

Counterfactual Model for Online Systems

CS 7792 - Fall 2016

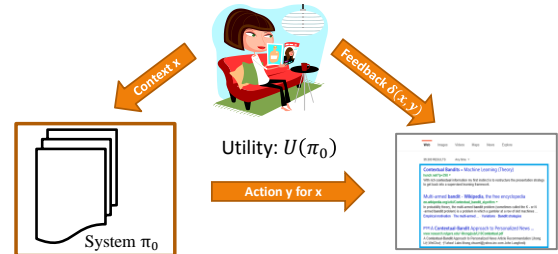
Thorsten Joachims

Department of Computer Science & Department of Information Science
Cornell University



Imbens, Rubin, Causal Inference for Statistical Social Science, 2015. Chapters 1,3,12.

Interactive System Schematic



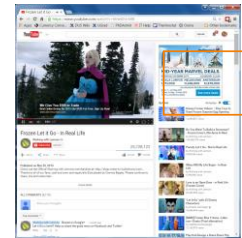
News Recommender

- Context x :
 - User
- Action y :
 - Portfolio of newsarticles
- Feedback $\delta(x, y)$:
 - Reading time in minutes



Ad Placement

- Context x :
 - User and page
- Action y :
 - Ad that is placed
- Feedback $\delta(x, y)$:
 - Click / no-click



Search Engine

- Context x :
 - Query
- Action y :
 - Ranking
- Feedback $\delta(x, y)$:
 - win/loss against baseline in interleaving



Log Data from Interactive Systems

- Data
 - context
 - π_0 action
 - reward / loss
$$S = ((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n))$$
 - Partial Information (aka "Contextual Bandit") Feedback
- Properties
 - Contexts x_i drawn i.i.d. from unknown $P(X)$
 - Actions y_i selected by existing system π_0 : $X \rightarrow Y$
 - Feedback δ_i from unknown function δ : $X \times Y \rightarrow \mathfrak{R}$

[Zadrozny et al., 2003][Langford & Li], [Bottou, et al., 2014]

Goal

- Use interaction log data

$$S = ((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n))$$

for evaluation of system π :

- Estimate online measures of some system π offline.
- System π can be different from π_0 that generated log.

Evaluation: Outline

- Evaluating Online Metrics Offline
 - A/B Testing (on-policy)
 - Counterfactual estimation from logs (off-policy)
- Approach 1: "Model the world"
 - Estimation via reward prediction
- Approach 2: "Model the bias"
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Online Performance Metrics

Example metrics

- CTR
- Revenue
- Time-to-success
- Interleaving
- Etc.

→ Correct choice depends on application and is not the focus of this lecture.

This lecture:

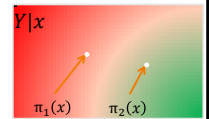
Metric encoded as $\delta(x, y)$ [click/payoff/time for (x,y) pair]

System

- Definition [Deterministic Policy]:
Function

$$y = \pi(x)$$

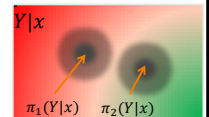
that picks action y for context x .



- Definition [Stochastic Policy]:
Distribution

$$\pi(y|x)$$

that samples action y given context x



System Performance

Definition [Utility of Policy]:

The expected reward / utility $U(\pi)$ of policy π is

$$U(\pi) = \int \int \delta(x, y) \pi(y|x) P(x) dx dy$$



Online Evaluation: A/B Testing

Given $S = ((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n))$ collected under π_0 ,

$$\hat{U}(\pi_0) = \frac{1}{n} \sum_{i=1}^n \delta_i$$

→ A/B Testing

Deploy π_1 : Draw $x \sim P(X)$, predict $y \sim \pi_1(Y|x)$, get $\delta(x, y)$

Deploy π_2 : Draw $x \sim P(X)$, predict $y \sim \pi_2(Y|x)$, get $\delta(x, y)$

⋮

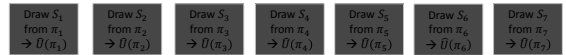
Deploy $\pi_{|H|}$: Draw $x \sim P(X)$, predict $y \sim \pi_{|H|}(Y|x)$, get $\delta(x, y)$

Pros and Cons of A/B Testing

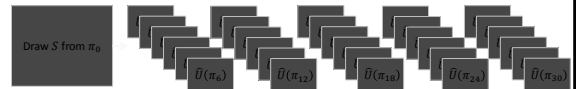
- Pro
 - User centric measure
 - No need for manual ratings
 - No user/expert mismatch
- Cons
 - Requires interactive experimental control
 - Risk of fielding a bad or buggy π_i
 - Number of A/B Tests limited
 - Long turnaround time

