

- Previous Lecture:
 - Linear search, binary search
 - Insertion sort
 - (Reading: Bubble Sort)
- Today's Lecture:
 - Merge Sort
 - What's next?
- Announcements
 - P6 due Thursday at 11pm
 - Final exam: Dec 17th 7pm, Barton Indoor Track WEST

Announcements

- **P6** due Thursday at 11pm
- **Final exam:**
 - Dec 17th, 7pm, **Barton Hall Indoor Track WEST**
- Please fill out course evaluation on-line, see “Exercise 16”
- Revised office/consulting hours
- Pick up papers during consulting hours at Carpenter
- **Read announcements on course website!**

Linear search and binary search

■ Linear search

- “Effort” is linearly proportional to n , the size of the search space (e.g., the length of the vector)
- Can represent effort by the number of comparisons against the search target done during the search

■ Binary search

- Effort is proportional to $\log_2(n)$ where n is the size of the search space
- Saving of $\log_2(n)$ over n is significant when n is large! But binary search requires sorted vector

Binary search is efficient, but we need to sort the vector in the first place so that we can use binary search

- Many different algorithms out there...
- We saw insertion sort (and read about bubble sort)
- Let's look at **merge sort**
- An example of the “divide and conquer” approach using recursion

Which task is “easier,” **sort a length 1000 array** or **merge* two length 500 sorted arrays into one?**

A. Sort

B. Merge

*Merge two sorted arrays so that the resultant array is sorted

Motivation: merging is an easier job than sorting!

If I have two helpers, I'd...

- Give each helper half the array to sort
- Then I get back the sorted subarrays and **merge** them.

What if those two helpers each had two sub-helpers?

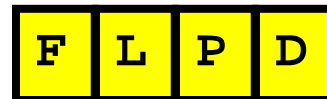
And the sub-helpers each had two sub-sub-helpers? And...

Subdivide the sorting task

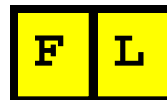
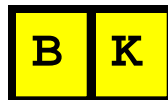
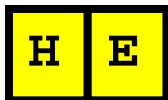
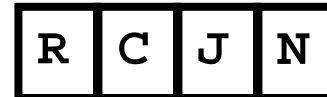
H	E	M	G	B	K	A	Q	F	L	P	D	R	C	J	N
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H	E	M	G	B	K	A	Q	F	L	P	D	R	C	J	N
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Subdivide again



And again



And one last time



H **E**

M **G**

B **K**

A **Q**

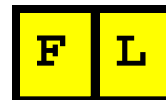
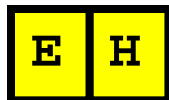
F **L**

P **D**

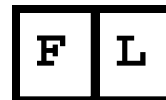
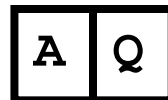
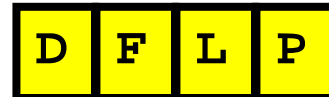
R **C**

J **N**

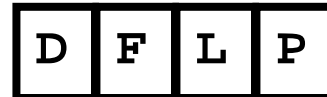
Now merge



And merge again



And again



And one last time

A	B	C	D	E	F	G	H	J	K	L	M	N	P	Q	R
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

A	B	E	G	H	K	M	Q
---	---	---	---	---	---	---	---

C	D	F	J	L	N	P	R
---	---	---	---	---	---	---	---

Done!

A	B	C	D	E	F	G	H	J	K	L	M	N	P	Q	R
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

```

function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL(x(1:m));
    yR = mergeSortR(x(m+1:n));
    y = merge(yL,yR);
end

```

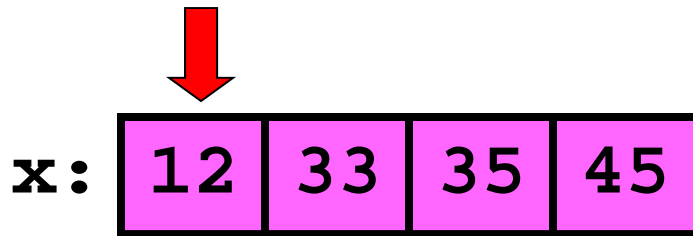

The central sub-problem is the **merging** of two sorted arrays into one single sorted array

12	33	35	45
----	----	----	----

15	42	55	65	75
----	----	----	----	----

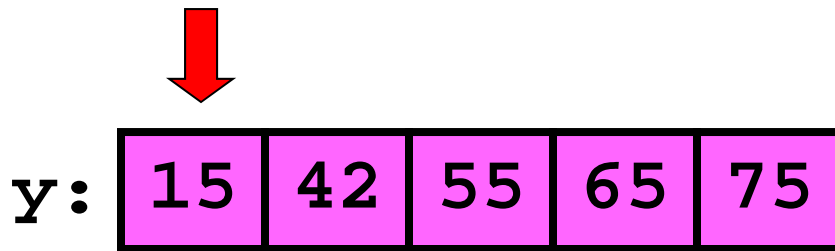
12	15	33	35	42	45	55	65	75
----	----	----	----	----	----	----	----	----

Merge



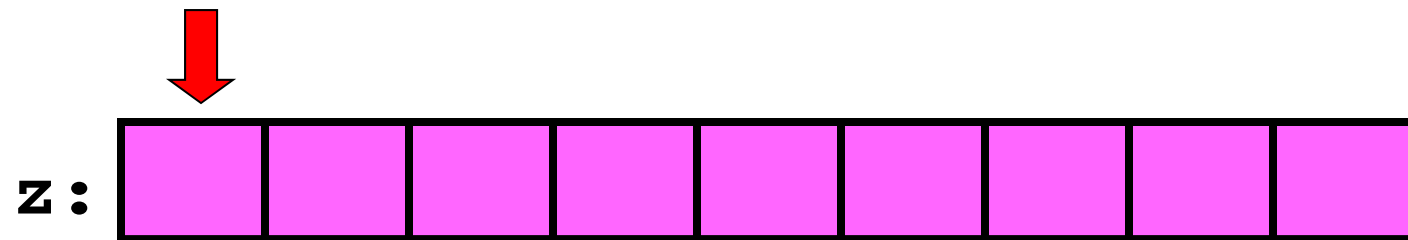
ix:

1



iy:

1

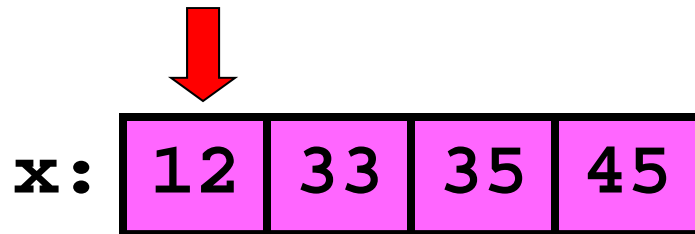


iz:

