

# Machine Learning for Data Science (CS4786)

## Lecture 20

### Hidden Markov Models

Course Webpage :

<http://www.cs.cornell.edu/Courses/cs4786/2017fa/>

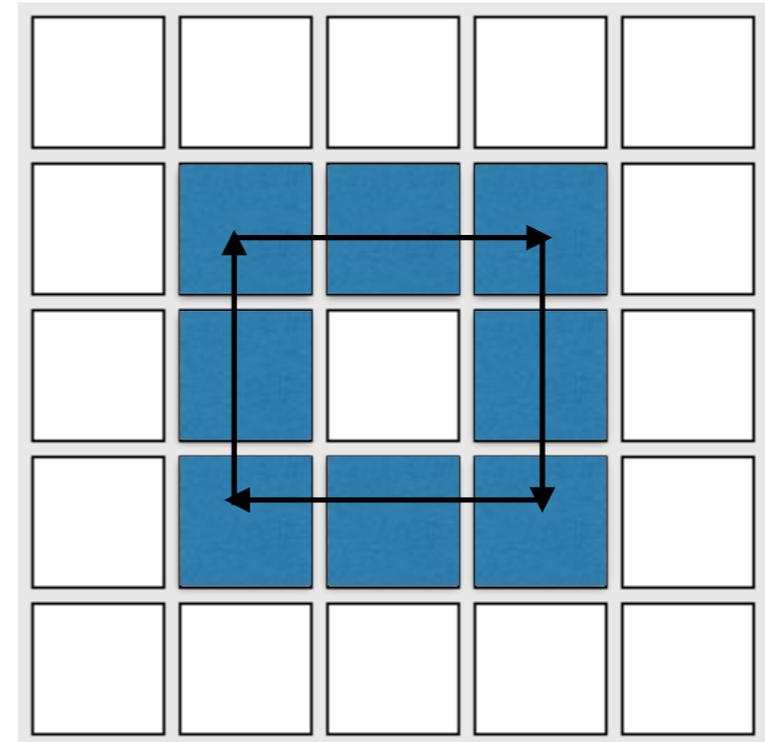
# HIDDEN MARKOV MODEL (HMM)

Same example:

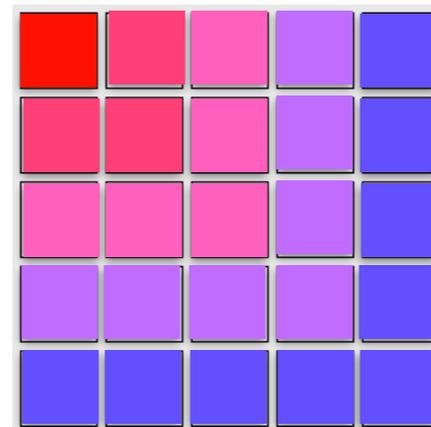


But you don't observe location  
(dark room)

You hear how close the bot is!



What you hear:



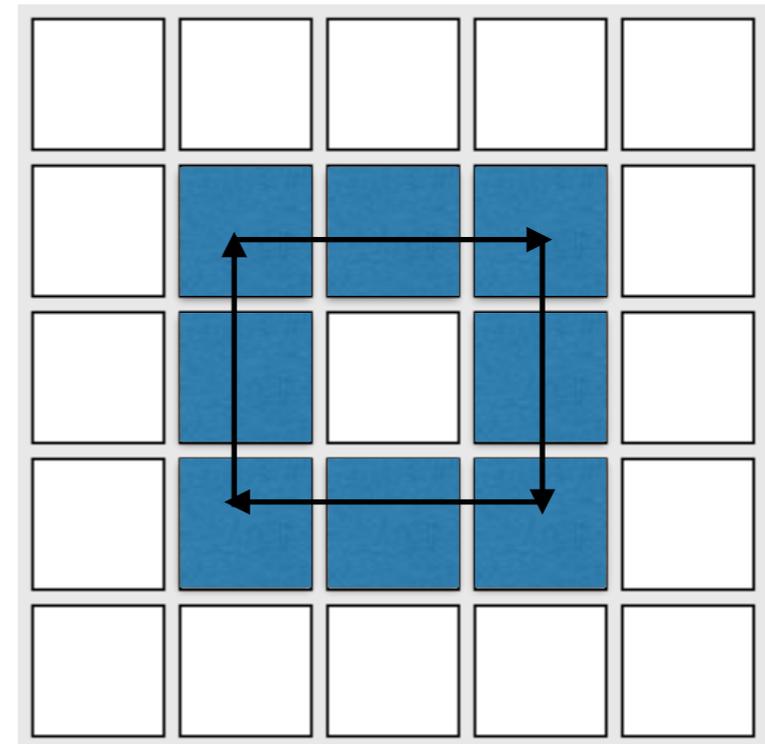
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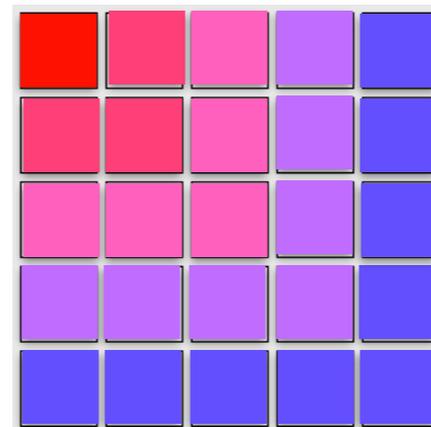


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What you hear:



Can you catch the Bot?

# HIDDEN MARKOV MODEL (HMM)

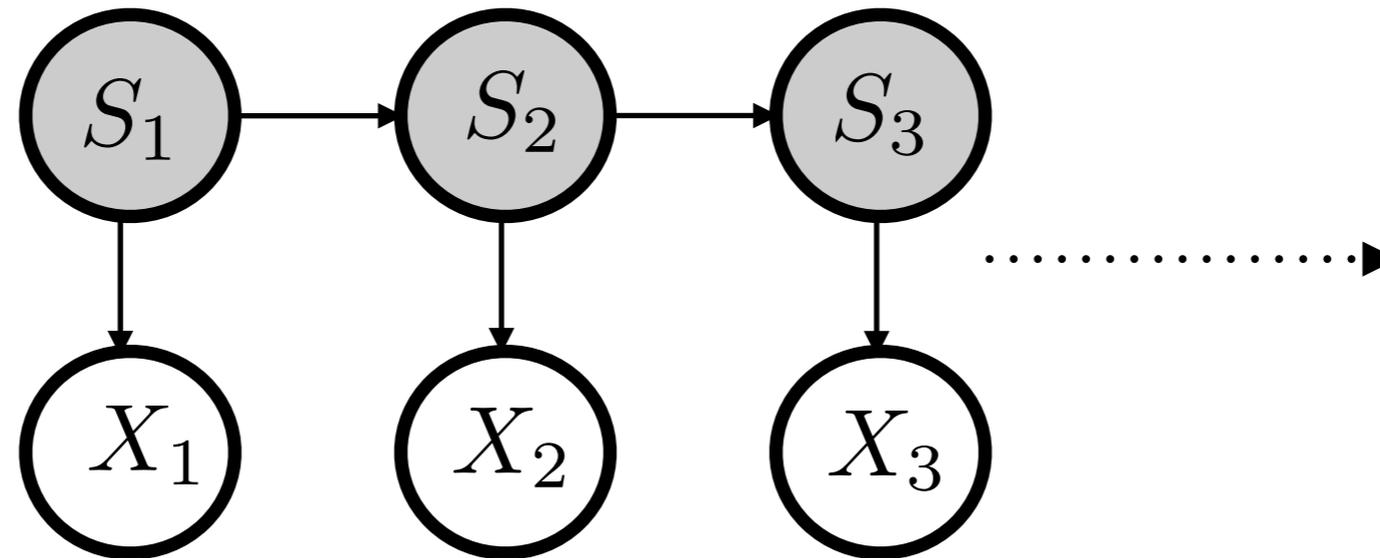
$X_t$ 's are what you hear (observation)

