

Graph Algorithms

- **Search**
 - Depth-first search
 - Breadth-first search
- **Shortest paths**
 - Dijkstra's algorithm
- **Minimum spanning trees**
 - Prim's algorithm
 - Kruskal's algorithm

Representations of Graphs

```

graph TD
    1 --- 2
    1 --- 4
    2 --- 3
    3 --- 4
    4 --- 2
  
```

Adjacency List

```

1 → 2 → 4
2 → 3
3
4 → 2 → 3
  
```

Adjacency Matrix

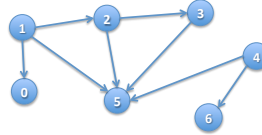
	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

Adjacency Matrix or Adjacency List?

- **Definitions:**
 - n = number of vertices
 - m = number of edges
 - $d(u)$ = degree of u = number of edges leaving u
- **Adjacency Matrix**
 - Uses space $O(n^2)$
 - Can iterate over all edges in time $O(n^2)$
 - Can answer “Is there an edge from u to v ?” in $O(1)$ time
 - Better for dense graphs (lots of edges)
- **Adjacency List**
 - Uses space $O(m + n)$
 - Can iterate over all edges in time $O(m + n)$
 - Can answer “Is there an edge from u to v ?” in $O(d(u))$ time
 - Better for sparse graphs (fewer edges)

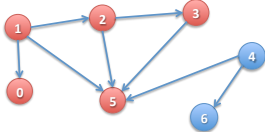
Depth-First Search

- Given a graph and one of its nodes u
(say node 1 below)



Depth-First Search

- Given a graph and one of its nodes u
(say node 1 below)
- We want to “visit” each node reachable from u
(nodes 1, 0, 2, 3, 5)



There are many paths to some nodes.

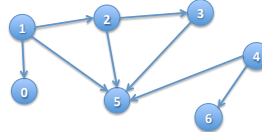
How do we visit all nodes efficiently, without doing extra work?

Depth-First Search

`boolean[] visited;`

- Node u is visited means: `visited[u]` is true
- To visit u means to: set `visited[u]` to true
- Node v is REACHABLE from node u if there is a path (u, \dots, v) in which all nodes of the path are unvisited.

Suppose all nodes are unvisited.



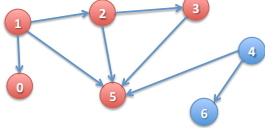
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Nodes REACHABLE from node 1:
`{1, 0, 2, 3, 5}`



Depth-First Search

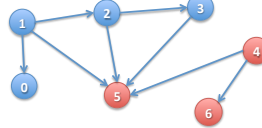
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Suppose all nodes are unvisited.

Nodes REACHABLE from node 1:
`{1, 0, 2, 3, 5}`

Nodes REACHABLE from 4: `{4, 5, 6}`



Depth-First Search

`boolean[] visited;`

- Node *u* is visited means: `visited[u]` is true
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- Node *v* is REACHABLE from node *u* if there is a path (*u*, ..., *v*) in which all nodes of the path are unvisited.

Green: visited
Blue: unvisited



Depth-First Search

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Nodes REACHABLE from node 1: {1, 0, 5}



Depth-First Search

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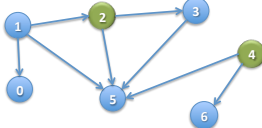
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Green: visited
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Nodes REACHABLE from node 1: {1, 0, 5}

Nodes REACHABLE from 4: none

Not even 4 itself, because it's already been visited!