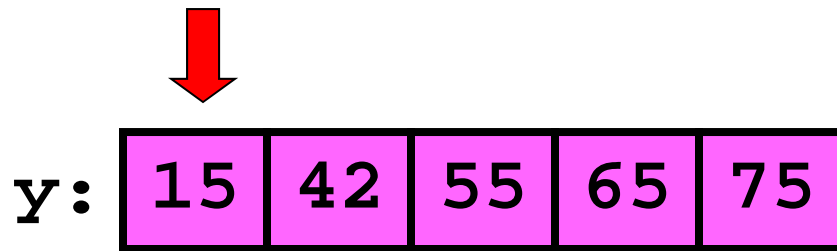
1

ix ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

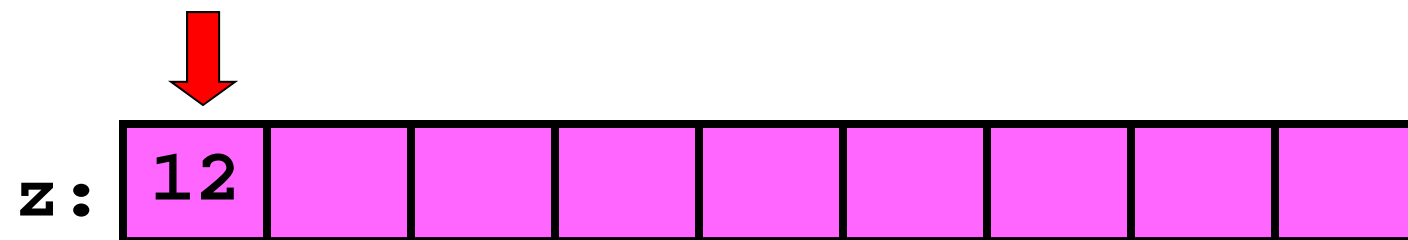
Merge



ix: 1



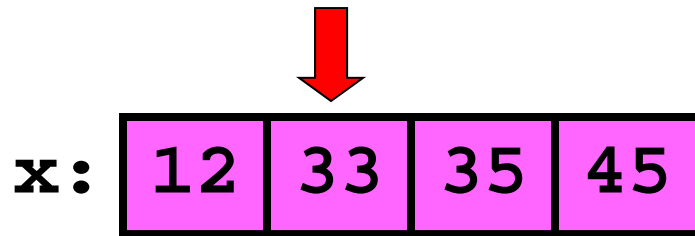
iy: 1



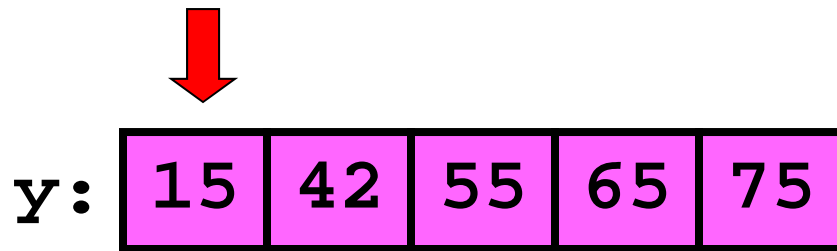
iz: 1

ix ≤ 4 and iy ≤ 5: x(ix) ≤ y(iy) **YES**

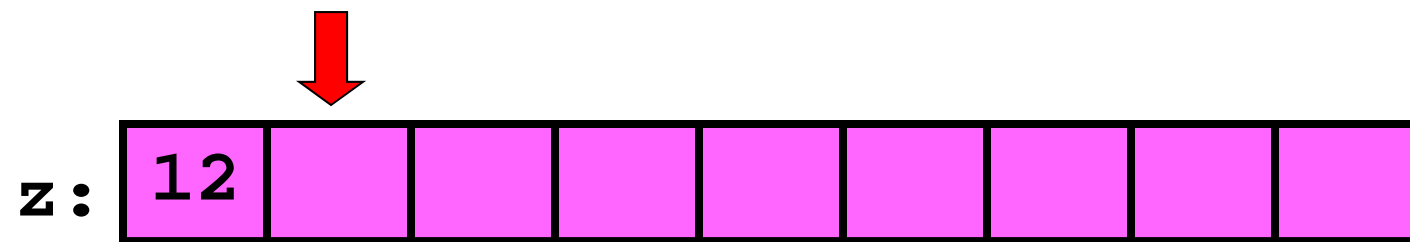
Merge



ix: [2]



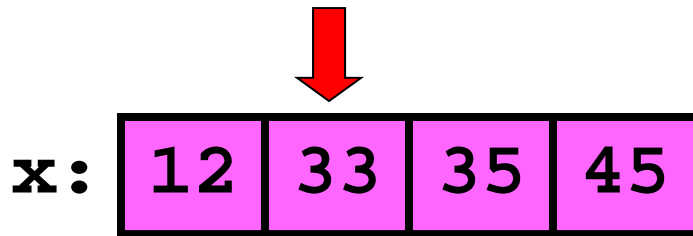
iy: [1]



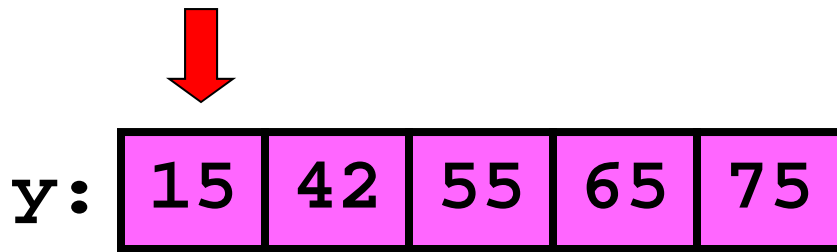
iz: [2]

ix ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

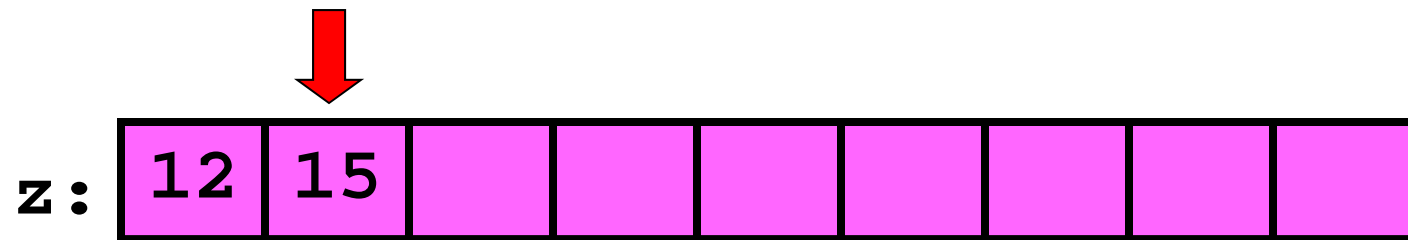
Merge



ix: 2



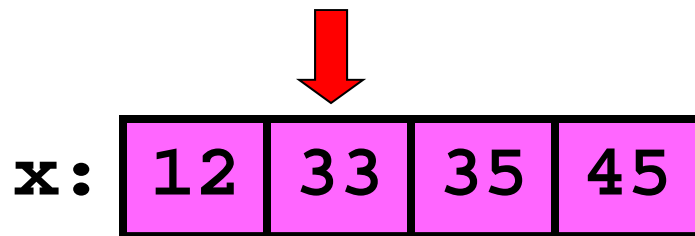
iy: 1



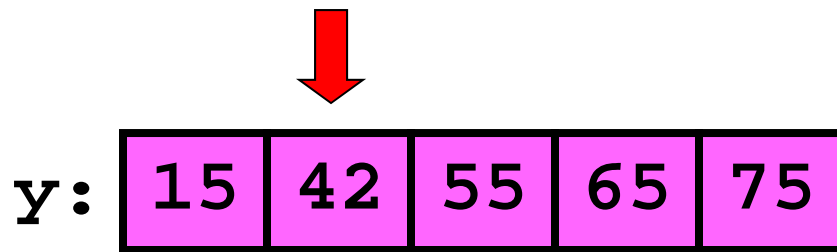
iz: 2

$ix \leq 4$ and $iy \leq 5$: $x(ix) \leq y(iy)$ NO

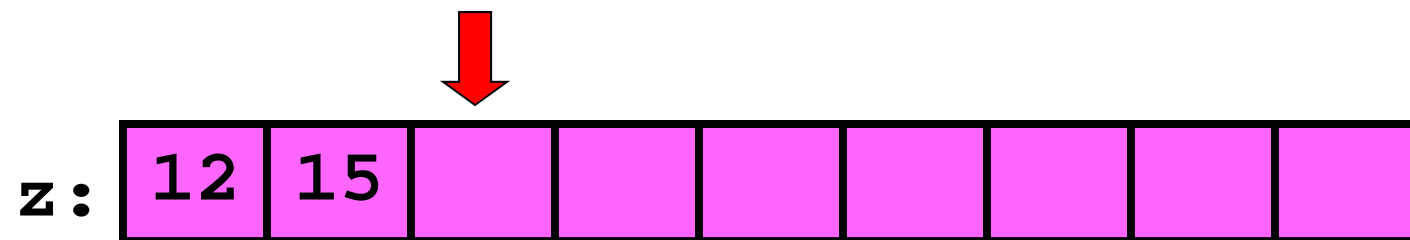
Merge



ix: [2]



