

CS 611
Advanced Programming Languages

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Lecture 32
Type inference & ML polymorphism
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Type inference

Simple typed language:

$e ::= x \mid b \mid \text{fn } x:\tau. e \mid e_1 e_2 \mid e_1 \oplus e_2$
 $\mid \text{if } e_0 e_1 e_2 \mid \text{let } x=e_1 \text{ in } e_2$
 $\mid \text{rec } y:\tau_1 \rightarrow \tau_2. \text{fn } x.e$
 $\tau ::= \text{unit} \mid \text{bool} \mid \text{int} \mid \tau_1 \rightarrow \tau_2$

- Question: Do we really need to write down all the type declarations?

$e ::= x \mid b \mid \text{fn } x. e \mid e_1 e_2 \mid e_1 \oplus e_2$
 $\mid \text{if } e_0 e_1 e_2 \mid \text{let } x=e_1 \text{ in } e_2 \mid \text{rec } y. \text{fn } x.e$

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Typing rules

$e ::= x \mid b \mid \text{fn } x. e \mid e_1 e_2 \mid e_1 \oplus e_2$
 $\mid \text{if } e_0 e_1 e_2 \mid \text{let } x=e_1 \text{ in } e_2 \mid \text{rec } y. \text{fn } x.e$

$$\frac{\Gamma, x:\tau \vdash e:\tau'}{\Gamma \vdash \text{fn } x. e:\tau \rightarrow \tau'}$$

Problem: how
does type checker
construct proof?
Guess τ ?

$$\frac{\Gamma, y:\tau \rightarrow \tau', x:\tau \vdash e:\tau'}{\Gamma \vdash \text{rec } y. \text{fn } x. e:\tau \rightarrow \tau'}$$

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Example

let square = rec s.fn x z. z*z in
 (fn f.fn x.fn y.
 if (f x y)
 (f (square x) y)
 (f x (f x y)))

What is the type of this program?

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Example

let square = rec s.fn x z. z*z in
 (fn f.fn x.fn y.
 if (f x y)
 (f (square x) y)
 (f x (f x y)))

$z:\text{int}$
 $s, \text{square}:\text{int} \rightarrow \text{int}$
 $f:\tau_x \rightarrow \tau_y \rightarrow \text{bool}$
 $y:\tau_y = \text{bool}$
 $x:\tau_x = \text{int}$

Answer:

$(\text{int} \rightarrow \text{bool} \rightarrow \text{bool}) \rightarrow \text{int} \rightarrow \text{bool} \rightarrow \text{bool}$

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Type inference

- Goal: reconstruct types even after erasure
- Idea: run ordinary type-checking algorithm, generate *type equations*

$f:\text{T2}, x:\text{T5} \vdash f:\text{int} \rightarrow \text{T6} \quad f:\text{T2}, x:\text{T5} \vdash 1:\text{int}$

$f:\text{T2}, x:\text{T5} \vdash f 1:\text{T6}$

$f:\text{T2} \vdash \text{fn } x. f 1:\text{T1} (= \text{T5} \rightarrow \text{T6}) \quad y:\text{T3} \vdash y:\text{T4}$

$\text{fn } f. \text{fn } x. f 1:\text{T2} \rightarrow \text{T1} \quad (\text{fn } y.y):\text{T2} (= \text{T3} \rightarrow \text{T4})$

$(\text{fn } f. \text{fn } x. (f 1)) (\text{fn } y.y):\text{T1}$

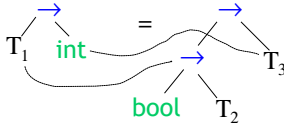
$\text{T2} = \text{T3} \rightarrow \text{T4}, \text{T3} = \text{T4}, \text{T1} = \text{T5} \rightarrow \text{T6}, \text{T2} = \text{int} \rightarrow \text{T6}$

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Unification

- How to solve equations?
- Idea: given equation $\tau_1 = \tau_2$, *unify* type expressions to solve for unknowns in both
- Example: $T_1 \rightarrow \text{int} = (\text{bool} \rightarrow T_2) \rightarrow T_3$
- Result: Substitution $T_1 \mapsto \text{bool} \rightarrow T_2, T_3 \mapsto \text{int}$



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Robinson's algorithm (1965)

- *Unification* produces *weakest substitution* that equates two trees
 - $T_1 \rightarrow \text{int} = (\text{bool} \rightarrow T_2) \rightarrow T_3$ equated by any $T_1 \mapsto \text{bool} \rightarrow T_2, T_3 \mapsto \text{int}, T_2 \mapsto ?$
 - **Defn.** S_1 is weaker than S_2 if $S_2 = S_3 \circ S_1$ for S_3 a non-identity substitution
- **Unify**(E) where E is set of equations gives weakest equating substitution: define recursively

