

# Optimal Hyperplanes

CS478 – Machine Learning  
Spring 2008

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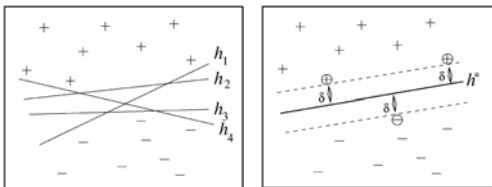
Reading: Schoelkopf/Smola Chapter 7.1-7.3, 7.5 (online)

## Outline

- Optimal hyperplanes and margins
- Hard-margin Support Vector Machine
- Primal optimization problem
- Soft-margin Support Vector Machine

## Optimal Hyperplanes Linear Hard-Margin Support Vector Machine

**Assumption:** Training examples are linearly separable.

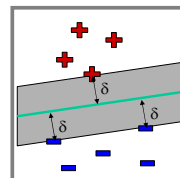


## Hard-Margin Separation

**Goal:** Find hyperplane with the largest distance to the closest training examples.

**Optimization Problem (Primal):**

$$\begin{aligned} \min_{\vec{w}, b} \quad & \frac{1}{2} \vec{w} \cdot \vec{w} \\ \text{s.t.} \quad & y_1(\vec{w} \cdot \vec{x}_1 + b) \geq 1 \\ & \dots \\ & y_n(\vec{w} \cdot \vec{x}_n + b) \geq 1 \end{aligned}$$

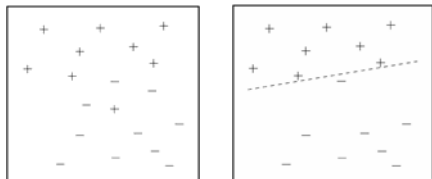


**Support Vectors:** Examples with minimal distance (i.e. margin).

## Non-Separable Training Data

**Limitations of hard-margin formulation**

- For some training data, there is no separating hyperplane.
- Complete separation (i.e. zero training error) can lead to suboptimal prediction error.



## Soft-Margin Separation

**Idea:** Maximize margin and minimize training error.

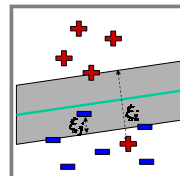
**Hard-Margin OP (Primal):**

$$\begin{aligned} \min_{\vec{w}, b} \quad & \frac{1}{2} \vec{w} \cdot \vec{w} \\ \text{s.t.} \quad & y_1(\vec{w} \cdot \vec{x}_1 + b) \geq 1 \\ & \dots \\ & y_n(\vec{w} \cdot \vec{x}_n + b) \geq 1 \end{aligned}$$

**Soft-Margin OP (Primal):**

$$\begin{aligned} \min_{\vec{w}, b, \xi} \quad & \frac{1}{2} \vec{w} \cdot \vec{w} + C \sum_{i=1}^n \xi_i \\ \text{s.t.} \quad & y_1(\vec{w} \cdot \vec{x}_1 + b) \geq 1 - \xi_1 \wedge \xi_1 \geq 0 \\ & \dots \\ & y_n(\vec{w} \cdot \vec{x}_n + b) \geq 1 - \xi_n \wedge \xi_n \geq 0 \end{aligned}$$

- Slack variable  $\xi_i$  measures by how much  $(x_i, y_i)$  fails to achieve margin  $\delta$
- $\sum \xi_i$  is upper bound on number of training errors
- $C$  is a parameter that controls trade-off between margin and training error.



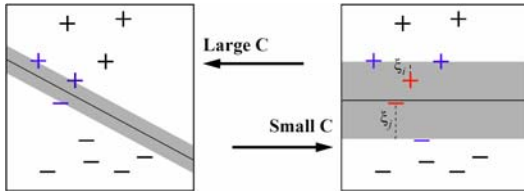
## Controlling Soft-Margin Separation

- $\sum \xi_i$  is upper bound on number of training errors
- $C$  is a parameter that controls trade-off between margin and training error.

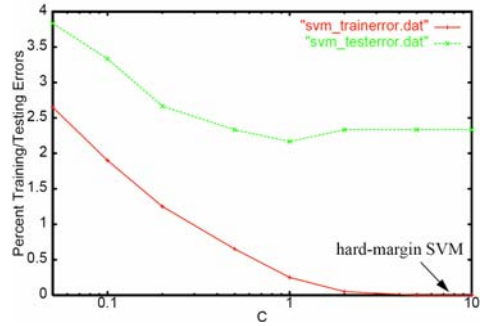
Soft-Margin OP (Primal):

$$\min_{\vec{w}, \xi, b} \frac{1}{2} \|\vec{w}\|^2 + C \sum_{i=1}^n \xi_i$$

s.t.  $y_1(\vec{w} \cdot \vec{x}_1 + b) \geq 1 - \xi_1 \wedge \xi_1 \geq 0$   
 ...  
 $y_n(\vec{w} \cdot \vec{x}_n + b) \geq 1 - \xi_n \wedge \xi_n \geq 0$



## Example Reuters "acq": Varying C



## Example: Margin in High-Dimension

Training Sample $S_{train}$	$\vec{x}$							$y$
	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	
$(\vec{x}_1, y_1)$	1	0	0	1	0	0	0	1
$(\vec{x}_2, y_2)$	1	0	0	0	1	0	0	1
$(\vec{x}_3, y_3)$	0	1	0	0	0	1	0	-1
$(\vec{x}_4, y_4)$	0	1	0	0	0	0	1	-1
	$\vec{w}$							$b$
	$w_1$	$w_2$	$w_3$	$w_4$	$w_5$	$w_6$	$w_7$	
Hyperplane 1	1	1	0	0	0	0	0	2
Hyperplane 2	0	0	0	1	1	-1	-1	0
Hyperplane 3	1	-1	1	0	0	0	0	0
Hyperplane 4	0.5	-0.5	0	0	0	0	0	0
Hyperplane 5	1	-1	0	0	0	0	0	0
Hyperplane 6	0.95	-0.95	0	0.05	0.05	-0.05	-0.05	0