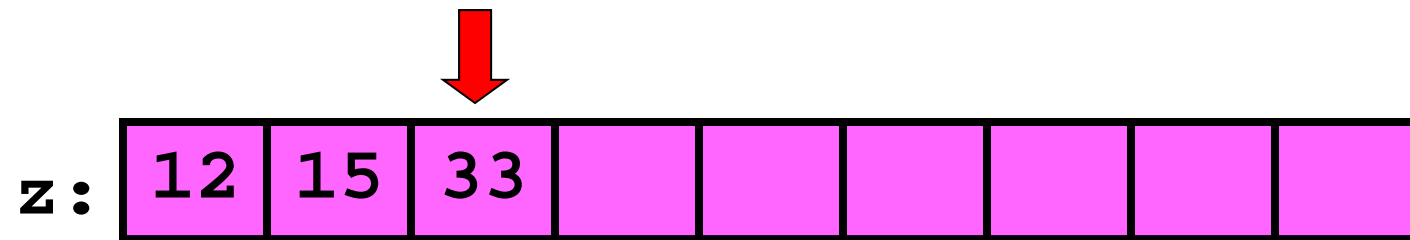
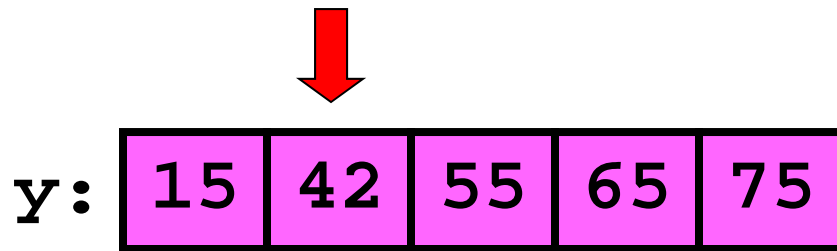
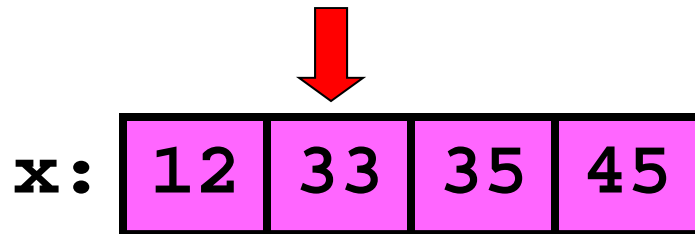
iy: [2]



iz: [3]

ix ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

Merge



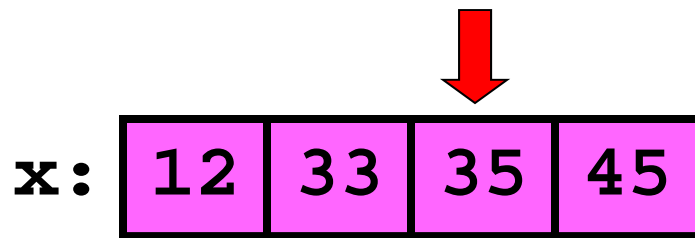
ix: 2

iy: 2

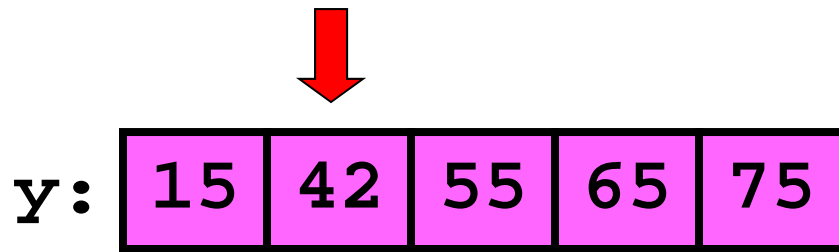
iz: 3

ix ≤ 4 and **iy** ≤ 5: **x(ix)** ≤ **y(iy)** **YES**

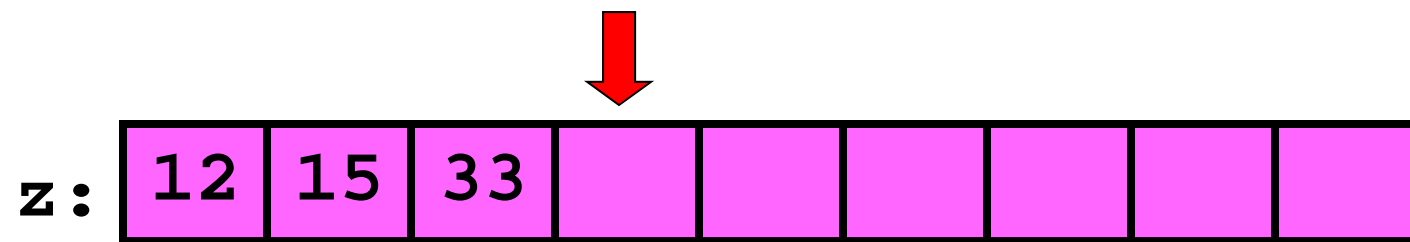
Merge



ix: [3]



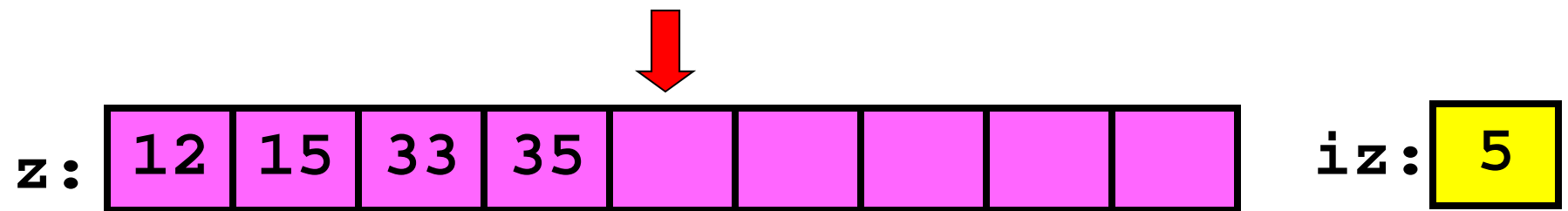
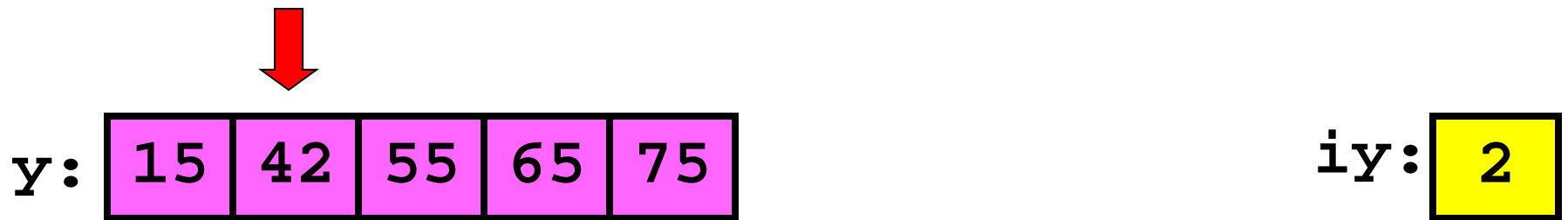
iy: [2]



iz: [4]

