

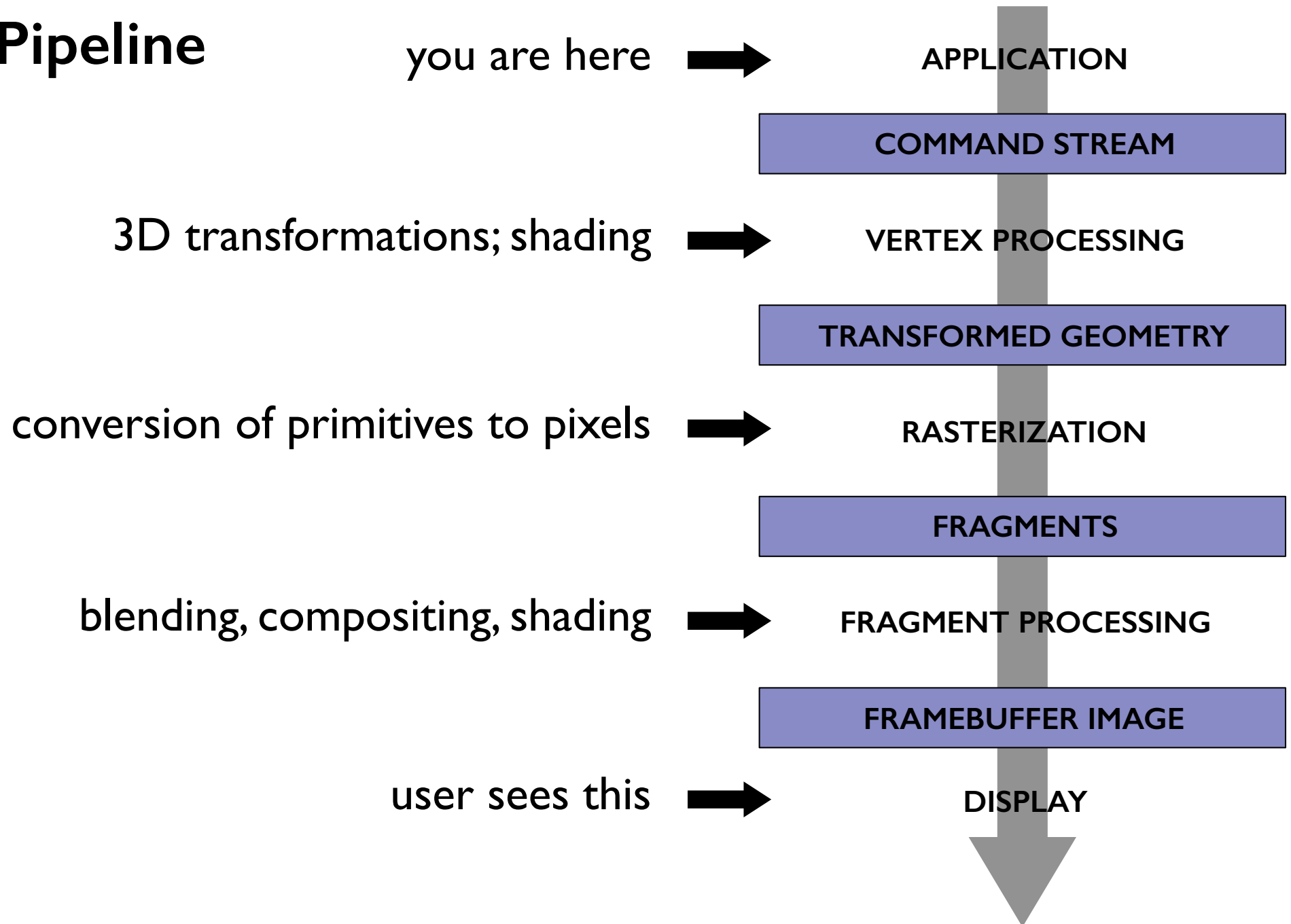
# Pipeline

## CS 4620 Lecture 17

# Announcements

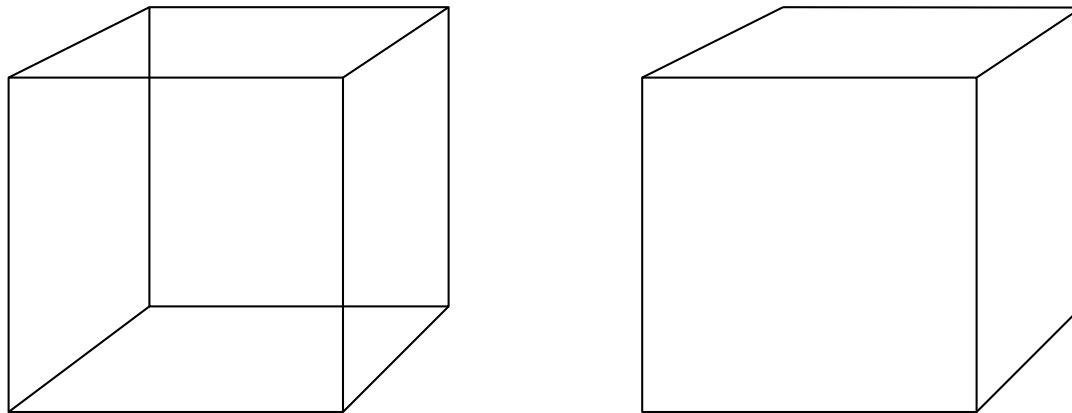
- A3 due on Thu
  - Will send mail about grading once finalized

