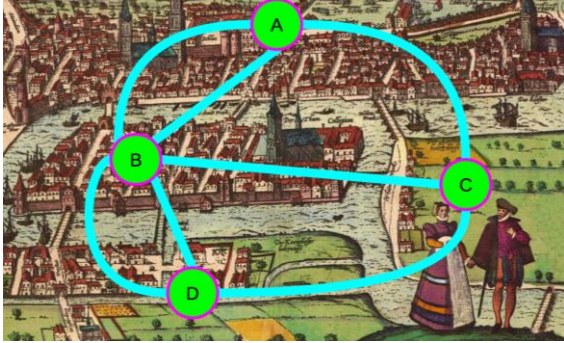


# Graphs - I

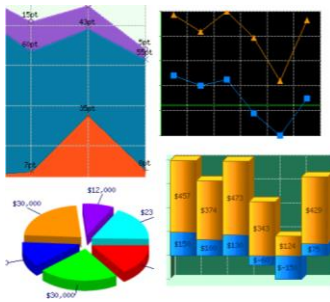
CS 2110, Spring 2016



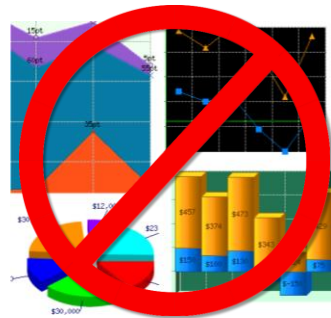
## Announcements

- Reading:
  - Chapter 28: Graphs
  - Chapter 29: Graph Implementations

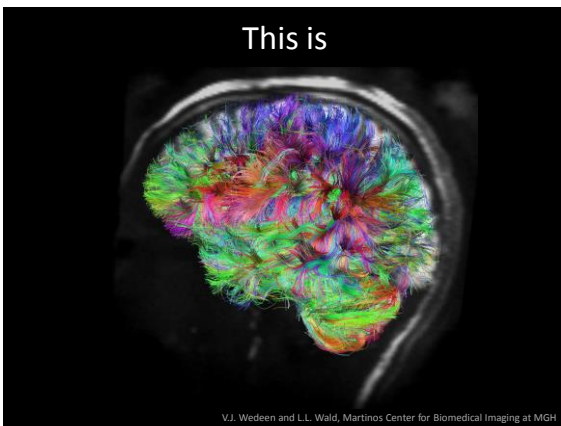
These *aren't* the graphs we're interested in



These *aren't* the graphs we're interested in

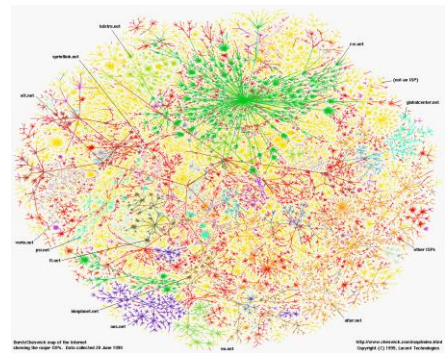


This is



V.J. Wedeen and L.L. Wald, Martinos Center for Biomedical Imaging at MGH

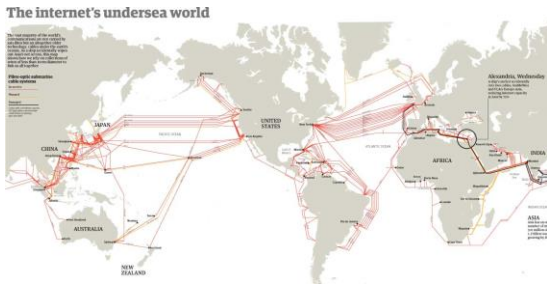
And so is this



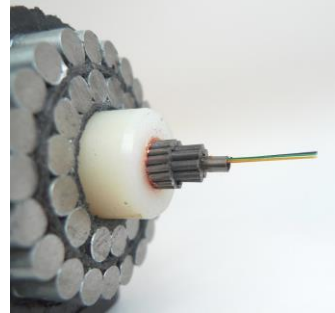
Identification map of the Internet  
Showing the major ISPs. Data collected 01 June 1999

