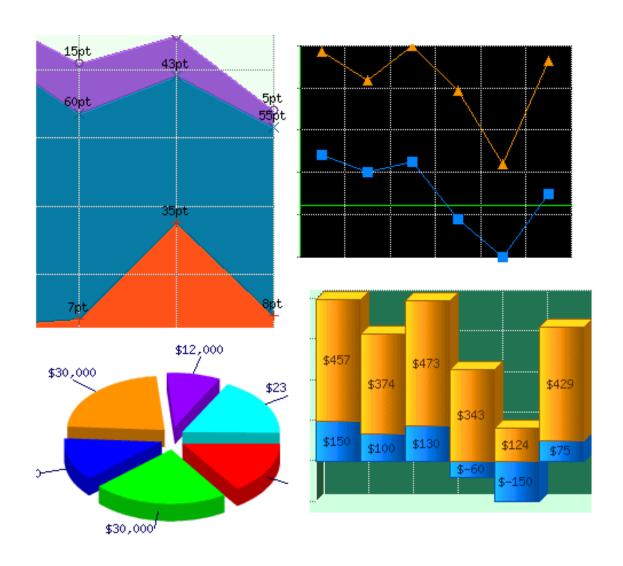


#### Announcements

- Reading:
  - Chapter 28: Graphs
  - Chapter 29: Graph Implementations

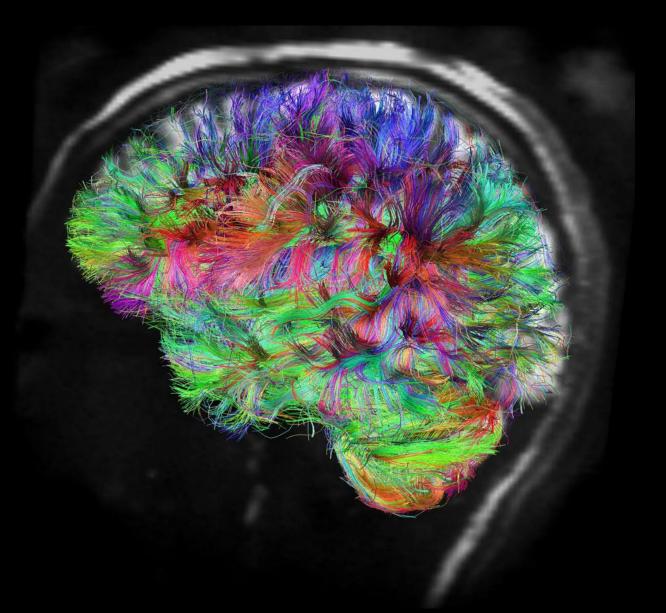
#### These aren't the graphs we're interested in



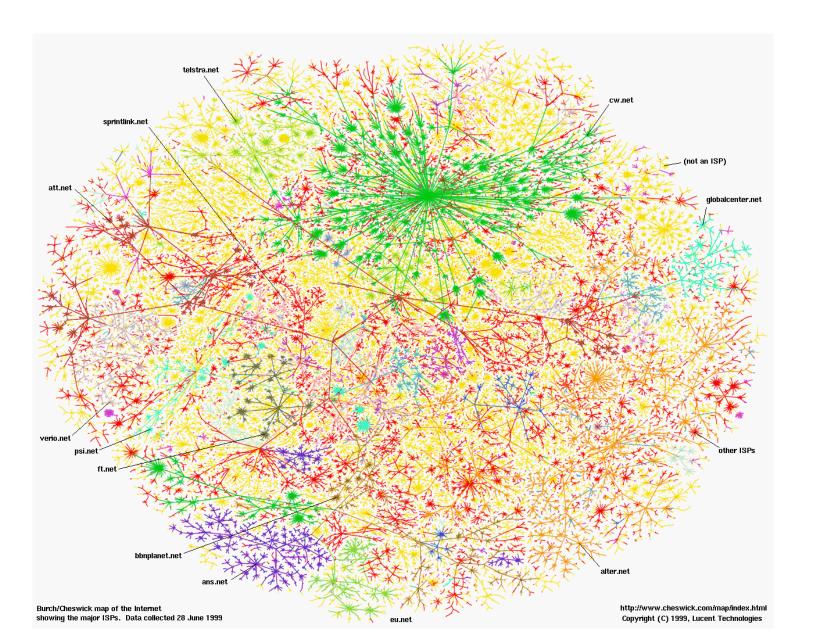
#### These aren't the graphs we're interested in



