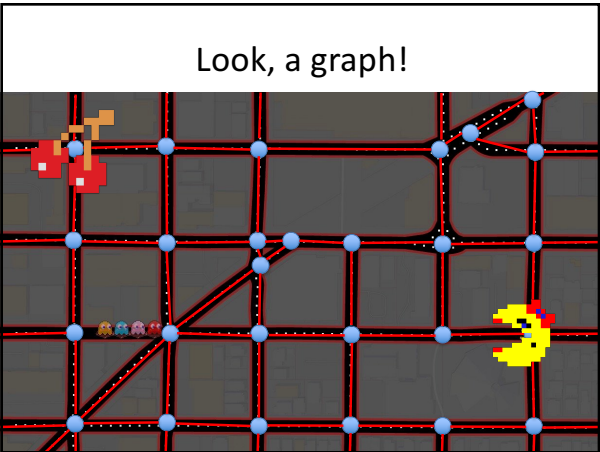
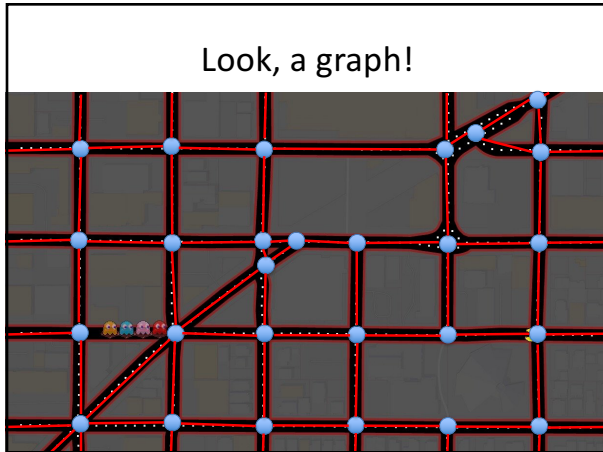
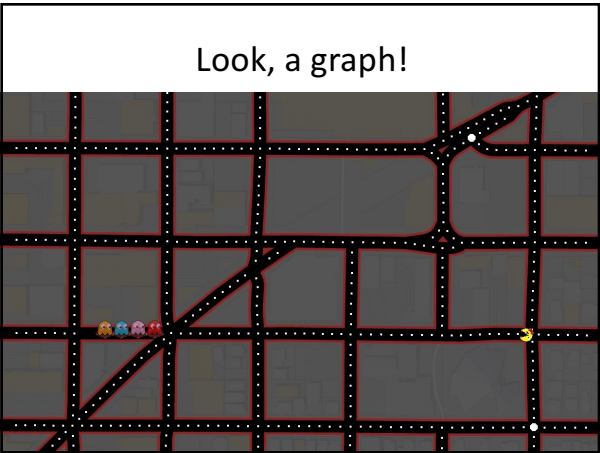


Announcements

- Lunch** with instructors: Still many slots open!
 - See pinned Piazza note @275
- Hidden Figures**: Thursday at 8:30 and 11:00!
 - If you haven't signed up on the CMS schedule do so now!
 - so far: 8:30 114/330
11:00 147/330

Announcements

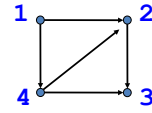
- For next Tuesday's lecture, you **MUST** watch the tutorial on the shortest path algorithm beforehand:
 - <http://www.cs.cornell.edu/courses/cs2110/2017sp/online/shortestPath/shortestPath.html>
 - Tuesday's lecture **will assume** that you understand it. Watch the tutorial once or twice and execute the algorithm on a small graph.
- Information about **Prelim 2** is now on the Exams page of the course website and P2Conflict will be available on the CMS today (Tuesday).



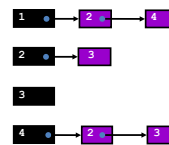
Graph Algorithms

- Search
 - Depth-first search
 - Breadth-first search
- Shortest paths
 - Dijkstra's algorithm
- Minimum spanning trees
 - Prim's algorithm
 - Kruskal's algorithm

Representations of Graphs



Adjacency List



Adjacency Matrix

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

Adjacency Matrix or Adjacency List?