Map of the human brain  
Copyright © 1999, Lucid Technology

And this



This carries Internet traffic across the oceans



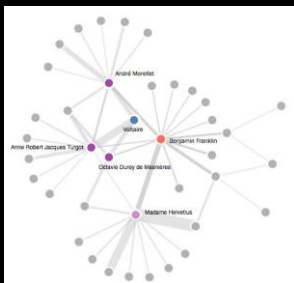
A social graph



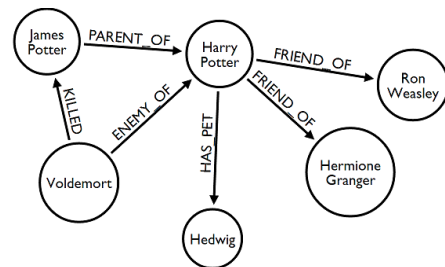
An older social graph



An older social graph



A fictional social graph



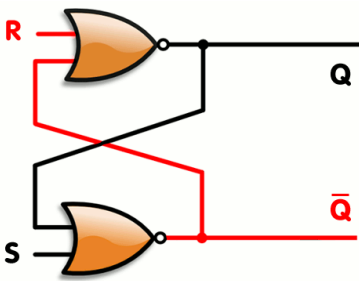
A transport graph



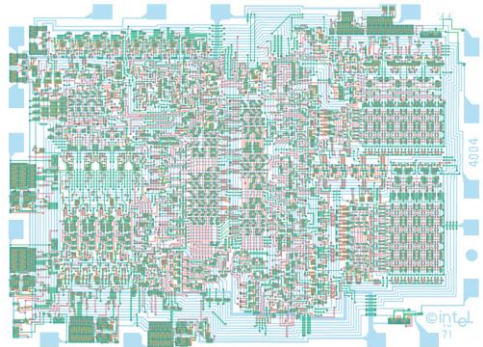
Another transport graph



A circuit graph (flip-flop)



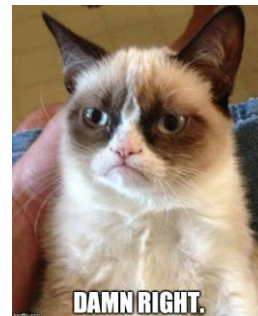
A circuit graph (Intel 4004)



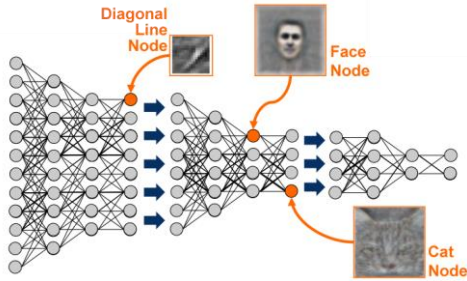
A circuit graph (Intel Haswell)



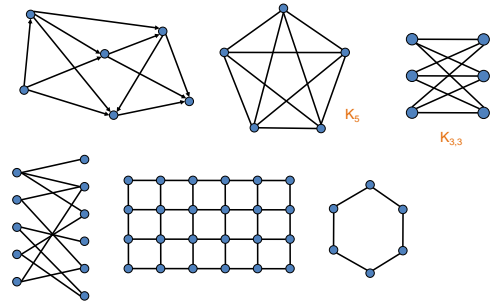
This is not a graph, this is a cat



This is a graph(ical model) that has learned to recognize cats

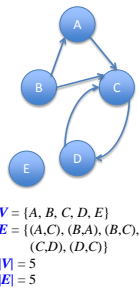


Some abstract graphs



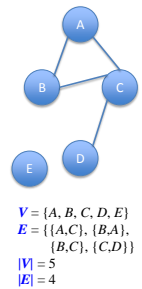
## Directed Graphs

- A **directed graph (digraph)** is a pair  $(V, E)$  where
  - $V$  is a (finite) set
  - $E$  is a set of **ordered** pairs  $(u, v)$  where  $u, v \in V$ 
    - Often require  $u \neq v$  (i.e. no self-loops)
- An element of  $V$  is called a **vertex** or **node**
- An element of  $E$  is called an **edge** or **arc**
- $|V|$  = size of  $V$ , often denoted by  $n$
- $|E|$  = size of  $E$ , often denoted by  $m$