## This is

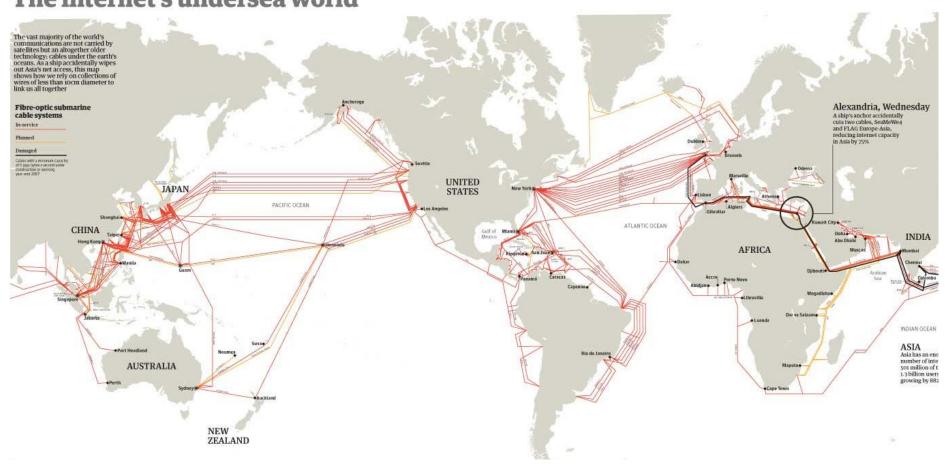


#### And so is this

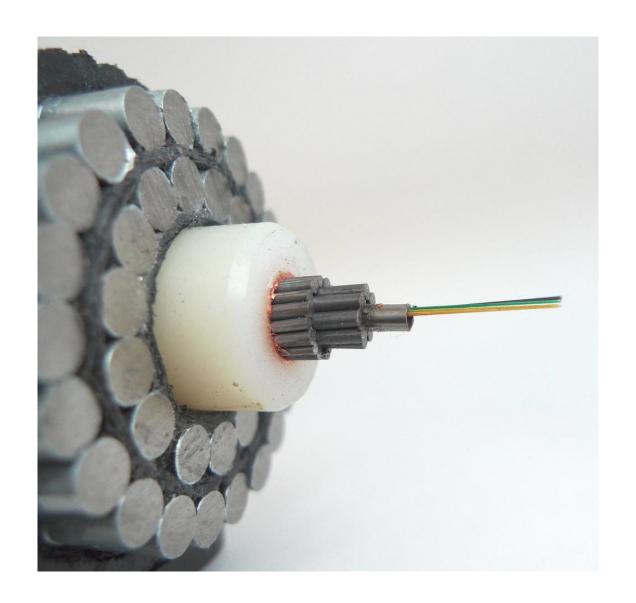


#### And this

#### The internet's undersea world



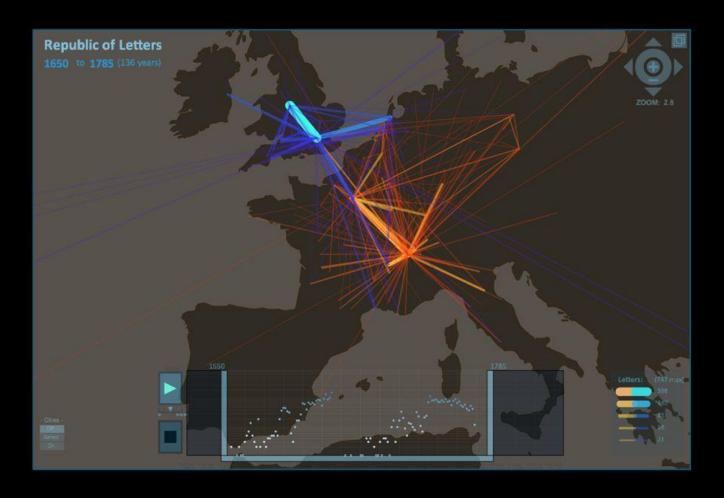
#### This carries Internet traffic across the oceans



## A social graph



## An older social graph

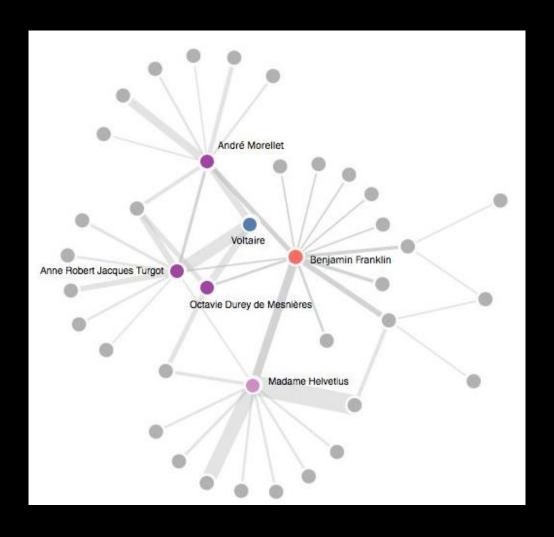


Locke's (blue) and Voltaire's (yellow) correspondence.

Only letters for which complete location information is available are shown.