$S_t$ 's are the unseen locations (states)

Eg: for  $n \times n$  grid we have,  $K = n^2$  states

Number of alphabets = 5  
(colors you can observe)

# HIDDEN MARKOV MODEL (HMM)



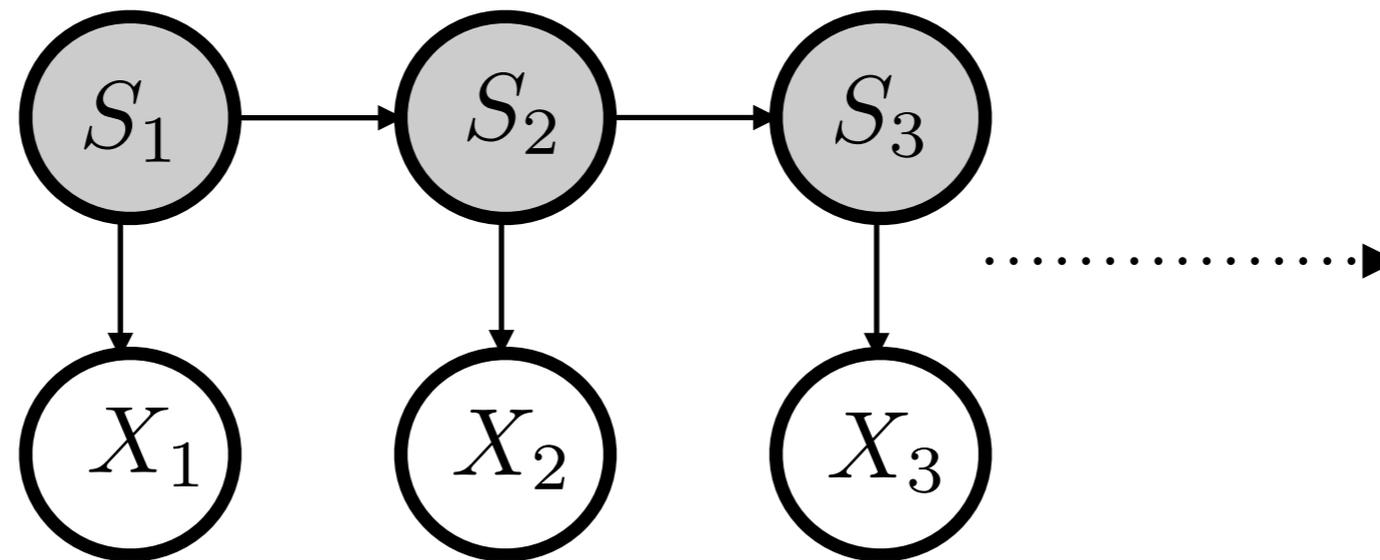
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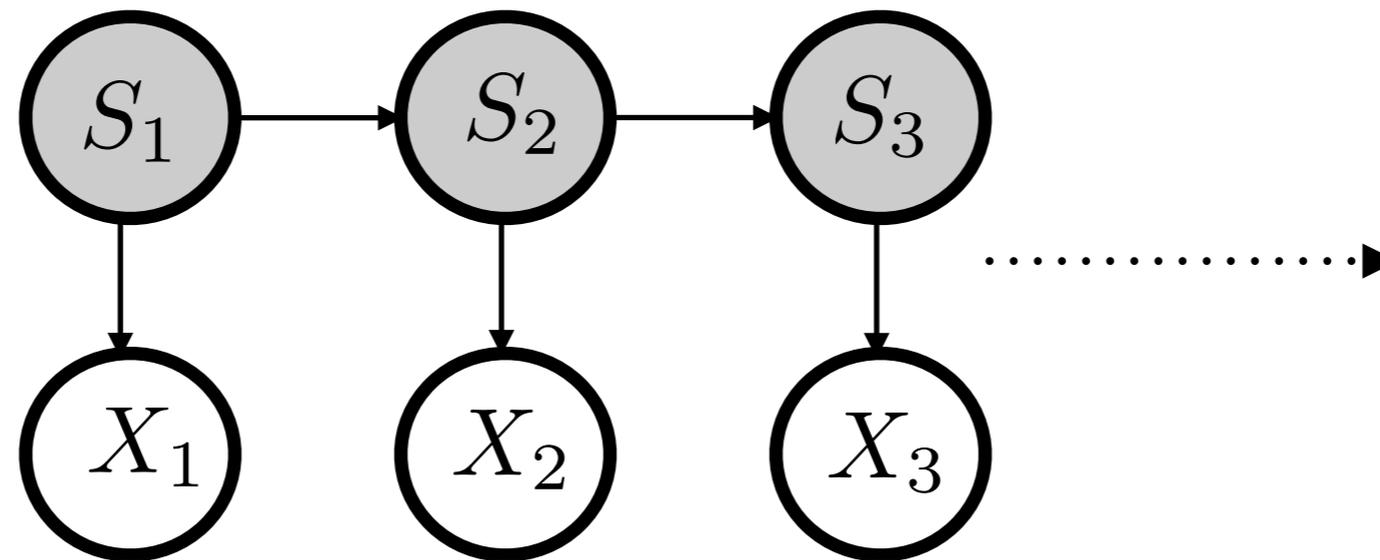
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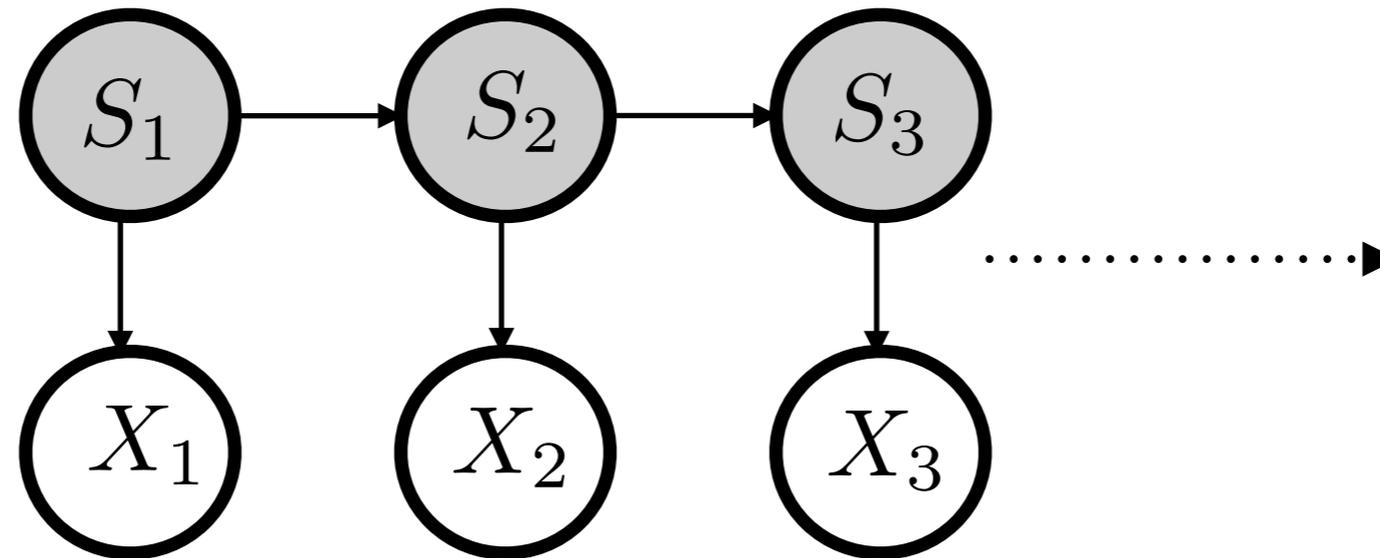