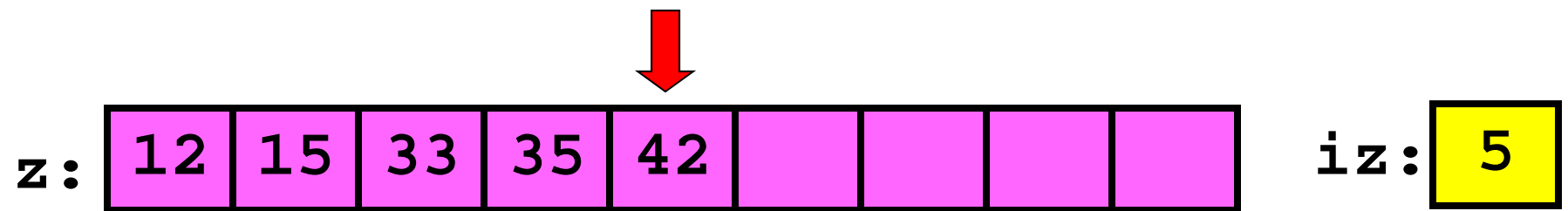
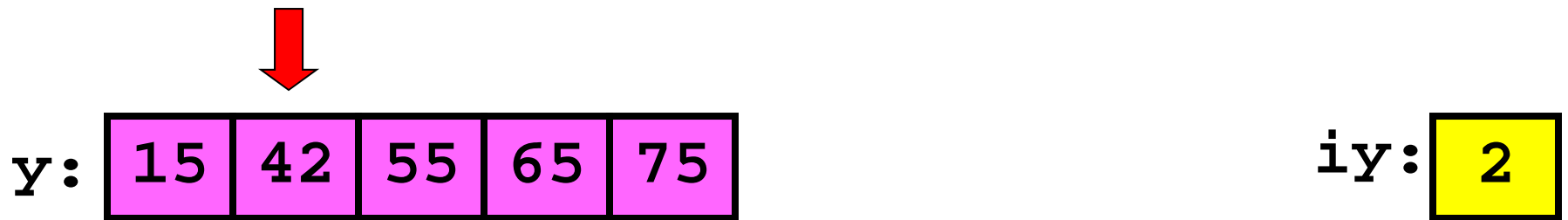
ix ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

Merge



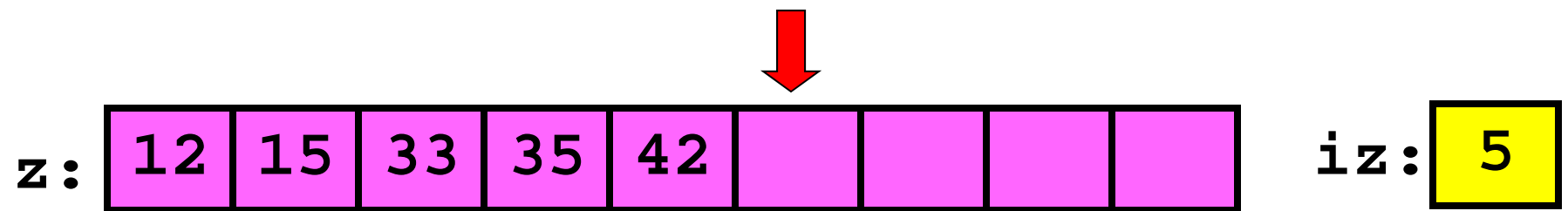
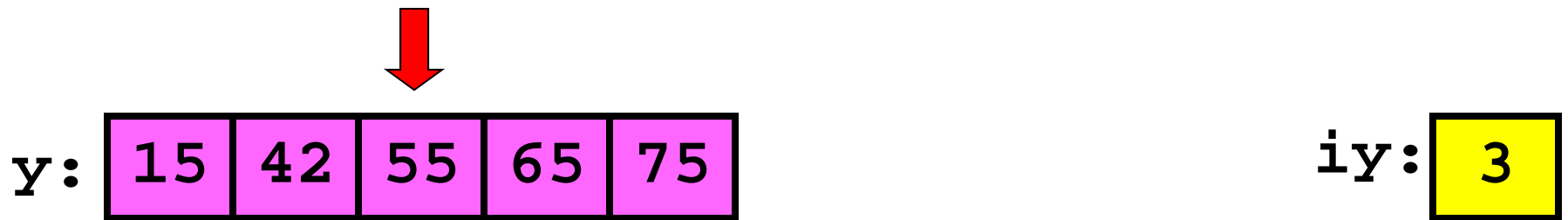
ix ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

Merge



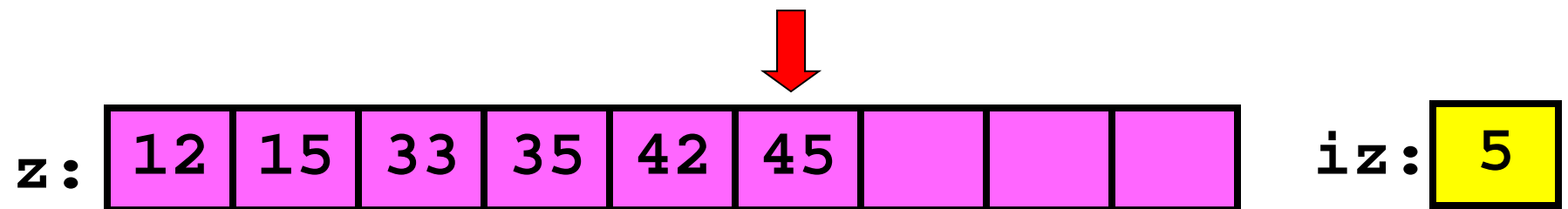
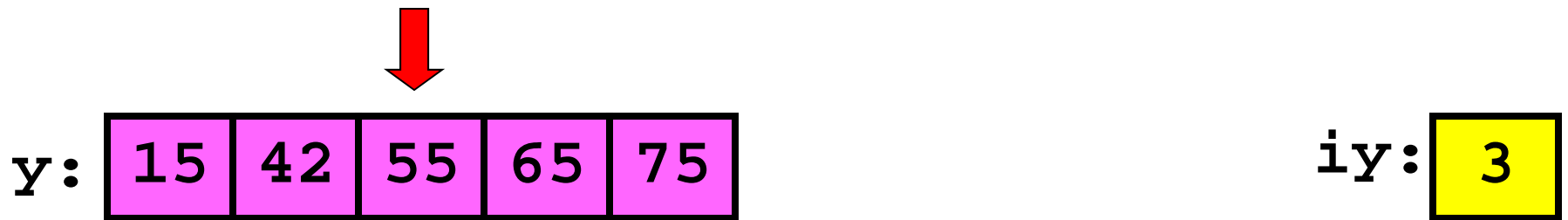
$ix \leq 4$ and $iy \leq 5$: $x(ix) \leq y(iy)$ **NO**

Merge



$ix \leq 4$ and $iy \leq 5$: $x(ix) \leq y(iy)$???

