# gamedesigninitiative at cornell university

#### Lecture 22

# Strategic Al

#### Role of AI in Games

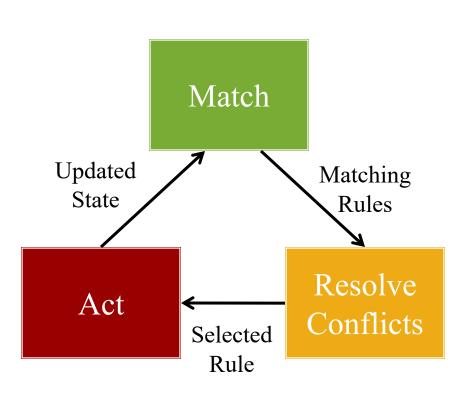
- Autonomous Characters (NPCs)
  - Mimics the "personality" of the character
  - May be opponent or support character
- Strategic Opponents
  - AI at the "player level"
  - Closest to classical AI
- Character Dialog
  - Intelligent commentary
  - Narrative management (e.g. Façade)



#### Rule-Based Al

#### If X is true, Then do Y

# **Three-Step Process**



#### Match

- For each rule, check if
- Return *all* matches

#### Resolve

- Can only use one rule
- Use metarule to pick one

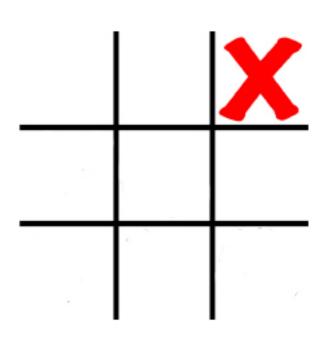
#### Act

Do then-part



# Example: Tic-Tac-Toe

- Next move for player O?
  - If have a winning move, make it
  - If opponent can win, block it
  - Take the center if available
  - Corners are better than edges
- Very easy to program
  - Just check the board state
  - Tricky part is prioritization



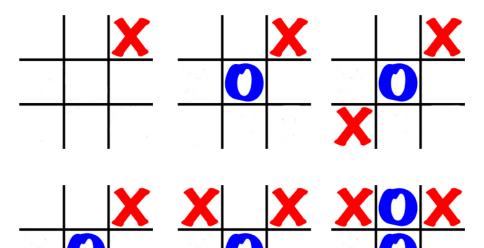


# Example: Microsoft's Age of Kings

```
; The AI will attack once at 1100 seconds and then again
; every 1400 sec, provided it has enough defense soldiers.
(defrule
   (game-time > 1100)
   =>
   (attack-now)
   (enable-timer 7 1100))
(defrule
   (timer-triggered 7) (defend-soldier-count >= 12)
   =>
   (attack-now)
   (disable-timer 7)
   (enable-timer 7 1400)
```

### The Problems with Rules

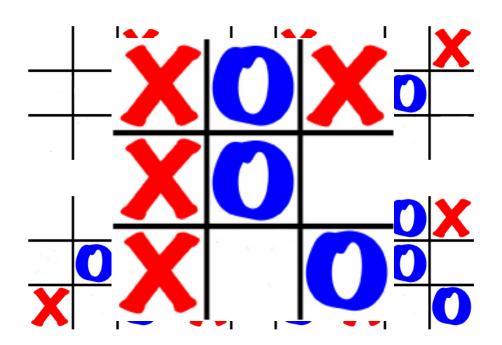
- Rules only do one step
  - May not be best move
  - Could lose long term
- Next move for player O?
  - If can win, then do it
  - If X can win, then block it
  - Take the center if possible
  - Corners > edges
- Need to look ahead





#### The Problems with Rules

- Rules only do one step
  - May not be best move
  - Could lose long term
- Next move for player O?
  - If can win, then do it
  - If X can win, then block it
  - Take the center if possible
  - Corners > edges
- Need to look ahead