# Pipeline



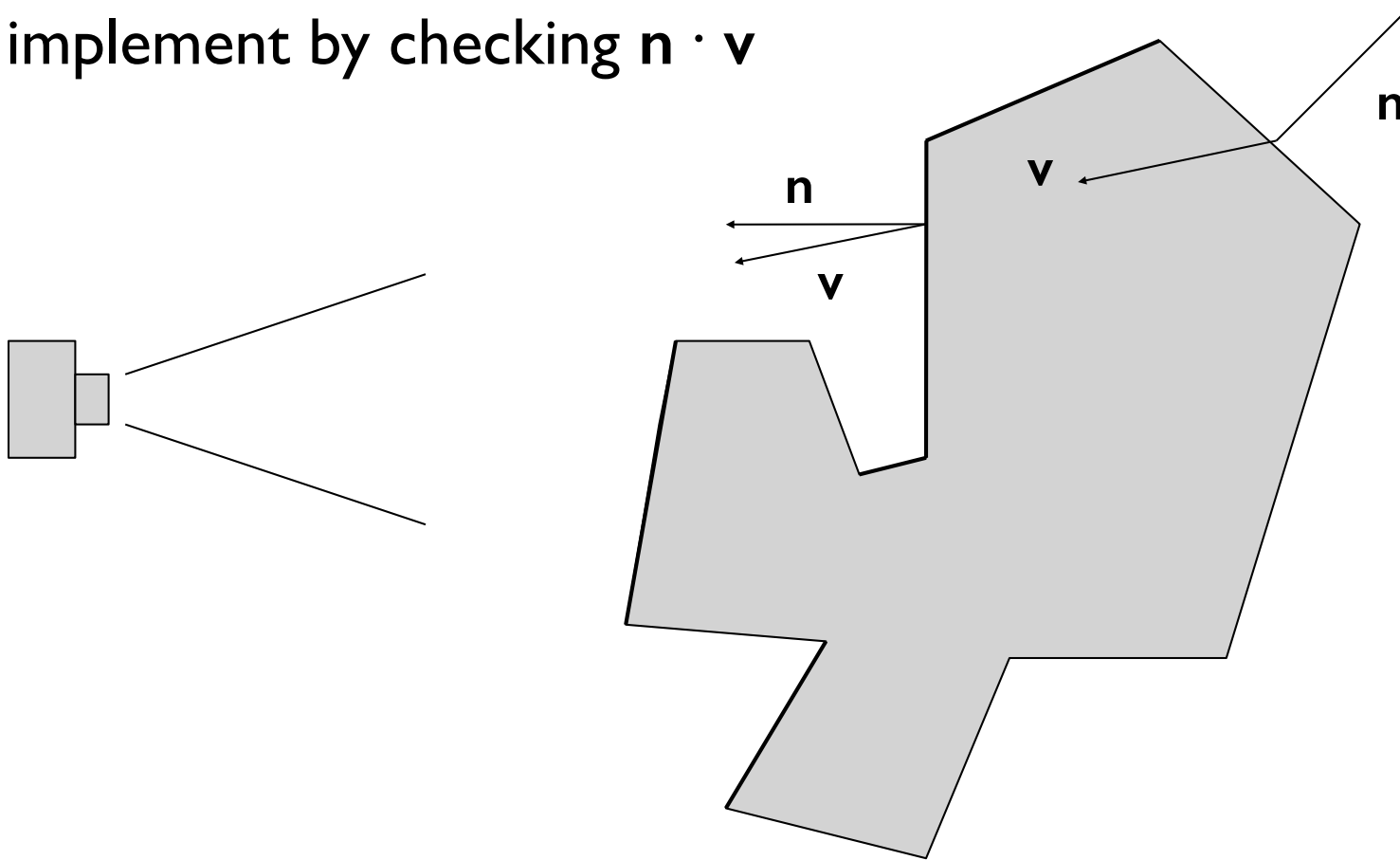
# Hidden surface elimination

- We have discussed how to map primitives to image space
  - projection and perspective are depth cues
  - occlusion is another very important cue



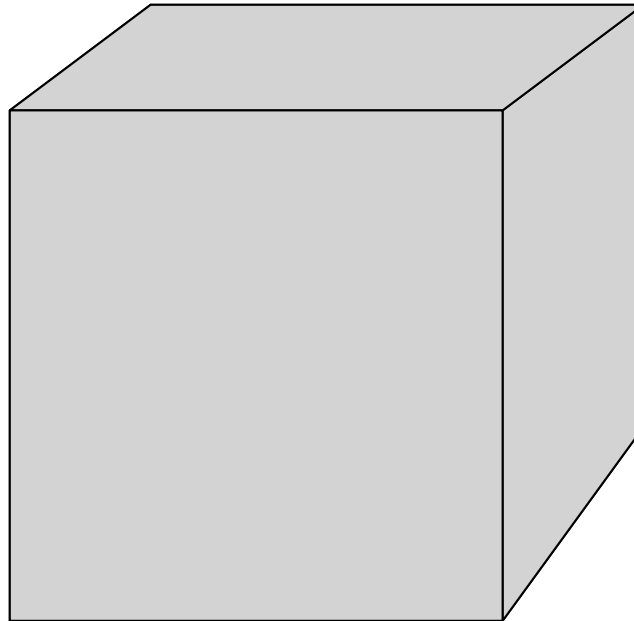