Evaluating Online Metrics Offline

- Online: On-policy A/B Test



- Offline: Off-policy Counterfactual Estimates

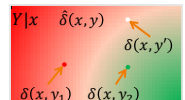


Evaluation: Outline

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Approach 1: Reward Predictor

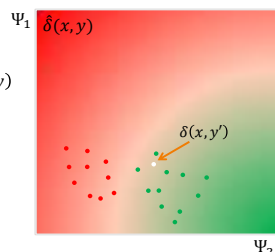
- Idea:
 - Use $S = ((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n))$ from π_0 to estimate reward predictor $\hat{\delta}(x, y)$
- Deterministic π : Simulated A/B Testing with predicted $\hat{\delta}(x, y)$
 - For actions $y'_i = \pi(x_i)$ from new policy π , generate predicted log $S' = ((x_1, y'_1, \hat{\delta}(x_1, y'_1)), \dots, (x_n, y'_n, \hat{\delta}(x_n, y'_n)))$
 - Estimate performance of π via $\hat{U}_{rp}(\pi) = \frac{1}{n} \sum_{i=1}^n \hat{\delta}(x_i, y'_i)$
- Stochastic π : $\hat{U}_{rp}(\pi) = \frac{1}{n} \sum_{i=1}^n \sum_y \hat{\delta}(x_i, y) \pi(y|x_i)$



Regression for Reward Prediction

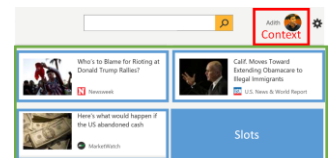
Learn $\hat{\delta}: x \times y \rightarrow \mathcal{R}$

1. Represent via features $\Psi(x, y)$
2. Learn regression based on $\Psi(x, y)$ from S collected under π_0
3. Predict $\hat{\delta}(x, y')$ for $y' = \pi(x)$ of new policy π

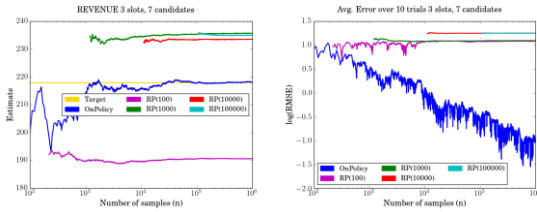


News Recommender: Exp Setup

- Context x : User profile
- Action y : Ranking
 - Pick from 7 candidates to place into 3 slots
- Reward δ : “Revenue”
 - Complicated hidden function
- Logging policy π_0 : Non-uniform randomized logging system
 - Placket-Luce “explore around current production ranker”



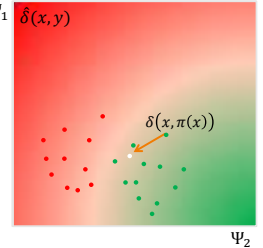
News Recommender: Results



RP is inaccurate even with more training and logged data

Problems of Reward Predictor

- Modeling bias
 - choice of features and model
- Selection bias
 - π_0 's actions are over-represented



$$\rightarrow \hat{U}_{rp}(\pi) = \frac{1}{n} \sum_i \delta(x_i, \pi(x_i))$$

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Approach "Model the Bias"

- Idea:
 - Fix the mismatch between the distribution $\pi_0(Y|x)$ that generated the data and the distribution $\pi(Y|x)$ we aim to evaluate.

$$U(\pi_0) = \int \int \delta(x, y) \pi_0(y|x) P(x) dx dy$$

Counterfactual Model

- Example: Treating Heart Attacks
 - Treatments: Y
 - Bypass / Stent / Drugs
 - Chosen treatment for patient x_i : y_i
 - Outcomes: δ_i
 - 5-year survival: 0 / 1
 - Which treatment is best?

Patients $x_i \in \{1, \dots, n\}$	Bypass	Stent	Drugs
	0	1	1
0	0	1	1
1	1	1	0
0	1	1	0
1	1	1	0

Counterfactual Model

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Counterfactual Model

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 - Chosen treatment for patient x_i : y_i
 - Outcomes: δ_i
 - 5-year survival: 0 / 1
 - Which treatment is best?
 - Everybody Drugs
 - Everybody Stent
 - Everybody Bypass
- Drugs 3/4, Stent 2/3, Bypass 2/4 – really?