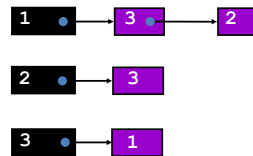
- Definitions:
 - n = number of vertices
 - e = number of edges
 - $d(u)$ = degree of u = number of edges leaving u
- Adjacency Matrix
 - Uses space $O(n^2)$
 - Can iterate over all edges in time $O(n^2)$
 - Can answer “Is there an edge from u to v ?” in $O(1)$ time
 - Better for dense graphs (lots of edges)
- Adjacency List
 - Uses space $O(e + n)$
 - Can iterate over all edges in time $O(e + n)$
 - Can answer “Is there an edge from u to v ?” in $O(d(u))$ time
 - Better for sparse graphs (fewer edges)

Breaking DAG

Which of the following two graphs are DAGs?

Directed Acyclic Graph

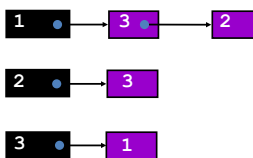
Graph 1:



Graph 2:

	1	2	3
1	0	1	1
2	0	0	0
3	0	1	0

Breaking DAG



	1	2	3
1	0	1	1
2	0	0	0
3	0	1	0

Back to Important Things:



Depth-First Search

- Given a graph and one of its nodes u
(say node 1 below)

Depth-First Search

- Given a graph and one of its nodes u
(say node 1 below)
- We want to "visit" each node reachable from u
(nodes 1, 0, 2, 3, 5)

There are many paths to some nodes.
How do we visit all nodes efficiently, without doing extra work?

Depth-First Search

boolean[] visited;

- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- v is REACHABLE* from u if there is a path (u, \dots, v)
*in which all nodes of the path are unvisited.

Suppose all nodes are unvisited.

Depth-First Search

boolean[] visited;

- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- v is REACHABLE* from u if there is a path (u, \dots, v)
*in which all nodes of the path are unvisited.

Suppose all nodes are unvisited.

Nodes REACHABLE* from node 1:
{1, 0, 2, 3, 5}

Depth-First Search

boolean[] visited;

- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- v is REACHABLE* from u if there is a path (u, \dots, v)
*in which all nodes of the path are unvisited.

Suppose all nodes are unvisited.

Nodes REACHABLE* from node 1:
{1, 0, 2, 3, 5}

Nodes REACHABLE* from 4:
{4, 5, 6}

Depth-First Search

boolean[] visited;

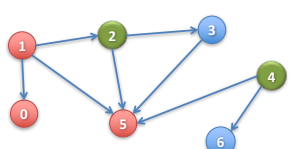
- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- v is REACHABLE* from u if there is a path (u, \dots, v)
*in which all nodes of the path are unvisited.

Green: visited
Blue: unvisited

Depth-First Search

```
boolean[] visited;
```

- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- v is REACHABLE* from u if there is a path (u, \dots, v) *in which all nodes of the path are unvisited.



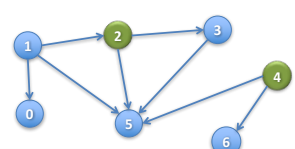
Green: visited
Blue: unvisited

Nodes REACHABLE* from node 1: {1, 0, 5}

Depth-First Search

```
boolean[] visited;
```

- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- v is REACHABLE* from u if there is a path (u, \dots, v) *in which all nodes of the path are unvisited.



Green: visited
Blue: unvisited

Nodes REACHABLE* from node 1: {1, 0, 5}

Nodes REACHABLE* from 4: none

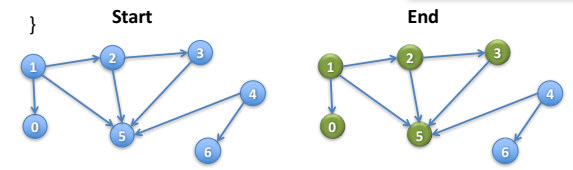
Not even 4 itself, because it's already been visited!

