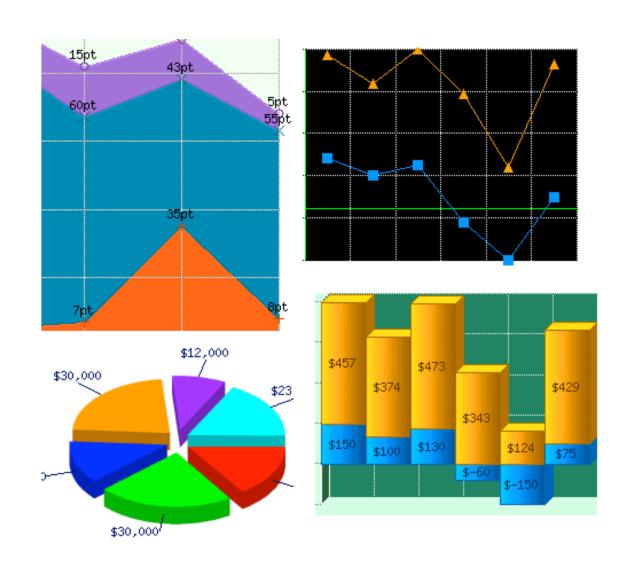


## Readings

Chapter 28: Graphs

Chapter 29: Graph Implementations

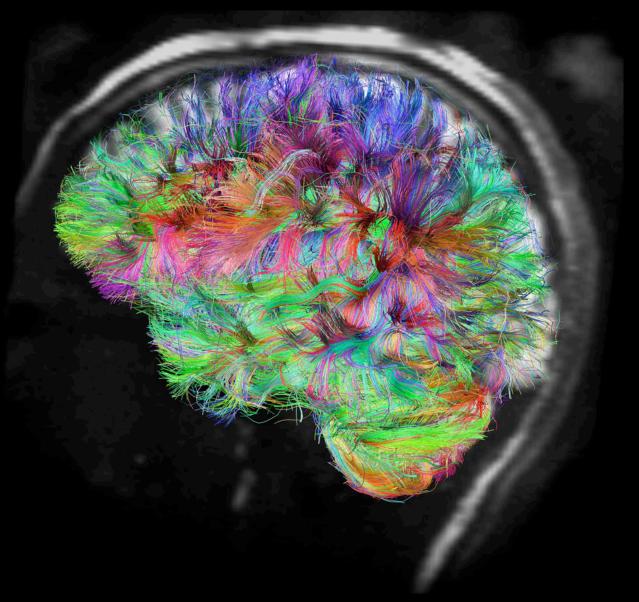
#### These aren't the graphs we're interested in