# Back face culling

- For closed shapes you will never see the inside
  - therefore only draw surfaces that face the camera
  - implement by checking  $\mathbf{n} \cdot \mathbf{v}$



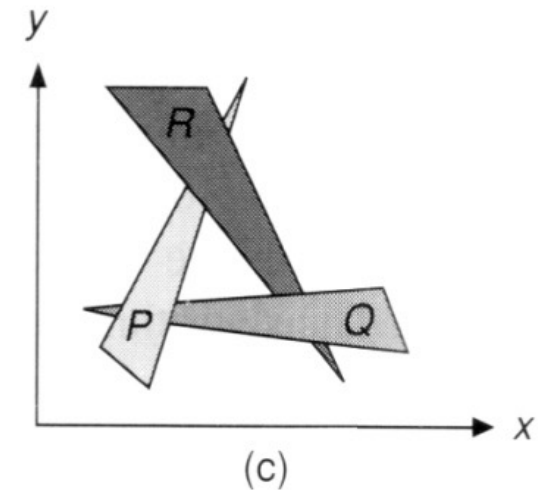
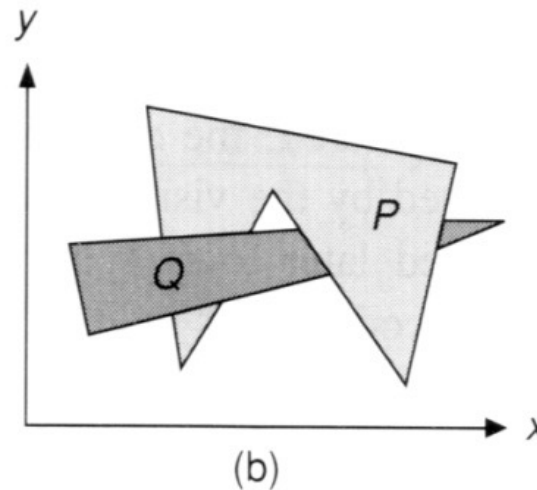
# Painter's algorithm