Depth-First Search

```
/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited. */
public static void dfs(int u) {
```

Let u be 1

The nodes REACHABLE* from 1 are 1, 0, 2, 3, 5



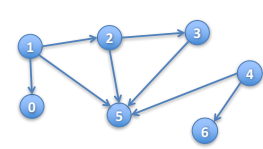
```
}
```

Depth-First Search

```
/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited. */
public static void dfs(int u) {
```

Let u be 1

The nodes REACHABLE* from 1 are 1, 0, 2, 3, 5



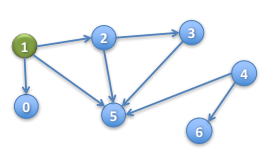
```
}
```

Depth-First Search

```
/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited. */
public static void dfs(int u) {
    visited[u] = true;
```

Let u be 1

The nodes REACHABLE* from 1 are 1, 0, 2, 3, 5



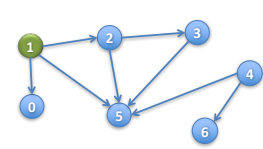
```
}
```

Depth-First Search

```
/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited. */
public static void dfs(int u) {
    visited[u] = true;
```

Let u be 1 (visited)

The nodes to be visited are 0, 2, 3, 5



```
}
```

Depth-First Search

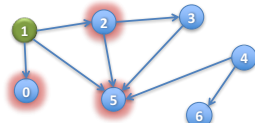
/** Visit all nodes that are REACHABLE*
from u. Precondition: u is unvisited. */

```
public static void dfs(int u) {
    visited[u] = true;
    for all edges (u, v) leaving u:
        if v is unvisited then dfs(v);
}
```

Let u be 1 (visited)

The nodes to be visited are 0, 2, 3, 5

Have to do DFS on all unvisited neighbors of u!

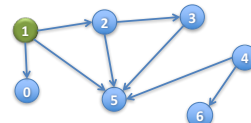


Depth-First Search

/** Visit all nodes that are REACHABLE*
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```
public static void dfs(int u) {
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        if v is unvisited then dfs(v);
}
```

Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1 ...

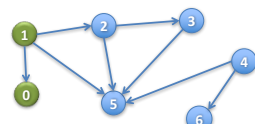


Depth-First Search

/** Visit all nodes that are REACHABLE*
from u. Precondition: u is unvisited. */

```
public static void dfs(int u) {
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}
```

Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1, 0 ...

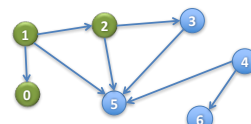


Depth-First Search

/** Visit all nodes that are REACHABLE*
from u. Precondition: u is unvisited. */

```
public static void dfs(int u) {
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}
```

Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1, 0, 2 ...

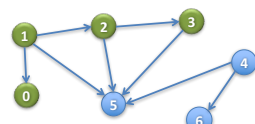


Depth-First Search

/** Visit all nodes that are REACHABLE*
from u. Precondition: u is unvisited. */

```
public static void dfs(int u) {
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Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1, 0, 2, 3 ...

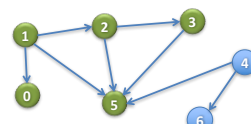


Depth-First Search

/** Visit all nodes that are REACHABLE*
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public static void dfs(int u) {
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}
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Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1, 0, 2, 3, 5



Depth-First Search

/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited. */

```
public static void dfs(int u) {
    visited[u] = true;
    for all edges (u, v) leaving u:
        if v is unvisited then dfs(v);
}
```

Suppose n nodes are REACHABLE* along e edges (in total). What is

- Worst-case runtime? $O(n+e)$
- Worst-case space? $O(n)$

Depth-First Search

/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited. */

```
public static void dfs(int u) {
    visited[u] = true;
    for all edges (u, v) leaving u:
        if v is unvisited then dfs(v);
}
```

Example: Use different way (other than array visited) to know whether a node has been visited

Example: We really haven't said what data structures are used to implement the graph

That's all there is to basic DFS. You may have to change it to fit a particular situation.

