

**Agenda:** Examples and definitions; computability of functions; from machines to programs.

**I. Example one-tape Turing machine** We specify the state set as “carry” and “no-carry”; the start state as “carry”; the allowable input symbols as 0, 1,...,9 (note that “blank” should not be an allowable input symbol); we’ll ignore other details that would be required in a full specification; and specify the machine’s behavior as follows.

If reading a “0” and in state “carry”, write “1”, change to state “no-carry”, stay put.

If reading a “1” and in state “carry”, write “2”, change to state “no-carry”, stay put.

If reading a “2” and in state “carry”, write “3”, change to state “no-carry”, stay put.

...

If reading a “9” and in state “carry”, write “0”, stay in state “carry”, move right.

If reading a “blank” and in state “carry”, write “1”, change to state “no-carry”, stay put.

(In a way, we are allowing a completely blank tape to represent the input number zero even though we have a symbol “0”, but for simplicity we have elected not to deal with this issue.)

**II. Another example one-tape TM** For brevity, we’ll skip most of the initial specification that should be given. We’ll assume there’s a special marker “!” at the beginning of the tape. The start state is “no-carry”.

end-of-tape rule:

If reading a “!” and in state “no-carry”, write “!”, change to state “carry”, move right.

carry rules:

If reading a “0” and in state “carry”, write “1”, change to state “no-carry”, move left.

If reading a “1” and in state “carry”, write “2”, change to state “no-carry”, move left.

If reading a “2” and in state “carry”, write “3”, change to state “no-carry”, move left.

...

If reading a “9” and in state “carry”, write “0”, stay in state “carry”, move right.

If reading a “blank” and in state “carry”, write “1”, change to state “no-carry”, move left.

return-to-tape-end rules:

If reading a “0” and in state “no-carry”, write “0”, stay in state “no-carry”, move left.

If reading a “1” and in state “no-carry”, write “1”, stay in state “no-carry”, move left.

If reading a “2” and in state “no-carry”, write “2”, stay in state “no-carry”, move left.

...

If reading a “9” and in state “no-carry”, write “9”, stay in state “no-carry”, move left.

**III. Definition of TM function computation** Let  $f : D \rightarrow R$  be a function. A Turing machine  $M$  *computes*  $f$  if, for every  $x \in D$ , when  $M$  is initialized with input  $x$ , it eventually *halts* — ends up in a situation where no rule applies — with  $f(x)$  on its (output) tape.

We will also allow for encodings of  $x$  and  $f(x)$ . For example, we might have a Turing machine that, given  $n$  “hash marks” as input, returns  $n^2$  “hash marks”; we would then still say that the Turing machine computes  $f(x) = x^2$ , where  $x$  is a non-negative integer.

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**IV. Enumeration of “A-machines”** We denote by  $M_1, M_2, \dots$  a infinite list (with no repeats) of *all* TMs that take only sequences of A’s as input and produce sequences of A’s as output. The list is such that given a (suitably encoded) number  $i$ , it is possible to recover the program for  $M_i$  (i.e., there exists a Turing machine that does the job).

The sequences of A’s are intended to be encodings of non-negative integers. Thus, *all computable functions from the non-negative integers to the non-negative integers are represented in the list.*

**V. The halting function**

$$h(M_i, j) = \begin{cases} 1 \text{ (yes),} & \text{if } M_i \text{ would halt given } j \text{ A's as input} \\ 0 \text{ (no)} & \text{if } M_i \text{ would not halt given } j \text{ A's as input} \end{cases}$$