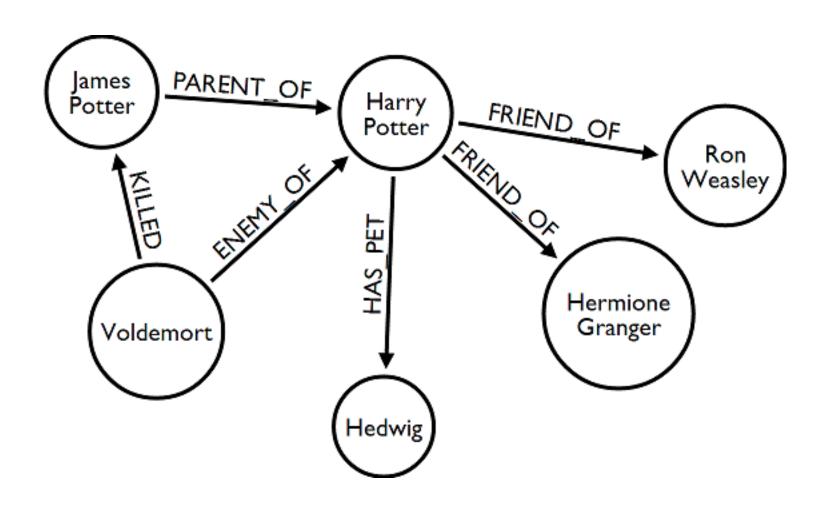
Data courtesy the Electronic Enlightenment Project, University of Oxford.