# HIDDEN MARKOV MODEL (HMM)



What are the parameters?

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**Transition Probability table:  $T = P(S_t|S_{t-1})$**

**Emission Probabilities:  $E = P(X_t|S_t)$**

**Initial State Probabilities:  $P(S_1)$**

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$$P(S_t = k | X_1, \dots, X_N)?$$

# INFERENCE IN HMM

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$$P(S_t = k | X_1, \dots, X_N)$$

$$\propto P(X_{t+1}, \dots, X_N | S_t = k, X_1, \dots, X_t) P(S_t = k | X_1, \dots, X_t)$$

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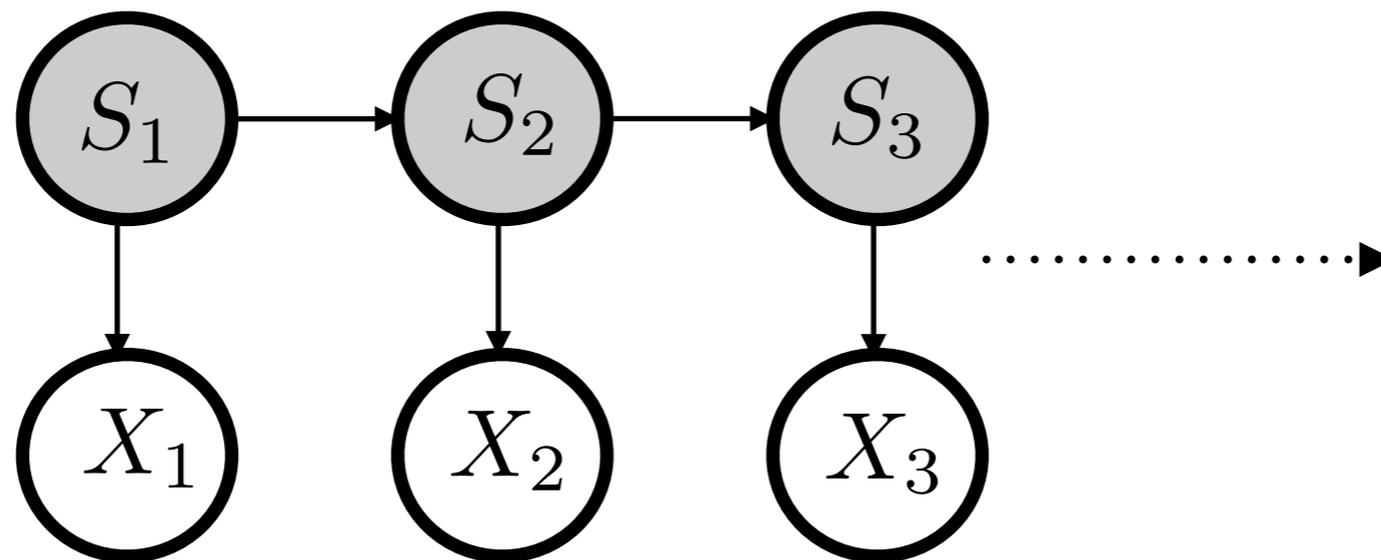
# INFERENCE IN HMM

$$\begin{aligned} P(S_t = k | X_1, \dots, X_N) & \\ & \propto P(X_{t+1}, \dots, X_N | S_t = k, X_1, \dots, X_t) P(S_t = k | X_1, \dots, X_t) \\ & \propto P(X_{t+1}, \dots, X_N | S_t = k, X_1, \dots, X_t) P(S_t = k, X_1, \dots, X_t) \\ & \propto P(X_{t+1}, \dots, X_N | S_t = k, X_1, \dots, X_t) P(X_t | S_t = k, X_1, \dots, X_{t-1}) P(S_t = k, X_1, \dots, X_{t-1}) \\ & \propto P(X_{t+1}, \dots, X_N | S_t = k) P(X_t | S_t = k) P(S_t = k, X_1, \dots, X_{t-1}) \end{aligned}$$

We know  $P(X_t | S_t = k)$ 's and  $P(S_t | S_{t-1})$

Compute  $P(X_{t+1}, \dots, X_N)$  and  $P(S_t = k, X_1, \dots, X_{t-1})$  recursively.