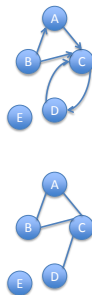
## Undirected Graphs

- An **undirected graph** is just like a directed graph!
  - ... except that  $E$  is now a set of **unordered** pairs  $\{u, v\}$  where  $u, v \in V$
- Every undirected graph can be easily converted to an equivalent directed graph via a simple transformation:
  - Replace every undirected edge with two directed edges in opposite directions
- ... but not vice versa



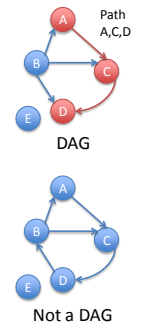
## Graph Terminology

- Vertices  $u$  and  $v$  are called
  - the **source** and **sink** of the directed edge  $(u, v)$ , respectively
  - the **endpoints** of  $(u, v)$  or  $\{u, v\}$
- Two vertices are **adjacent** if they are connected by an edge
- The **outdegree** of a vertex  $u$  in a directed graph is the number of edges for which  $u$  is the source
- The **indegree** of a vertex  $v$  in a directed graph is the number of edges for which  $v$  is the sink
- The **degree** of a vertex  $u$  in an undirected graph is the number of edges of which  $u$  is an endpoint

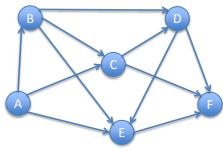


## More Graph Terminology

- A **path** is a sequence  $v_0, v_1, v_2, \dots, v_p$  of vertices such that for  $0 \leq i < p$ ,
  - $(v_i, v_{i+1}) \in E$  if the graph is directed
  - $\{v_i, v_{i+1}\} \in E$  if the graph is undirected
- The **length of a path** is its number of edges
  - In this example, the length is 2
- A path is **simple** if it doesn't repeat any vertices
- A **cycle** is a path  $v_0, v_1, v_2, \dots, v_p$  such that  $v_0 = v_p$
- A cycle is **simple** if it does not repeat any vertices except the first and last
- A graph is **acyclic** if it has no cycles
- A **directed acyclic graph** is called a **DAG**

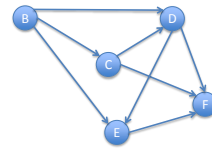


Is this a DAG?



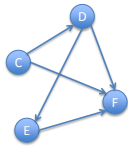
- **Intuition:**
  - If it's a DAG, there must be a vertex with indegree zero
- This idea leads to an *algorithm*
  - A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears

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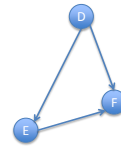
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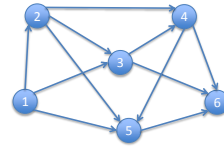


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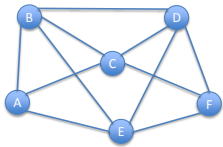
## Topological Sort



- We just computed a **topological sort** of the DAG
  - This is a numbering of the vertices such that all edges go from lower- to higher-numbered vertices
  - Useful in job scheduling with precedence constraints

## Graph Coloring

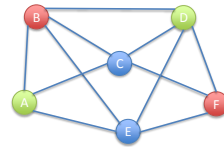
- A **coloring** of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



- How many colors are needed to color this graph?

## Graph Coloring

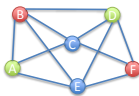
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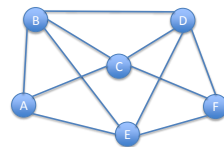
## An Application of Coloring

- **Vertices** are **tasks**
- **Edge**  $(u, v)$  is present if tasks  $u$  and  $v$  each require access to the **same shared resource**, and thus cannot execute simultaneously
- **Colors** are **time slots** to schedule the tasks
- Minimum number of colors needed to color the graph = minimum number of time slots required



## Planarity

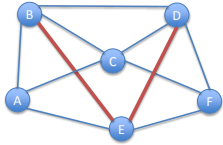
- A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?

## Planarity

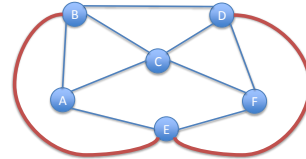
- A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?  
– Yes!