Unify($T = \tau, E$) = **Unify**($E\{\tau/T\}$) \circ [$T \mapsto \tau$]
(if $T \notin \text{FTV}[\tau]$)

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Rest of algorithm

Unify($T = \tau, E$) = **Unify**($E\{\tau/T\}$) \circ [$T \mapsto \tau$]

(if $T \notin \text{FTV}[\tau]$)

Unify(\emptyset) = \emptyset

Unify($B = B, E$) = **Unify**(E)

Unify($B_1 = B_2, E$) = ?

Unify($T = T, E$) = **Unify**(E)

Unify($\tau_1 \rightarrow \tau_2 = \tau_3 \rightarrow \tau_4, E$)

= **Unify**($\tau_1 = \tau_3, \tau_2 = \tau_4, E$)

Termination?

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Type inference algorithm

- $\mathcal{R}(e, \Gamma, S) = \langle \tau, S' \rangle$ means
“Reconstructing the type of e in type context Γ with respect to substitution S yields type τ , stronger substitution S' or
“ S' is weakest subst. stronger than S such that $S'(\Gamma) \vdash e : S'(\tau)$ ”

Define: **Unify**(E, S) = **Unify**(SE) \circ S

- solve substituted equations E and fold in new substitutions

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Inductive defn of inference

- $\mathcal{R}(e, \Gamma, S) = \langle \tau, S' \rangle \Leftrightarrow$ “ S' is weakest subst. stronger than S such that $S'(\Gamma) \vdash e : S'(\tau)$ ”
- **Unify**(E, S) = **Unify**(SE) \circ S

$\mathcal{R}(n, \Gamma, S) = \langle \text{int}, S \rangle$ $\mathcal{U}(\#t, \Gamma, S) = \langle \text{bool}, S \rangle$
 $\mathcal{R}(x, \Gamma, S) = \langle \Gamma(x), S \rangle$
 $\mathcal{R}(e_1 e_2, \Gamma, S) = \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(e_1, \Gamma, S) \text{ in}$
 $\text{let } \langle T_2, S_2 \rangle = \mathcal{R}(e_2, \Gamma, S_1) \text{ in}$
 $\langle T_1, \text{Unify}(T_2 \rightarrow T_1 = T_1, S_2) \rangle$
 $\mathcal{R}(\text{fn } x.e, \Gamma, S) = \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(e, \Gamma[x \mapsto T_1], S) \text{ in}$
 $\langle T_1 \rightarrow T_1, S_1 \rangle$

where... T_i is “fresh” (not mentioned anywhere in e, Γ, S)

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Example

$\mathcal{R}((\text{fn } x x) 1, \emptyset, \emptyset) =$
 $\text{let } \langle T_1, S_1 \rangle = \mathcal{R}(\text{fn } x x, \emptyset, \emptyset) \text{ in}$
 $\text{let } \langle T_2, S_2 \rangle = \mathcal{R}(1, \emptyset, S_1) \text{ in}$
 $\langle T_3, \text{Unify}(T_1 \rightarrow T_3 = T_2, S_2) \rangle$
 $\mathcal{R}(\text{fn } x x, \emptyset, \emptyset) = \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(x, \Gamma[x \mapsto T_4], \emptyset) \text{ in}$
 $\langle T_4 \rightarrow T_1, S_1 \rangle$
 $= \langle T_4 \rightarrow T_4, \emptyset \rangle$
 = $\text{let } \langle T_2, S_2 \rangle = \mathcal{R}(1, \emptyset, \emptyset) \text{ in}$
 $\langle T_3, \text{Unify}(T_2 \rightarrow T_3 = T_4 \rightarrow T_4, \emptyset) \rangle$
 = $\langle T_3, \text{Unify}(\text{int} \rightarrow T_3 = T_4 \rightarrow T_4, \emptyset) \rangle$
 = $\langle T_3, \text{Unify}(\text{int} = T_4, T_3 = T_4, \emptyset) \rangle$
 = $\langle T_3, \text{Unify}(T_3 = \text{int}, [T_4 \mapsto \text{int}]) \rangle$
 = $\langle T_3, [T_3 \mapsto \text{int}, T_4 \mapsto \text{int}] \rangle$

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Polymorphism

$$\mathcal{R}(\text{fn } x x, \emptyset, \emptyset) = \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(x, \Gamma[x \mapsto T_1], \emptyset) \text{ in} \\ \langle T_4 \rightarrow T_1, S_1 \rangle \\ = \langle T_4 \rightarrow T_4, \emptyset \rangle$$