# INFERENCE IN HMM

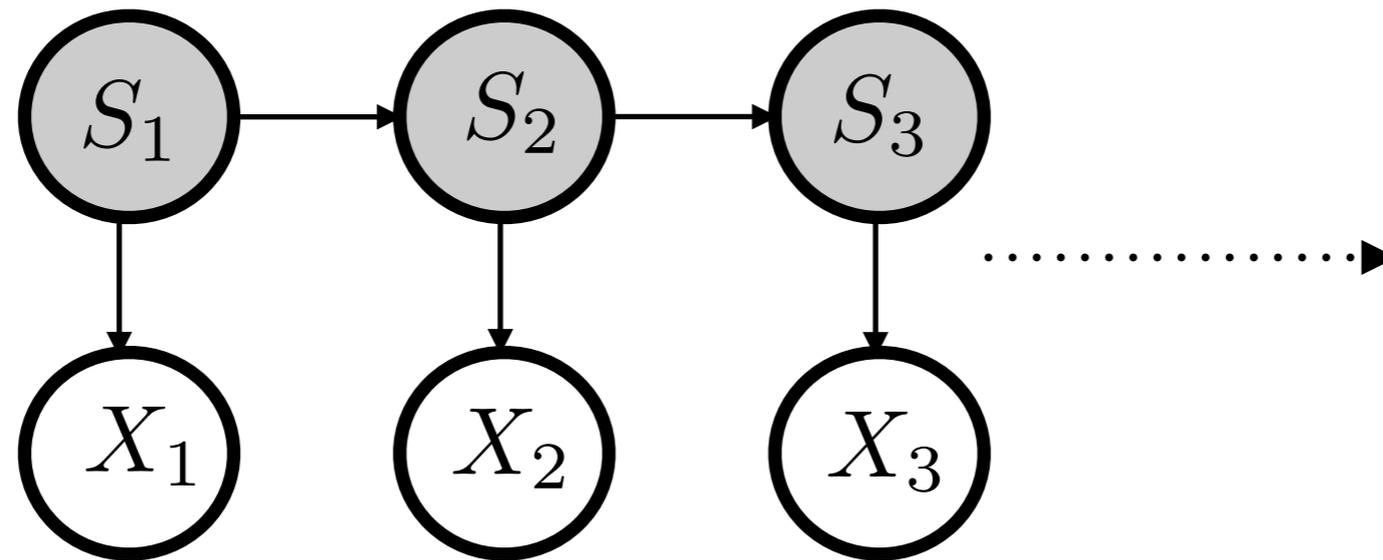


$$\text{message}_{S_{t-1} \mapsto S_t}(k) = P(S_t = k, X_1, \dots, X_{t-1})$$

$$\text{message}_{S_{t+1} \mapsto S_t}(k) = P(X_n, \dots, X_{t+1} | S_t = k)$$

$$P(S_t = k | X_1, \dots, X_n) \propto \text{message}_{S_{t-1} \mapsto S_t}(k) \times \text{message}_{S_{t+1} \mapsto S_t}(k) \times P(X_t | S_t = k)$$

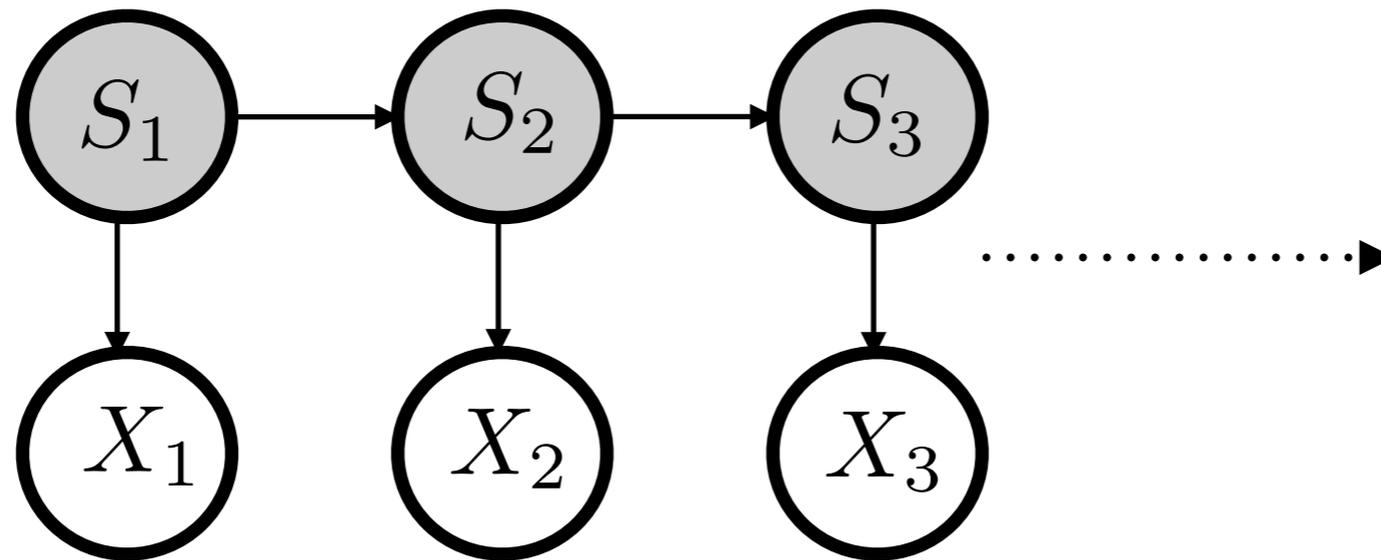
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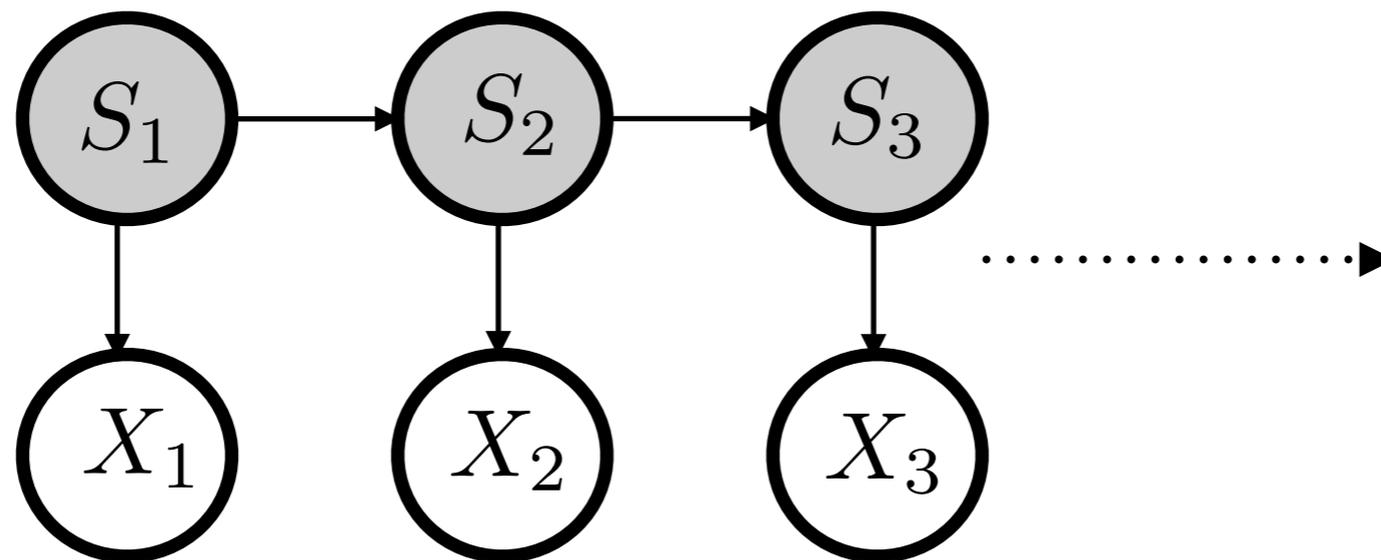
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Forward:

$$P(X_1, \dots, X_{t-1}, S_t = k) = \sum_{j=1}^K P(S_t = k | S_{t-1} = j) P(X_{t-1} | S_{t-1} = j) P(X_1, \dots, X_{t-2}, S_{t-1} = j)$$