## An older social graph

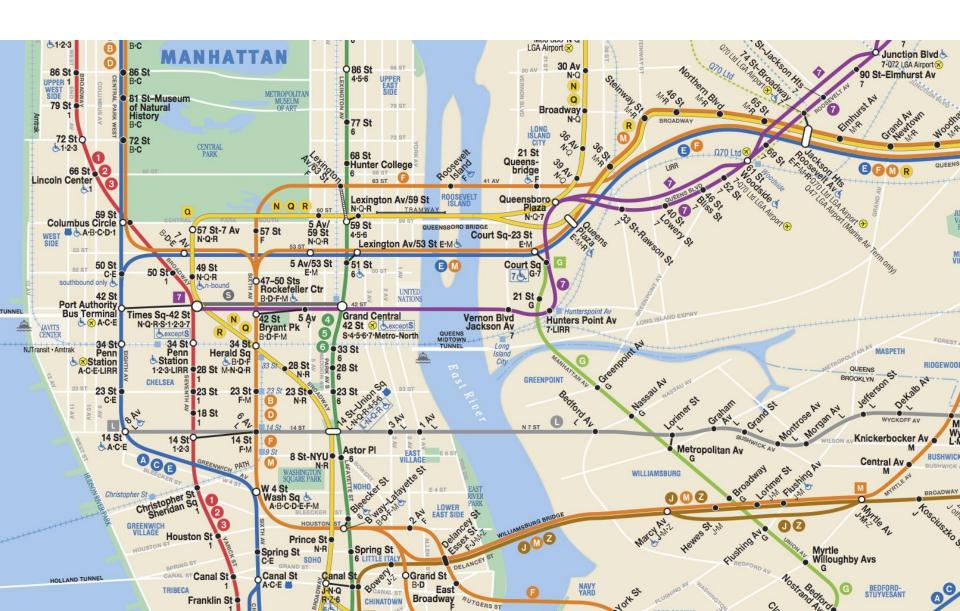


Voltaire and Benjamin Franklin

## A fictional social graph



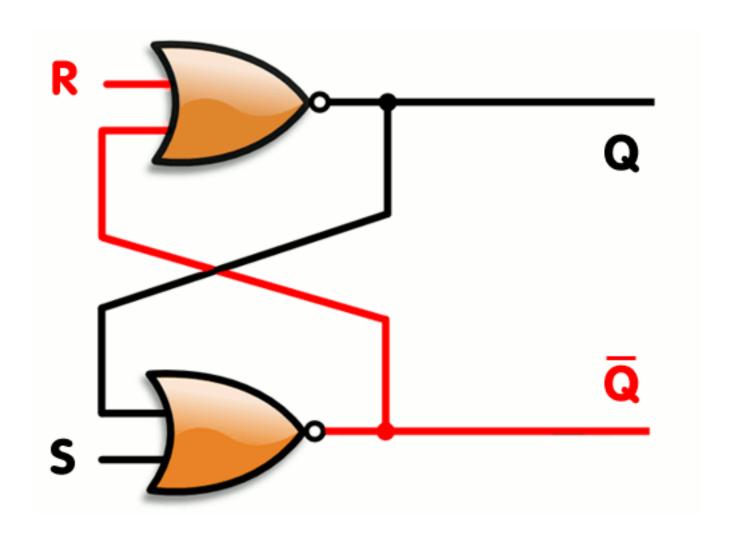
#### A transport graph



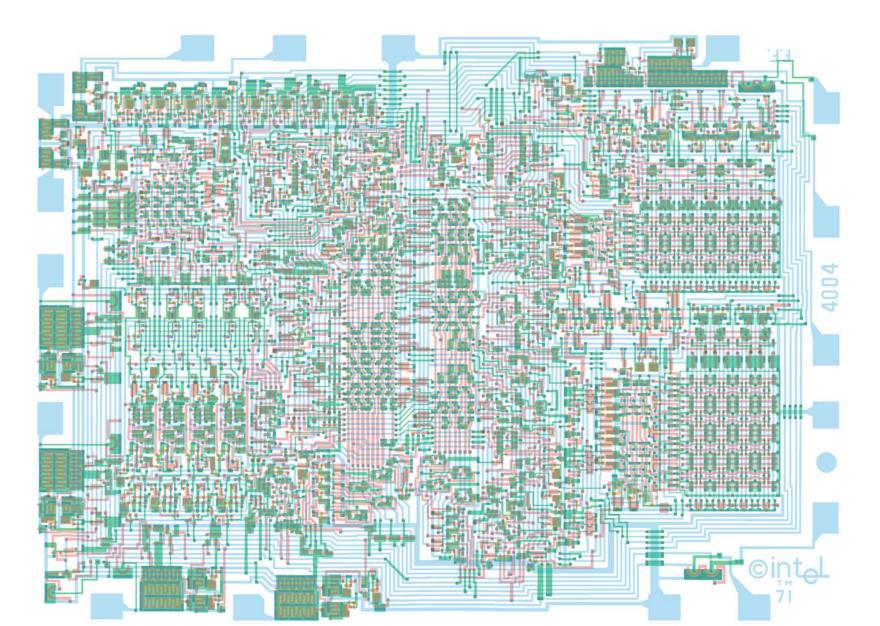
## Another transport graph



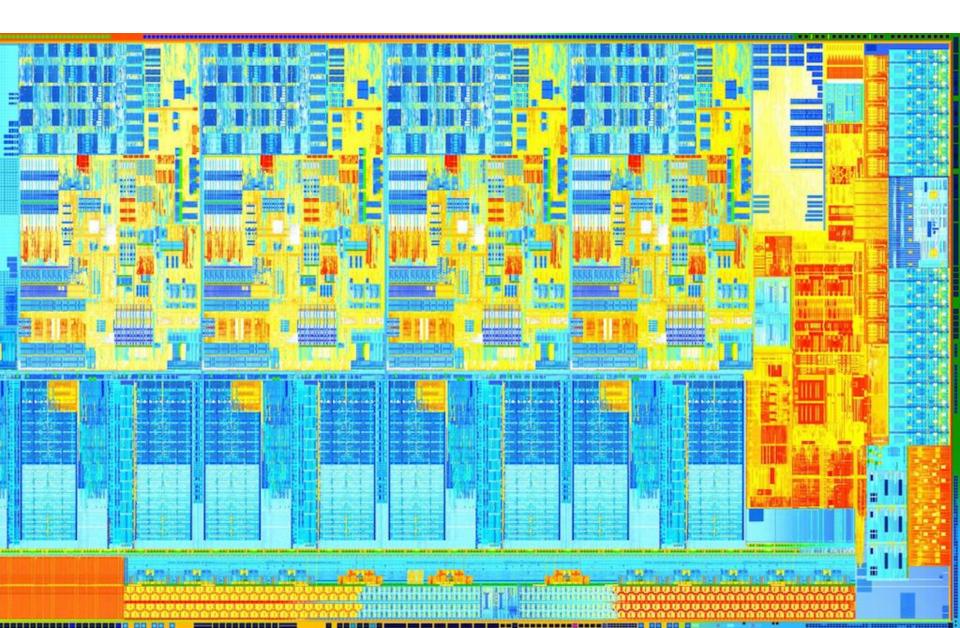
## A circuit graph (flip-flop)



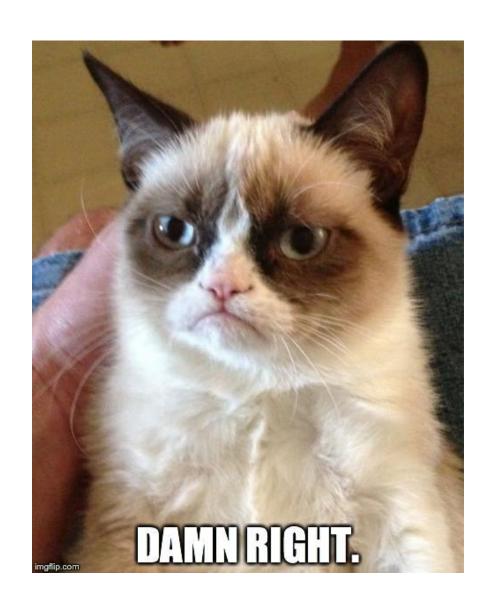
## A circuit graph (Intel 4004)