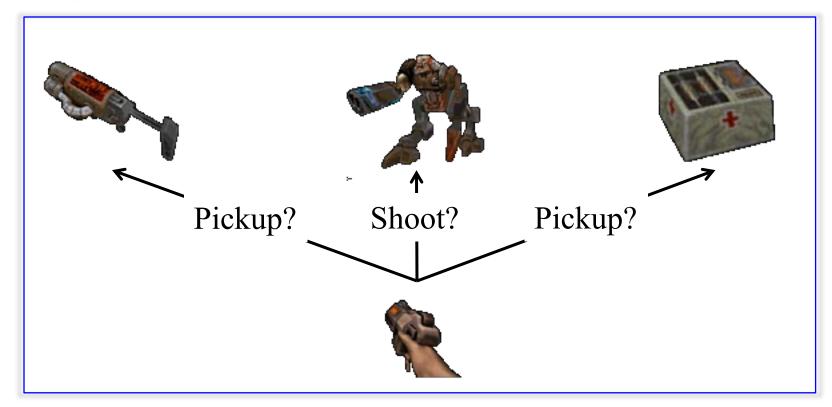
# Multiple Steps: Planning

- Plan: actions necessary to reach a goal
  - Goal is a (pseudo) specific game state
  - Actions change game state (e.g. verbs)
- Planning: steps to generate a plan
  - Initial State: state the game is currently in
  - Goal Test: determines if state meets goal
  - Operators: action the NPC can perform



# What Should We Do?

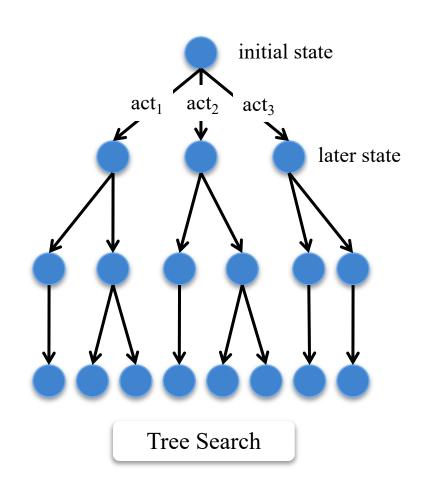
Slide courtesy of John Laird





# Simplification: No Opponent

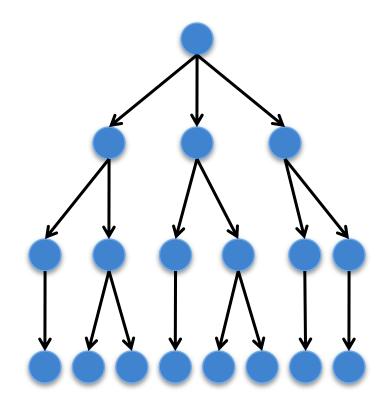
- Identify desired goal
  - Ex: Kill enemy, get gold
  - Design appropriate test
- List all relevant actions
  - Ex: Build, send troops
- Look-ahead Search
  - Start with initial state
  - Try all actions (look-ahead)
  - Stop if reached goal
  - Continue if not at goal





# Planning Issues

- Exponential choices
  - Search action *sequences*
  - How far are we searching?
  - Cannot do this in real life!
- Game state is complex
  - Do we look at entire state?
  - Faster to "do" than to plan
- Must limit search
  - Reduce actions examined
  - Simplify game state





# Internal State Representation

#### Simplified World Model

- Includes primary resources
  - Example: ammo, health
- Rough notion of position
  - **Example**: in/outside room
  - Both characters and items
- Game mechanic details
  - **Example**: respawn rate
  - Allows tactical decisions

#### **Uses of Internal State**

- Notice changes
  - Health is dropping
  - Enemy must be nearby
- Remember recent events
  - Enemy has left the room
  - Chase after fleeing enemy
- Remember older events
  - Picked up health 30 sec ago



# Internal State Representation

#### Simplified World Model

- Includes primary resources
  - Example: ammo, health
- Rough notion of position
  - Examp
  - Both
- Game mechanic uetails
  - Example: respawn rate
  - Allows tactical decisions

#### **Uses of Internal State**

- Notice changes
  - Health is dropping
  - rby
- Similar to Non-Digital Prototype
  - Chase after fleeing enemy