#### These aren't the graphs we're interested in

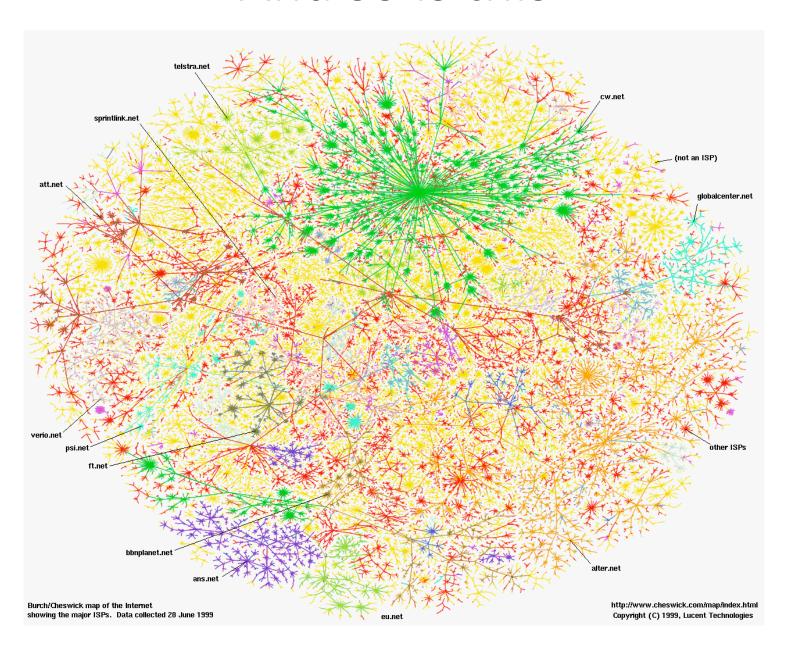


# This is



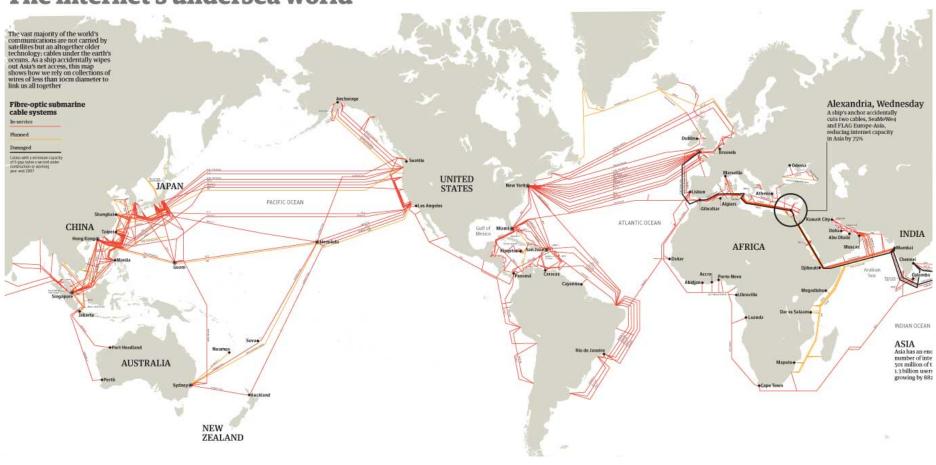
V.J. Wedeen and L.L. Wald, Martinos Center for Biomedical Imaging at MGH

#### And so is this

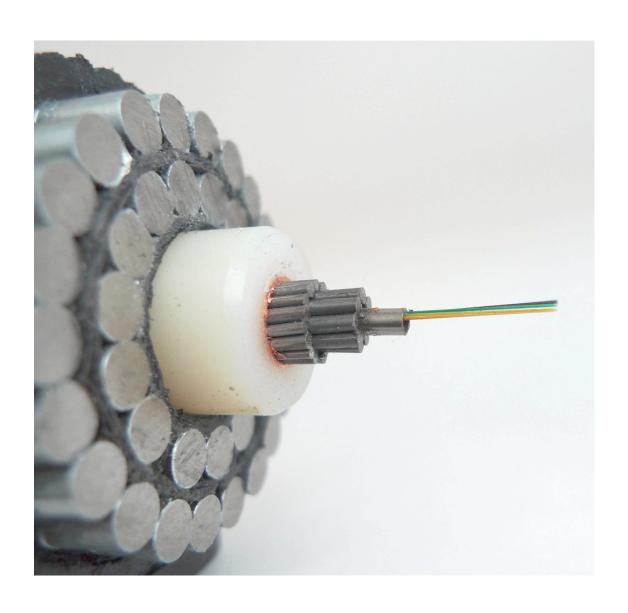


#### And this

#### The internet's undersea world



#### This carries Internet traffic across the oceans



# A social graph



# An older social graph

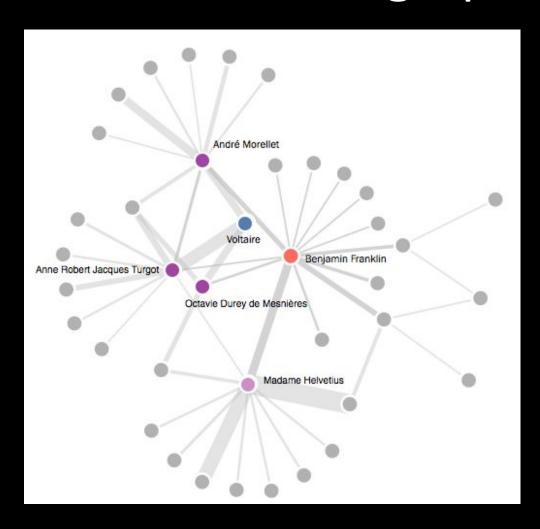


Locke's (blue) and Voltaire's (yellow) correspondence.

Only letters for which complete location information is available are shown.