Patients $x_i, i \in \{1, \dots, n\}$	Treatments		
	Bypass	Stent	Drugs
0	1	1	0
1	0	1	1
1	1	1	0
0	1	0	0
1	1	1	1

Treatment Effects

- Average Treatment Effect of Treatment y
 - $U(y) = \frac{1}{n} \sum_i \delta(x_i, y)$
- Example
 - $U(\text{bypass}) = \frac{4}{11}$
 - $U(\text{stent}) = \frac{6}{11}$
 - $U(\text{drugs}) = \frac{3}{11}$

Patients	Treatments			Outcome
	Bypass	Stent	Drugs	
0	1	1	0	0
1	1	1	0	1
0	0	0	1	0
0	0	0	1	1
1	1	0	0	0
1	0	0	1	1
0	1	1	0	0
0	1	1	0	0
1	1	1	0	0
1	1	1	0	0

Assignment Mechanism

- Probabilistic Treatment Assignment
 - For patient i : $\pi_0(Y_i = y | x_i)$
 - Selection Bias
- Inverse Propensity Score Estimator
 - $\hat{U}_{ips}(y) = \frac{1}{n} \sum_i \frac{\mathbb{1}\{y_i = y\}}{p_i} \delta(x_i, y_i)$
 - Propensity: $p_i = \pi_0(Y_i = y_i | x_i)$
 - Unbiased: $E[\hat{U}(y)] = U(y)$, if $\pi_0(Y_i = y | x_i) > 0$ for all i
- Example
 - $\hat{U}(\text{drugs}) = \frac{1}{11} \left(\frac{1}{0.8} + \frac{1}{0.7} + \frac{1}{0.8} + \frac{0}{0.1} \right) = 0.36 < 0.75$

Patients	Propensity $\pi_0(Y_i = y x_i)$			Treatments		
	Bypass	Stent	Drugs	Bypass	Stent	Drugs
0.3	0.6	0.1	0	1	0	0
0.5	0.4	0.1	1	1	0	0
0.1	0.1	0.8	0	0	1	1
0.6	0.3	0.1	0	0	0	0
0.2	0.5	0.7	0	1	1	1
0.7	0.2	0.1	1	0	0	0
0.1	0.1	0.8	1	0	1	1
0.1	0.8	0.1	0	1	0	0
0.3	0.3	0.4	0	1	0	0
0.3	0.6	0.1	1	1	0	0
0.4	0.4	0.2	1	1	0	0

Experimental vs Observational

- Controlled Experiment
 - Assignment Mechanism under our control
 - Propensities $p_i = \pi_0(Y_i = y_i | x_i)$ are known by design
 - Requirement: $\forall y: \pi_0(Y_i = y | x_i) > 0$ (probabilistic)
- Observational Study
 - Assignment Mechanism not under our control
 - Propensities p_i need to be estimated
 - Estimate $\hat{\pi}_0(Y_i | z_i) = \pi_0(Y_i | x_i)$ based on features z_i
 - Requirement: $\hat{\pi}_0(Y_i | z_i) = \hat{\pi}_0(Y_i | \delta_i, z_i)$ (unconfounded)

Conditional Treatment Policies

- Policy (deterministic)
 - Context x_i describing patient
 - Pick treatment y_i based on x_i : $y_i = \pi(x_i)$
 - Example policy:
 - $\pi(A) = \text{drugs}, \pi(B) = \text{stent}, \pi(C) = \text{bypass}$
- Average Treatment Effect
 - $U(\pi) = \frac{1}{n} \sum_i \delta(x_i, \pi(x_i))$
- IPS Estimator
 - $\hat{U}_{ips}(\pi) = \frac{1}{n} \sum_i \frac{\mathbb{1}\{y_i = \pi(x_i)\}}{p_i} \delta(x_i, y_i)$

Patients	Treatments			Context X
	Bypass	Stent	Drugs	
0	1	0	0	B
1	1	0	0	C
0	0	0	1	A
0	0	0	1	B
0	1	1	1	A
1	1	0	0	B
0	1	0	1	A
0	1	0	0	C
0	1	0	0	A
1	1	0	0	C
1	1	0	0	B

