

# Machine Learning Theory (CS 6783)

## Lecture 2 : Learning Frameworks, Examples

### 1 Setting up learning problems

#### 1. $\mathcal{X}$ : instance space or input space

Examples:

- Computer Vision: Raw  $M \times N$  image vectorized  $\mathcal{X} = [0, 255]^{M \times N}$ , SIFT features (typically  $\mathcal{X} \subseteq \mathbb{R}^d$ )
- Speech recognition: Mel Cepstral co-efficients  $\mathcal{X} \subset \mathbb{R}^{12 \times \text{length}}$
- Natural Language Processing: Bag-of-words features ( $\mathcal{X} \subset \mathbb{N}^{\text{document size}}$ ), n-grams

#### 2. $\mathcal{Y}$ : Outcome space, label space

Examples: Binary classification  $\mathcal{Y} = \{\pm 1\}$ , multiclass classification  $\mathcal{Y} = \{1, \dots, K\}$ , regression  $\mathcal{Y} \subset \mathbb{R}$ )

#### 3. $\ell : \mathcal{Y} \times \mathcal{Y} \mapsto \mathbb{R}$ : loss function (measures prediction error)

Examples: Classification  $\ell(y', y) = \mathbb{1}_{\{y' \neq y\}}$ , Support vector machines  $\ell(y', y) = \max\{0, 1 - y' \cdot y\}$ , regression  $\ell(y', y) = (y - y')^2$

#### 4. $\mathcal{F} \subset \mathcal{Y}^{\mathcal{X}}$ : Model/ Hypothesis class (set of functions from input space to outcome space)

Examples:

- Linear classifier:  $\mathcal{F} = \{x \mapsto \text{sign}(f^\top x) : f \in \mathbb{R}^d\}$
- Linear SVM:  $\mathcal{F} = \{x \mapsto f^\top x : f \in \mathbb{R}^d, \|f\|_2 \leq R\}$
- Neural Networks (deep learning):  $\mathcal{F} = \{x \mapsto \sigma(W_{out}\sigma(W_K\sigma(\dots\sigma(W_2(W_1\sigma(W_{in}x))))))\}$  where  $\sigma$  is some non-linear transformation (Eg. ReLU)

Learner observes sample:  $S = (x_1, y_1), \dots, (x_n, y_n)$

**Learning Algorithm :** (forecasting strategy, estimation procedure)

$$\hat{\mathbf{y}} : \mathcal{X} \times \bigcup_{t=1}^{\infty} (\mathcal{X} \times \mathcal{Y})^t \mapsto \mathcal{Y}$$

Given new input instance  $x$  the learning algorithm predicts  $\hat{\mathbf{y}}(x, S)$ . When context is clear (ie. sample  $S$  is understood) we will fudge notation and simply use notation  $\hat{\mathbf{y}}(\cdot) = \hat{\mathbf{y}}(\cdot, S)$ .  $\hat{\mathbf{y}}$  is the predictor returned by the learning algorithm.

Example: linear SVM Learning algorithm solves the optimization problem:

$$\mathbf{w}_{\text{SVM}} = \underset{\mathbf{w}}{\operatorname{argmin}} \sum_{t=1}^n \max\{0, 1 - y_t \mathbf{w}^\top x_t\} + \lambda \|\mathbf{w}\|$$

and the predictor is  $\hat{\mathbf{y}}(x) = \hat{\mathbf{y}}(x, S) = \mathbf{w}_{\text{SVM}}^\top x$

### 1.1 PAC framework

$$\mathcal{Y} = \{\pm 1\}, \quad \ell(y', y) = \mathbf{1}_{\{y' \neq y\}}$$

Input instances generated as  $x_1, \dots, x_n \sim D_X$  where  $D_X$  is some unknown distribution over input space. The labels are generated as

$$y_t = f^*(x_t)$$

where target function  $f^* \in \mathcal{F}$ . Learning algorithm only gets sample  $S$  and does not know  $f^*$  or  $D_X$ .

Goal: Find  $\hat{\mathbf{y}}$  that minimizes

$$\mathbb{P}_{x \sim D_X} (\hat{\mathbf{y}}(x) \neq f^*(x))$$

### 1.2 Non-parametric Regression

$$\mathcal{Y} \subseteq \mathbb{R}, \quad \ell(y', y) = (y' - y)^2$$

Input instances generated as  $x_1, \dots, x_n \sim D_X$  where  $D_X$  is some unknown distribution over input space. The labels are generated as

$$y_t = f^*(x_t) + \varepsilon_t \quad \text{where } \varepsilon_t \sim N(0, \sigma)$$

where target function  $f^* \in \mathcal{F}$ . Learning algorithm only gets sample  $S$  and does not know  $f^*$  or  $D_X$ .

