Interactive Rendering of Translucent Objects

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Outline

- Motivation
- Background
- Preprocessing
- Rendering
- Results

Motivation

- Translucent objects = subsurface scattering
- Calculating subsurface scattering is expensive
- Observation: multiple scattering blurs and smoothes radiance

Motivation

- Low frequency can be taken advantage of
 - Global response
 - Long distance
 - Lots of scattering
 - Radiance can be calculated sparsely and interpolated
 - Local response
 - Short distance
 - Little scattering
 - Need to maintain detail for small neighborhood

Background

- Full BSSRDF: 8 dimensions - $S(x_i, \omega_i, x_o, \omega_o)$
- Diffuse subsurface scattering reflectance function: 4 dimensions

$$-R_d(x_i, x_o)$$

Background

• *R_d* relates incoming flux to outgoing diffuse radiance:

$$L^{\rightarrow}(x_o, \omega_o) = \frac{1}{\pi} F_t(\eta, \omega_o) B(x_o)$$
$$B(x_o) = \int_S E(x_i) R_d(x_i, x_o) dx_i$$
$$E(x_i) = \int_{\Omega_+(x_i)} L^{\leftarrow}(x_i, \omega_i) F_t(\eta, \omega_i) |N_i \cdot \omega_i| d\omega_i$$

Background

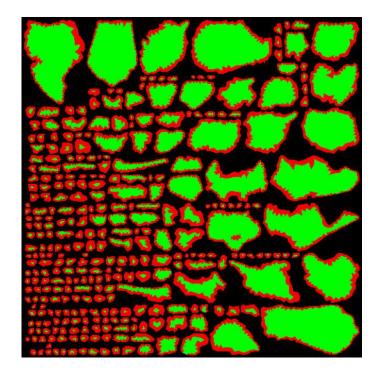
- R_d is very similar to G in radiosity
 - Both are *throughput factors* (discrete version in Galerkin radiosity is *form factor*)
- *G* only encodes geometric information; storage costs are too high for relighting
- *R_d* maintains light transport properties between any two points and can handle dynamic lighting

Preprocessing

- Need discrete formulation of $B(x_o)$
- Actually use 2 formulations with two sets of basis functions
 - Global basis: hat functions at object vertices
 - Local basis: Piecewise-constant functions corresponding to surface texels

Preprocessing - Geometry

• Split mesh up into chunks of nearly-planar triangles and build 2D texture atlas



Preprocessing – Global Response

- Scattering over long distances is smooth
- Vertex-to-vertex throughput factors are used $F_{ij} \approx R_d(v_i, v_j) \cdot \int_S \psi_i(x) dx \cdot \int_S \widetilde{\psi}(y) dy = \frac{A_i}{3} R_d(v_i, v_j)$ $B_j^g = \sum_i E_i F_{ij}$

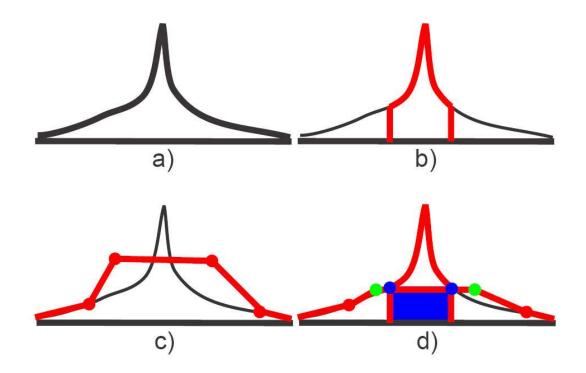
Preprocessing – Local Response

- Use texel-to-texel throughput factors to preserve details
- Modeled as 7 x 7 filter kernel

$$K_{(u,v)}(s,t) = A(u,v)R_d(x_c(u,v), x_c(s,t))$$

Preprocessing – Blending Local and Global

• Adding local and global results in twice the correct amount in direct illumination areas



Preprocessing – Blending Local and Global

- Direct illumination found along diagonal of form factor matrix *F*
- F^0 is F without direct illumination
- B(x) found by introducing B^d

$$B(x) = B^{l}(x) + B^{d}(x) + B^{g_{0}}(x)$$
$$B_{j}^{g_{0}} = \sum_{i} E_{i}^{g} F_{ij}^{0}$$

Preprocessing – Blending Local and Global

- Also need to blend border between local and global
- Calculate "correct" radiosity by generating 9 x 9 kernel
- Adjust weighting of global radiosity to minimize difference