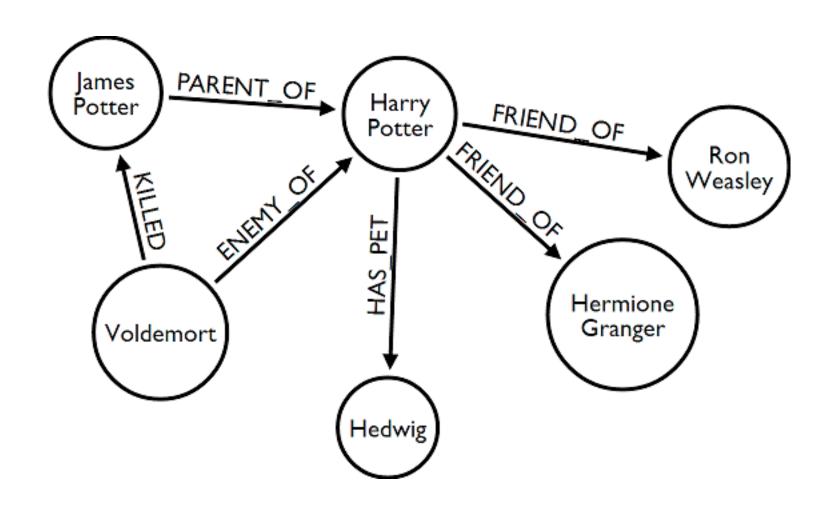
Data courtesy the Electronic Enlightenment Project, University of Oxford.