Goal: Find  $\hat{\mathbf{y}}$  that minimizes

$$\mathbb{E}_{x \sim D_X} [(\hat{\mathbf{y}}(x) - f^*(x))^2] =: \|\hat{\mathbf{y}} - f^*\|_{L_2(D_X)}$$

### 1.3 Statistical Learning (Agnostic PAC)

Generic  $\mathcal{X}$ ,  $\mathcal{Y}$ ,  $\ell$  and  $\mathcal{F}$

Samples generated as  $(x_1, y_1), \dots, (x_n, y_n) \sim D$  where  $D$  is some unknown distribution over  $\mathcal{X} \times \mathcal{Y}$ .

Goal: Find  $\hat{\mathbf{y}}$  that minimizes

$$\mathbb{E}_{(x,y) \sim D} [\ell(\hat{\mathbf{y}}(x), y)] - \inf_{f \in \mathcal{F}} \mathbb{E}_{(x,y) \sim D} [\ell(f(x), y)]$$

For any mapping  $g : \mathcal{X} \mapsto \mathcal{Y}$  we shall use the notation  $L_D(g) = \mathbb{E}_{(x,y) \sim D} [\ell(g(x), y)]$  and so our goal can be re-written as:

$$L_D(\hat{\mathbf{y}}) - \inf_{f \in \mathcal{F}} L_D(f)$$

Remarks:

1.  $\hat{\mathbf{y}}$  is a random quantity as it depends on the sample
2. Hence formal statements we make will be in high probability over the sample or in expectation over draw of samples

## 1.4 Online Learning

For  $t = 1$  to  $n$

- (a) Input instance  $x_t \in \mathcal{X}$  is produced
- (b) Learning algorithm outputs prediction  $\hat{y}_t$
- (c) True outcome  $y_t$  is revealed to learner

End For

One can think of  $\hat{y}_t = \hat{\mathbf{y}}_t(x_t, ((x_1, y_1), \dots, (x_{t-1}, y_{t-1})))$ .

Goal: Find learning algorithm  $\hat{\mathbf{y}}$  that minimizes regret w.r.t. hypothesis class  $\mathcal{F} \subset \mathcal{Y}^{\mathcal{X}}$  given by,

$$\text{Reg}_n = \frac{1}{n} \sum_{t=1}^n \ell(\hat{y}_t, y_t) - \inf_{f \in \mathcal{F}} \frac{1}{n} \sum_{t=1}^n \ell(f(x_t), y_t)$$

## 2 Example 1: Classification using Finite Class, Realizable Setting

In this section we consider the classification setting where  $\mathcal{Y} = \{\pm 1\}$  and  $\ell(y', y) = \mathbf{1}\{y' \neq y\}$ . We further make the realizability assumption meaning  $y_t = f^*(x_t)$  where  $f^*$  is obviously not known to the learner.

### 2.1 Online Framework

The online framework is just as described earlier with the realizability assumption added in. That is, at every round the true label  $y_t$  revealed to us is set as  $y_t = f^*(x_t)$  for some fixed  $f^*$  not known to the learning algorithm. However  $x_t$ 's can be presented to us arbitrarily. First note that under the realizability assumption, we have that

$$\min_{f \in \mathcal{F}} \frac{1}{n} \sum_{t=1}^n \ell(f(x_t), y_t) = \frac{1}{n} \sum_{t=1}^n \mathbf{1}\{f^*(x_t) \neq y_t\} = 0$$

Hence the aim in such a framework is to simply minimize number of mistakes  $\sum_{t=1}^n \ell(\hat{y}_t, y_t)$  and prove mistake bounds.

Now say  $\mathcal{F} = \{f_1, \dots, f_N\}$ , a finite set of hypothesis. What strategy can we provide for this problem? How well does it work?

If we simply pick some hypothesis that has not made a mistake so far, such an algorithm can make a large number of mistakes (Eg. as many as  $N$ ). A simple strategy that works in this scenario is the following. At any point  $t$ , we have observed  $x_1, \dots, x_{t-1}$  and labels  $y_1, \dots, y_{t-1}$ . Now say

$$\mathcal{F}_t = \{f \in \mathcal{F} : \forall i \in [t-1], f(x_i) = y_i\}.$$

Now given  $x_t$ , we pick  $\hat{y}_t = \text{sign}(\sum_{f \in \mathcal{F}_t} f(x_t))$ . That is we go with the majority of predictions by hypothesis in  $\mathcal{F}_t$ . How well does this algorithm work?

**Claim 1.** For any sequence  $x_1, \dots, x_n$ , the above algorithm makes at most  $\lceil \log_2 N \rceil$  number of mistakes.