Merge



$ix \leq 4$ and $iy \leq 5$: $x(ix) \leq y(iy)$ **YES**

Merge



x:

12	33	35	45
----	----	----	----

ix:

5



y:

15	42	55	65	75
----	----	----	----	----

iy:

3



z:

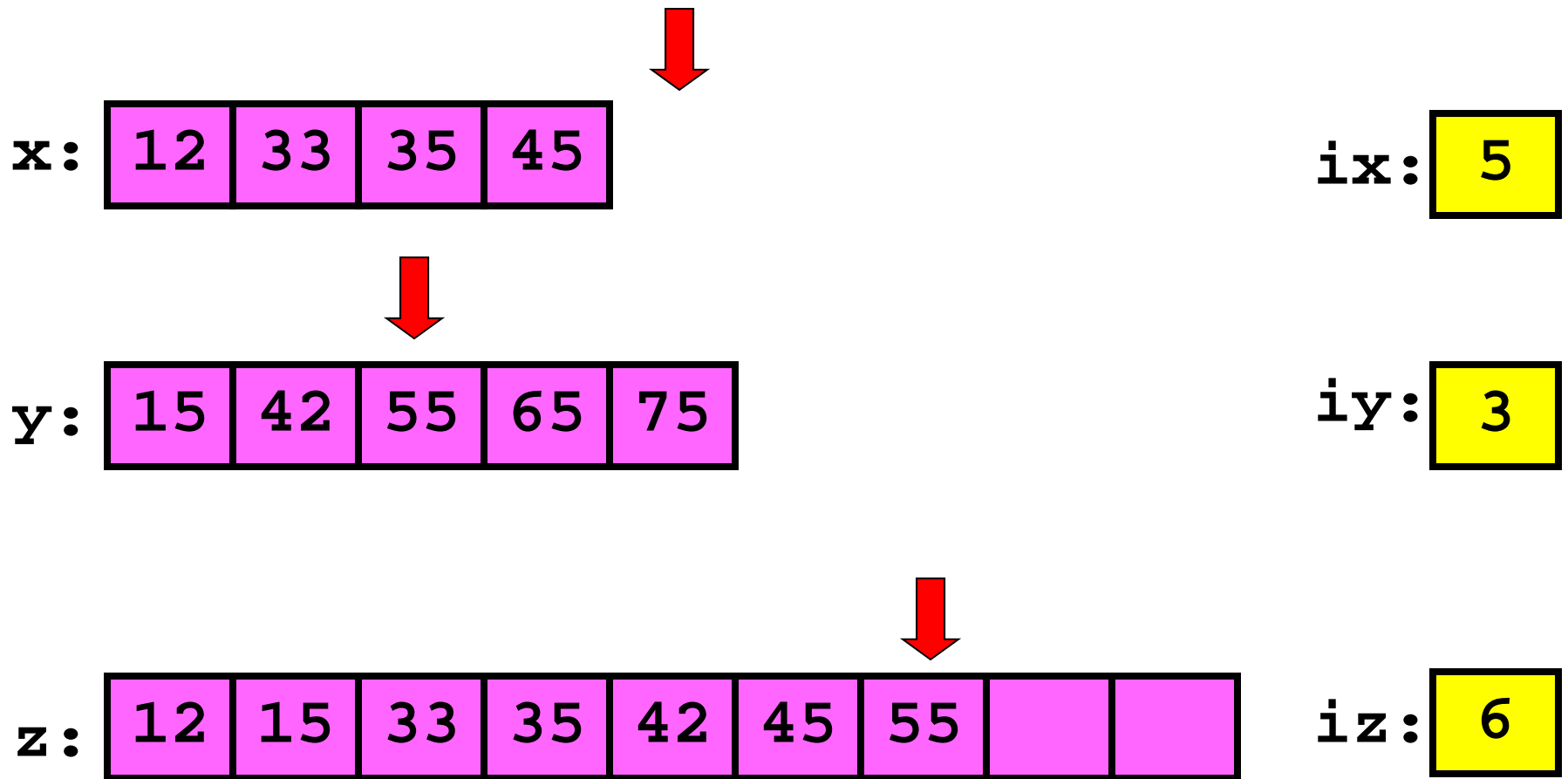
12	15	33	35	42	45			
----	----	----	----	----	----	--	--	--

iz:

6

$ix > 4$

Merge



ix > 4: take y(iy)

Merge



x:

12	33	35	45
----	----	----	----

ix:

5



y:

15	42	55	65	75
----	----	----	----	----

iy:

4



z:

12	15	33	35	42	45	55		
----	----	----	----	----	----	----	--	--

iz:

8

$iy \leq 5$

Merge



x:

12	33	35	45
----	----	----	----

ix:

5



y:

15	42	55	65	75
----	----	----	----	----

iy:

4



z:

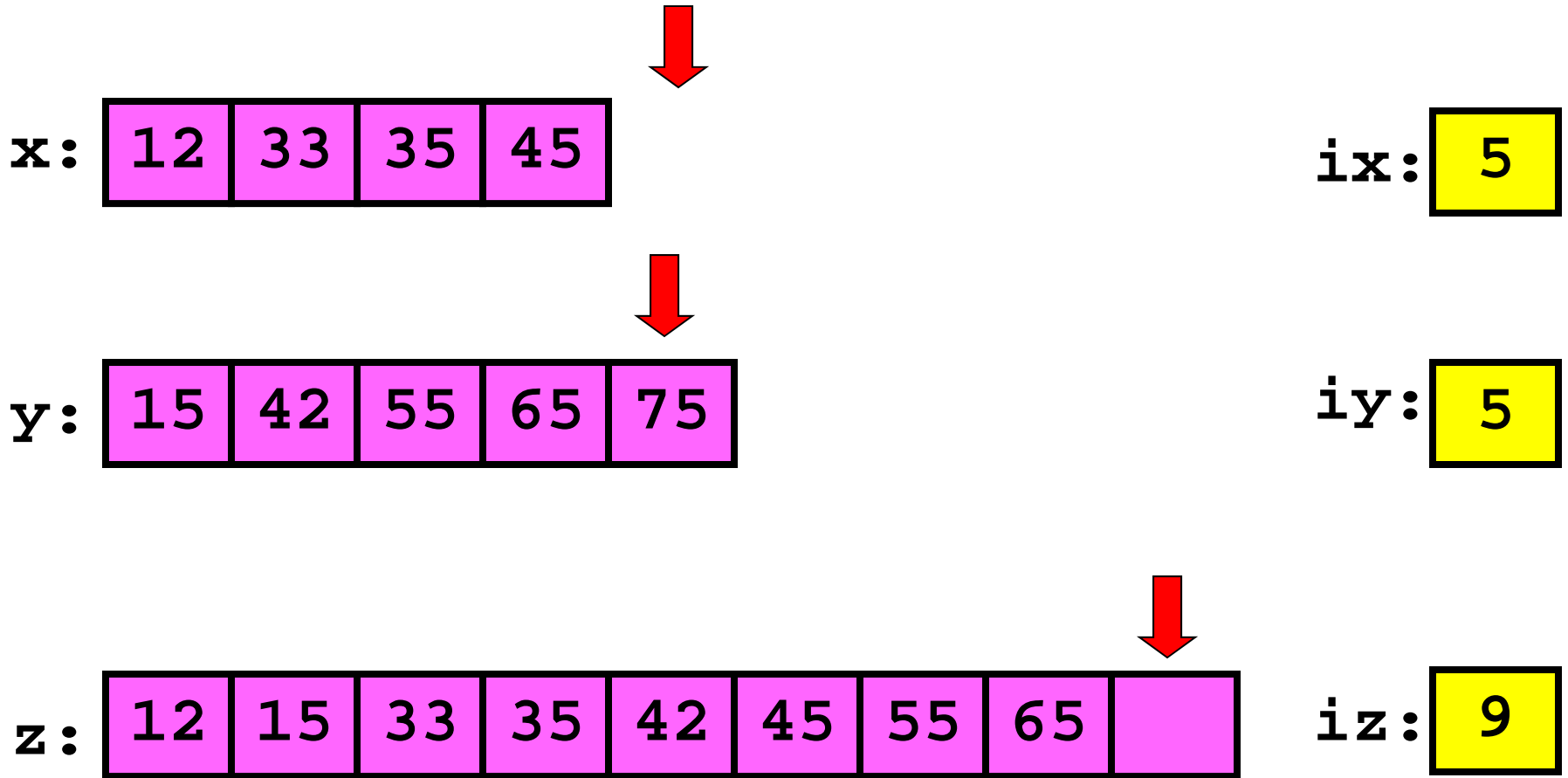
12	15	33	35	42	45	55	65	
----	----	----	----	----	----	----	----	--

iz:

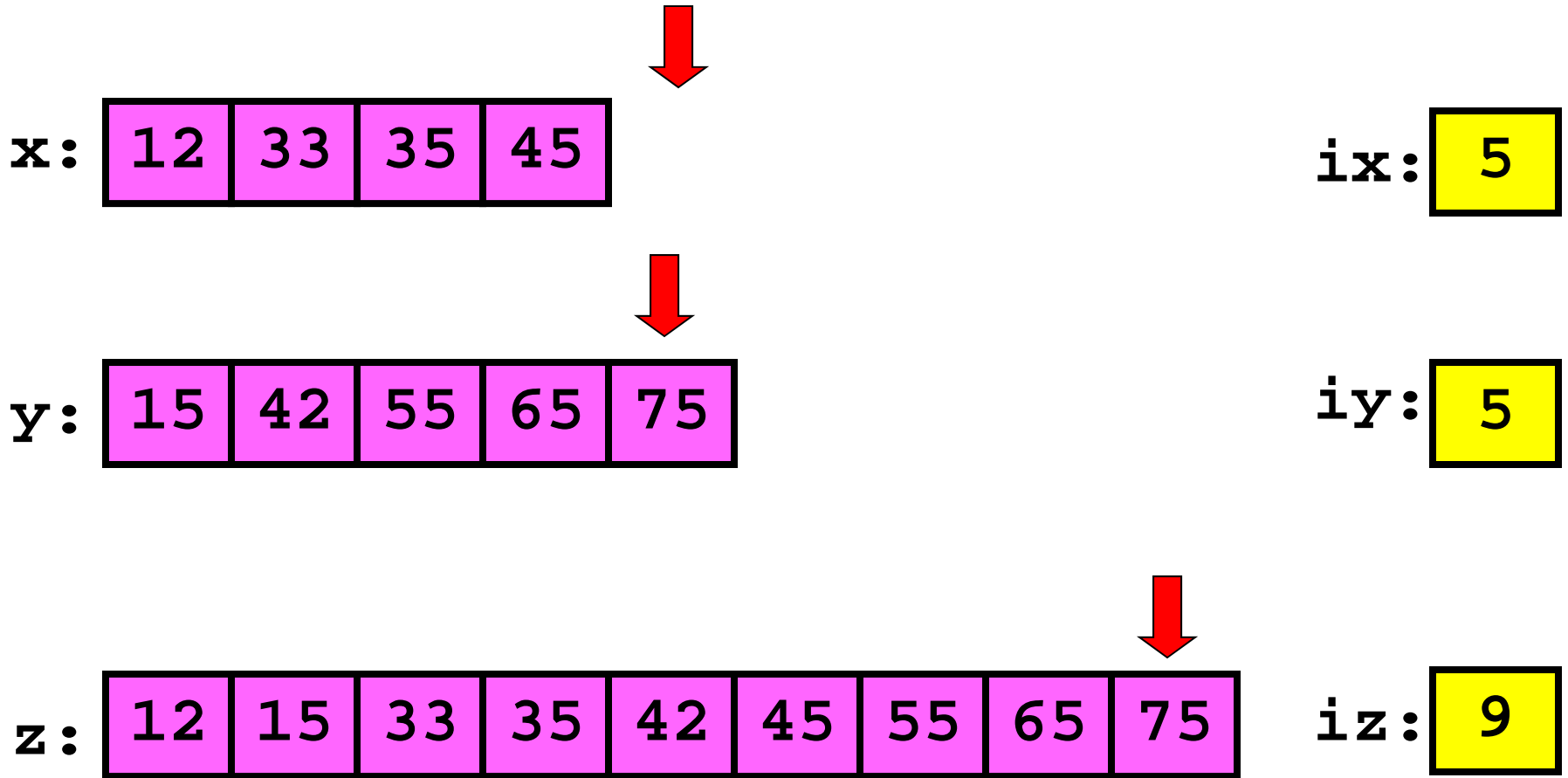
8

$iy \leq 5$

Merge



Merge



$$iy \leq 5$$

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
```

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny

end
% Deal with remaining values in x or y
```

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
end
% Deal with remaining values in x or y
```

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
while ix<=nx % copy remaining x-values
    z(iz)= x(ix); ix=ix+1; iz=iz+1;
end
while iy<=ny % copy remaining y-values
    z(iz)= y(iy); iy=iy+1; iz=iz+1;
end
```

```

function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL(x(1:m));
    yR = mergeSortR(x(m+1:n));
    y = merge(yL,yR);
end

```



```

function y = mergeSortL(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL_L(x(1:m));
    yR = mergeSortL_R(x(m+1:n));
    y = merge(yL,yR);
end

```

```

function y = mergeSortL_L(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL_L_L(x(1:m));
    yR = mergeSortL_L_R(x(m+1:n));
    y = merge(yL,yR);
end

```

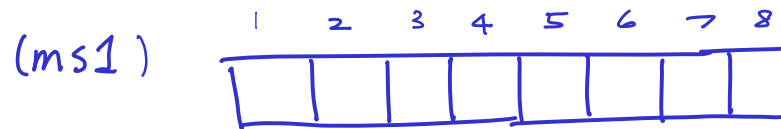
```
function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSort(x(1:m));
    yR = mergeSort(x(m+1:n));
    y = merge(yL,yR);
end
```

```
function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end
```

```
function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end
```