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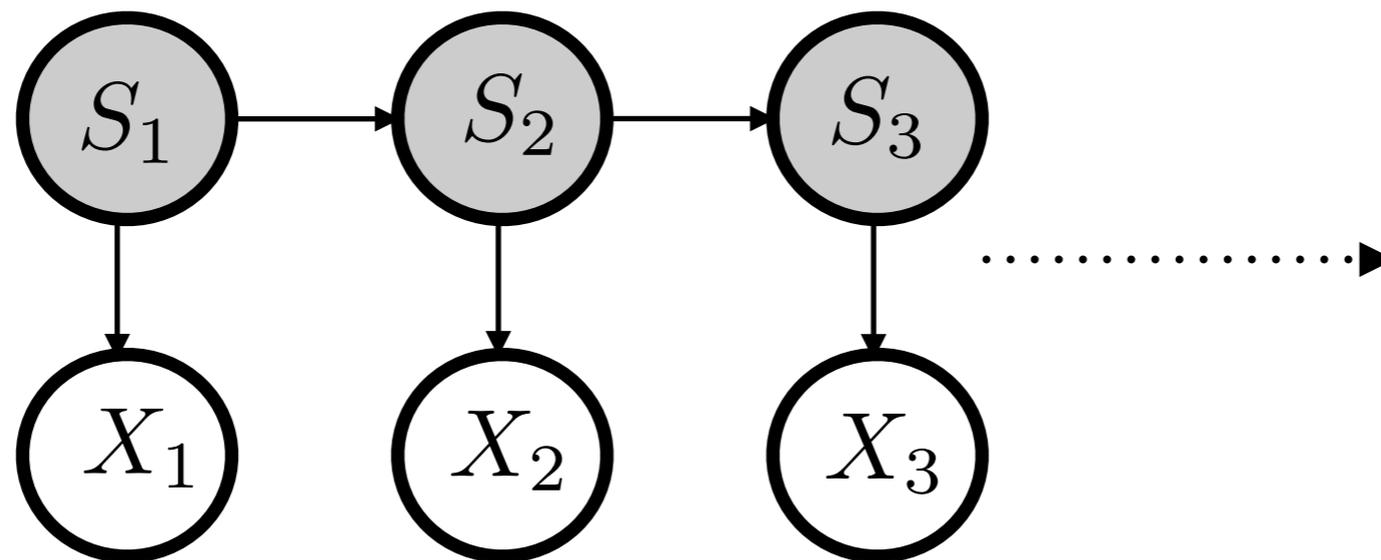
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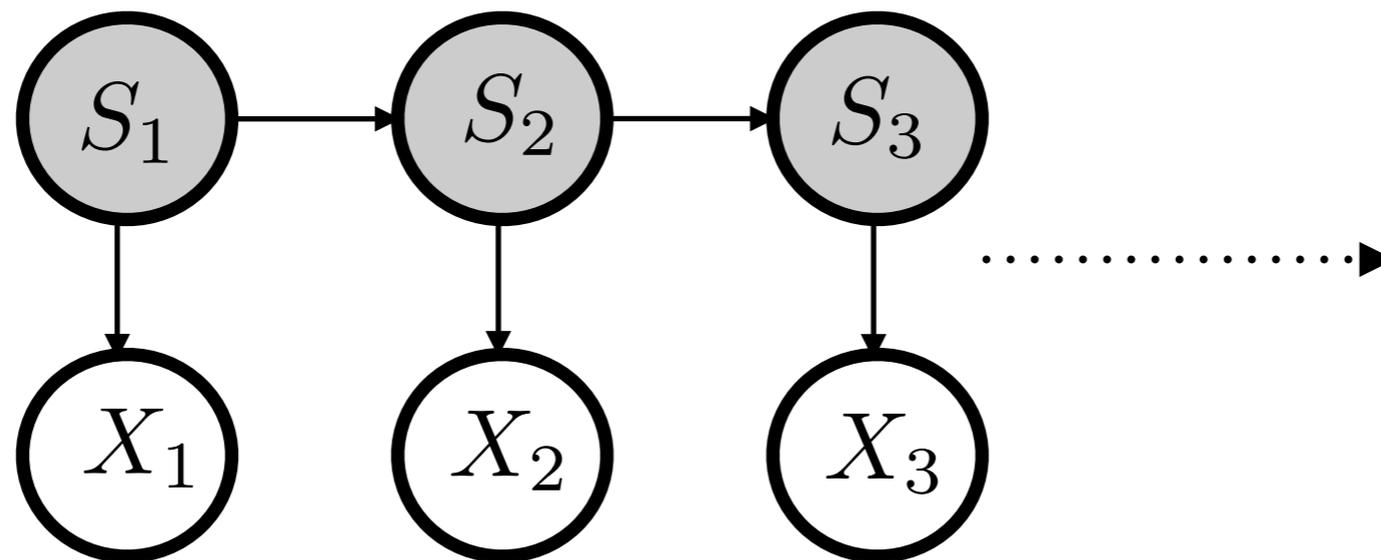
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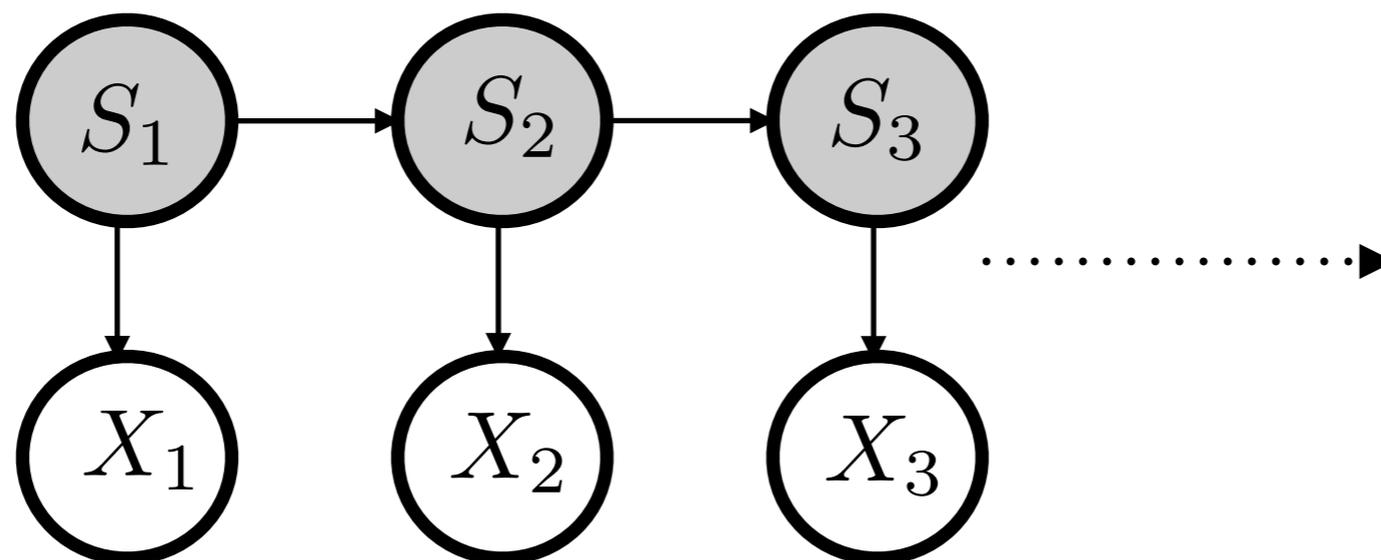
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# LEARNING PARAMETERS FOR HMM