.... rest the room

- Remember older events
  - Picked up health 30 sec ago



ents

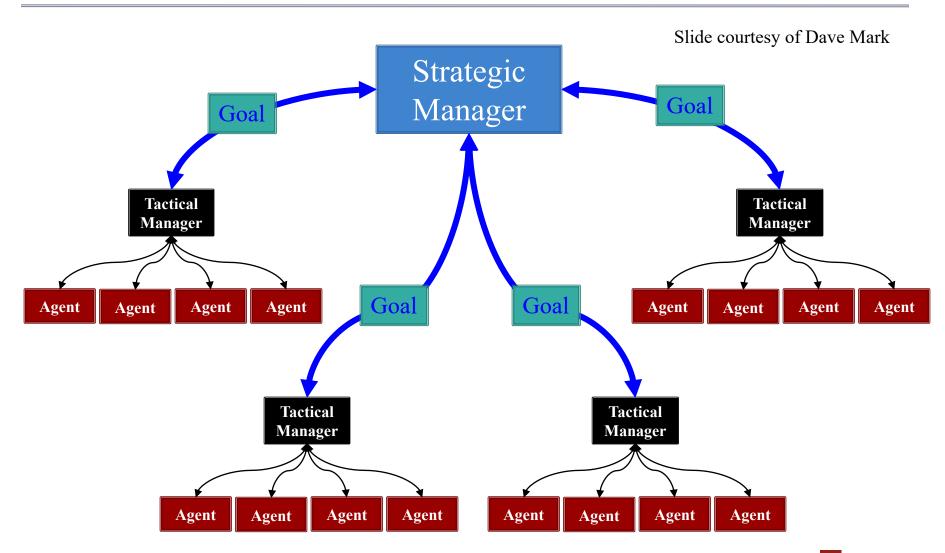
# **Internal State and Memory**

- Each NPC has own state
  - Represents NPC *memory*
  - Might not be consistent
- Useful for character AI
  - Models sensory data
  - Models communication
- Isolates planning
  - Each NPC plans separately
  - Coordinate planning with a strategic manager





# **Strategy versus Tactics**



# Internal State for Quake II

- Self
  - Current-health
    - Last-health
  - Current-weapon
    - Ammo-left
  - Current-room
    - Last-room
  - Current-armor
    - Last-armor
  - Available-weapons
- Enemy
  - Current-weapon
  - Current-room
  - Last-seen-time
  - Estimated-health
- Current-time

- Random-number
- Powerup
  - Type
  - Room
  - Available
  - Estimated-spawn-time
- Map
  - Rooms
  - Halls
  - Paths
- Parameters
  - Full-health
  - Health-powerup-amount
  - Ammo-powerup-amount
  - Respawn-rate



# Internal Action Representation

#### **Simplified Action Model**

- Internal Actions = operators
  - Just mathematical functions
  - Operators alter internal state
- Pre-conditions
  - What is required for action
  - Often resource requirement
- Effects
  - How action changes state
  - Both global and for NPC

#### **Designing Actions**

- Extrapolate from gameplay
  - Start with an internal state
  - Pick "canonical" game state
  - Apply game action to state
  - Back to internal state
- Remove any uncertainty
  - Deterministic NPC behavior
  - "Average" random results
  - Or pick worse case scenario



# Internal Action Representation

### **Simplified Action Model**

- Internal Actions = *operators* 
  - Just mathematical functions
  - Operators alter internal state

### **Designing Actions**

- Extrapolate from gameplay
  - Start with an internal state
  - rame state

- Pre-cond
  - What
  - Often

Like Gameplay Specification, but actions, interactions combined

#### **Effects**

- How action changes state
- Both global and for NPC

Remove any uncertainty

- Deterministic NPC behavior
- "Average" random results
- Or pick worse case scenario



o state

# Example: Pick-Up Health Op

#### • Preconditions:

- Self.current-room = Powerup.current-room
- Self.current-health < full-health
- Powerup.type = health
- Powerup.available = yes

#### • Effects:

- Self.last-health = self.current-health
- Self.current-health = current-health + health-powerup-amount
- Powerup.available = no
- Powerup.estimated-spawn-time = current-time + respawn-rate