mergeSort — 1st call

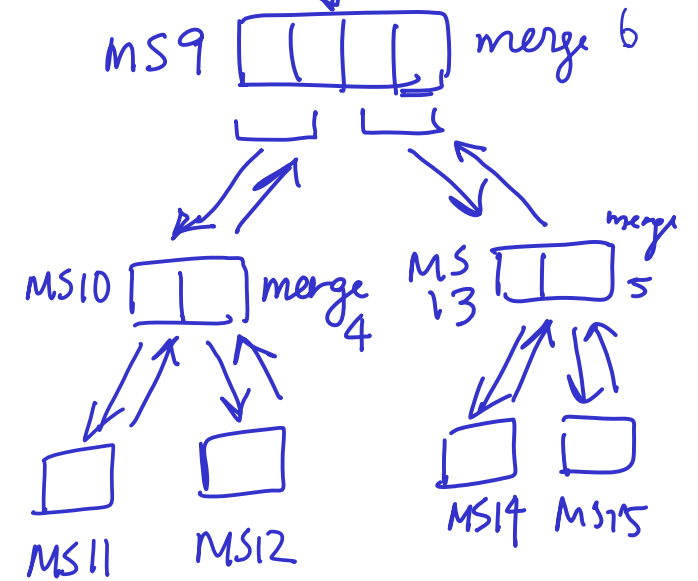
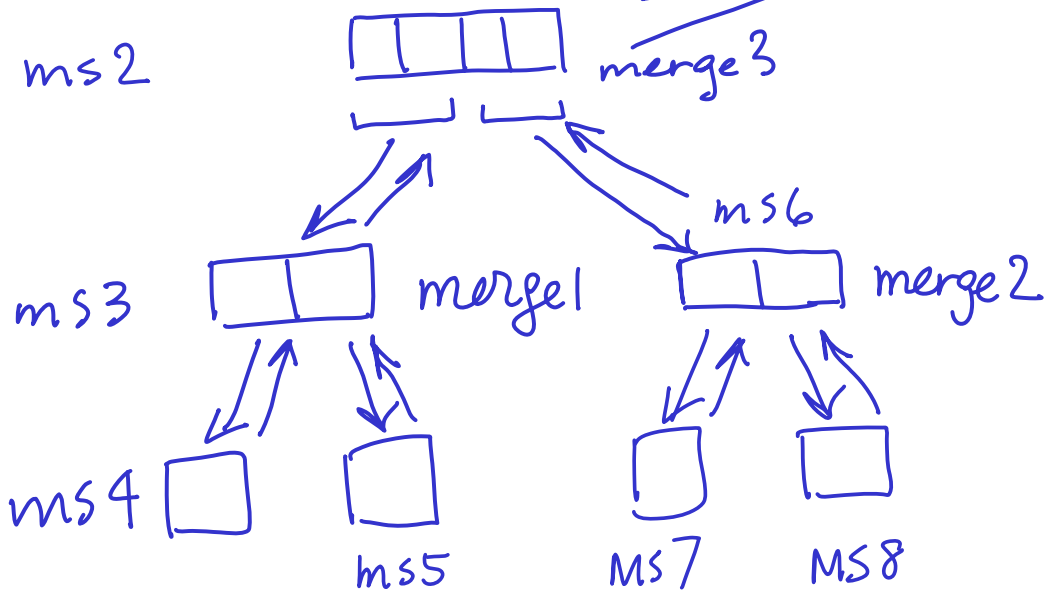
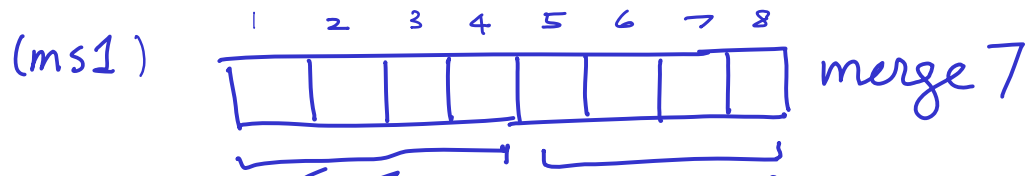


```

function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end

```

mergeSort - 1st call

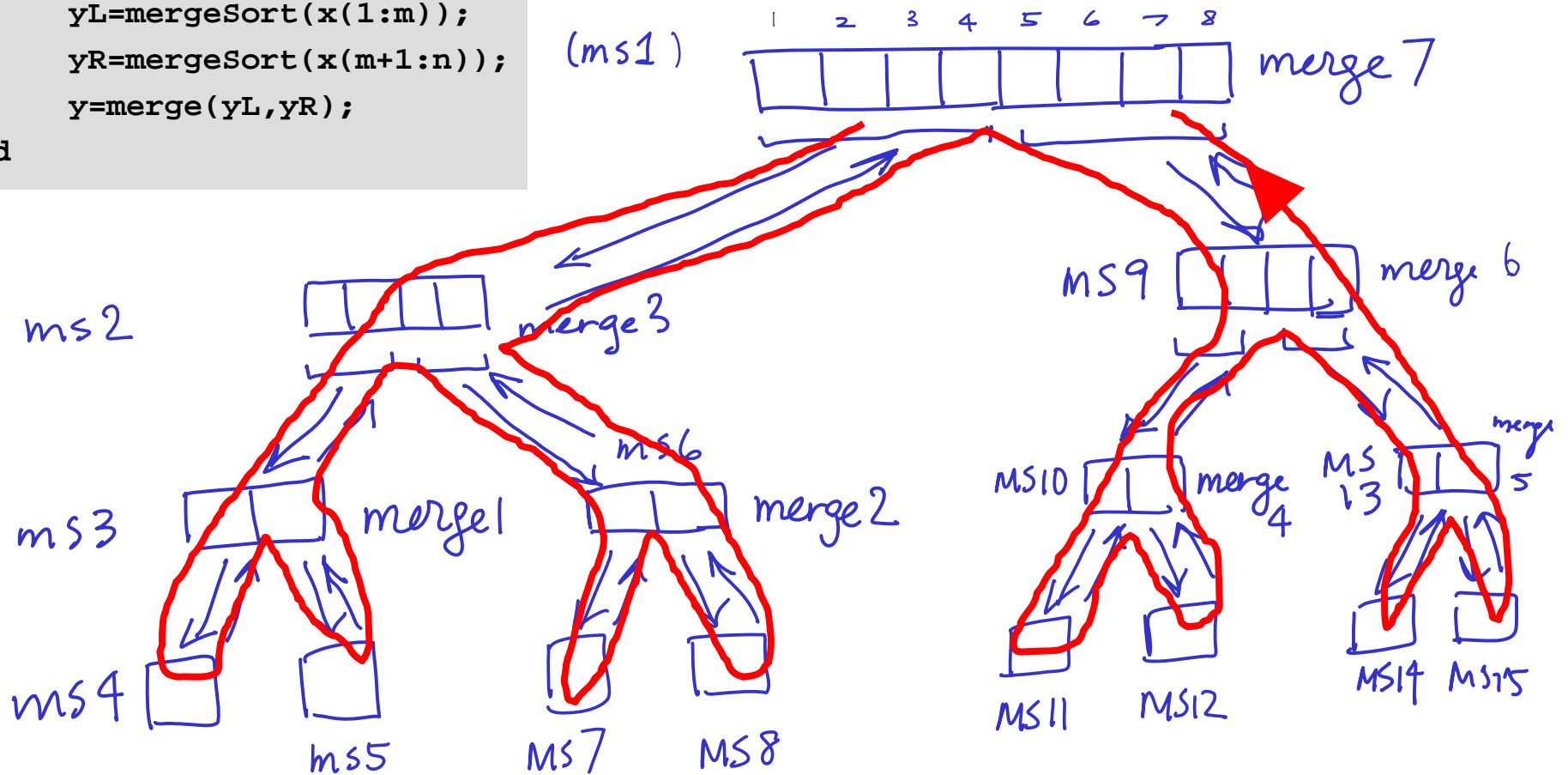


```

function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end

```

mergeSort - 1st call



How do merge sort, insertion sort, and bubble sort compare?