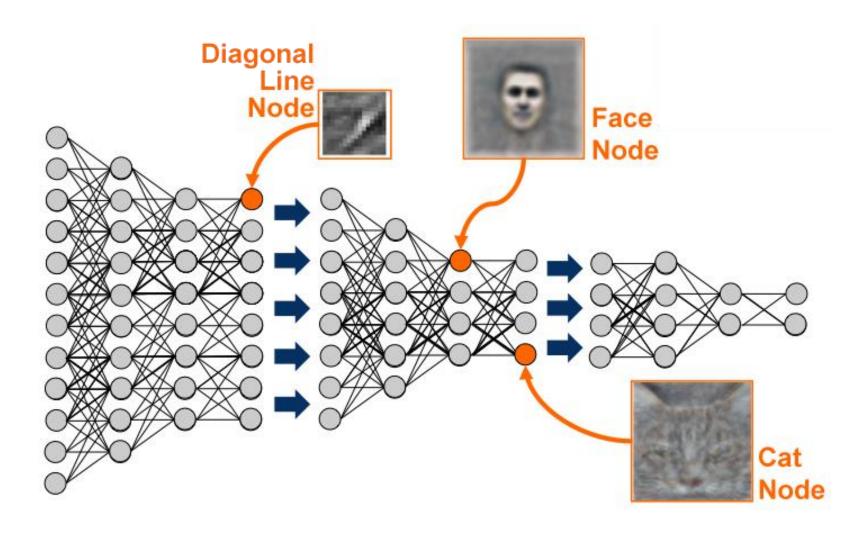
## A circuit graph (Intel Haswell)



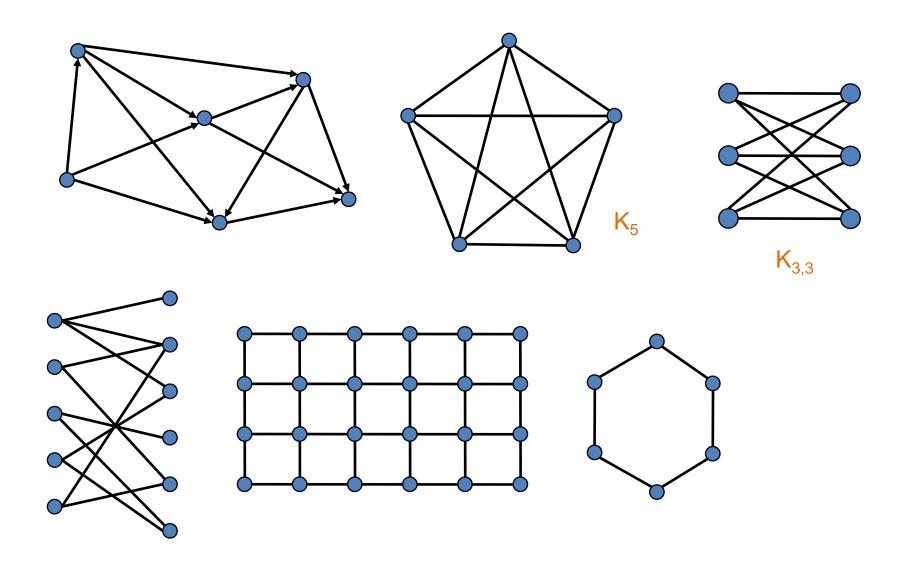
## This is not a graph, this is a cat



# This is a graph(ical model) that has learned to recognize cats

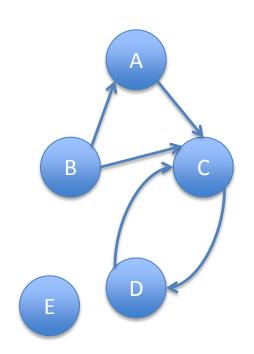


## Some abstract graphs



#### **Directed Graphs**

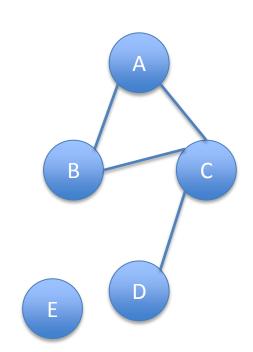
- A directed graph (digraph) is a pair (V, E) where
  - V is a (finite) set
  - E is a set of **ordered** pairs (u, v) where  $u, v \in V$ 
    - Often require  $u \neq v$  (i.e. no self-loops)
- An element of V is called a vertex or node
- An element of E is called an edge or arc
- |V| = size of V, often denoted by n
- |E| = size of E, often denoted by m



$$V = \{A, B, C, D, E\}$$
 $E = \{(A,C), (B,A), (B,C), (C,D), (D,C)\}$ 
 $|V| = 5$ 
 $|E| = 5$ 

#### **Undirected Graphs**

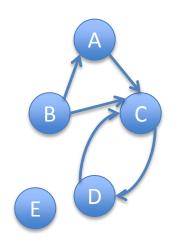
- An undirected graph is just like a directed graph!
  - ... except that E is now a set of **unordered** pairs  $\{u, v\}$  where  $u, v \in V$
- Every undirected graph can be easily converted to an equivalent directed graph via a simple transformation:
  - Replace every undirected edge with two directed edges in opposite directions
- ... but not vice versa

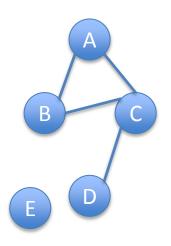


```
V = \{A, B, C, D, E\}
E = \{\{A,C\}, \{B,A\}, \{B,C\}, \{C,D\}\}
|V| = 5
|E| = 4
```