- Simplest way to do hidden surfaces
- Draw from back to front, use overwriting in framebuffer



# Painter's algorithm

- Amounts to a topological sort of the graph of occlusions
  - that is, an edge from A to B means A sometimes occludes B
  - any sort is valid
    - ABCDEF
    - BADCFE
  - if there are cycles there is no sort



[Foley et al.]

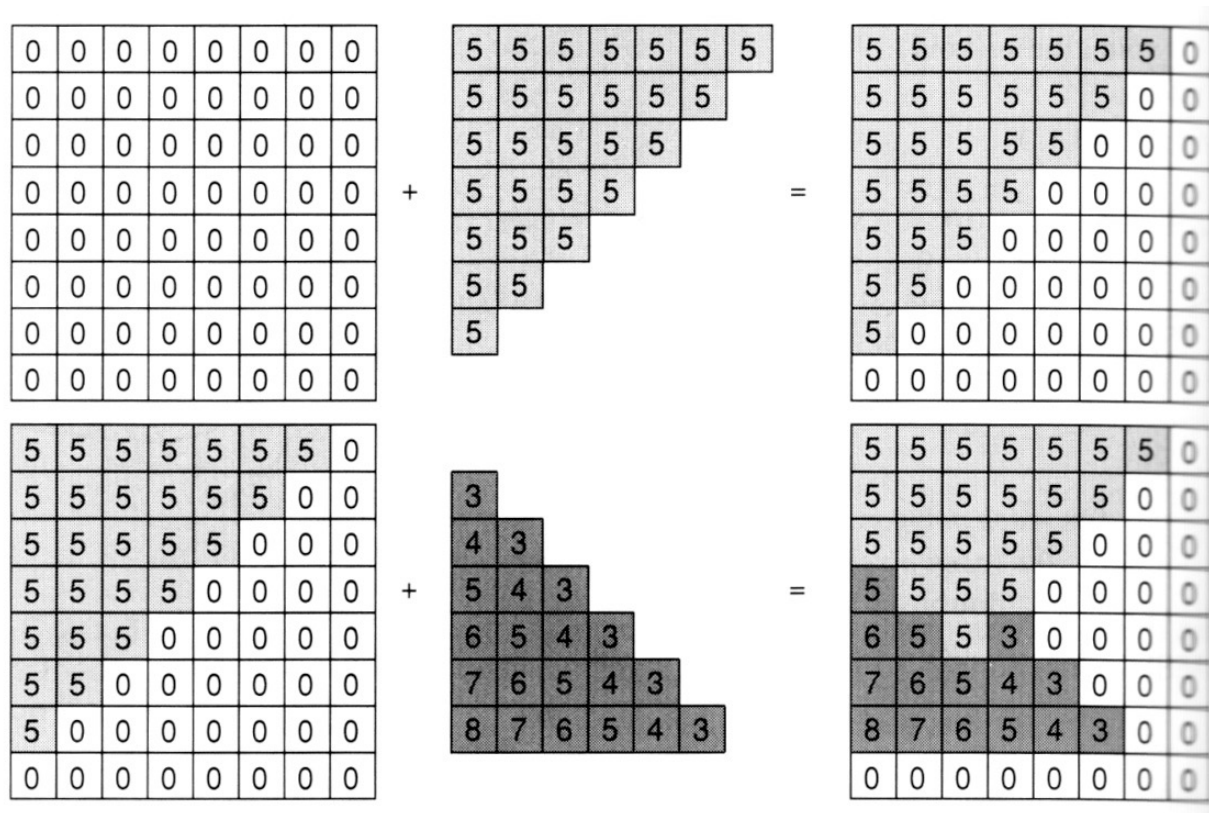
# The z buffer

- In many (most) applications maintaining a z sort is too expensive
  - changes all the time as the view changes
  - many data structures exist, but complex
- Solution: draw in any order, keep track of closest
  - allocate extra channel per pixel to keep track of closest depth so far
  - when drawing, compare object's depth to current closest depth and discard if greater