- Now that we have algorithm for inference, what about learning
- Given observations, how do we estimate parameters for HMM?  
Three guesses ...

# EM FOR HMM (BAUM WELCH)

- EM algorithm of course, for HMM its referred to as Baum Welch algorithm
- Initialize Transition and Emission probability tables arbitrarily
- For  $i = 1$  to convergence:

**E-step** For every state variable  $t \in \{1, \dots, n\}$ ,  
Use forward-backward algorithm to compute probabilities of latent variables given observation

**M-step** Optimize weighted log likelihood as usual:

$$\theta^{(i)} = \arg \max_{\theta \in \Theta} \sum_{S_{1,\dots,n}} P(S_{1,\dots,n} | X_{1,\dots,n}, \theta^{(i-1)}) \log P(X_{1,\dots,n}, S_{1,\dots,n} | \theta)$$

# LETS SIMPLIFY M-STEP

$$\log P(X_{1,\dots,n}, S_{1,\dots,n}|\theta) :$$

:

# LETS SIMPLIFY M-STEP

$$\log P(X_{1,\dots,n}, S_{1,\dots,n}|\theta) = \log \left( \prod_{t=1}^n P(X_t|S_t, \theta) \prod_{t=1}^n P(S_t|S_{t-1}, \theta) \right)$$

:

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Hence,

$$\begin{aligned}&\sum_{S_{1,\dots,n}} P(S_{1,\dots,n}|X_{1,\dots,n}, \theta^{(i-1)}) \log P(X_{1,\dots,n}, S_{1,\dots,n}|\theta) \\ &= \sum_{t=1}^n \sum_{s_t=1}^K P(S_t = s_t|X_{1,\dots,n}, \theta^{i-1}) \log P(X_t|S_t = s_t, \theta) \\ &\quad + \sum_{t=1}^n \sum_{s_t, s_{t-1}=1}^K P(S_t = s_t, S_{t-1} = s_{t-1}|X_{1,\dots,n}, \theta^{i-1}) \log P(S_t|S_{t-1}, \theta)\end{aligned}$$

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- Only need to compute  $P(S_t = s_t | X_{1,\dots,n}, \theta^{i-1})$  and  $P(S_t = s_t, S_{t-1} = s_{t-1} | X_{1,\dots,n}, \theta^{i-1})$  using forward-backward

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- First term is immediate

$$P(S_t = s_t | X_{1,\dots,n}, \theta^{i-1}) \propto m_{S_{t-1} \mapsto S_t}(s_t) \cdot m_{S_{t+1} \mapsto S_t}(s_t) \cdot E^{(i-1)}[s_t, X_t]$$

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- For second term,

$$\begin{aligned} & P(S_t = s_t, S_{t-1} = s_{t-1} | X_{1,\dots,n}, \theta^{i-1}) \\ & \propto m_{S_{t-1} \mapsto S_t}(s_t) T^{(i-1)}[s_{t-1}, s_t] P(S_{t-1} = s_{t-1} | X_{1,\dots,n}, \theta^{i-1}) \\ & \propto m_{S_{t-1} \mapsto S_t}(s_t) T^{(i-1)}[s_{t-1}, s_t] m_{S_{t-2} \mapsto S_{t-1}}(s_{t-1}) m_{S_t \mapsto S_{t-1}}(s_{t-1}) E^{(i-1)}[s_{t-1}, X_{t-1}] \end{aligned}$$

Why?

# E-STEP

$$P(S_t = s_t, S_{t-1} = s_{t-1} | X_{1,\dots,n}, \theta^{i-1})$$

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For  $i = 1$  to convergence

- E-step:
  - Run Forward-Backward algorithm and compute messages

# BAUM WELCH ALGORITHM

Initialize  $T^0, E^0$  probability tables

For  $i = 1$  to convergence

- E-step:
  - Run Forward-Backward algorithm and compute messages
  - For every  $t$  compute  $P(S_t = s_t, S_{t-1} = s_{t-1} | X_{1,\dots,n}, \theta^{i-1})$  and  $P(S_t = s_t | X_{1,\dots,n}, \theta^{i-1})$  as in previous slides

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- M-step:

$$\forall u, v \quad T^{(i)}[u, v] = \frac{\sum_{t=2}^n P(S_t = v, S_{t-1} = u | X_{1,\dots,n}, \theta^{i-1})}{\sum_{t=2}^n P(S_{t-1} = u | X_{1,\dots,n}, \theta^{i-1})}$$

$$\forall v, e \quad E^{(i)}[v, e] = \frac{\sum_{t=1}^n P(S_t = v | X_{1,\dots,n}, \theta^{i-1}) \cdot \mathbf{1}_{X_t=e}}{\sum_{t=1}^n P(S_t = v | X_{1,\dots,n}, \theta^{i-1})}$$

