

## CS 611 Advanced Programming Languages

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Lecture 30  
Recursive Types  
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### tF example

- Last time: finally got a type-safe universal language (tF)

$$e ::= x \mid b \mid \text{fn } x:\tau . e \mid e_1 e_2 \mid e_1 + e_2 \mid \langle e_1, e_2 \rangle \mid \text{first } e \mid \text{rest } e \mid \text{inl } e \mid \text{inr } e \mid \text{case } e_0 e_1 e_2 \mid \text{rec } y:\tau . \text{fn } x.e \mid \text{let } x=e_1 \text{ in } e_2$$

$$\tau ::= B \mid \tau_1 \rightarrow \tau_2 \mid \tau_1^* \tau_2 \mid \tau_1 + \tau_2$$

```
let factorial = (rec fact: int→int.
  fn n. if (n<2) 1 (fact(n-1)*n)) in
factorial(5)
```

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### Type equivalence

- Many languages: multiple ways to write a type
- Write  $\vdash \tau_1 \equiv \tau_2$  when type expressions  $\tau_i$  are equivalent types:

$$\frac{\vdash \tau_1 \equiv \tau_2 \quad \Gamma \vdash e : \tau_1}{\Gamma \vdash e : \tau_2}$$

Example: Extend tF with  $(\tau_1^* \tau_2) \rightarrow \tau_3 \equiv \tau_1 \rightarrow (\tau_2 \rightarrow \tau_3)$

- curried fns applicable to pairs, vice versa
- based on (compiler-inserted) bijection between types: *curry* and *uncurry*

$$\mathcal{C}[\![e : (\tau_1^* \tau_2) \rightarrow \tau_3]\!] = \mathcal{C}[\![\lambda x:\tau_1 . \lambda y:\tau_2 . e(x,y) : \tau_1 \rightarrow (\tau_2 \rightarrow \tau_3)]\!]$$

$$\mathcal{C}[\![e : \tau_1 \rightarrow (\tau_2 \rightarrow \tau_3)]\!] = \mathcal{C}[\![\lambda p:\tau_1^* \tau_2 . e(\pi_1 p)(\pi_2 p) : (\tau_1^* \tau_2) \rightarrow \tau_3]\!]$$

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### Name vs. structural equivalence

- When are two types equivalent?
  - tF**: identical syntactic form (*structural equivalence*)
  - C, Java, Pascal**: *name equivalence* (name is part of type identity)
- Binding a type to a name also brands it with unique identity

**Modula-3**: structural equivalence, explicit branding:

```
TYPE intpair = RECORD x,y: int END
TYPE foo = BRANDED intpair, bar = BRANDED intpair;
foo ≠ bar ≠ intpair ≅ RECORD x,y: int END
```

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### Data structures?

- tF is inconvenient: no data structures

Binary tree in C:

```
struct Tree {
  bool leaf;
  union {
    struct { Tree *left, Tree *right; } children;
    int value;
  } u;
}
```

- How to express in our type notation? A try:
  - $\tau = \text{bool}^*(\tau^* \tau + \text{int})$
- Equation!

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### Other examples:

- How to assign a type to  $(\lambda x (x x))$ ?
- Can write terms that don't get stuck:
  - $(\lambda x (x x)) (\lambda x (x x))$  diverges
  - $(\lambda x (x x)) (\lambda y \#f) \Downarrow \#f$
- Need solution to  $\tau = \tau \rightarrow \text{bool}$

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## Fixed point type constructor

- Want to solve equations of form  $X = \tau$  where  $X$  is type variable mentioned in type expression  $\tau$
- Type constructor  $\mu X. \tau$  produces this solution
  - analogue of `rec x e` for types
  - ≈ ML datatype declaration
- Can define useful types:
  - $tree \triangleq \mu T. T * T + int$
  - $nat \triangleq \mu N. unit + N$
  - $0 \triangleq inl(\#u), 1 \triangleq inr(inl(\#u)), 2 \triangleq inr(inr(inl(\#u))) \dots$
  - $successor \triangleq \lambda n: nat. inr(n)$

