Generative Models for Classification

CS6780 - Advanced Machine Learning Spring 2019

> Thorsten Joachims Cornell University

Reading: Murphy 3.5, 4.1, 4.2, 8.6.1

Generative vs. Conditional vs. ERM

- **Empirical Risk Minimization**
 - $\begin{array}{lll} & \text{Find } h = \underset{h \in \mathcal{H}}{\operatorname{argmin}} \, Err_S(h) \text{ s.t. overfitting control} \\ & \text{Pro: directly estimate decision rule} \\ & \text{Con: need to commit to loss, input, and output before training} \end{array}$
- Discriminative Conditional Model
 - Find P(Y|X), then derive h(x) via Bayes rule
 - Pro: not yet committed to loss during training
 - Con: need to commit to input and output before training; learning conditional distribution is harder than learning decision rule
- · Generative Model
 - Find P(X,Y), then derive h(x) via Bayes rule
 - Pro: not yet committed to loss, input, or output during training; often computationally easy
 - Con: Needs to model dependencies in X

Bayes Decision Rule

- Assumption:
 - learning task P(X,Y)=P(Y|X) P(X) is known
- · Question:
 - Given instance x, how should it be classified to minimize prediction error?
- · Bayes Decision Rule:

$$h_{bayes(\vec{x})} = argmax_{y \in Y}[P(Y = y | X = \vec{x})]$$

Example: Modeling Flu Patients

• Data:

fever (h,l,n)	cough (y,n)	pukes (y,n)	flu?
high	yes	no	1
high	no	yes	1
low	yes	no	-1
low	yes	yes	1

• Approach: One model for flu, one for not-flu.

Bayes Theorem

- · It is possible to "switch" conditioning according to the following rule
- · Given any two random variables X and Y, it holds that

$$P(Y = y | X = x) = \frac{P(X = x | Y = y)P(Y = y)}{P(X = x)}$$

Note that

$$P(X=x) = \sum_{y \in Y} P(X=x|Y=y)P(Y=y)$$

Naïve Bayes' Classifier (Multivariate)

· Model for each class

$$P(X = \vec{x}|Y = +1) = \prod_{l=1}^{N} P(X_l = x_l|Y = +1)$$

$$P(X = \vec{x}|Y = -1) = \prod_{l=1}^{N} P(X_l = x_l|Y = -1)$$

	fever (h,l,n)	cough (y,n)	pukes (y,n)	flu?	
	high	yes	no	1	
	high	no	yes	1	
	low	yes	no	-1	
	low	yes	yes	1	
	high	no	ves	???	

Prior probabilities

$$P(Y=+1), P(Y=-1)$$

Classification rule:

$$h_{naive}(\vec{x}) = \underset{y \in \{+1,-1\}}{\operatorname{argmax}} \left\{ P(Y = y) \prod_{i=1}^{N} P(X_i = x_i | Y = y) \right\}$$

1

Estimating the Parameters of NB

high yes

yes

low

1

-1

yes ???

no

- Count frequencies in training data
 - n: number of training examples
 - n₊ / n₋ : number of pos/neg examples
 - #(X_i=x_i, y): number of times feature X_i takes value x_i for examples in class y

 - |X_i|: number of values attribute X_i can take
- Estimating P(Y)
 - Fraction of positive / negative examples in training data

$$\hat{P}(Y = +1) = \frac{n_+}{n} \qquad \hat{P}(Y = -1) = \frac{n_-}{n}$$

- Estimating P(X|Y)
 - Maximum Likelihood Estimate

and Estimate
$$\hat{P}(X_i = x_i | Y = y) = \frac{\#(X_i = x_i, y)}{n_y}$$

Smoothing with Laplace estimate

pplace estimate
$$\hat{P}(X_i = x_i | Y = y) = \frac{\#(X_i = x_i, y) + 1}{n_y + |X_i|}$$

Linear Discriminant Analysis

· Spherical Gaussian model with unit variance for each class

$$P(X = \vec{x}|Y = +1) \sim \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu}_{+})^{2}\right)$$
$$P(X = \vec{x}|Y = -1) \sim \exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu}_{-})^{2}\right)$$

· Prior probabilities

$$P(Y=+1), P(Y=-1)$$

· Classification rule

on rule
$$\begin{split} h_{LDA}(\vec{x}) &= \underset{y \in \{\pm 1, -1\}}{\operatorname{argmax}} \left\{ P(Y = y) exp\left(-\frac{1}{2}(\vec{x} - \vec{\mu}_y)^2\right) \right\} \\ &= \underset{y \in \{\pm 1, -1\}}{\operatorname{argmax}} \left\{ \log(P(Y = y)) - \frac{1}{2}(\vec{x} - \vec{\mu}_y)^2 \right\} \end{split}$$

Estimating the Parameters of LDA

- · Count frequencies in training data
 - $(\vec{x}_1,\vec{y}_1),\ldots,(\vec{x}_n,\vec{y}_n){\sim}P(X,Y)$: training data
 - n: number of training examples
 - $-n_{+}/n_{-}$: number of positive/negative training examples
- Estimating P(Y)
 - Fraction of pos / neg examples in training data

$$\hat{P}(Y = +1) = \frac{n_+}{n}$$
 $\hat{P}(Y = -1) = \frac{n_-}{n}$

Estimating class means

$$\vec{\mu}_{+} = \frac{1}{n_{+}} \sum_{\{i: y_{i} = 1\}} \vec{x}_{i} \qquad \quad \vec{\mu}_{-} = \frac{1}{n_{-}} \sum_{\{i: y_{i} = -1\}} \vec{x}_{i}$$

Naïve Bayes Classifier (Multinomial)

• Application: Text classification $(x = (w_1, ..., w_l)$ sequence)

$$\begin{array}{ll} \text{text} & \text{CS} \\ x_1 = (The, art, of, Programming) & +1 \\ x_2 = (Introduction, to, Calculus) & -1 \\ x_3 = (Introduction, to, Complexity, Theory) & +1 \\ x_4 = (Introduction, to, Programming) & ?? \\ \end{array}$$

Assumption

Position
$$P(X = x | Y = +1) = \prod_{i=1}^{l} P(W = w_i | Y = +1)$$

$$P(X = x | Y = -1) = \prod_{i=1}^{l} P(W = w_i | Y = -1)$$

· Classification Rule

$$h_{naive}(x) = \underset{y \in \{+1,-1\}}{\operatorname{argmax}} \left\{ P(Y = y) \prod_{i=1}^{l} P(W = w_i | Y = y) \right\}$$

Estimating the Parameters of Multinomial Naïve Bayes

- Count frequencies in training data
 - n: number of training examples
 - $-n_{+}/n_{.}$: number of
 - pos/neg examples
 - #(W=w, y): number of
 - times word w occurs in examples of class y
 - I₊/I₋: total number of words in pos/neg examples
 - | V |: size of vocabulary
- Estimating P(Y)

$$\hat{P}(Y = +1) = \frac{n_+}{n}$$
 $\hat{P}(Y = -1) = \frac{n_-}{n}$

• Estimating P(X|Y) (smoothing with Laplace estimate):

$$\hat{P}(X|Y) \text{ (smoothing with Laplace estimate)}$$

$$\hat{P}(W=w|Y=y) = \frac{\#(W=w,y)+1}{l_y+|V|}$$