## **Graph Terminology**

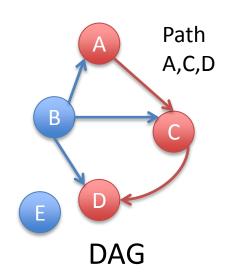
- Vertices u and v are called
  - the source and sink of the directed edge (u, v), respectively
  - the endpoints of (u, v) or  $\{u, v\}$
- Two vertices are adjacent if they are connected by an edge
- The outdegree of a vertex u in a directed graph is the number of edges for which u is the source
- The indegree of a vertex v in a directed graph is the number of edges for which v is the sink
- The degree of a vertex u in an undirected graph is the number of edges of which u is an endpoint

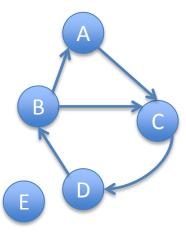




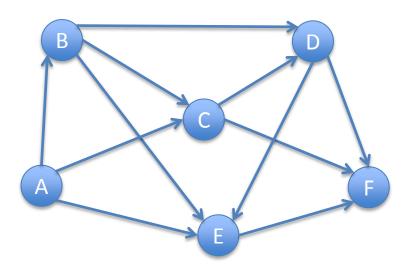
#### More Graph Terminology

- A path is a sequence  $v_0, v_1, v_2, ..., v_p$  of vertices such that for  $0 \le i < p$ ,
  - $-(v_i,v_{i+1}) \in E$  if the graph is directed
  - $\{v_i, v_{i+1}\} \in E$  if the graph is undirected
- The length of a path is its number of edges
  - In this example, the length is 2
- A path is simple if it doesn't repeat any vertices
- A cycle is a path  $v_0, v_1, v_2, ..., v_p$  such that  $v_0 = v_p$
- A cycle is simple if it does not repeat any vertices except the first and last
- A graph is acyclic if it has no cycles
- A directed acyclic graph is called a DAG

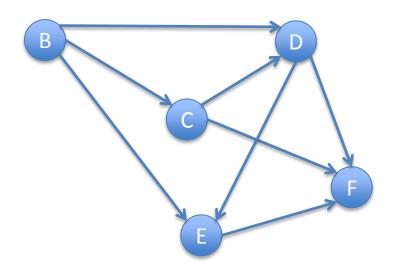




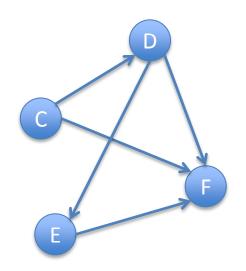
Not a DAG



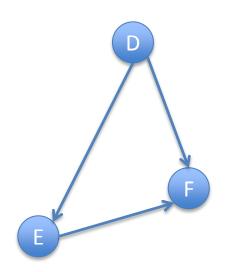
- Intuition:
  - If it's a DAG, there must be a vertex with indegree zero
- This idea leads to an algorithm
  - A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears



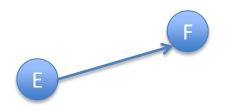
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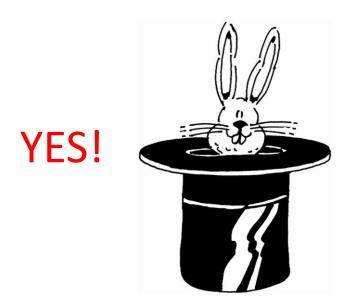
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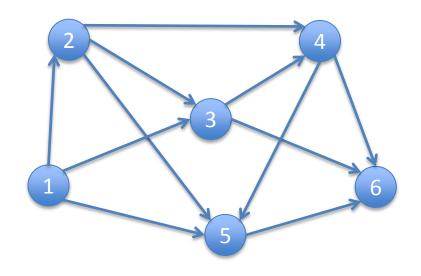
F

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  - If it's a DAG, there must be a vertex with indegree zero
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  - A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears

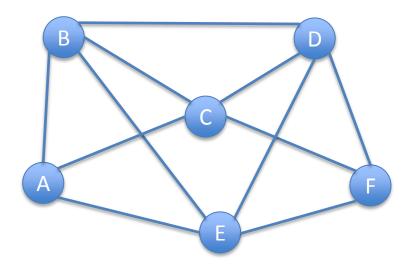
#### **Topological Sort**



- We just computed a topological sort of the DAG
  - This is a numbering of the vertices such that all edges go from lower- to higher-numbered vertices
  - Useful in job scheduling with precedence constraints

## **Graph Coloring**

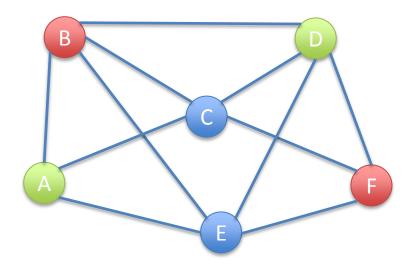
 A coloring of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



How many colors are needed to color this graph?

#### **Graph Coloring**

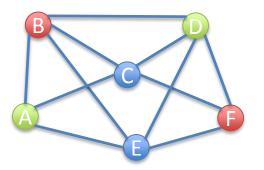
 A coloring of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



How many colors are needed to color this graph?