- Insertion sort and bubble sort are similar
 - Both involve a series of comparisons and swaps
 - Both involve nested loops
- Merge sort uses recursion

`See InsertionSort.m`


```

function x = insertSort(x)
% Sort vector x in ascending order with insertion sort

n = length(x);
for i= 1:n-1

    % Sort x(1:i+1) given that x(1:i) is sorted
    j= i;
    while  j>0 && x(j+1)<x(j)

        % swap x(j+1) and x(j)
        temp= x(j);
        x(j)= x(j+1);
        x(j+1)= temp;

        j= j-1;

    end
end
end

```

How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes k comparisons to insert an element in a sorted array of k elements. For an array of length N :

$$1+2+\dots+(N-1) = N(N-1)/2, \text{ say } N^2 \text{ for big } N$$

- Merge sort:

```
function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.
```

```
n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSort(x(1:m));
    yR = mergeSort(x(m+1:n));
    y = merge(yL,yR);
end
```

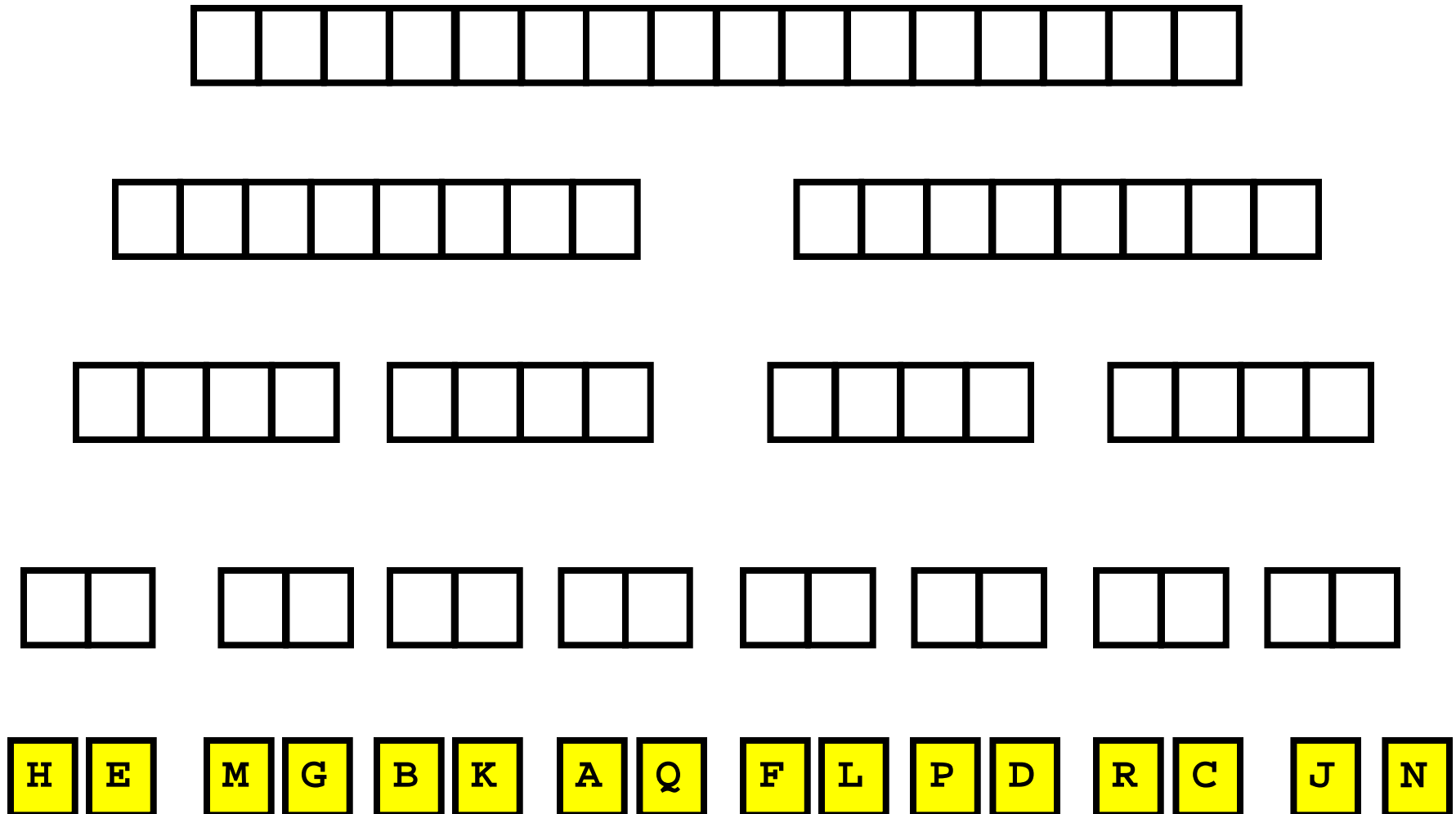
All the comparisons between
vector values are done in merge

```

function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
while ix<=nx % copy remaining x-values
    z(iz)= x(ix); ix=ix+1; iz=iz+1;
end
while iy<=ny % copy remaining y-values
    z(iz)= y(iy); iy=iy+1; iz=iz+1;
end

```

Merge sort: $\log_2(N)$ “levels”; N comparisons each level



How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes i comparisons to insert an element in a sorted array of i elements. For an array of length N :

$$1+2+\dots+(N-1) = N(N-1)/2, \text{ say } N^2 \text{ for big } N$$

$O(N^2)$

- Merge sort: $N \cdot \log_2(N)$

$O(N \log_2(N))$

Order of magnitude

- Insertion sort is done *in-place*; merge sort (recursion) requires much more memory

See `compareInsertMerge.m`

How to choose??

- Depends on application
- Merge sort is especially good for sorting **large data set** (but watch out for memory usage)
- Insertion sort is “order N^2 ” at **worst case**, but what about an **average case**? If the application requires that you *maintain* a sorted array, insertion sort may be a good choice

Why not just use Matlab's sort function?

- **Flexibility**
- E.g., to maintain a sorted list, just write the code for insertion sort
- E.g., sort strings or other complicated structures
- Sort according to some criterion set out in a function file
 - Observe that we have the comparison $x(j+1) < x(j)$
 - The comparison can be a function that returns a **boolean** value
- Can combine different sort/search algorithms for specific problem

We've reached the end of CS1112... now what?

- Continue practicing your problem solving—
problem decomposition—skills, in programming
and other arenas!
- Interested in further study?
 - ENGRD/CS 2110 Object-oriented programming and
data structure

ENGRG/CS 2110 OOP and Data Structures

- Learn new programming concepts and further explores those you've seen in CS1112
 - OOP, program design and development
 - Recursion
 - Complex data structures and related algorithms
- Taught in **Java**
- Optional **CS 2111** meets 1 hr/week; additional practice with OOP, Java, and other course topics
- During break, check out this website:
<http://www.cs.cornell.edu/courses/CS1130/2014sp/>

We've reached the end of CS 112... now what?

- Continue practicing your problem solving—problem decomposition—skills, in programming and other arenas!
- Interested in further study?
 - ENGRD/CS 2110 Object-oriented programming and data structure
 - Short courses in Python (CS 1133), C++ (CS 2024), ..., etc.
 - More general CS courses: CS 2800 Discrete structures, CS 2850 Networks

What we learned...

- Develop/implement **algorithms** for problems
- Develop programming skills
 - Design, implement, document, test, and debug
- Programming “tool bag”
 - Functions for reducing redundancy
 - Control flow (if-else; loops)
 - Recursion
 - Data structures
 - Graphics
 - File handling

What we learned... (cont'd)

- Applications and concepts
 - Image processing
 - Object-oriented programming
 - Sorting and searching—you should know the algorithms covered
 - Divide-and-conquer strategies
 - Approximation and error
 - Simulation
 - Computational effort and efficiency

Computing gives us *insight* into a problem

- Computing is not about getting one answer!
- We build models and write programs so that we can “play” with the models and programs, learning—gaining insights—as we vary the parameters and assumptions
- Good models require domain-specific knowledge (and experience)
- Good programs ...
 - are modular and cleanly organized
 - are well-documented
 - use appropriate data structures and algorithms
 - are reasonably efficient in time and memory

Final Exam

- Dec 17, 7-9:30pm, Barton Hall indoor tracks WEST
- Covers entire course; some emphasis on material after Prelim 2
- Closed-book exam, no calculators
- Bring student ID card

- Check for announcements on webpage:
 - Study break office/consulting hours
 - Review session time and location
 - Review questions
 - List of potentially useful functions

Final Exam

- Dec 17, 7-9:30pm, Barton Hall indoor tracks WEST
- Covers entire course; some emphasis on material of Prelim 2
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- Bring

Best wishes
and
good luck with all your exams!

List of potentially useful functions