# An older social graph

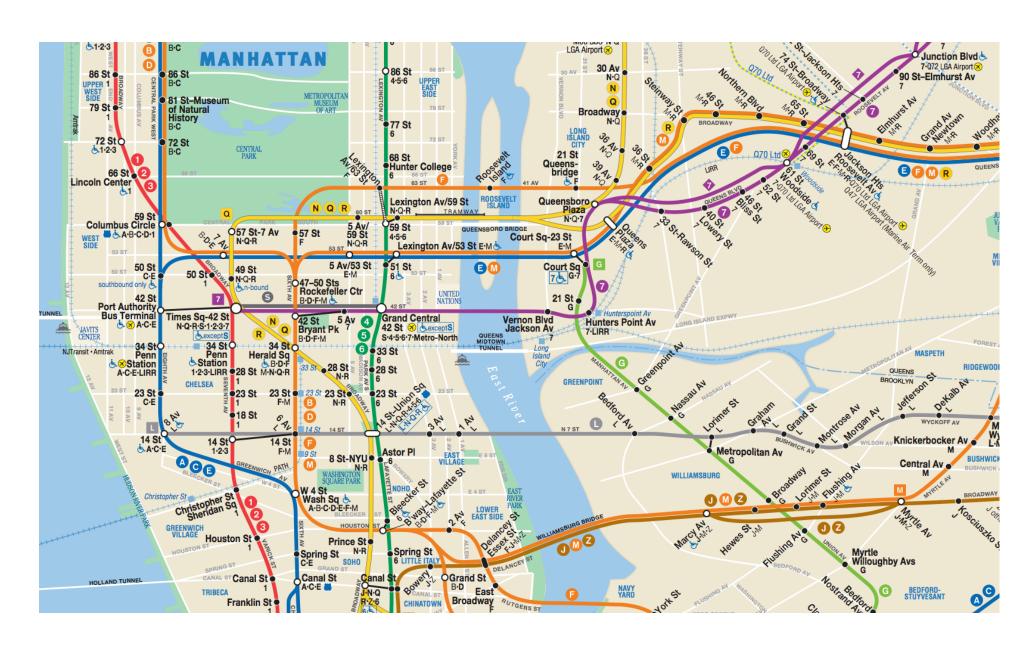


Voltaire and Benjamin Franklin

## A fictional social graph



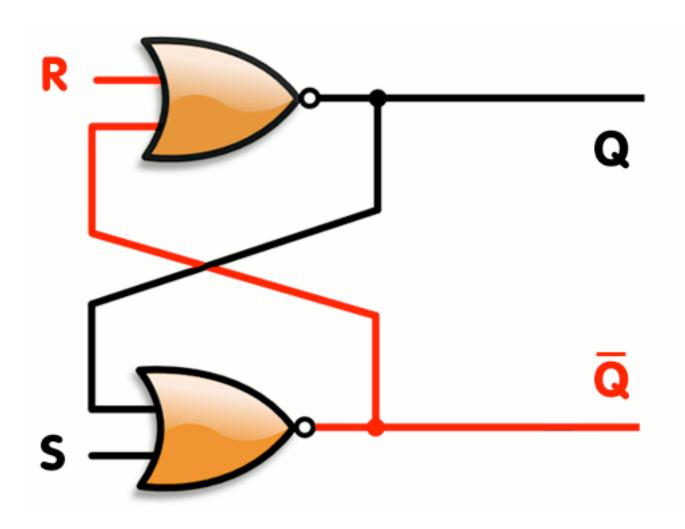
## A transport graph



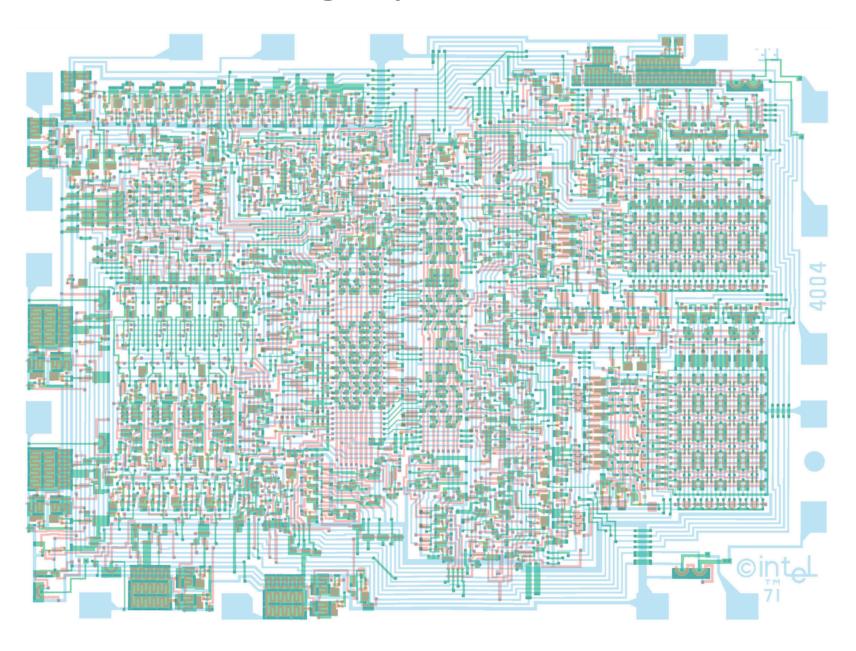
# Another transport graph



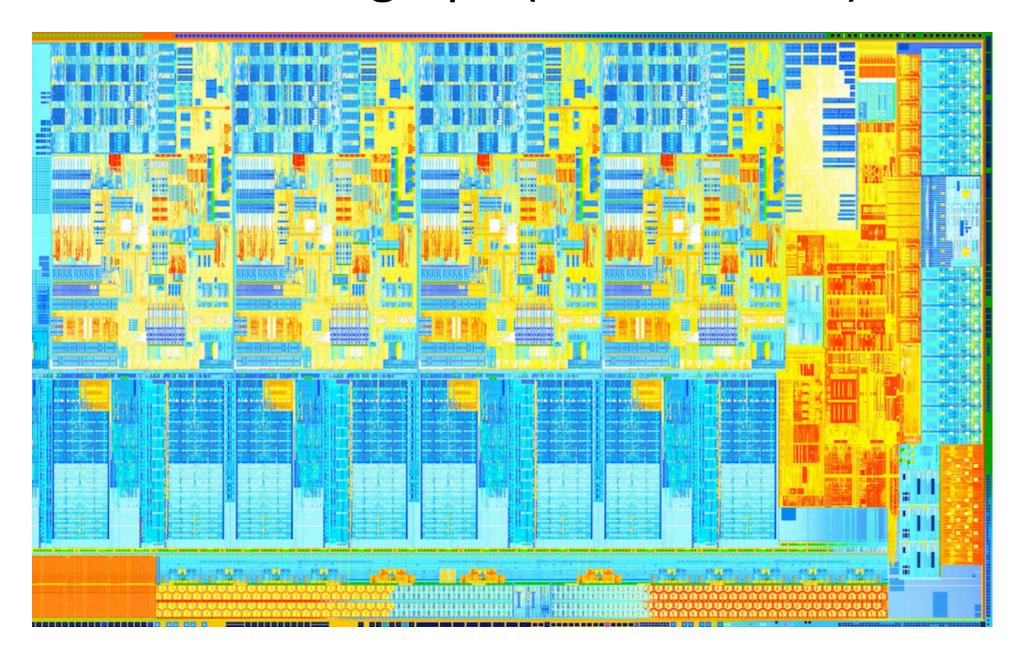
# A circuit graph (flip-flop)



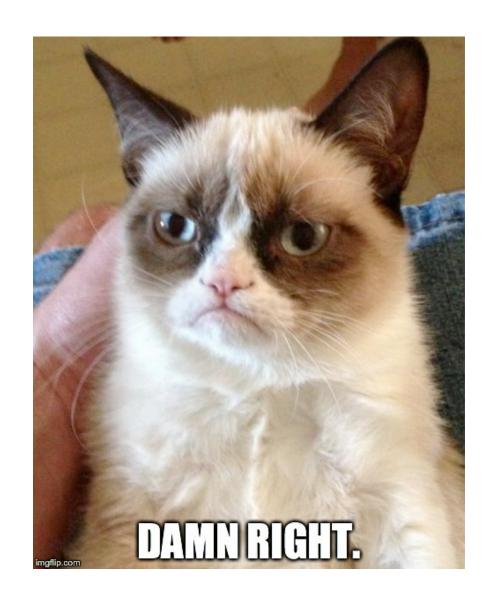
# A circuit graph (Intel 4004)