If you don't have this spec and you do something different, it's probably wrong.

Depth-First Search in OO fashion

```
public class Node {
    boolean visited;
    List<Node> neighbors;
}
```

Each node of the graph is an object of type Node

/** Visit all nodes that are REACHABLE* from u. Precondition: u is unvisited */

```
public void dfs() {
    visited = true;
    for (Node n: neighbors) {
        if (!n.visited) n.dfs();
    }
}
```

No need for a parameter. The object is the node.

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

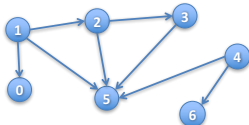
```
public static void dfs(int u) {
    Stack s = (u); // Not Java!
    // inv: all nodes that have to be visited are
    // REACHABLE* from some node in s
    while (s is not empty) {
        u = s.pop(); // Remove top stack node, put in u
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

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        u = s.pop();
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        }
    }
}
```

Call dfs(1)



1
Stack s

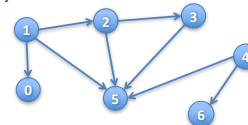
Depth-First Search written iteratively

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                s.push(v);
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    }
}
```

Call dfs(1)

Iteration 0



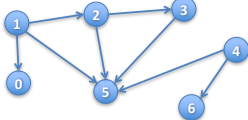
1
Stack s

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void dfs(int u) {
    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 0



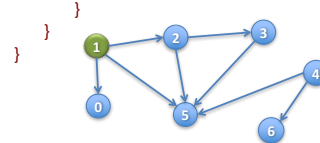
Stack s

Depth-First Search written iteratively

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        }
    }
}
```

Call dfs(1) Iteration 0



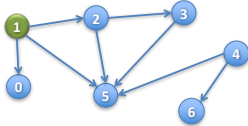
Stack s

Depth-First Search written iteratively

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```

Call dfs(1) Iteration 0



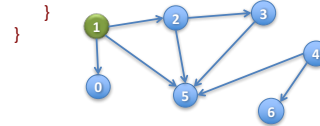
0
2
5
Stack s

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void dfs(int u) {
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    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
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            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 1



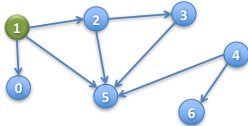
0
2
5
Stack s

Depth-First Search written iteratively

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    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
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            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 1



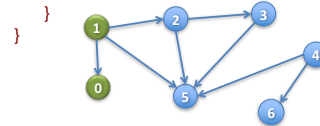
2
5
Stack s

Depth-First Search written iteratively

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    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 1



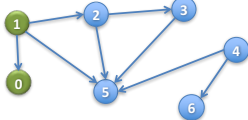
2
5
Stack s

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void dfs(int u) {
    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 2



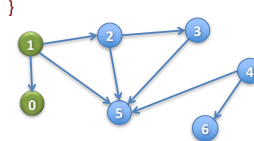
2
5
Stack s

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void dfs(int u) {
    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 2



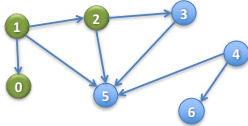
5
Stack s

Depth-First Search written iteratively

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```
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        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 2



5
Stack s

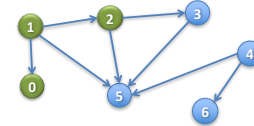
Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. . */

```
public static void dfs(int u) {
    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Call dfs(1) Iteration 2

Yes, 5 is put on the stack twice, once for each edge to it. It will be visited only once.



3
5
5
Stack s

Depth-First Search written iteratively

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. . */

```
public static void dfs(int u) {
    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

That's DFS!