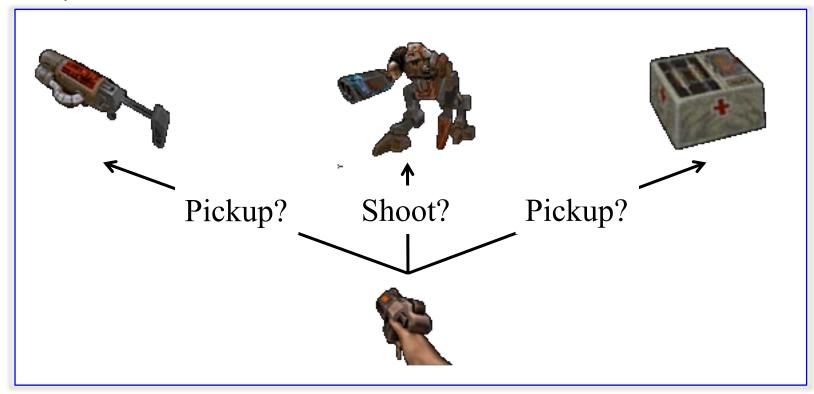
# **Building Internal Models**

- Planning is only as accurate as model
  - Bad models → bad plans
  - But complex models → slow planning
- Look at your nondigital prototype!
  - Heavily simplified for playability
  - Resources determine internal state
  - Nondigital verbs are internal actions
- One of many reasons for this exercise



# What Should We Do?

Slide courtesy of John Laird

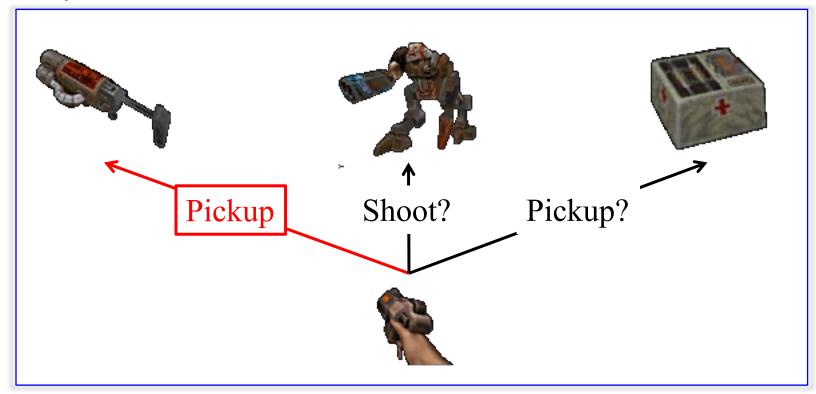


Self.current-health = 20 Self.current-weapon = blaster Enemy.estimated-health = 50

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = yes

# One Step: Pick-up Railgun

Slide courtesy of John Laird



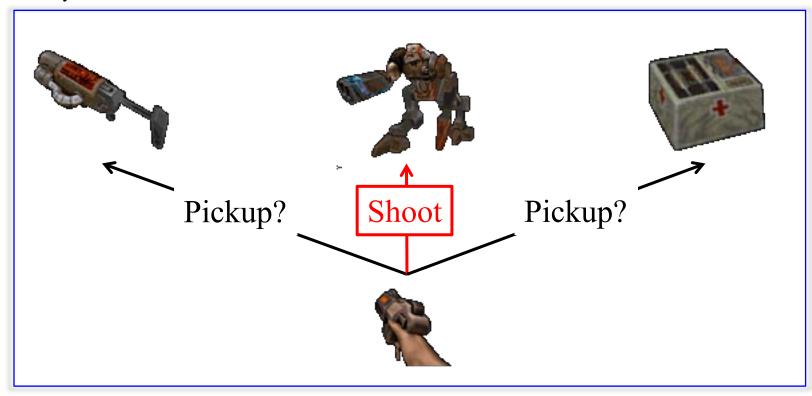
Self.current-health = 10 Self.current-weapon = railgun Enemy.estimated-health = 50