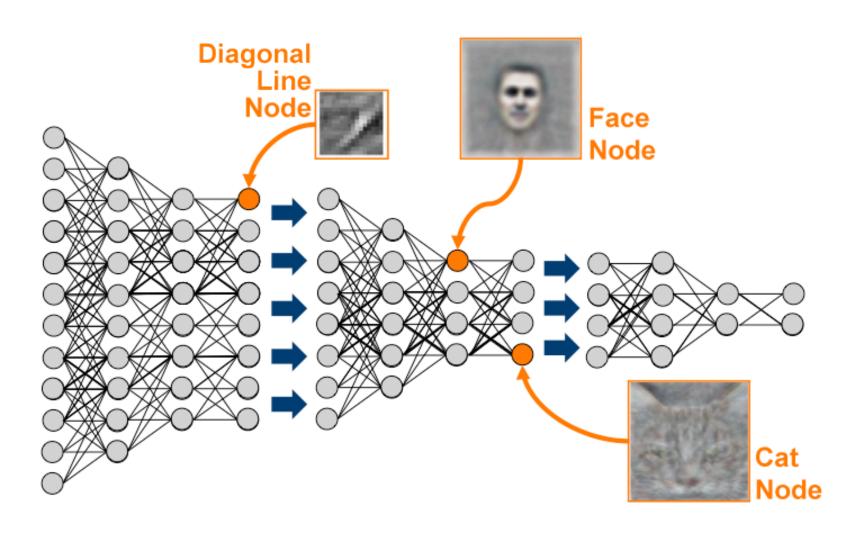
# A circuit graph (Intel Haswell)



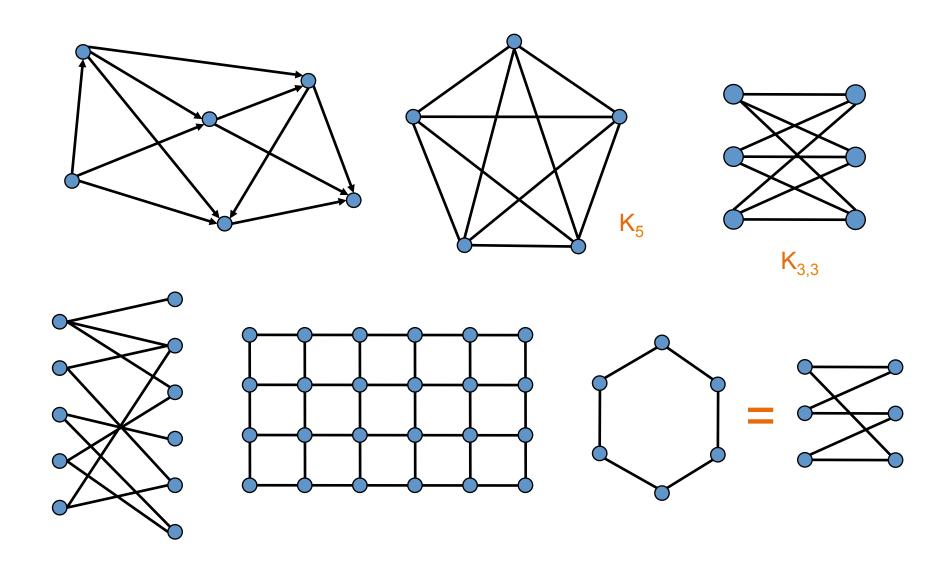
# This is not a graph, this is a cat



# This is a graph(ical model) that has learned to recognize cats



# Some abstract graphs

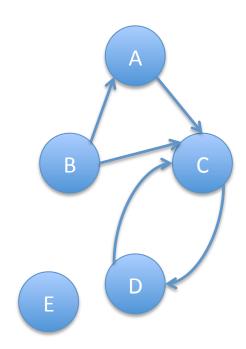


#### **Applications of Graphs**

- Communication networks
- Social networks
- Routing and shortest path problems
- Commodity distribution (network flow)
- Traffic control
- Resource allocation
- Numerical linear algebra (sparse matrices)
- Geometric modeling (meshes, topology, ...)
- Image processing (e.g. graph cuts)
- Computer animation (e.g. motion graphs)
- Systems biology
- Digital humanities (e.g. Republic of Letters)
- ...