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void dfs(int u) {
    Stack s = (u); // Not Java!
    // inv: all nodes that have to be visited are
    // REACHABLE* from some node in s
    while ( s is not empty ) {
        u = s.pop(); // Remove top stack node, put in u
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}
```

Want to see a magic trick?

Depth-First Search

```

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */
public static void dfs(int u) {
    Stack s= (u); // Not Java!
    // inv: all nodes that have to be visited are
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        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}

```



Breadth-First Search

```

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */
public static void bfs(int u) {
    Queue q= (u); // Not Java!
    // inv: all nodes that have to be visited are
    // REACHABLE* from some node in s
    while ( q is not empty ) {
        u= q.popFirst(); // Remove first node in queue, put in u
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v); // Add to end of queue
        }
    }
}

```

Breadth-First Search

```

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */
public static void bfs(int u) {
    Queue q= (u); // Not Java!
    // inv: all nodes that have to be visited are
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        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v); // Add to end of queue
        }
    }
}

```

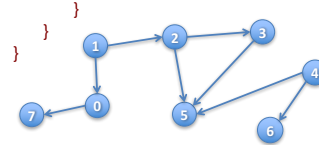
Breadth-First Search

```

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1)



1
Queue q

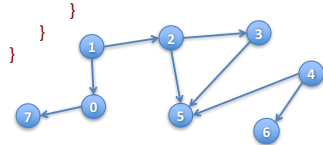
Breadth-First Search

```

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 0



1
Queue q

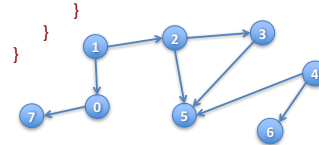
Breadth-First Search

```

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 0



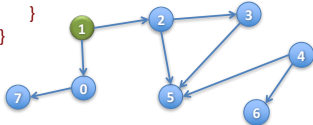
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 0



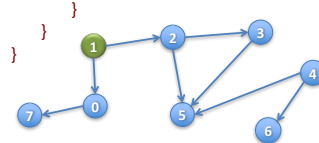
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 0



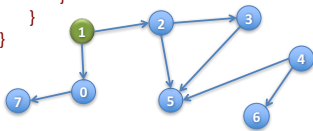
0 2
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 1



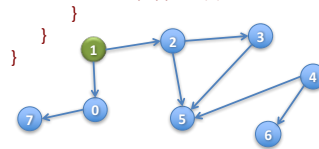
0 2
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 1



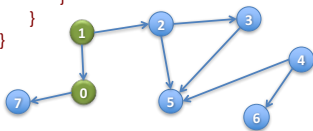
2
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 1



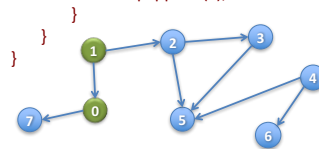
2
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 1



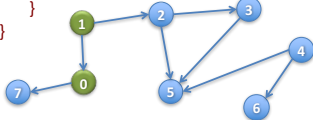
2 7
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 2



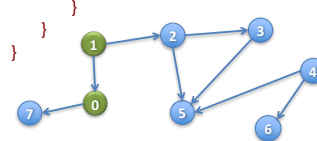
27
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 2



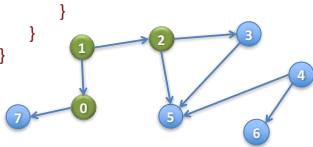
7
Queue q

Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 2



7
Queue q

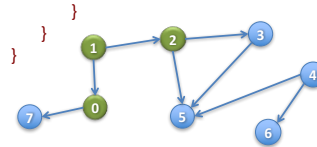
Breadth-First Search

/** Visit all nodes REACHABLE* from u. Pre: u is unvisited. */

```
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}
```

Call bfs(1) Iteration 2

Breadth first:
(1) Node u
(2) All nodes 1 edge from u
(3) All nodes 2 edges from u
(4) All nodes 3 edges from u
...



7 3 5
Queue q

Some food for thought:

- BFS(root) on a tree corresponds to which tree traversal?
- Write out the order nodes are visited in this undirected graph, when calling:
 - BFS(5)
 - DFS(5)
 - DFS(0)

(if there are ties, visit the lower # first)