*Proof.* Notice that each time we make a mistake, ie.  $\text{sign}(\sum_{f \in \mathcal{F}_t} f(x_t)) \neq y_t$ , then we know that at least half the number of functions in  $\mathcal{F}_t$  are wrong and so each time we make a mistake,  $|\mathcal{F}_{t+1}| \leq |\mathcal{F}_t|/2$  and hence, we can make at most  $\log_2 N$  number of mistakes.  $\square$

That is the average error is  $\frac{\log_2 N}{n}$ .

## 2.2 PAC Framework

In the PAC framework,  $x_1, \dots, x_n$  are drawn iid from some fixed distribution  $D_{\mathcal{X}}$  and our goal is to minimize  $P_{x \sim D_{\mathcal{X}}}(\hat{y}(x) \neq f^*(x))$  either in expectation or high probability over sample  $\{x_1, \dots, x_n\}$ . Unlike the online setting, in the PAC setting one can simply pick any hypothesis that has not made any mistakes on training sample. That is,

$$\hat{y}(\cdot, S) = \operatorname{argmin}_{f \in \mathcal{F}} \sum_{(x_t, y_t) \in S} \mathbf{1}\{f(x_t) \neq y_t\}.$$

How well does this algorithm work? How should we analyze this?

Let us show a bound of error with high probability over samples. To this end we will use the so called Bernstein concentration bound.

**Fact:** Consider binary r.v.  $Z_1, \dots, Z_n$  drawn iid. Let  $\mu = \mathbb{E}[Z]$  be their expectation. We have the following bound on the average of these random variables. (notice that since  $Z$ 's are binary their variance is given by  $\mu - \mu^2$ )

$$P\left(\mu - \frac{1}{n} \sum_{t=1}^n Z_t > \theta\right) \leq \exp\left(-\frac{n\theta^2}{2\mu + \frac{\theta}{3}}\right)$$

Now for any  $f \in \mathcal{F}$ , let  $Z_t^f = \mathbf{1}\{f(x_t) \neq f^*(x_t)\}$  where  $x_t$  are drawn from  $D_{\mathcal{X}}$ . Note that  $\mathbb{E}[Z^f] = P_{x \sim D_{\mathcal{X}}}(f(x) \neq f^*(x))$ . Hence note that for any single  $f \in \mathcal{F}$ ,

$$P_S\left(P_{x \sim D_{\mathcal{X}}}(f(x) \neq f^*(x)) - \frac{1}{n} \sum_{t=1}^n \mathbf{1}\{f(x_t) \neq f^*(x_t)\} > \theta\right) \leq \exp\left(-\frac{n\theta^2}{2\mu + \frac{\theta}{3}}\right)$$

Let us write the R.H.S. above as  $\delta$ , and hence, rewriting, we have that with probability at least  $1 - \delta$  over sample,

$$P_{x \sim D_{\mathcal{X}}}(f(x) \neq f^*(x)) - \frac{1}{n} \sum_{t=1}^n \mathbf{1}\{f(x_t) \neq f^*(x_t)\} \leq \frac{\log(1/\delta)}{3n} + \sqrt{\frac{P_{x \sim D_{\mathcal{X}}}(f(x) \neq f^*(x)) \log(1/\delta)}{n}}$$

This upon further massaging (use inequality  $\sqrt{ab} \leq a/2 + b/2$ ) leads to the bound

$$P_{x \sim D_{\mathcal{X}}}(f(x) \neq f^*(x)) - \frac{2}{n} \sum_{t=1}^n \mathbf{1}\{f(x_t) \neq f^*(x_t)\} \leq \frac{2 \log(1/\delta)}{n}$$

Using union bound, we have that for any  $\delta > 0$ , with probability at least  $1 - \delta$  over sample, simultaneously,

$$\forall f \in \mathcal{F} \quad P_{x \sim D_{\mathcal{X}}}(f(x) \neq f^*(x)) - \frac{2}{n} \sum_{t=1}^n \mathbf{1}\{f(x_t) \neq f^*(x_t)\} \leq \frac{2 \log(|\mathcal{F}|/\delta)}{n}$$

Since  $\hat{y} \in \mathcal{F}$ , from the above we conclude that, for any  $\delta > 0$ , with probability at least  $1 - \delta$  over sample,

$$P_{x \sim D_{\mathcal{X}}}(\hat{y}(x) \neq f^*(x)) - \frac{2}{n} \sum_{t=1}^n \mathbf{1}\{\hat{y}(x_t) \neq f^*(x_t)\} \leq \frac{2 \log(|\mathcal{F}|/\delta)}{n}$$