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = no



# One Step: Shoot Enemy

Slide courtesy of John Laird



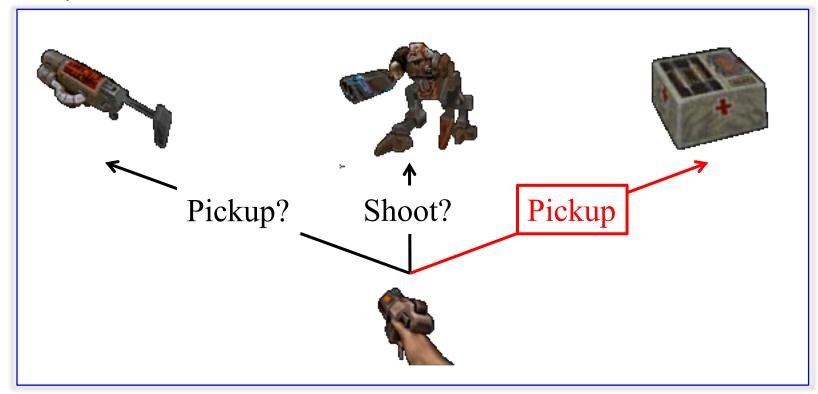
**Self.current-health = 10** Self.current-weapon = blaster Enemy.estimated-health = 40

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = yes



# One Step: Pick-up Health-Pak

Slide courtesy of John Laird



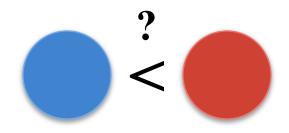
**Self.current-health = 90** Self.current-weapon = blaster

Enemy.estimated-health = 50

Powerup.type = health-pak
Powerup.available = no
Powerup.type = Railgun
Powerup.available = yes

### State Evaluation Function

- Need to compare states
  - Is either state better?
  - How far away is goal?
- Might be partial order
  - Some states incomparable
  - If not goal, just continue
- Purpose of planning
  - Find good states
  - Avoid bad states





# State Evaluation: Quake II

- Example 1: Prefer higher self.current-health
  - Always pick up health powerup
  - Counter example:
    - Self.current-health = 99%
    - Enemy.current-health = 1%
- Example 2: Prefer lower enemy.current-health
  - Always shoot enemy
  - Counter example:
    - Self.current-health = 1%
    - Enemy.current- health = 99%



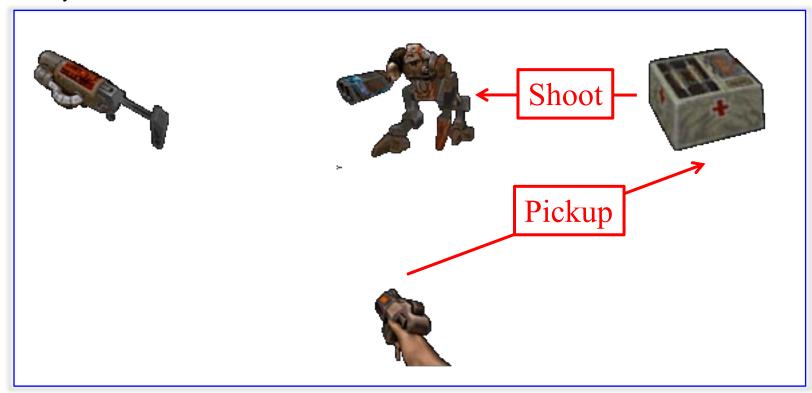
# State Evaluation: Quake II

- Example 3: Prefer higher self.health enemy.health
  - Shoot enemy if I have health to spare
  - Otherwise pick up a health pack
  - Counter examples?
- Examples of more complex evaluations
  - If self.health > 50% prefer lower enemy.health
    - Otherwise, want higher self.health
  - If self.health > low-health prefer lower enemy.health
    - Otherwise, want higher self.health



# Two Step Look-Ahead

Slide courtesy of John Laird



**Self.current-health = 80** Self.current-weapon = blaster

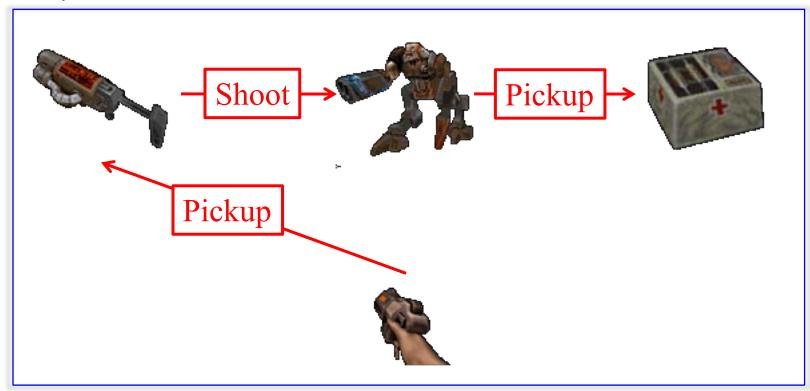
Enemy.estimated-health = 40

Powerup.type = health-pak
Powerup.available = no
Powerup.type = Railgun
Powerup.available = yes