#### **Directed Graphs**

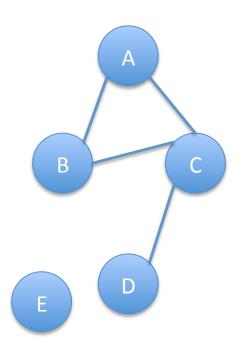
- A directed graph (digraph) is a pair (V, E) where
  - V is a set
  - E is a set of **ordered** pairs (u, v) where  $u, v \in V$ 
    - Often require  $u \neq v$  (i.e. no self-loops)
- An element of V is called a vertex or node
- An element of E is called an edge or arc
- V = size of V, often denoted n
- |E| = size of E, often denoted m



$$V = \{A, B, C, D, E\}$$
 $E = \{(A,C), (B,A), (B,C), (C,D), (D,C)\}$ 
 $|V| = 5$ 
 $|E| = 5$ 

#### **Undirected Graphs**

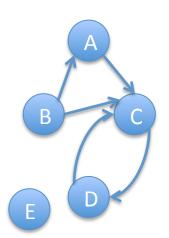
- An undirected graph is just like a directed graph!
  - ... except that E is now a set of **unordered** pairs  $\{u, v\}$  where  $u, v \in V$
- Every undirected graph is easily converted to an equivalent directed graph
  - Replace every undirected edge with two directed edges in opposite directions
- ... but not vice versa

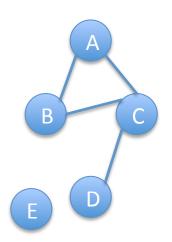


$$V = \{A, B, C, D, E\}$$
 $E = \{\{A,C\}, \{B,A\}, \{B,C\}, \{C,D\}\}$ 
 $|V| = 5$ 
 $|E| = 4$ 

## **Graph Terminology**

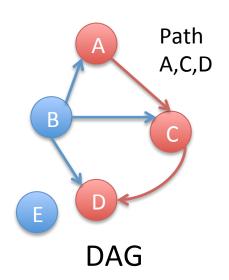
- Vertices u and v are called
  - the source and sink of the directed edge (u, v), respectively
  - the endpoints of (u, v) or  $\{u, v\}$
- Two vertices are adjacent if they are connected by an edge
- The outdegree of a vertex u in a directed graph is the number of edges for which u is the source
- The indegree of a vertex v in a directed graph is the number of edges for which v is the sink
- The degree of a vertex  $\boldsymbol{u}$  in an undirected graph is the number of edges of which  $\boldsymbol{u}$  is an endpoint

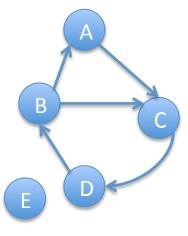




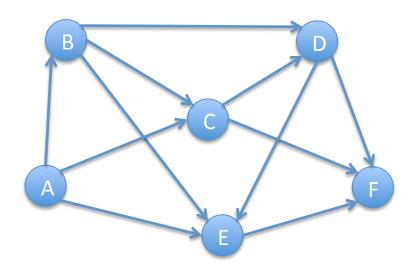
## More Graph Terminology

- A path is a sequence  $v_0, v_1, v_2, ..., v_p$  of vertices such that for  $0 \le i \le p-1$ ,
  - $-(v_i,v_{i+1}) \subseteq E$  if the graph is directed
  - $\{v_i, v_{i+1}\}$  ∈ *E* if the graph is undirected
- The length of a path is its number of edges
  - In this example, the length is 2
- A path is simple if it doesn't repeat any vertices
- A cycle is a path  $v_0, v_1, v_2, ..., v_p$  such that  $v_0 = v_p$
- A cycle is simple if it does not repeat any vertices except the first and last
- A graph is acyclic if it has no cycles
- A directed acyclic graph is called a DAG



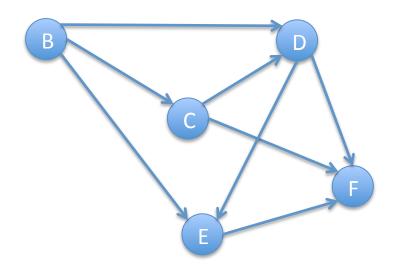


Not a DAG



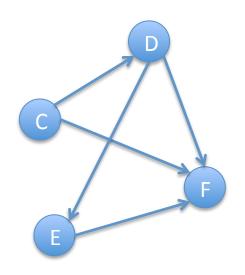
#### Intuition:

- If it's a DAG, there must be a vertex with indegree zero
- This idea leads to an algorithm
  - A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears



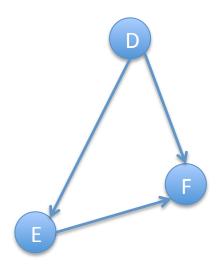
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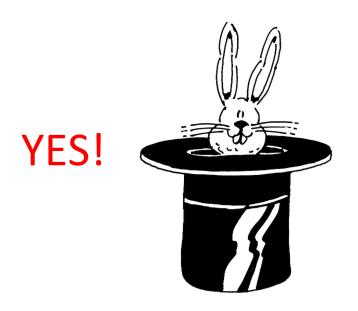


- Intuition:
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F

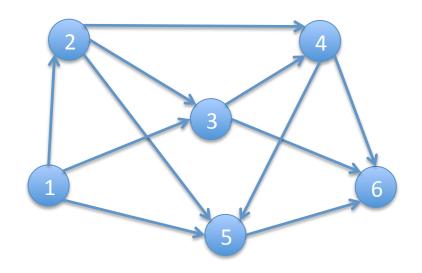
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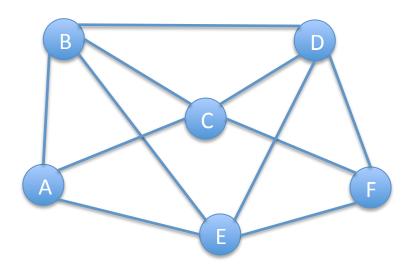
#### **Topological Sort**



- We just computed a topological sort of the DAG
  - This is a numbering of the vertices such that all edges go from lower- to higher-numbered vertices
  - Useful in job scheduling with precedence constraints

## **Graph Coloring**

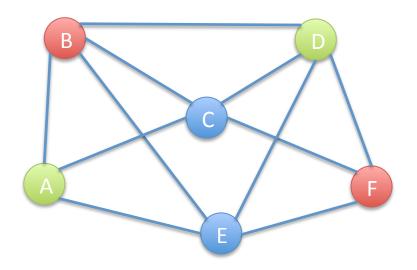
 A coloring of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



How many colors are needed to color this graph?

## **Graph Coloring**

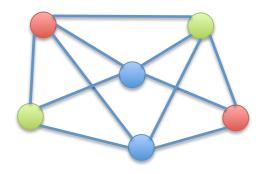
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How many colors are needed to color this graph?

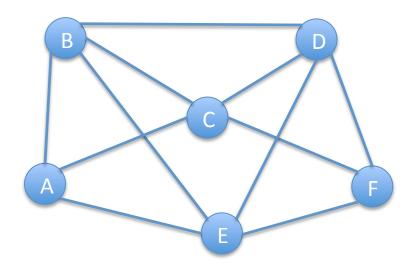
#### An Application of Coloring

- Vertices are jobs
- Edge (u, v) is present if jobs u and v each require access to the same shared resource, and thus cannot execute simultaneously
- Colors are time slots to schedule the jobs
- Minimum number of colors needed to color the graph = minimum number of time slots required



### **Planarity**

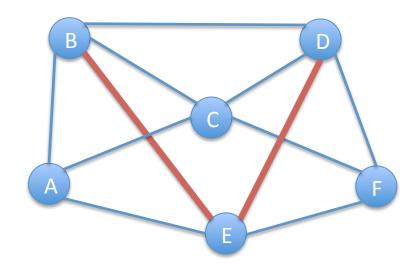
 A graph is planar if it can be drawn in the plane without any edges crossing



• Is this graph planar?

### **Planarity**

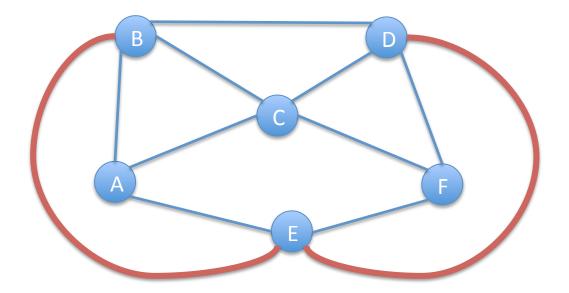
 A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?
  - Yes!

### Planarity

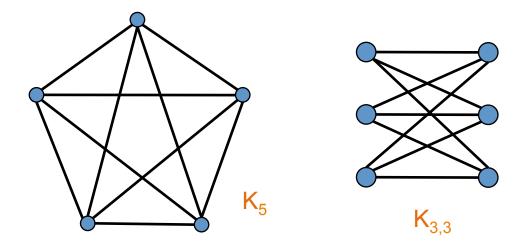
 A graph is planar if it <u>can</u> be drawn in the plane without any edges crossing



- Is this graph planar?
  - Yes!