But note that by realizability assumption and the definition of  $\hat{y}$ , we have that

$$\sum_{t=1}^n \mathbf{1}\{\hat{y} \neq f^*(x_t)\} = \sum_{t=1}^n \mathbf{1}\{\hat{y} \neq y_t\} = 0$$

and so, with probability at least  $1 - \delta$  over sample,

$$P_{x \sim D_{\mathcal{X}}}(\hat{y}(x) \neq f^*(x)) \leq \frac{2 \log(|\mathcal{F}|/\delta)}{n}$$

## 3 Example 2: Predicting Bits

### 3.1 Statistical Learning

We consider as a warmup example, the simplest statistical learning/prediction problem. That of learning coin flips ! Let us consider the case where we don't receive any input instance (or  $\mathcal{X} = \{\}$ ) and  $\mathcal{Y} = \{\pm 1\}$ . We receive  $\pm 1$  valued samples  $y_1, \dots, y_n \in \{\pm 1\}$  drawn iid from Bernoullis distribution with parameter  $p$  (ie.  $Y$  is  $+1$  with probability  $p$  and  $-1$  with probability  $1 - p$ ). Our loss function is the zero-one loss function  $\ell(y', y) = \mathbf{1}_{\{y' \neq y\}}$ . Recall that our goal in statistical learning is to minimize  $L_p(\hat{y}) - \inf_{f \in \{\pm 1\}} L_p(f)$ . (Effectively our only choice of  $\mathcal{F}$  for this problem is the set of constant mappings,  $\mathcal{F} = \{\pm 1\}$ ).

**Claim 2.** *Let  $\hat{y} = \text{sign}(\frac{1}{n} \sum_{t=1}^n y_t)$  be the prediction rule we use. For the problem above, one has the bound,*

$$L_p(\hat{y}) - \inf_{f \in \{\pm 1\}} L_p(f) \leq \sqrt{\log n/n}$$

*The prediction rule that enjoys the above bound is*

*Proof.* Now note that :

$$\begin{aligned}
L_p(\hat{y}) - \min_{f \in \{\pm 1\}} L_p(f) &= \mathbb{E}_{y \sim p} [\mathbf{1}_{\{y \neq \hat{y}\}}] - \min_{f \in \{\pm 1\}} \mathbb{E}_{y \sim p} [\mathbf{1}_{\{f \neq y\}}] \\
&= \mathbb{E}_{y \sim p} [\mathbf{1}_{\{y \neq \hat{y}\}}] - \mathbb{E}_{y \sim p} [\mathbf{1}_{\{\text{sign}(2p-1) \neq y\}}] \\
&= \mathbb{E}_{y \sim p} [\mathbf{1}_{\{y \neq \hat{y}\}}] - \frac{1}{n} \sum_{t=1}^n \mathbf{1}_{\{\hat{y} \neq y_t\}} + \frac{1}{n} \sum_{t=1}^n \mathbf{1}_{\{\hat{y} \neq y_t\}} - \mathbb{E}_{y \sim p} [\mathbf{1}_{\{\text{sign}(2p-1) \neq y\}}] \\
&\leq \mathbb{E}_{y \sim p} [\mathbf{1}_{\{y \neq \hat{y}\}}] - \frac{1}{n} \sum_{t=1}^n \mathbf{1}_{\{\hat{y} \neq y_t\}} + \frac{1}{n} \sum_{t=1}^n \mathbf{1}_{\{\text{sign}(2p-1) \neq y_t\}} - \mathbb{E}_{y \sim p} [\mathbf{1}_{\{\text{sign}(2p-1) \neq y\}}] \\
&\leq 2 \max_{f \in \{\pm 1\}} \left| \mathbb{E}_{y \sim p} [\mathbf{1}_{\{y \neq f\}}] - \frac{1}{n} \sum_{t=1}^n \mathbf{1}_{\{f \neq y_t\}} \right|
\end{aligned}$$

Hence we conclude that

$$P_S(L_p(\hat{y}) - \min_{f \in \{\pm 1\}} L_p(f) > \theta) \leq P \left( 2 \max_{f \in \{\pm 1\}} \left| \mathbb{E}_{y \sim p} [\mathbf{1}_{\{y \neq f\}}] - \frac{1}{n} \sum_{t=1}^n \mathbf{1}_{\{f \neq y_t\}} \right| > \theta \right)$$

Now we can bound the RHS above using Hoeffding/Bernstein bound + union bound over the two choices as

$$P_S(L_p(\hat{y}) - \min_{f \in \{\pm 1\}} L_p(f) > \theta) \leq 4 \exp(-2n\theta^2)$$

Written another way, we can claim that for any  $\delta > 0$ , with probability at least  $1 - \delta$ ,

$$L_p(\hat{y}) - \min_{f \in \{\pm 1\}} L_p(f) \leq \sqrt{\frac{\log(4/\delta)}{2n}}$$

□

### 3.2 Can we even hope to handle this problem in the online setting?