Stochastic Treatment Policies

- Policy (stochastic)
 - Context x_i describing patient
 - Pick treatment y based on x_i : $\pi(Y | x_i)$
- Note
 - Assignment Mechanism is a stochastic policy as well!
- Average Treatment Effect
 - $U(\pi) = \frac{1}{n} \sum_i \sum_y \delta(x_i, y) \pi(y | x_i)$
- IPS Estimator
 - $\hat{U}(\pi) = \frac{1}{n} \sum_i \frac{\pi(y_i | x_i)}{p_i} \delta(x_i, y_i)$

Patients	Treatments			Context X
	Bypass	Stent	Drugs	
0	1	0	0	B
1	1	0	0	C
0	0	0	1	A
0	0	0	1	B
0	1	1	1	A
1	1	0	0	B
0	1	0	1	A
0	1	0	0	C
0	1	0	0	A
1	1	0	0	C
1	1	0	0	B

Counterfactual Model = Logs

Recorded in Log	
Context x_i	
Treatment y_i	
Outcome δ_i	
Propensities p_i	
New Policy π	
T-effect $U(\pi)$	Average quality of new policy.

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System Evaluation via Inverse Propensity Scoring

Definition [IPS Utility Estimator]:

Given $S = ((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n))$ collected under π_0 ,

$$\hat{U}_{IPS}(\pi) = \frac{1}{n} \sum_{i=1}^n \delta_i \frac{\pi(y_i | x_i)}{\pi_0(y_i | x_i)}$$

Propensity p_i

→ Unbiased estimate of utility for any π , if propensity nonzero whenever $\pi(y_i | x_i) > 0$.

Note:

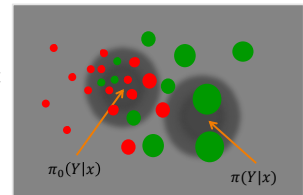
if $\pi = \pi_0$, then online A/B Test with $\hat{U}_{IPS}(\pi_0) = \frac{1}{n} \sum_i \delta_i$
 → Off-policy vs. On-policy estimation.

[Horvitz & Thompson, 1952] [Rubin, 1983] [Zadrozny et al., 2003] [Li et al., 2011]

Illustration of IPS

IPS Estimator:

$$\hat{U}_{IPS}(\pi) = \frac{1}{n} \sum_i \frac{\pi(y_i | x_i)}{\pi_0(y_i | x_i)} \delta_i$$

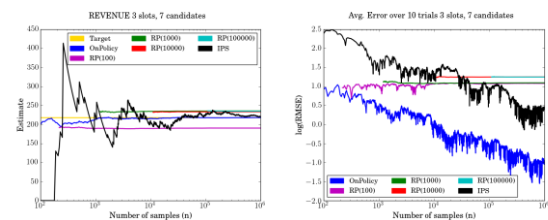


IPS Estimator is Unbiased

$$\begin{aligned} E[\hat{U}(\pi)] &= \frac{1}{n} \sum_{x_1, y_1} \dots \sum_{x_n, y_n} \left[\sum_t \frac{\pi(y_t | x_t)}{\pi_0(y_t | x_t)} \delta(x_t, y_t) \right] \pi_0(y_1 | x_1) \dots \pi_0(y_n | x_n) P(x_1) \dots P(x_n) \\ &= \frac{1}{n} \sum_{x_1, y_1} \pi_0(y_1 | x_1) P(x_1) \dots \sum_{x_n, y_n} \pi_0(y_n | x_n) P(x_n) \left[\sum_t \frac{\pi(y_t | x_t)}{\pi_0(y_t | x_t)} \delta(x_t, y_t) \right] \\ &= \frac{1}{n} \sum_t \sum_{x_t, y_t} \pi_0(y_t | x_t) P(x_t) \dots \sum_{x_n, y_n} \pi_0(y_n | x_n) P(x_n) \left[\frac{\pi(y_t | x_t)}{\pi_0(y_t | x_t)} \delta(x_t, y_t) \right] \\ &= \frac{1}{n} \sum_t \sum_{x_t, y_t} \pi_0(y_t | x_t) P(x_t) \left[\frac{\pi(y_t | x_t)}{\pi_0(y_t | x_t)} \delta(x_t, y_t) \right] \\ &= \frac{1}{n} \sum_t \sum_{x_t, y_t} \pi(y_t | x_t) P(x_t) \delta(x_t, y_t) = \frac{1}{n} \sum_t U(\pi) = U(\pi) \end{aligned}$$

Probabilistic Assignment

News Recommender: Results



IPS eventually beats RP; variance decays as $O\left(\frac{1}{\sqrt{n}}\right)$

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