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## Closed vs. Open recursion

- Many modern languages allow types to refer to one another arbitrarily (even to other source file!)
- Open recursion*: type expression not closed
- Requires fixed point over all types in scope

```
class Node {
  Edge[] outgoing_edges;
  Edge[] incoming_edges;
}
class Edge {
  Node from;
  Node to;
}
Node =
  μN. array[N*N] *
  array[N*N]
Edge =
  μE. (array[E] * array[E]) *
  (array[E] * array[E])
```

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## Type equivalence

- Problem: types no longer have one unique syntactic form
- $\mu X. \tau$  is solution to  $X = \tau$ : can substitute  $\mu X. \tau$  for  $X$  wherever it appears in  $\tau$ 
  - $\mu N. (unit + N) = \mu N. (unit + (\mu N. unit + N))$
  - $nat = (unit + nat) = (unit + (unit + nat)) \dots$
- Unfolding* of type  $\mu X. \tau$  is equivalent type  $\tau\{\mu X. \tau / X\}$
- $\mu X. \tau \cong \tau\{\mu X. \tau / X\}$ 
  - implicit notion of equivalence: type expressions are fully substitutable for each other
  - weaker notion: types are isomorphic, expressions must be explicitly mapped between types

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## Abstract and concrete views

$$\begin{array}{c} \text{unfold} \\ \text{rep} \\ \xrightarrow{\quad} \\ \mu X. \tau \cong \tau\{\mu X. \tau / X\} \\ \xleftarrow{\quad} \\ \text{fold} \\ \text{abs} \end{array}$$

- unfold operator allows access to internals of value of recursive type; fold operator packages concrete value as abstract value
- Winskel: abs/rep
- fold/unfold are bijection: types are isomorphic

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## Typing, evaluation rules

$$\frac{\Gamma \vdash e : \tau\{\mu X. \tau / X\}}{\Gamma \vdash \text{fold}_{\mu X. \tau} e : \mu X. \tau}$$

$$\frac{\Gamma \vdash e : \mu X. \tau}{\Gamma \vdash \text{unfold } e : \tau\{\mu X. \tau / X\}}$$

$$\text{unfold } (\text{fold}_{\mu X. \tau} e) \rightarrow e$$

$$C ::= \dots \mid \text{fold } C \mid \text{unfold } C$$

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## Example

- Goal: show  $(\lambda x (x x))$  can be typed as  $\mu T. T \rightarrow \text{bool}$
- Add declarations, explicit fold and unfold:  $\text{fold}_{\mu T. T \rightarrow \text{bool}} (\lambda x : (\mu T. T \rightarrow \text{bool}) . ((\text{unfold } x) x))$

$$\frac{\{x : \mu T. T \rightarrow \text{bool}\} \vdash x : (\mu T. T \rightarrow \text{bool})}{\{x : \mu T. T \rightarrow \text{bool}\} \vdash \text{unfold } x : (\mu T. T \rightarrow \text{bool}) \rightarrow \text{bool} \quad \dots}$$

$$\frac{\{x : \mu T. T \rightarrow \text{bool}\} \vdash ((\text{unfold } x) x) : \text{bool}}{\vdash [\lambda x : (\mu T. T \rightarrow \text{bool}) . ((\text{unfold } x) x)] : (\mu T. T \rightarrow \text{bool}) \rightarrow \text{bool}}$$

$$\vdash [\text{fold}_{\mu T. T \rightarrow \text{bool}} (\lambda x : (\mu T. T \rightarrow \text{bool}) . ((\text{unfold } x) x))] : \mu T. T \rightarrow \text{bool}$$

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## Capturing the untyped $\lambda$