- Reconstruction algorithm doesn't solve type fully... opportunity!
 - $\text{fn } x x$ can have type $T_4 \rightarrow T_4$ for any T_4 !
 - polymorphic (= “many shape”) term
 - be nice to reuse same expression multiple places in program with different types:
- let id = (fn x x) in ... (f id) ... (g x id) ... id

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Polymorphic types

- Type expression may have some unsolved type identifiers after type reconstruction
- Type $T_4 \rightarrow T_4$ is a *type schema* that can be instantiated with any T_4 to make a type
- Idea: allow “let” to bind identifiers to polymorphic terms
 - type context Γ maps variable either to
 - type τ or
 - type schema $\forall T_1, \dots, T_n. \tau$ where $\text{FTV}(\tau) \subseteq \{T_1, \dots, T_n\}$
- Can still do type inference! (ML)

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Typing rules

$\Gamma \in \text{Var} \rightarrow \sigma$
 $\sigma ::= \tau \mid \forall T_1, \dots, T_n. \tau$
 $\Delta = \{T_1, \dots, T_n\}$ (Δ : set of legal type variables)
 $\Delta \vdash \tau$ (judgment: τ is well formed)
 $\Delta; \Gamma \vdash e : \tau$

$$\frac{}{\Delta; \Gamma, x : \tau \vdash x : \tau} \quad \frac{\Delta; \Gamma, x : \tau \vdash e : \tau' \quad \Delta \vdash \tau, \tau'}{\Delta; \Gamma \vdash \text{fn } x e : \tau \rightarrow \tau'}$$

$$\frac{\Delta \vdash \tau_i \quad i \in 1..n}{\Delta; \Gamma, x : (\forall T_1, \dots, T_n. \tau) \vdash x : \tau\{T_i/T_i \quad i \in 1..n\}}$$

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More typing rules

$$\frac{\Delta; \Gamma \vdash e_1 : \tau \rightarrow \tau' \quad \Delta; \Gamma \vdash e_2 : \tau \rightarrow \tau' \quad \Delta \vdash \tau, \tau'}{\Delta; \Gamma \vdash e_1 e_2 : \tau'}$$

$$\frac{\Delta \cup \{T_1, \dots, T_n\}; \Gamma \vdash e_1 : \tau \quad \Delta \cup \{T_1, \dots, T_n\} \vdash \tau \quad \Delta; \Gamma, x : \forall T_1, \dots, T_n. \tau \vdash e_2 : \tau'}{\Delta; \Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau'}$$

$$\frac{\emptyset; \text{id} : \forall T_1. T_1 \rightarrow T_1 \vdash \text{id} : \text{int} \rightarrow \text{int} \quad T_1; \emptyset \vdash (\text{fn } x x) : T_1 \rightarrow T_1 \quad \emptyset; \text{id} : \forall T_1. T_1 \rightarrow T_1 \vdash \text{id } 2 : \text{int}}{\emptyset; \emptyset \vdash \text{let id} = (\text{fn } x x) \text{ in id } 2 : \text{int}}$$

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Algorithm \mathcal{W} (Milner)

- Infers types in language with let-bound type schemas! (& letrec)
 - Built into ML
- $\mathcal{W}(e, \Gamma, S) = \langle \tau, S' \rangle$ gives type, subst S' as before, (but Γ can map vars to type schemas)

$$\mathcal{W}(x, \Gamma, S) = \text{case } \Gamma(x) \text{ of} \\ \tau \Rightarrow \langle \tau, S \rangle \\ \mid \forall T_1, \dots, T_n. \tau \Rightarrow \langle \tau\{T_i/T_i\}, S \rangle$$

$$\mathcal{W}(\text{letrec } x = e_1 \text{ in } e_2, \Gamma, S) = \\ \text{let } \Gamma' = \Gamma[x \mapsto T_1] \text{ in let } \langle T_1, S_1 \rangle = \mathcal{W}(e_1, \Gamma', S) \text{ in} \\ \text{let } S_2 = \text{Unify}(\{T_1 = T_1\}, S_1) \text{ in} \\ \text{let } \Gamma'' = \Gamma[x \mapsto \text{Generic}(T_1, \Gamma, S_2)] \text{ in} \\ \mathcal{W}(e_2, \Gamma'', S_2)$$

$\text{Generic}(\tau, \Gamma, S) = \forall T_1, \dots, T_n. \tau$ where $\{T_1, \dots, T_n\} = \text{FTV}(S\tau) - \text{FTV}(S\Gamma)$

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