

Announcements

- Pick up Prelim I during consulting hrs (Carpenter Hall, ACCEL Green Rm)
- Dr. Fan will be away for the next three lectures. Lectures are being pre-recorded and will be put online W, M, and next W. Access them on the course website using your NetID, preferably before normal lecture time
- TAs will lead the lectures on 10/23, 10/28, 10/30. Attendance is optional
 - 10/23 Thurs: Go over Qs 1,2,5 of Prelim I; answer your questions on the recorded lecture
 - 10/28 Tues: Go over Qs 3 & 4 of Prelim I; answer your questions on the recorded lecture
 - 10/30 Thurs: Answer your questions on the recorded lecture

Lecture 16

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Previous Lecture:

- Image processing
 - Add frame, mirror

Today's Lecture:

- More image processing
 - color → grayscale
 - “Noise” filtering
 - Edge finding



Announcements:

- Discussion this week in the classrooms as listed on Student Center
- Project 4 due Mon Oct 27th

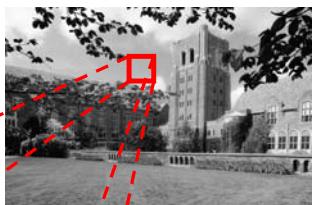
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Grayness: a value in [0..255]

0 = black
255 = white

These are *integer* values
Type: `uint8`



| | | | | | |
|-----|-----|-----|-----|-----|-----|
| 150 | 149 | 152 | 153 | 152 | 155 |
| 151 | 150 | 153 | 154 | 153 | 156 |
| 153 | 151 | 155 | 156 | 155 | 158 |
| 154 | 153 | 156 | 157 | 156 | 159 |
| 156 | 154 | 158 | 159 | 158 | 161 |
| 157 | 156 | 159 | 160 | 159 | 162 |

Lecture 16

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% Make mirror image of A -- the whole thing

```
A= imread('LawSchool.jpg');
[nr,nc,np]= size(A);

B= zeros(nr,nc,np);
B= uint8(B); % Type for image color values

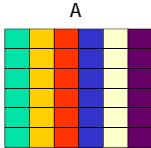
for r= 1:nr
    for c= 1:nc
        for p= 1:np
            B(r,c,p)= A(r,nc-c+1,p);
        end
    end
end
imshow(B) % Show 3-d array data as an image
imwrite(B,'LawSchoolMirror.jpg')
```

Lecture 15

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Vectorized code simplifies things...

Work with a whole column at a time

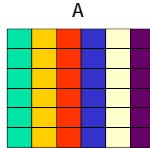


Lecture 15

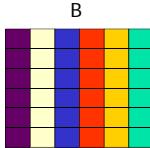
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Vectorized code simplifies things...

Work with a whole column at a time



1 2 3 4 5 6



1 2 3 4 5 6

Column c in B
is column nc-c+1 in A

Lecture 15

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Consider a single matrix (just one layer)

```
[nr,nc,np] = size(A);
for c= 1:nc
    B(1:nr,c ) = A(1:nr,nc-c+1 );
end
```

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Consider a single matrix (just one layer)

```
[nr,nc,np] = size(A);
for c= 1:nc
    B( : ,c ) = A( : ,nc-c+1 );
end
```

The colon says "all indices in this dimension." In this case it says "all rows."

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Vectorized code to create a mirror image

```
A = imread('LawSchool.jpg')
[nr,nc,np] = size(A);
for c= 1:nc
    B(:,c,1) = A(:,nc-c+1,1)
    B(:,c,2) = A(:,nc-c+1,2)
    B(:,c,3) = A(:,nc-c+1,3)
end
imwrite(B,'LawSchoolMirror.jpg')
```

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Even more compact vectorized code to create a mirror image...

```
for c= 1:nc
    B(:,c,1) = A(:,nc-c+1,1)
    B(:,c,2) = A(:,nc-c+1,2)
    B(:,c,3) = A(:,nc-c+1,3)
end
```



```
B = A(:,nc:-1:1,:)
```

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Example: color → black and white

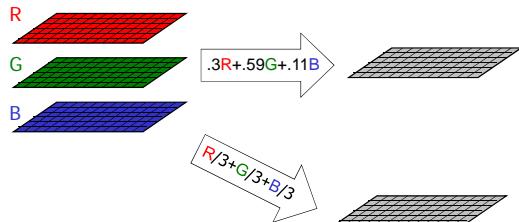


Can "average" the three color values to get one gray value.