# Three Step Look-Ahead

Slide courtesy of John Laird



Self.current-health = 100 Self.current-weapon = railgun Enemy.estimated-health = 0

Powerup.type = health-pak
Powerup.available = no
Powerup.type = Railgun
Powerup.available = no



# Look-Ahead Search

#### **One-Step Lookahead**

```
op pickBest(state) {
  foreach op satisfying precond {
     newstate = op(state)
     evaluate newstate
  return op with best evaluation
```

#### **Multistep Tree Search**

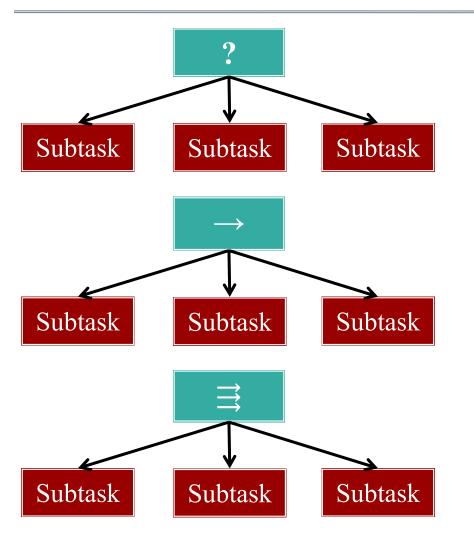
```
[op] bestPath(&state,depth) {
  if depth == 0 { return [] }
  foreach op satisfying precond {
     newstate = op(state)
     [nop]=bestPath(newstate,depth-1)
     evaluate newstate
  pick op+[nop] with best state
  modify state to reflect op+[nop]
  return op+[nop]
```

# Look-Ahead Search

- Are more steps better?
  - Longer, more elaborate plans
  - More time & space consuming
  - Opponent or environment can mess up plan
  - Simplicity of internal model causes problems
- In this class, limit three or four steps
  - Anything more, and AI is too complicated
  - Purpose is to be challenging, not to win



### Recall: LibGDX Behavior Trees



#### Selector rules

- Tests each subtask for success
- Tasks are tried independently
- Chooses first one to succeed

#### Sequence rules

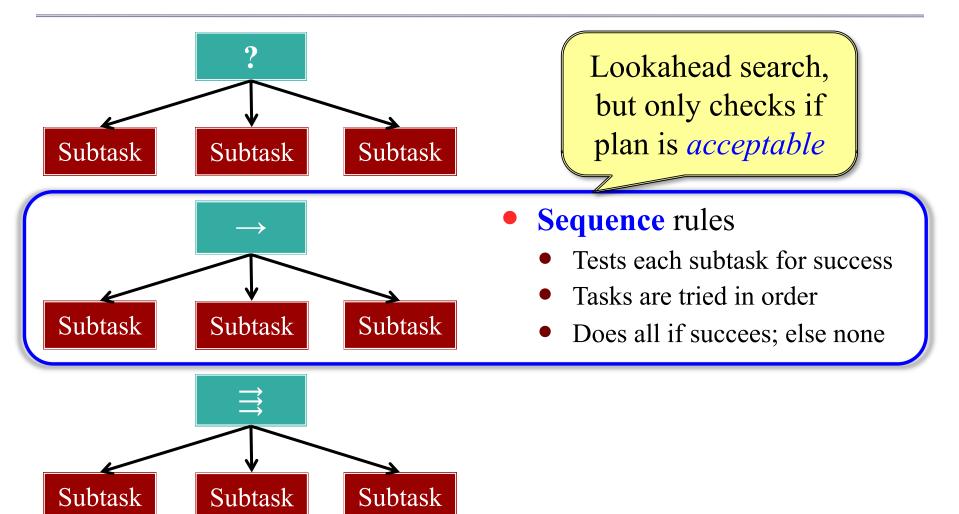
- Tests each subtask for success
- Tasks are tried in order
- Does all if succees; else none

