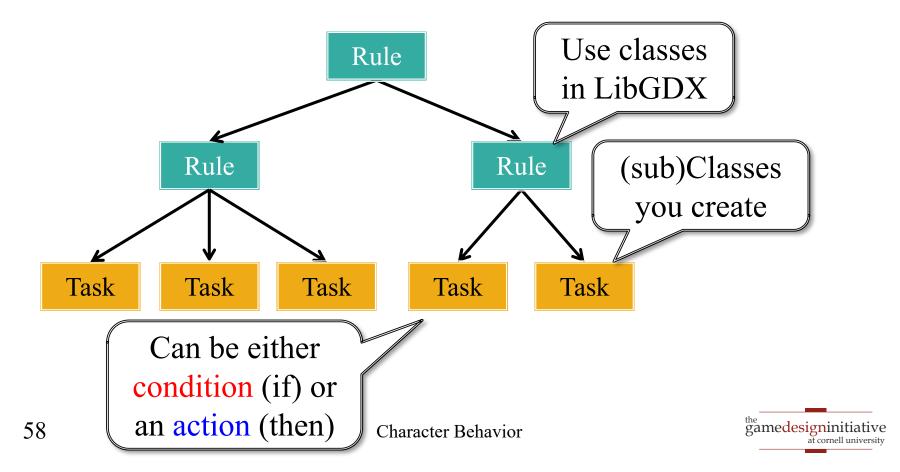
LibGDX Behavior Trees

- Base actions are defined at the leaves
- Internal nodes to select or even combine tasks

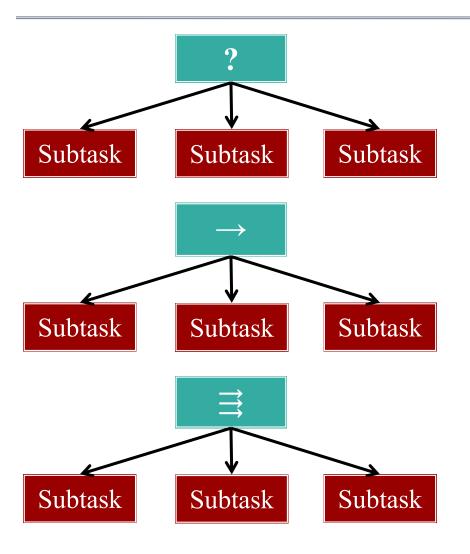


LibGDX Behavior Trees

- Base actions are defined at the leaves
- Internal nodes to select or even combine tasks



LibGDX Rules



Selector rules

- Tests each subtask for success
- Tasks are tried independently
- Chooses first one to succeed

• Sequence rules

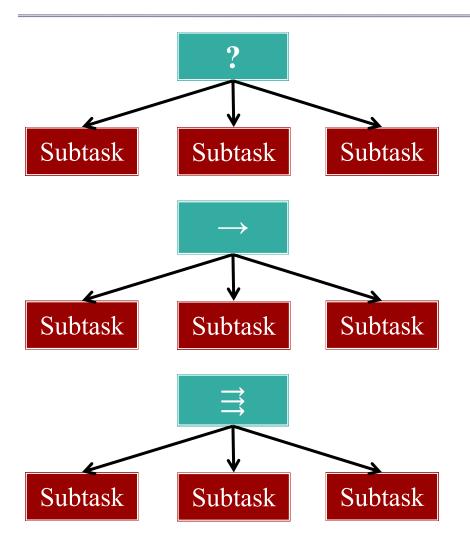
- Tests each subtask for success
- Tasks are tried in order
- Does all if succees; else none

Parallel rules

- Tests each subtask for success
- Tasks are tried simultaneously
- Does all if succees; else none



This is the Wrong Model



- Conflates actions/selection
 - Want way to pick subtask
 - Distinct from performing it
- Actions must be instant
 - Can switch each frame
 - Action unaware of switch
 - No way to suspend/recover
- Have a new API in 4152
 - Still being tested in class
 - Bring to 3152 eventually



Summary

- Character AI is a software engineering problem
 - Sense-think-act aids code reuse and ease of design
 - Least standardized aspect of game architecture
- Rule-based AI is the foundation for all character AI
 - Simplified variation of sense-think-act
 - Alternative systems made to limit number of rules
- Games use graphical models for data-driven AI
 - Controller outside of NPC model processes AI
 - Graph stored in NPC model tailors AI to individuals