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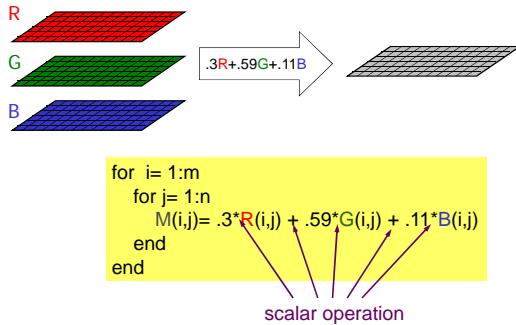
Averaging the RGB values to get a gray value



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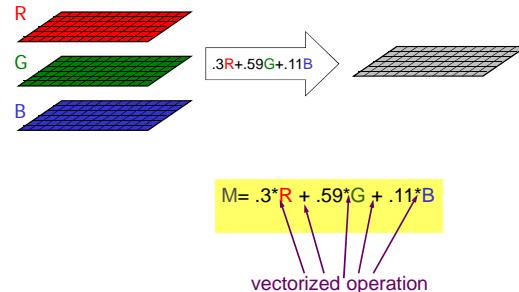
Averaging the RGB values to get a gray value



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Averaging the RGB values to get a gray value



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[showToGrayscale.m](#)

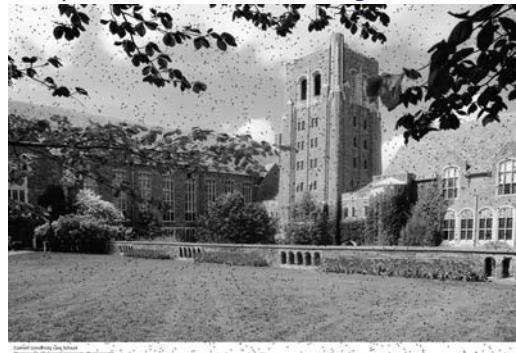
Matlab has a built-in function to convert from color to grayscale, resulting in a 2-d array:

$B = \text{rgb2gray}(A)$

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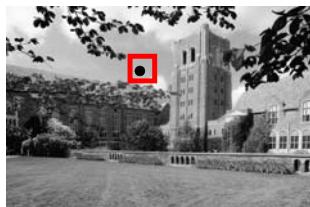
Clean up “noise” — median filtering



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Dirt in the image!



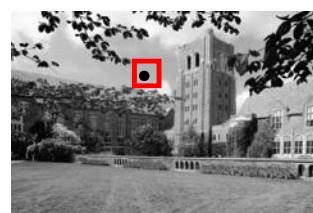
Note how the “dirty pixels” look out of place

| | | | | | |
|-----|-----|-----|-----|-----|-----|
| 150 | 149 | 152 | 153 | 152 | 155 |
| 151 | 150 | 153 | 154 | 153 | 156 |
| 153 | 2 | 3 | 156 | 155 | 158 |
| 154 | 2 | 1 | 157 | 156 | 159 |
| 156 | 154 | 158 | 159 | 158 | 161 |
| 157 | 156 | 159 | 160 | 159 | 162 |

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What to do with the dirty pixels?



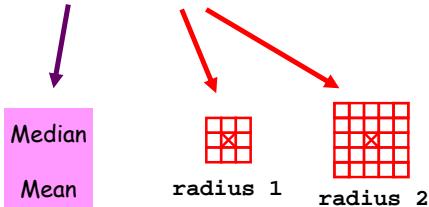
Assign “typical” neighborhood gray values to “dirty pixels”

| | | | | | |
|-----|-----|-----|-----|-----|-----|
| 150 | 149 | 152 | 153 | 152 | 155 |
| 151 | 150 | 153 | 154 | 153 | 156 |
| 153 | ? | ? | 156 | 155 | 158 |
| 154 | ? | ? | 157 | 156 | 159 |
| 156 | 154 | 158 | 159 | 158 | 161 |
| 157 | 156 | 159 | 160 | 159 | 162 |

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What are “typical neighborhood gray values”?



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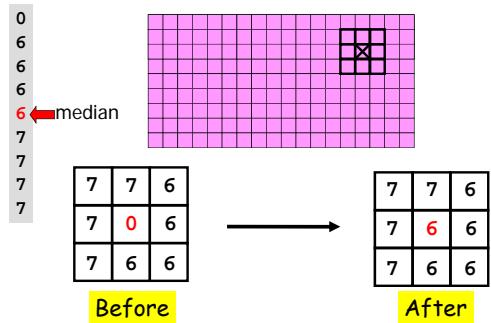
Median Filtering

- Visit each pixel
- Replace its gray value by the median of the gray values in the “neighborhood”

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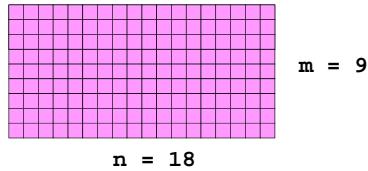
Using a radius 1 “neighborhood”



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Visit every pixel; compute its new value.



$n = 18$

```
for i=1:m
    for j=1:n
        Compute new gray value for pixel (i,j).
    end
end
```

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What we need...

- (1) A function that computes the median value in a 2-dimensional array C:
- ```
m = medVal(C)
```
- (2) A function that builds the filtered image by using median values of radius r neighborhoods:
- ```
B = medFilter(A,r)
```

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Computing the median

x : 21 89 36 28 19 88 43

x = sort(x)

x : 19 21 28 36 43 88 89

n = length(x); % n = 7

m = ceil(n/2); % m = 4

med = x(m); % med = 36

If n is even, then use : med = x(m)/2 + x(m+1)/2

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Median of a 2D array



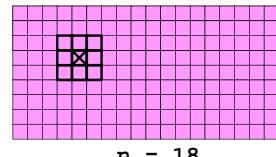
```
function med = medVal(C)
[nr,nc] = size(C);
x = zeros(1,nr*nc);
for r=1:nr
    x((r-1)*nc+1:r*nc) = C(r,:);
end
%Compute median of x and assign to med
%
```

See medVal.m

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Back to filtering...