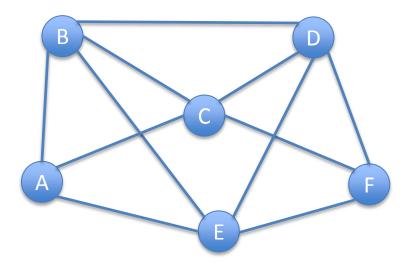
## An Application of Coloring

- Vertices are tasks
- Edge (u, v) is present if tasks u and v each require access to the same shared resource, and thus cannot execute simultaneously
- Colors are time slots to schedule the tasks
- Minimum number of colors needed to color the graph = minimum number of time slots required



#### Planarity

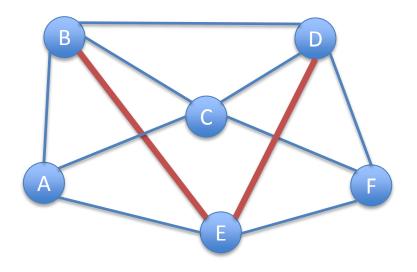
 A graph is planar if it can be drawn in the plane without any edges crossing



• Is this graph planar?

#### Planarity

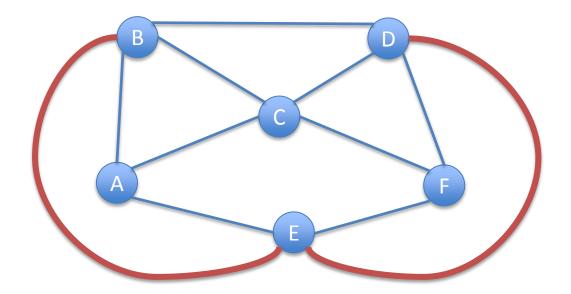
 A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?
  - Yes!

## **Planarity**

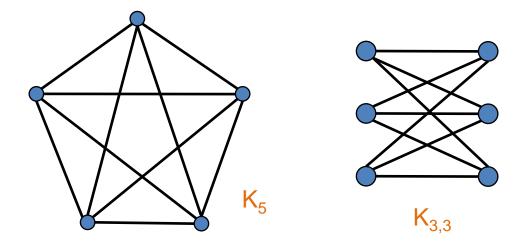
 A graph is planar if it <u>can</u> be drawn in the plane without any edges crossing



- Is this graph planar?
  - Yes!

#### **Detecting Planarity**

#### **Kuratowski's Theorem:**



• A graph is planar if and only if it does not contain a copy of  $K_5$  or  $K_{3,3}$  (possibly with other nodes along the edges shown)

#### Four-Color Theorem:

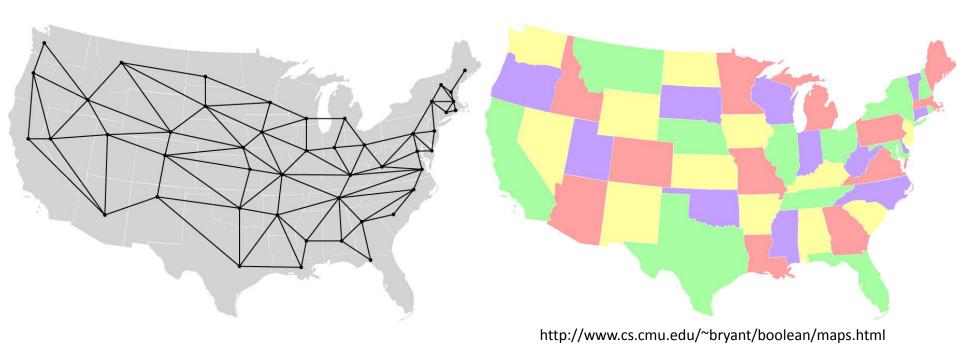
# Every planar graph is 4-colorable

[Appel & Haken, 1976]

(Every map defines a planar graph – countries are vertices, and two adjacent countries define an edge)



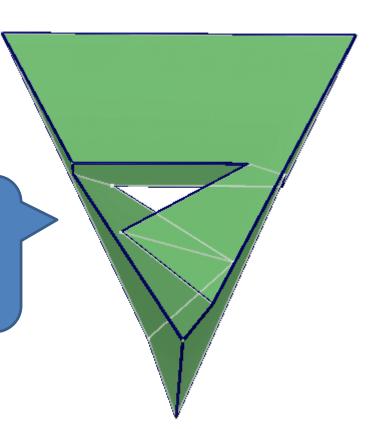
# Another 4-colored planar graph



## Szilassi polyhedron

Torus (donut)
maps are always
7-colorable

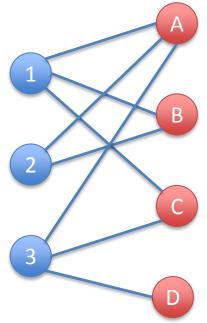
Has 7 hexagonal faces, all of which border every other face