Inference for general BN

# BAYESIAN NETWORKS

- Directed acyclic graph (DAG):  $G = (V, E)$
- Joint distribution  $P_\theta$  over  $X_1, \dots, X_n$  that factorizes over  $G$ :

$$P_\theta(X_1, \dots, X_n) = \prod_{i=1}^n P_\theta(X_i | \text{Parent}(X_i))$$

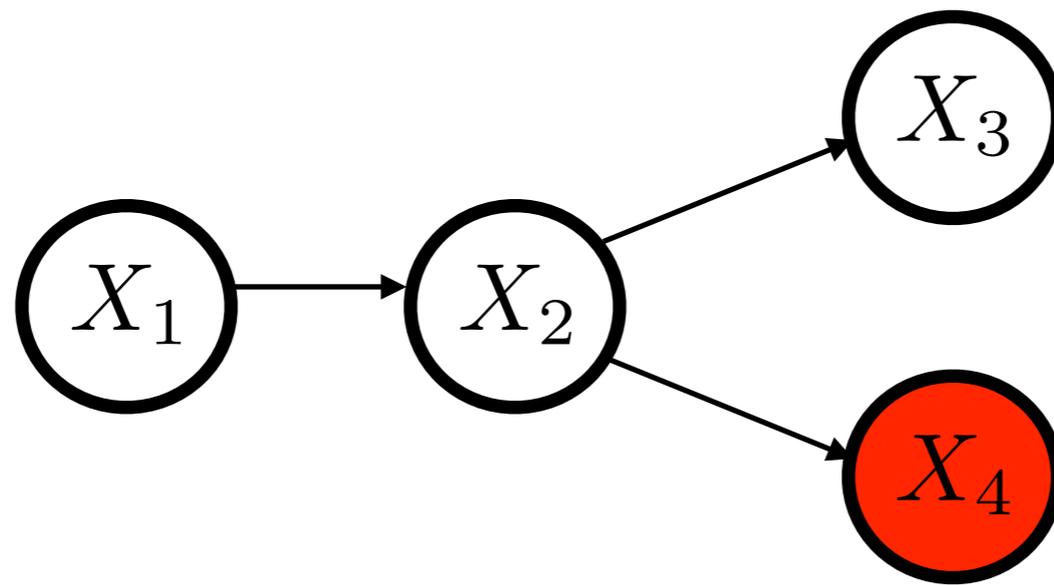
- Hence Bayesian Networks are specified by  $G$  along with CPD's over the variables (given their parents)

# VARIABLE ELIMINATION: EXAMPLES

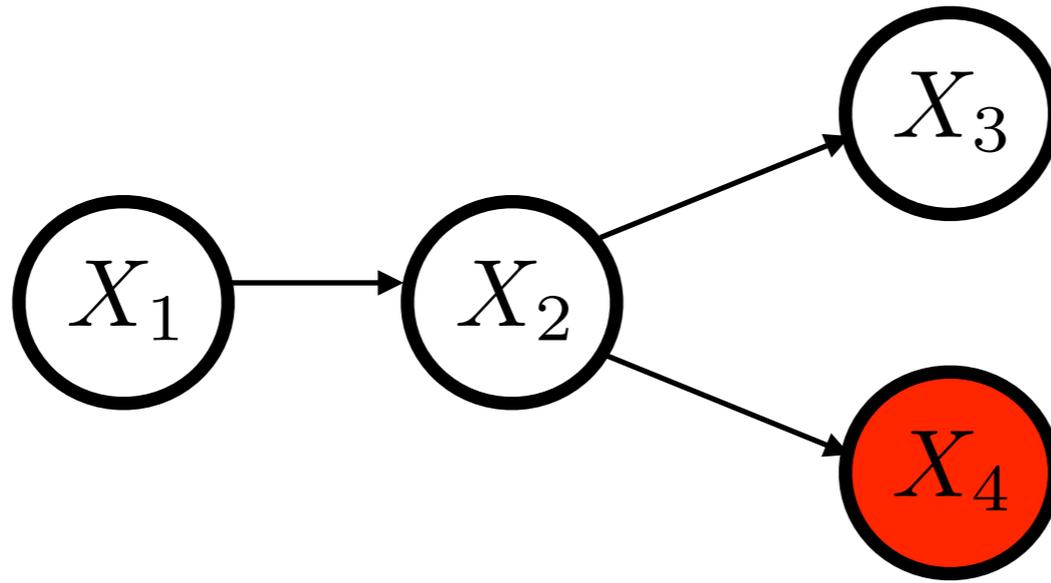
- Marginals are enough:

$$P(X_j = x_j, X_k = x_k | X_i = x_i, X_h = x_h) = \frac{P(X_j = x_j, X_k = x_k, X_i = x_i, X_h = x_h)}{P(X_i = x_i, X_h = x_h)}$$