#### Parallel rules

- Tests each subtask for success
- Tasks are tried simultaneously
- Does all if succees; else none

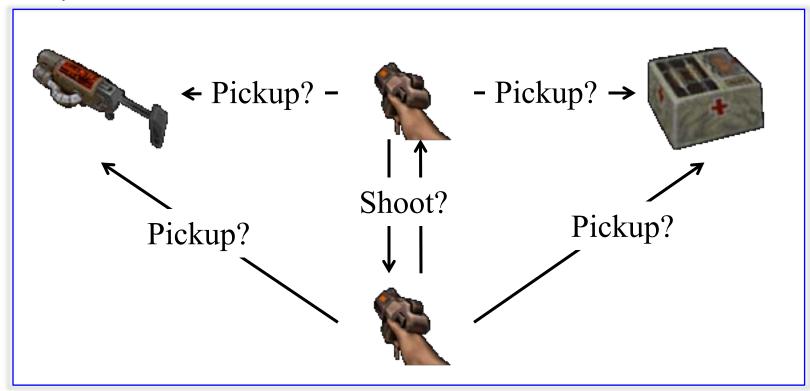


### Recall: LibGDX Behavior Trees



# **Opponent: New Problems**

Slide courtesy of John Laird



Self.current-health = 20 Self.current-weapon = blaster Enemy.estimated-health = 50

Powerup.type = health-pak Powerup.available = yes Powerup.type = Railgun Powerup.available = yes

# **Opponent Model**

- **Solution 1**: Assume the worst
  - Opponent does what would be worst for you
  - Full game tree search; exponential
- **Solution 2**: What would I do?
  - Opponent does what you would in same situation
- Solution 3: Internal opponent model
  - Remember what did last time
  - Or remember what they like to do

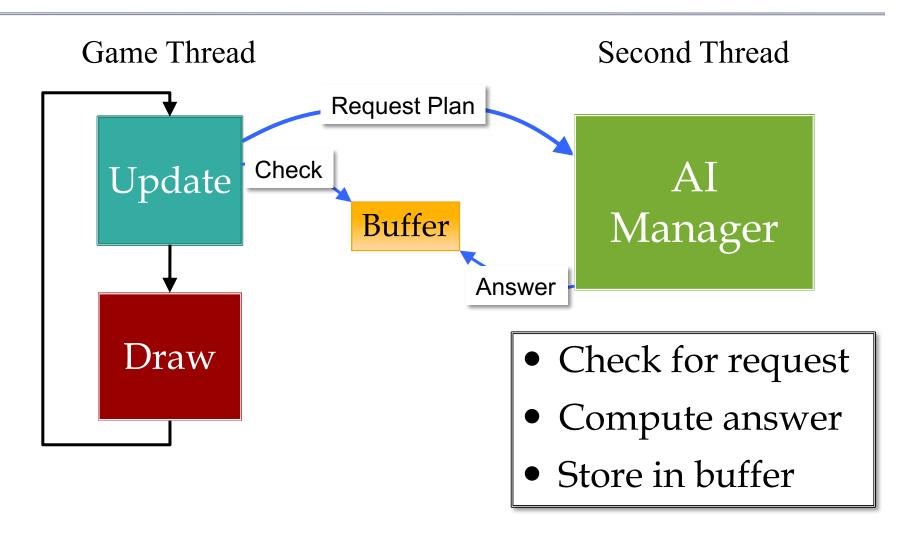


# Opponent Interference

- Opponent actions may prevent yours
  - Example: Opponent grabs railgun first
  - Need to take into account in your plan
- Solution: Iteration
  - Plan once with no interference
  - Run again, assuming best plans of the opponent
  - Keep iterating until happy (or run out of time)
- Planning is very expensive!