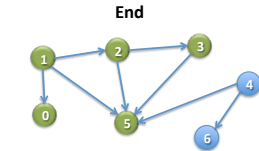
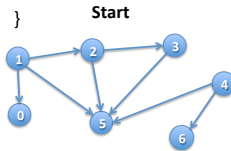
Depth-First Search

`/** Node u is unvisited. Visit all nodes that are REACHABLE from u. */`

`public static void dfs(int u) {`

Let *u* be 1

The nodes REACHABLE from 1 are 1, 0, 2, 3, 5



Depth-First Search

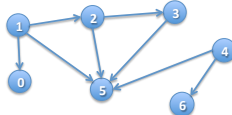
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Depth-First Search

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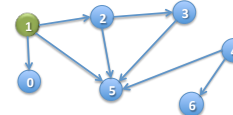
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Depth-First Search

/** Node u is unvisited. Visit all nodes that are REACHABLE from u. */

```
public static void dfs(int u) {
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```

```
}
```



Let u be 1 (visited)

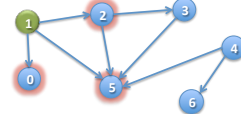
The nodes to be visited are 0, 2, 3, 5

Depth-First Search

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public static void dfs(int u) {
    visited[u] = true;
    for all edges (u, v) leaving u:
        if v is unvisited then dfs(v);
```

```
}
```



Let u be 1 (visited)

The nodes to be visited are 0, 2, 3, 5

Have to do DFS on all unvisited neighbors of u!

Depth-First Search

/** Node u is unvisited. Visit all nodes that are REACHABLE from u. */

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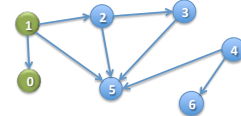
Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1 ...

Depth-First Search

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```
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```



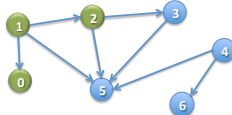
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```

```
}
```



Suppose the for loop visits neighbors in numerical order. Then **dfs(1)** visits the nodes in this order: 1, 0, 2 ...

Depth-First Search

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Depth-First Search

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```

Suppose n nodes are REACHABLE along e edges (in total). What is

- Worst-case execution?
- Worst-case space?

Depth-First Search

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public static void dfs(int u) {
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}
```

That's all there is to basic DFS. You may have to change it to fit a particular situation.

If you don't have this spec and you do something different, it's probably wrong.

Example: Use different way (other than array visited) to know whether a node has been visited

Example: We really haven't said what data structures are used to implement the graph

Depth-First Search in OO fashion

```
public class Node {
    boolean visited;
    List<Node> neighbors;
}
```

Each node of the graph is an object of type Node

/** This node is unvisited. Visit all nodes REACHABLE from this node */

```
public void dfs() {
    visited = true;
    for (Node n: neighbors) {
        if (!n.visited) n.dfs();
    }
}
```

No need for a parameter. The object is the node.

Depth-First Search written iteratively

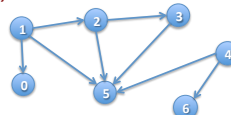
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```
public static void dfs(int u) {
    Stack s = (u); // Not Java!
    // inv: all nodes that have to be visited are
    // REACHABLE from some node in s
    while (s is not empty) {
        u = s.pop(); // Remove top stack node, put in u
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
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1
Stack s

Depth-First Search written iteratively

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```

Call dfs(1) Iteration 0



1
Stack s

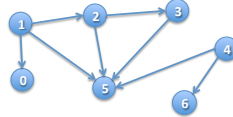
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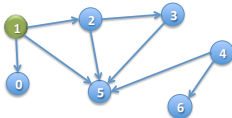
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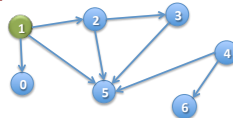
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```

Call dfs(1) Iteration 0



0
2
5
Stack s

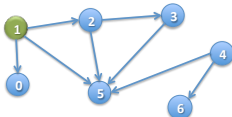
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```

Call dfs(1) Iteration 1



0
2
5
Stack s

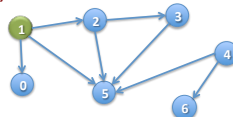
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```

Call dfs(1) Iteration 1



2
5
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        }
    }
}

```

Call dfs(1) Iteration 2



2
5
Stack s

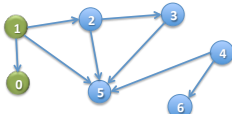
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Call dfs(1) Iteration 2



5
Stack s

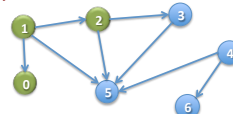
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        }
    }
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Call dfs(1) Iteration 2



5
Stack s

Depth-First Search written iteratively

```

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    Stack s = (u);
    while (s is not empty) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                s.push(v);
        }
    }
}

```

Call dfs(1) Iteration 2

Yes, 5 is put on the stack twice, once for each edge to it. It will be visited only once.