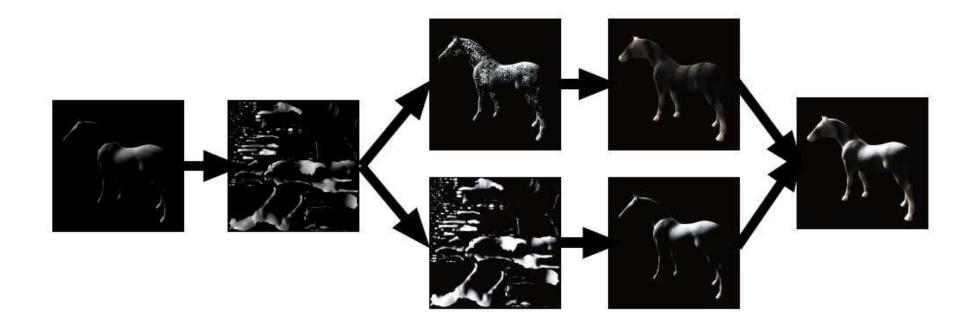
Rendering

• Compute direct illumination map

– Implemented with vertex shader

- Split processing into two branches: global and local
- Global and local responses combined by multi-texturing in hardware

Rendering



Rendering – Global Response

- Find irradiance at each vertex
- *B^g*(*y*) at intermediate surface point *y* is calculated by linear interpolation
- Surface radiosity can be modulated by texture, T_p

$$B_i^T = \frac{B_i^g}{T_p(v_i)}$$

Rendering – Local Response

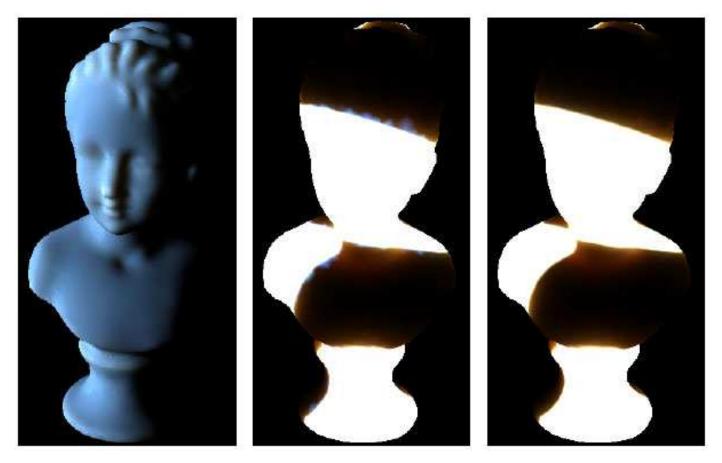
• Convolve illumination map with filter kernel of every texel

$$B^{l}(x) = K_{(u,v)}(s,t) \otimes E(s,t) = \sum_{(s,t) \in 7 \times 7} K_{(u,v)}(s,t) E(s,t)$$

• Initial implementation done in software

• Renderings done on dual 1.7 GHz Xeon with 1 GB RAM and GeForce3 video card

model	# vertices	#form factors	fps	illummap	local	global	display	total
horse	10000	16441460	2.3	29	149	33	371	431
horse textured	10000	12409116	2.7	29	145	302	33	364
bust	8574	4946764	5	24	147	144	28	199
bird	4000	1750862	5.6	16	139	86	26	180



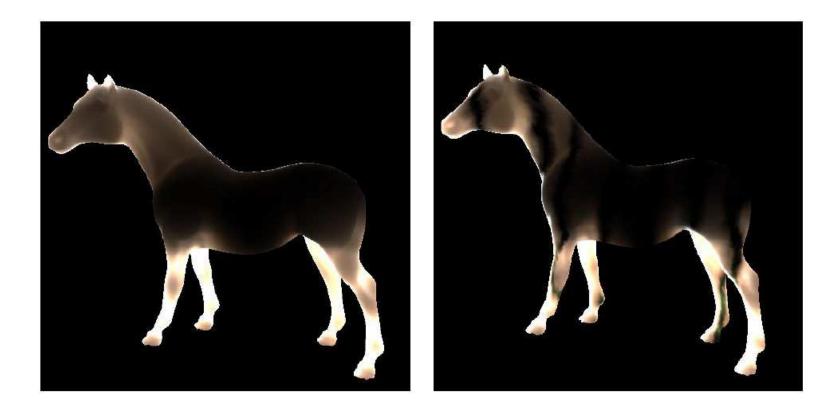
Middle: simple blending Right: optimized blending



Local response

Global response

Combined



With and without modulating texture



Skim milk?