## Planarity

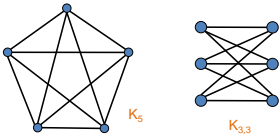
- A graph is planar if it **can** be drawn in the plane without any edges crossing



- Is this graph planar?  
– Yes!

## Detecting Planarity

Kuratowski's Theorem:



- A graph is planar if and only if it does not contain a copy of  $K_5$  or  $K_{3,3}$  (possibly with other nodes along the edges shown)

Four-Color Theorem:

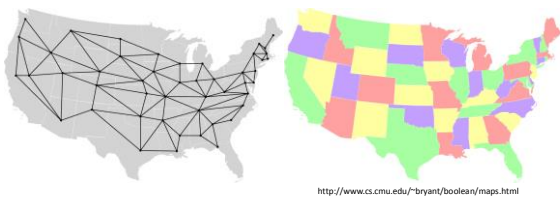
Every planar graph is 4-colorable

[Appel & Haken, 1976]

(Every map defines a planar graph – countries are vertices, and two adjacent countries define an edge)



## Another 4-colored planar graph

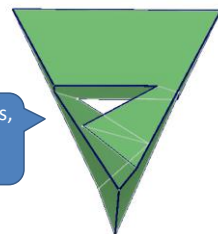


<http://www.cs.cmu.edu/~bryant/boolean/maps.html>

## Szilassi polyhedron

Torus (donut) maps are always 7-colorable

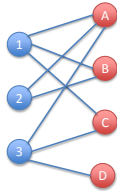
Has 7 hexagonal faces, all of which border every other face



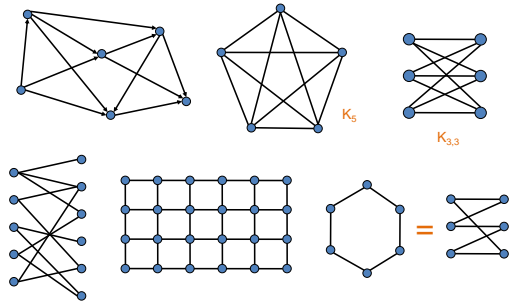
## Bipartite Graphs

- A directed or undirected graph is **bipartite** if the vertices can be partitioned into two sets such that no edge connects two vertices in the same set

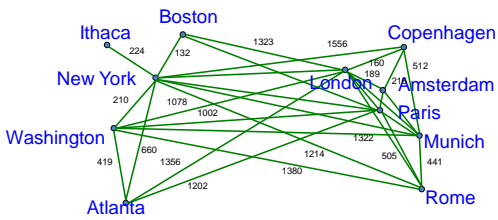
- The following are equivalent
  - $G$  is bipartite
  - $G$  is 2-colorable
  - $G$  has no cycles of odd length



## Some abstract graphs

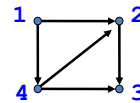


## Traveling Salesperson

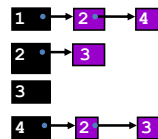


Find a path of minimum distance that visits every city

## Representations of Graphs



Adjacency List



Adjacency Matrix

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

## Adjacency Matrix or Adjacency List?

- $n$  = number of vertices
- $m$  = number of edges
- $d(u)$  = degree of  $u$  = no. of edges leaving  $u$
- Adjacency Matrix
  - Uses space  $O(n^2)$
  - Enumerate all edges in time  $O(n^2)$
  - Answer "Is there an edge from  $u$  to  $v$ ?" in  $O(1)$  time
  - Better for dense graphs (lots of edges)

## Adjacency Matrix or Adjacency List?

- $n$  = number of vertices
- $m$  = number of edges
- $d(u)$  = degree of  $u$  = no. of edges leaving  $u$
- Adjacency List
  - Uses space  $O(m+n)$
  - Enumerate all edges in time  $O(m+n)$
  - Answer "Is there an edge from  $u$  to  $v$ ?" in  $O(d(u))$  time
  - Better for sparse graphs (fewer edges)



## Graph Algorithms

- Search
  - Depth-first search
  - Breadth-first search
- Shortest paths
  - Dijkstra's algorithm
- Minimum spanning trees
  - Prim's algorithm
  - Kruskal's algorithm