 $m = 9$ $n = 18$

```
for i=1:m
    for j=1:n
        Compute new gray value for pixel (i,j)
    end
end
```

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```
function B = medFilter(A,r)
% B from A via median filtering
% with radius r neighborhoods.

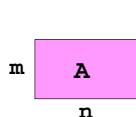
[m,n] = size(A);
B = uint8(zeros(m,n));
for i=1:m
    for j=1:n
        C = pixel (i,j) neighborhood
        B(i,j) = medVal(C);
    end
end
```

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The Pixel (i,j) Neighborhood

```
iMin = max(1,i-r)
iMax = min(m,i+r)
jMin = max(1,j-r)
jMax = min(n,j+r)
C = A(iMin:iMax,jMin:jMax)
```



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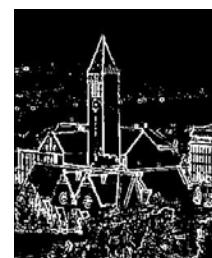
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 $B = \text{medianFilter}(A,3)$ 

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Finding Edges



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What is an edge?

Near an edge, grayness values change abruptly

```
200 200 200 200 200 200
200 200 200 200 200 100
200 200 200 200 100 100
200 200 200 100 100 100
200 200 100 100 100 100
200 100 100 100 100 100
```



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General plan for showing the edges in in image

- Identify the “edge pixels”
- Highlight the edge pixels
 - make edge pixels white; make everything else black

```
200 200 200 200 200 200
200 200 200 200 200 100
200 200 200 200 100 100
200 200 200 100 100 100
200 200 100 100 100 100
200 100 100 100 100 100
```



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General plan for showing the edges in in image

- Identify the “edge pixels”
- Highlight the edge pixels
 - make edge pixels white; make everything else black

BLACK **WHITE**

```
200 200 200 200 200 200
200 100 200 200 200 100
200 200 200 200 100 100
200 200 200 100 100 100
200 200 100 100 100 100
200 100 100 100 100 100
```

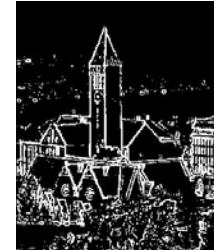
WHITE **BLACK**



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Finding Edges



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The Rate-of-Change-Array

Suppose **A** is an image array with integer values between 0 and 255.

Let **B(i,j)** be the maximum difference between and its eight neighbors.

So **B(i,j)** is the maximum value in

| | | |
|--|-------------------------------------|-----------------------|
| <code>A(max(1,i-1):min(m,i+1),...</code> | <code>max(1,j-1):min(n,j+1))</code> | <code>- A(i,j)</code> |
|--|-------------------------------------|-----------------------|

Neighborhood of A(i,j)

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Rate-of-change example

| | | |
|----|----|----|
| 90 | 81 | 65 |
| 62 | 60 | 59 |
| 56 | 57 | 58 |

Rate-of-change at middle pixel is 30

Be careful! In “uint8 arithmetic”
57 - 60 is 0

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```

function Edges(jpgIn,jpgOut,tau)
% jpgOut is the "edge diagram" of image jpgIn.
% At each pixel, if rate-of-change > tau
% then the pixel is considered to be on an edge.

A = rgb2gray(imread(jpgIn));           Built-in function to
[m,n] = size(A);                     convert to grayscale.
B = uint8(zeros(m,n));                Returns 2-d array.

for i = 1:m
    for j = 1:n

        B(i,j) = ??????

    end
end

```

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Recipe for rate-of-change $B(i,j)$

```

% The 3-by-3 subarray that includes A(i,j)
% and its 8 neighbors (for an interior pixel)
Neighbors = A(i-1:i+1,j-1:j+1);

% Subtract A(i,j) from each entry
Diff= abs(double(Neighbors) - double(A(i,j)));

% Compute largest value in each column
colMax = max(Diff);
% Compute the max of the column max's
B(i,j) = max(colMax);

```

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```

function Edges(jpgIn,jpgOut,tau)
% jpgOut is the "edge diagram" of image jpgIn.
% At each pixel, if rate-of-change > tau
% then the pixel is considered to be on an edge.

A = rgb2gray(imread(jpgIn));
[m,n] = size(A);
B = uint8(zeros(m,n));
for i = 1:m
    for j = 1:n
        Neighbors = A(max(1,i-1):min(i+1,m), ...
                      max(1,j-1):min(j+1,n));
        B(i,j)=max(max(abs(double(Neighbors)- ...
                      double(A(i,j)))));

        if B(i,j) > tau
            B(i,j) = 255;
        end
    end
end
imwrite(B,jpgOut,'jpg')

```

imwrite(B,jpgOut,'jpg')

Edge finding: Effect of edge threshold, τ  τ ——————>

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