#### **Detecting Planarity**

#### Kuratowski's Theorem:



• A graph is planar if and only if it does not contain a copy of  $K_5$  or  $K_{3,3}$  (possibly with other nodes along the edges shown)

#### Four-Color Theorem:

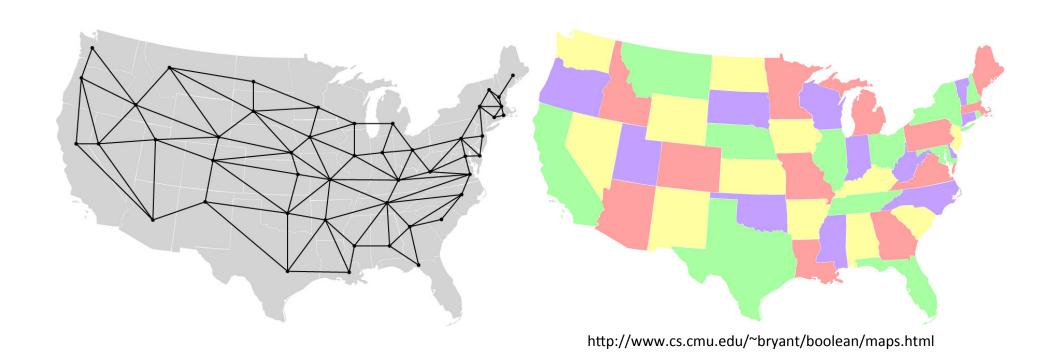
# Every planar graph is 4-colorable

[Appel & Haken, 1976]

(Every map defines a planar graph – countries are vertices, and two adjacent countries define an edge)



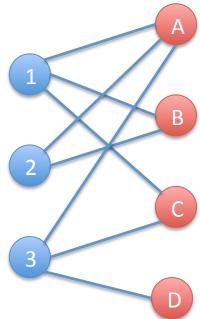
## Another 4-colored planar graph



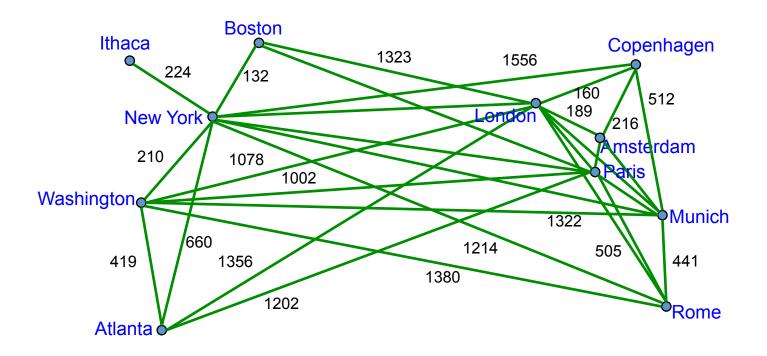
#### Bipartite Graphs

 A directed or undirected graph is bipartite if the vertices can be partitioned into two sets such that no edge connects two vertices in the same set

- The following are equivalent
  - -G is bipartite
  - − *G* is 2-colorable
  - -G has no cycles of odd length

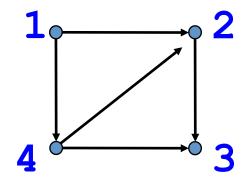


### **Traveling Salesperson**

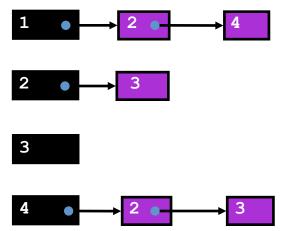


Find a path of minimum distance that visits every city

### Representations of Graphs



**Adjacency List** 



**Adjacency Matrix** 

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

#### Adjacency Matrix or Adjacency List?

#### • Definitions:

- -n = number of vertices
- -m = number of edges
- -d(u) = degree of u = number of edges leaving u

#### Adjacency Matrix

- Uses space  $O(n^2)$
- Can iterate over all edges in time  $O(n^2)$
- Can answer "Is there an edge from u to v?" in O(1) time
- Better for dense graphs (lots of edges)

#### Adjacency List

- Uses space O(m + n)
- Can iterate over all edges in time O(m + n)
- Can answer "Is there an edge from u to v?" in O(d(u)) time
- Better for sparse graphs (fewer edges)

### **Graph Algorithms**

- Search
  - Depth-first search
  - Breadth-first search
- Shortest paths
  - Dijkstra's algorithm
- Minimum spanning trees
  - Prim's algorithm
  - Kruskal's algorithm

### Readings

Chapter 28: Graphs

Chapter 29: Graph Implementations