# The z buffer

- An example of a memory-intensive brute force approach that works and has become the standard
- Another one is texture mapping

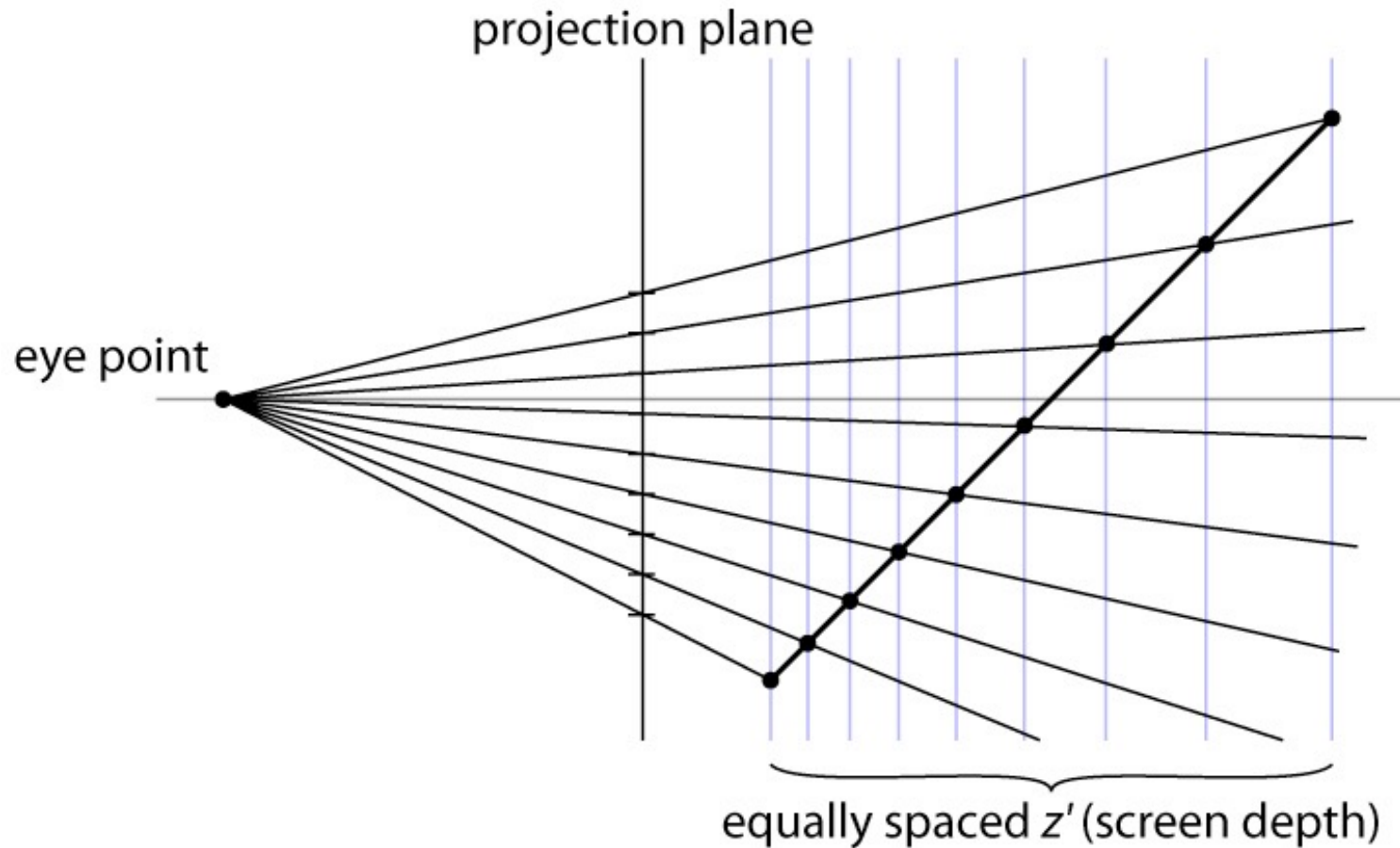


[Foley et al.]