# VARIABLE ELIMINATION: EXAMPLES

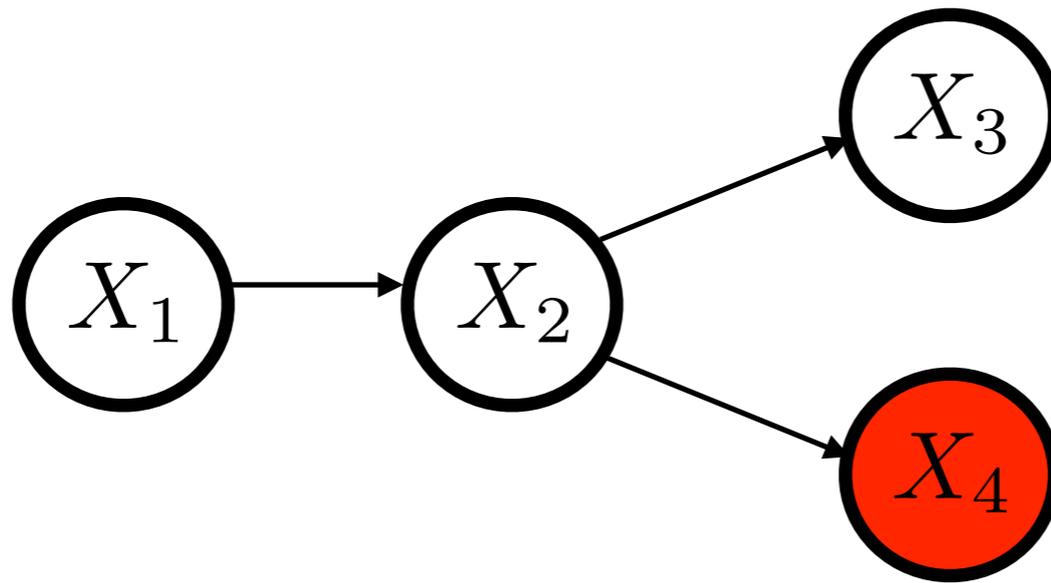


# VARIABLE ELIMINATION: EXAMPLES



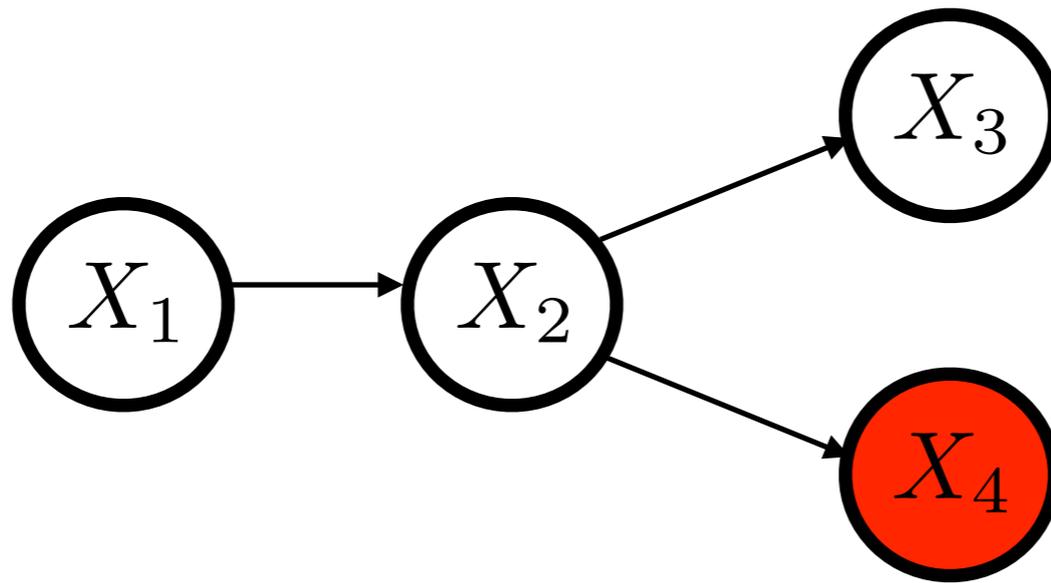
$$P(X_4) = \sum_{x_1} \sum_{x_2} \sum_{x_3} P(X_1 = x_1, X_2 = x_2, X_3 = x_3, X_4)$$

# VARIABLE ELIMINATION: EXAMPLES



$$\begin{aligned} P(X_4) &= \sum_{x_1} \sum_{x_2} \sum_{x_3} P(X_1 = x_1, X_2 = x_2, X_3 = x_3, X_4) \\ &= \sum_{x_1} \left( P(X_1 = x_1) \sum_{x_2} \left( P(X_2 = x_2 | X_1 = x_1) P(X_4 | X_2 = x_2) \left( \sum_{x_3} P(X_3 = x_3 | X_2 = x_2) \right) \right) \right) \end{aligned}$$

# VARIABLE ELIMINATION: EXAMPLES



$$\begin{aligned} P(X_4) &= \sum_{x_1} \sum_{x_2} \sum_{x_3} P(X_1 = x_1, X_2 = x_2, X_3 = x_3, X_4) \\ &= \sum_{x_1} \left( P(X_1 = x_1) \sum_{x_2} \left( P(X_2 = x_2 | X_1 = x_1) P(X_4 | X_2 = x_2) \left( \sum_{x_3} P(X_3 = x_3 | X_2 = x_2) \right) \right) \right) \\ &= \sum_{x_1} \left( P(X_1 = x_1) \left( \sum_{x_2} P(X_2 = x_2 | X_1 = x_1) P(X_4 | X_2 = x_2) \right) \right) \end{aligned}$$

# VARIABLE ELIMINATION: BAYESIAN NETWORK

Initialize **List** with conditional probability distributions

Pick an order of elimination  $I$  for remaining variables

**For** each  $X_i \in I$

    Find distributions in **List** containing variable  $X_i$  and remove them

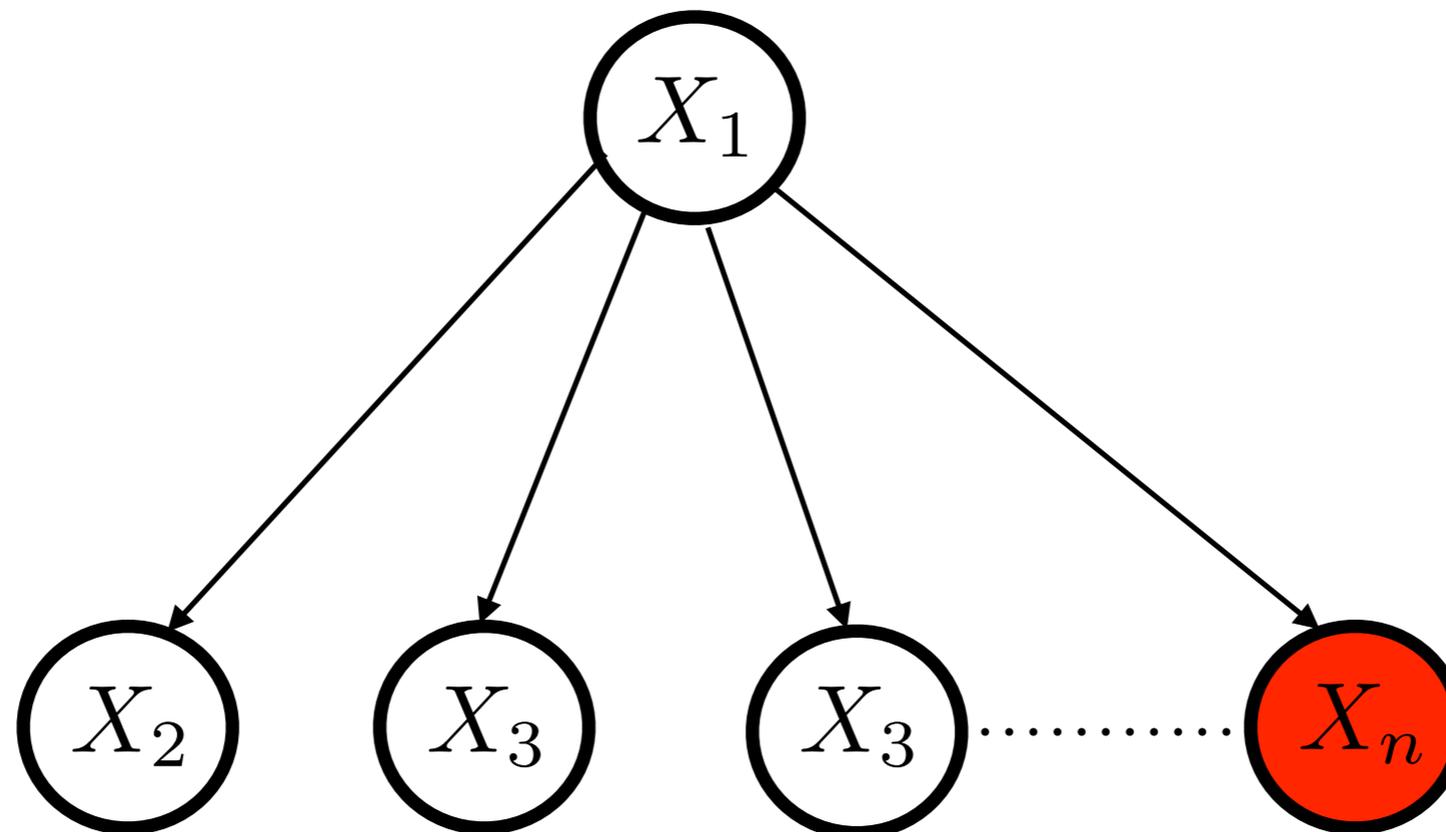
    Define new distribution as the sum (over values of  $X_i$ ) of the product of these distributions

    Place the new distribution on **List**

**End**

Return **List**

# VARIABLE ELIMINATION: ORDER MATTERS



Right order:  $O(n)$

Wrong order:  $O(2^n)$