3
5
5
Stack s

Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q = (u); // Not Java!
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    while (q is not empty) {
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            for each edge (u, v) leaving u:
                q.append(v); // Add to end of queue
        }
    }
}

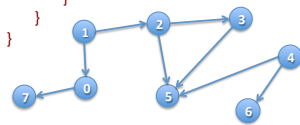
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}
```

Call bfs(1)



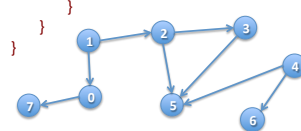
1
Queue q

Breadth-First Search

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            for each edge (u, v) leaving u:
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        }
    }
}
```

Call bfs(1) Iteration 0



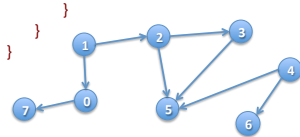
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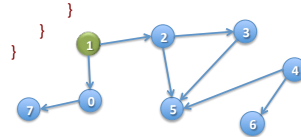
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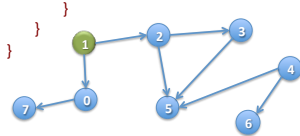
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Call bfs(1) Iteration 0



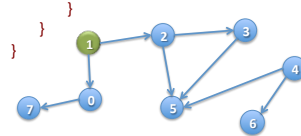
0 2
Queue q

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```

Call bfs(1) Iteration 1



0 2
Queue q

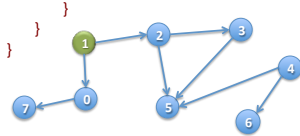
Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 1



2
Queue q

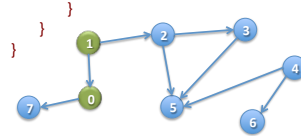
Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 1



2
Queue q

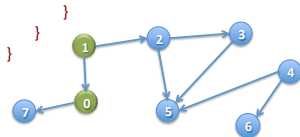
Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 1



2 7
Queue q

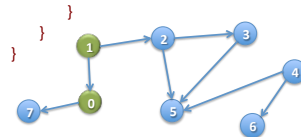
Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 2



2 7
Queue q

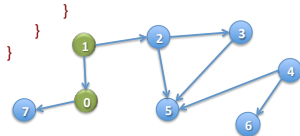
Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 2



7
Queue q

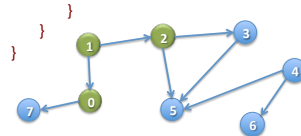
Breadth-First Search

```

/** Node u is unvisited. Visit all nodes REACHABLE from u. */
public static void bfs(int u) {
    Queue q= (u);
    while q is not empty) {
        u= q.popFirst();
        if (u has not been visited) {
            visit u;
            for each edge (u, v) leaving u:
                q.append(v);
        }
    }
}

```

Call bfs(1) Iteration 2



7
Queue q

Breadth-First Search

/** Node u is unvisited. Visit all nodes REACHABLE from u. */

```
public static void bfs(int u) {  
    Queue q= (u);  
    while q is not empty) {  
        u= q.popFirst();  
        if (u has not been visited) {  
            visit u;  
            for each edge (u, v) leaving u:  
                q.append(v);  
        }  
    }  
}
```

Call bfs(1) Iteration 2

Breadth first:
(1) Node u
(2) All nodes 1 edge from u
(3) All nodes 2 edges from u
(4) All nodes 3 edges from u
...



7 3 5
Queue q