# Precision in z buffer

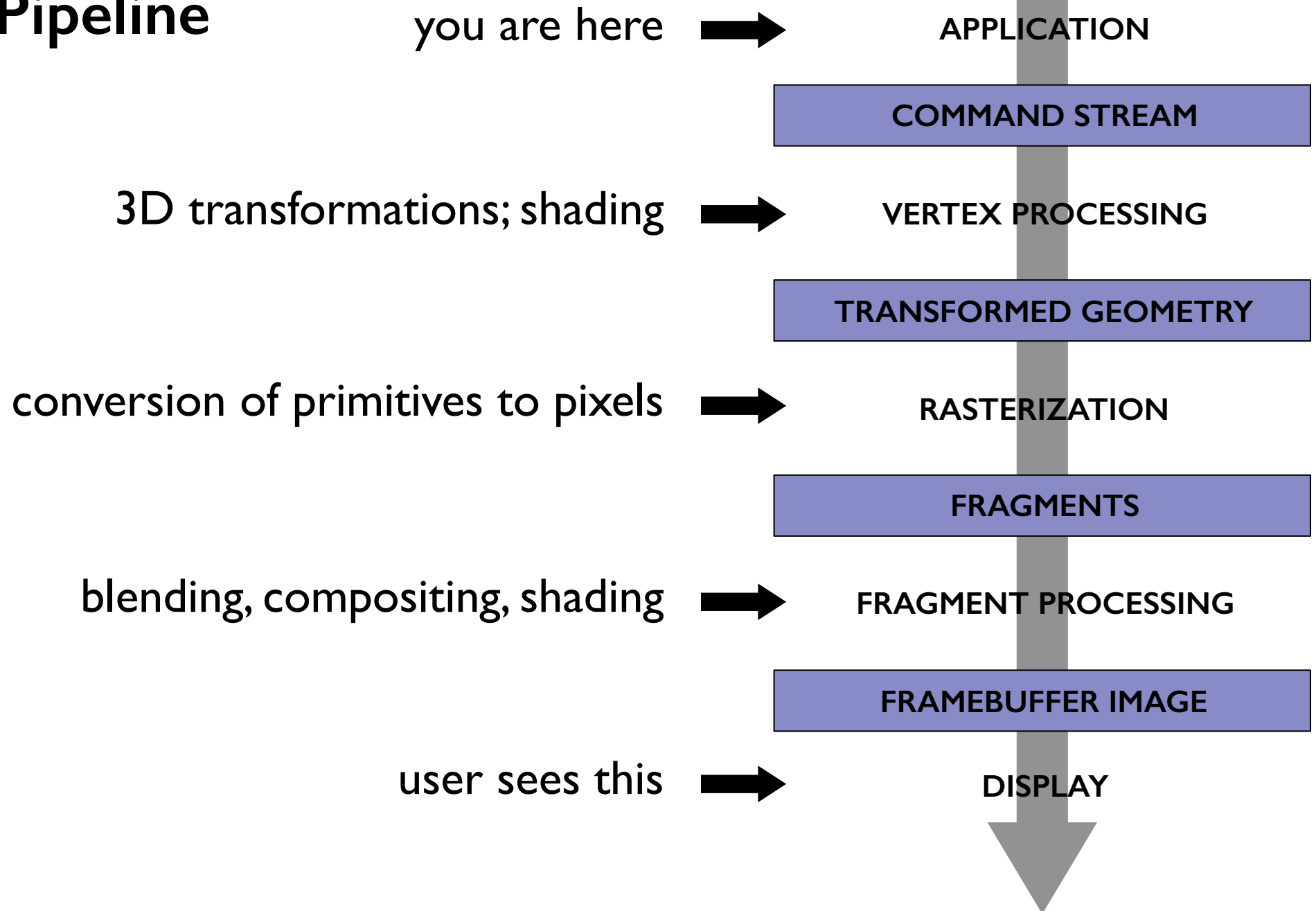
- The precision is distributed between the near and far clipping planes
  - this is why these planes have to exist
  - also why you can't always just set them to very small and very large distances
- Generally use  $z'$  (not world  $z$ ) in z buffer

# Interpolating in projection



linear interp. in screen space  $\neq$  linear interp. in world (eye) space

# Pipeline



# Demos

[Shader toy](#)