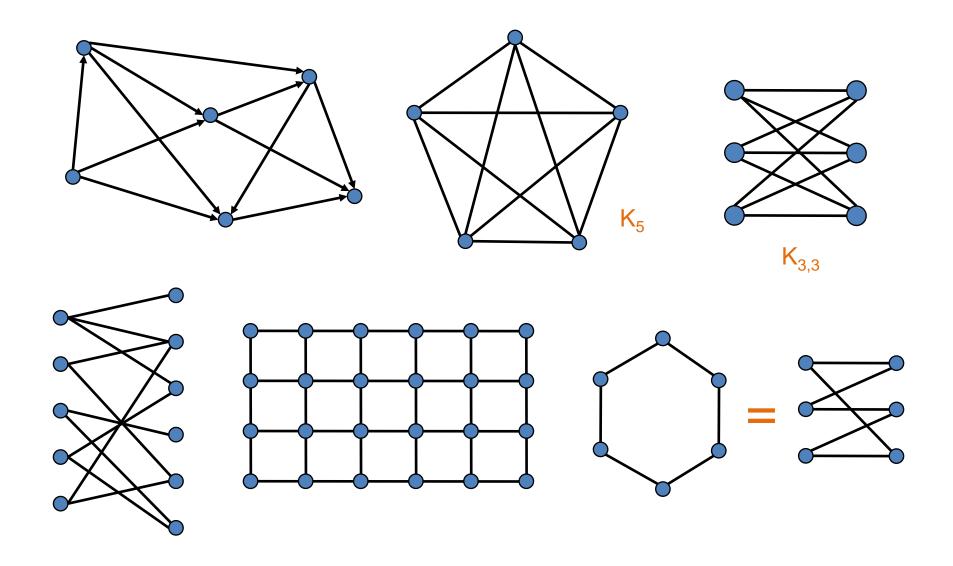
#### Bipartite Graphs

 A directed or undirected graph is bipartite if the vertices can be partitioned into two sets such that no edge connects two vertices in the same set

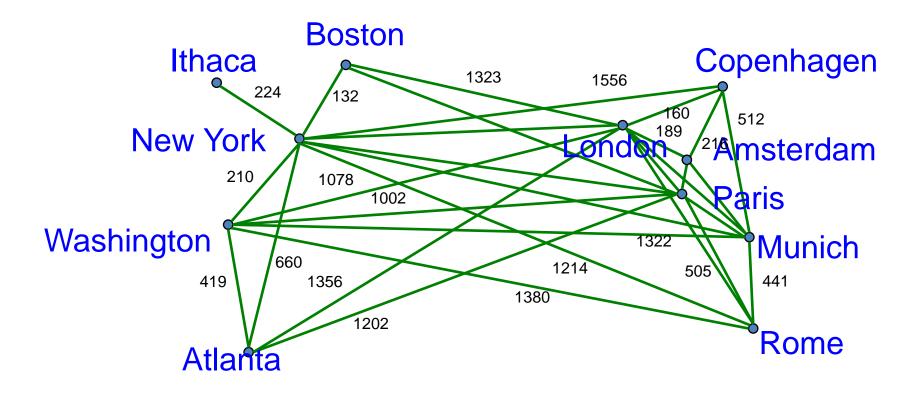
- The following are equivalent
  - G is bipartite
  - − G is 2-colorable
  - -G has no cycles of odd length



# Some abstract graphs

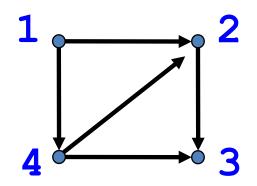


## **Traveling Salesperson**

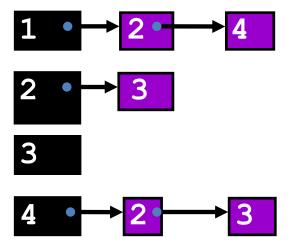


Find a path of minimum distance that visits every city

#### Representations of Graphs



**Adjacency List** 



**Adjacency Matrix** 

1234101201030004011

#### Adjacency Matrix or Adjacency List?

```
- n = number of vertices

- m = number of edges

- d(u) = degree of u = no. of edges leaving u

• Adjacency Matrix

- Uses space O(n^2)

1 2 3 4

1 0 1 0 1

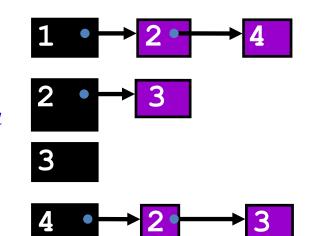
2 0 0 1 0

4 0 1 1 0
```

- Enumerate all edges in time  $O(n^2)$
- Answer "Is there an edge from u to v?" in O(1) time
- Better for dense graphs (lots of edges)

#### Adjacency Matrix or Adjacency List?

- -n = number of vertices
- -m = number of edges
- -d(u) = degree of u = no. edges leaving u
- Adjacency List
  - Uses space O(m + n)
  - Enumerate all edges in time O(m + n)
  - Answer "Is there an edge from u to v?" in O(d(u)) time
  - Better for sparse graphs (fewer edges)



#### **Graph Algorithms**

- Search
  - Depth-first search
  - Breadth-first search
- Shortest paths
  - Dijkstra's algorithm
- Minimum spanning trees
  - Prim's algorithm
  - Kruskal's algorithm