- All lambda calculus expressions can be used in any context
  - Evaluation never gets stuck
- Type of lambda calculus terms:
 
$$\Lambda = \mu X. X \rightarrow X \cong (\mu X. X \rightarrow X) \rightarrow (\mu X. X \rightarrow X)$$
- Translating  $\lambda$  to  $\lambda \rightarrow \mu$ : (note  $\Lambda \cong \Lambda \rightarrow \Lambda$ )
 
$$\mathcal{D}[[x]] = x$$

$$\mathcal{D}[[\lambda x. e]] = (\text{fold } (\lambda x: \Lambda. \mathcal{D}[[e]]))$$

$$\mathcal{D}[[e_1 e_2]] = (\text{unfold } \mathcal{D}[[e_1]]) \mathcal{D}[[e_2]]$$

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## fold and unfold in real languages

- Java, Modula-3: recursive type and unfolding are substitutable: fold/unfold supplied automatically as needed
- ML: datatype constructor is fold, match operation provides implicit unfold for each arm of the sum
- CLU, C requires explicit use of operators to shift between views (up/down), (&/\*)
- Note: fold and unfold are combined with other features (ML: sums, CLU & Java: classes/modules, C: references)

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## Y operator

- Can use recursive types to write  $Y_\tau$  operator as ordinary expression
- Desugar  $\text{rec } f:\tau. e_r$  as  $Y_\tau (\lambda f:\tau. e_r)$ !

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## Constructing a model

- Our semantics models  $\tau$  as domain  $\mathcal{J} [[\tau]]$
- How do we model the new type constructor?
 
$$\mathcal{J} [[\mu X. \tau]] = ?$$
- Since  $\mu X. \tau \cong \tau\{\mu X. \tau / X\}$ , we expect isomorphism to hold in domains as well:
 
$$\mathcal{J} [[\mu X. \tau]] \cong \mathcal{J} [[\tau\{\mu X. \tau / X\}]]$$
- Example: natural numbers
 
$$N = \mathcal{J} [[\mu N. \text{unit} + N]] \cong \mathcal{J} [[\text{unit} + (\mu N. \text{unit} + N)]]$$

$$N \cong \text{unit} + N$$
- Modeling these types requires solutions to domain equations we have been using all along

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## Recursive domain constructor

- Idea: assume a constructor for recursive domains:  $\mu D. \mathcal{J}(D)$ 
  - Functor  $\mathcal{J}$  maps one domain into another domain
  - If  $D = \mu X. \mathcal{J}(X)$ ,  $\mathcal{J}(D)$  produces a domain related to  $D$  by **continuous** functions *up* and *down* that are inverses of one another

$$\begin{array}{l} \xleftarrow{\text{up}} \\ D \cong \mathcal{J}(D) \\ \xrightarrow{\text{down}} \end{array} \quad \begin{array}{l} d_0 \sqsubseteq d_1 \sqsubseteq d_2 \dots \in D \Rightarrow \text{up}(\sqcup d_i) = \sqcup \text{up}(d_i) \\ e_0 \sqsubseteq e_1 \sqsubseteq e_2 \dots \in \mathcal{J}(D) \Rightarrow \\ \text{down}(\sqcap e_i) = \sqcap \text{down}(e_i) \end{array}$$

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## Interpreting types

- Types can define names; need type environment  $\chi : \text{Type} \rightarrow \text{Domain}$  to define inductively
  - $\mathcal{J} [[\tau]] \chi$  gives domain corresponding to  $\tau$
  - $\mathcal{J} [[\text{unit}]] \chi = \mathbf{u}$
  - $\mathcal{J} [[\text{int}]] \chi = \mathbf{z}$
  - $\mathcal{J} [[X]] \chi = \chi(X)$
  - $\mathcal{J} [[\tau_1 * \tau_2]] \chi = \mathcal{J} [[\tau_1]] \chi \times \mathcal{J} [[\tau_2]] \chi$
  - $\mathcal{J} [[\tau_1 \rightarrow \tau_2]] \chi = \mathcal{J} [[\tau_1]] \chi \rightarrow \mathcal{J} [[\tau_2]] \chi$
  - $\mathcal{J} [[\mu X. \tau]] \chi = \mu D. \mathcal{J} [[\tau]] \chi [X \mapsto D]$

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