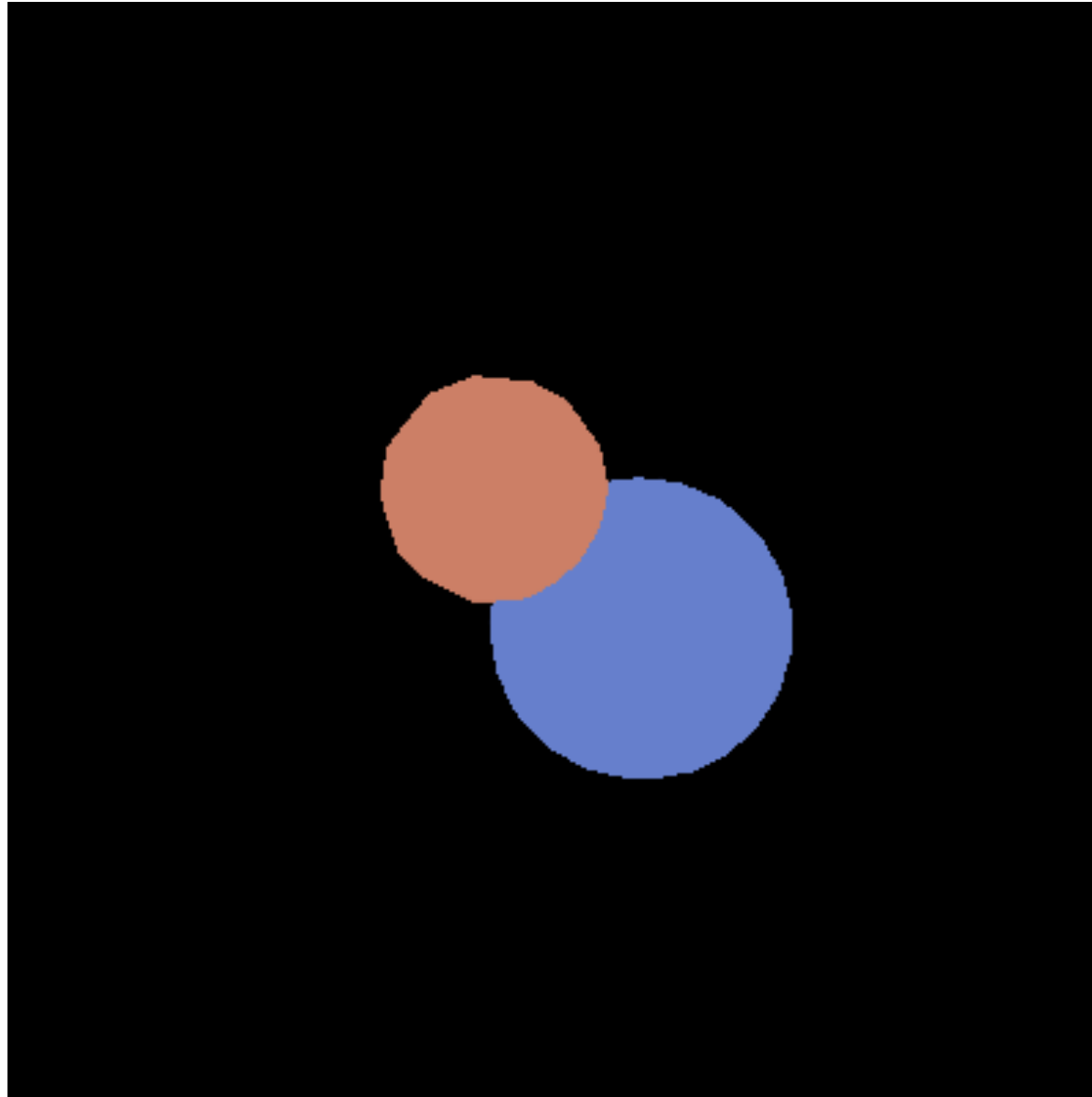
<https://www.shadertoy.com/>

<http://acko.net/files/gltalks/pixelfactory/online.html>

# Pipeline for minimal operation

- Vertex stage (input: position / vtx; color)
  - transform position (object to screen space)
  - pass through color
- Rasterizer
  - pass through color
- Fragment stage (output: color)
  - write to color planes