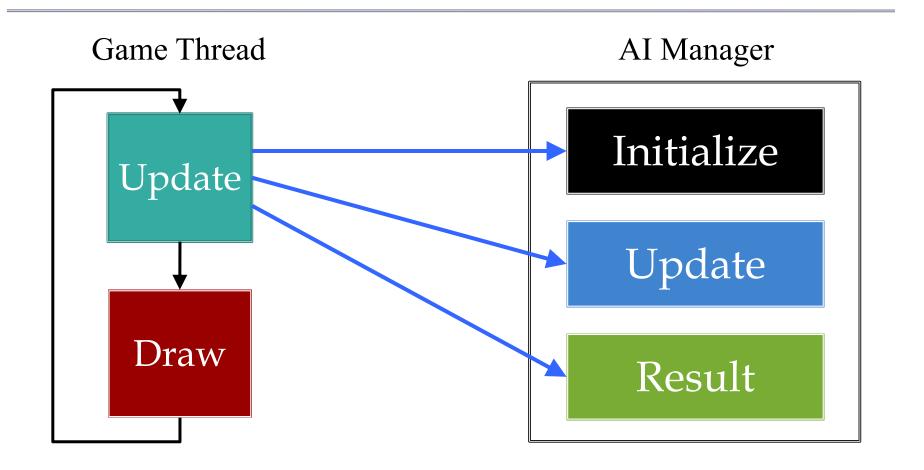


# Asynchronous Al



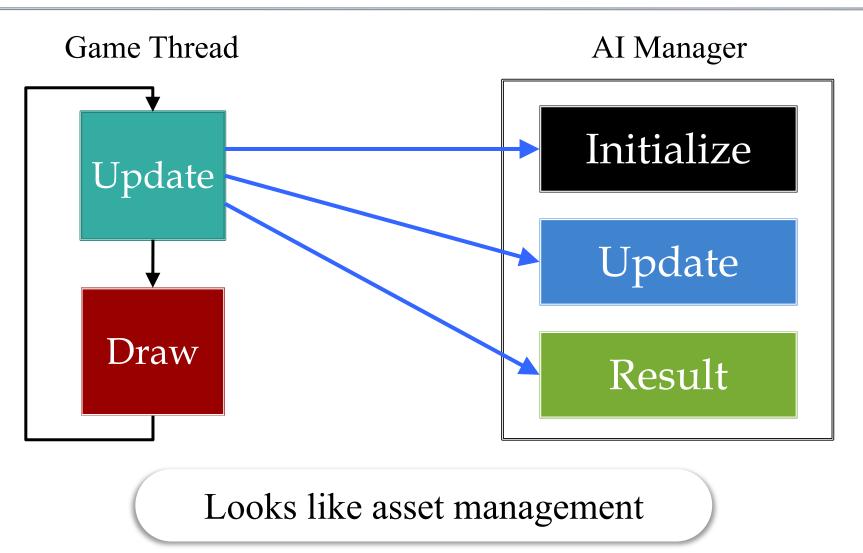


#### **Alternative:** Iterative Al





### **Alternative:** Iterative Al





# Using Asynchronous Al

- Give AI a time budget
  - If planning takes too long, abort it
  - Use counter in update loop to track time
- Beware of stale plans
  - Actual game state has probably changed
  - When find a plan, make sure it is still good
  - Evaluate (quickly) with new internal state
  - Make sure result is "close" to what thought



# Planning: Optimization

- Backwards Planning
  - Idea: few operators achieve goal conditions
  - Implementation:
    - For each operator, reverse the effect
    - Check reversed effect satisfies pre-conditions
- Possible to use backwards and forwards
  - Start on each end, and check for meets
  - Does not work well with numerical resources



### To Plan or Not to Plan

#### Advantages

- Less predictable behavior
- Can handle unexpected situations
- More accurate than rule-based AI

#### Disadvantages

- Less predictable behavior (harder to debug)
- Planning takes a lot of processor time
- Planning takes memory
- Need simple but accurate internal representations



#### Other Possibilities

- There are many more options available
  - Neural nets
  - Decision trees
  - General machine learning
  - Take **CS 4700** if want to learn more
- Quality is a matter of heated debate
  - Better to spend time on internal state design
  - Most AI is focused on perception modeling



# **Summary**

- Rule-based AI is simplest form of strategic AI
  - Only limited to one-step at a time
  - Can easily make decisions that lose in long term
- More complicated behavior requires planning
  - Simplify the game to turn-based format
  - Use classic AI search techniques
- Planning has advantages and disadvantages
  - Remember, the desire is to challenge, not to win