# Result of minimal pipeline

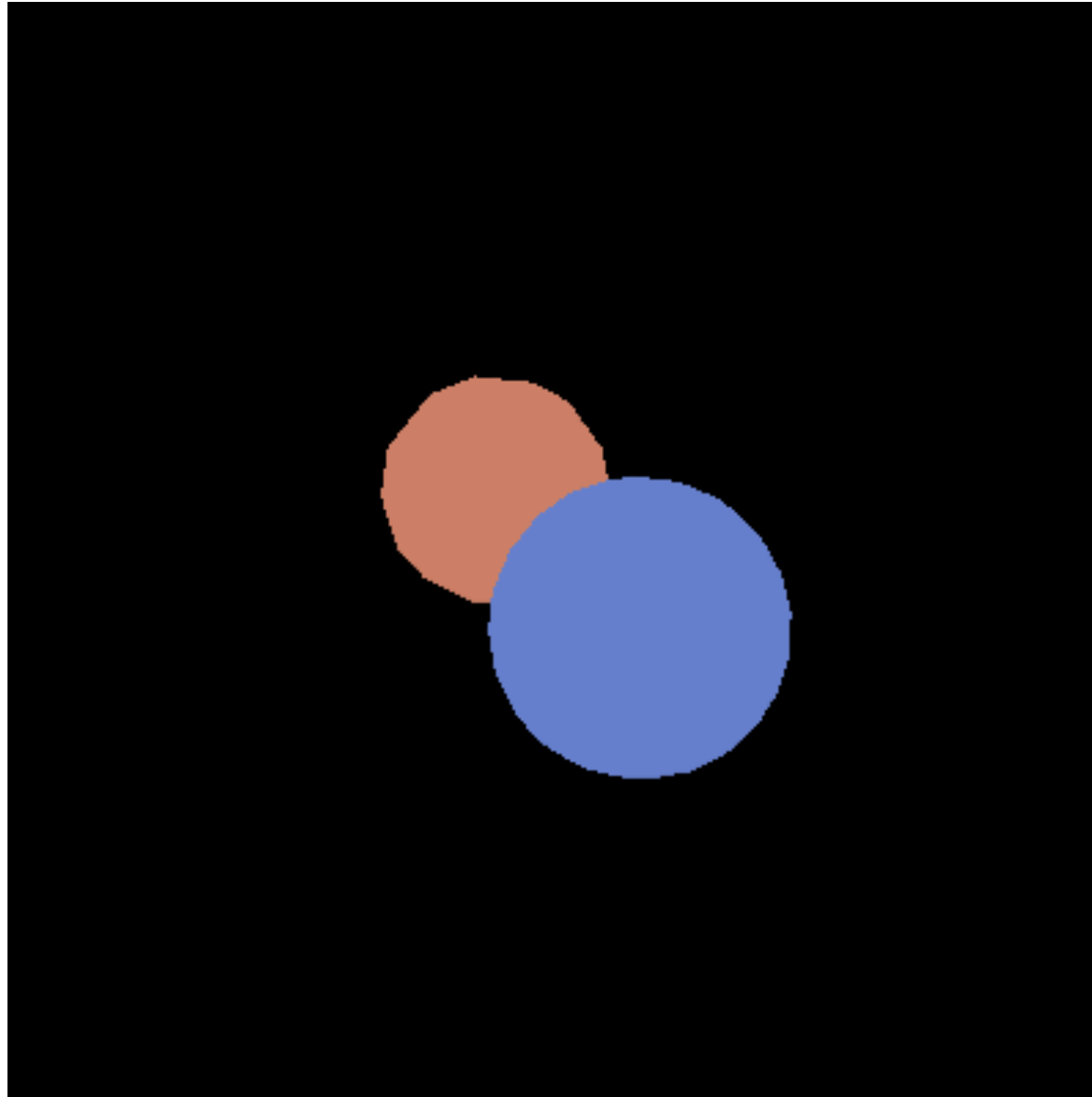


# Pipeline for basic z buffer

- Vertex stage (input: position / vtx; color)
  - transform position (object to screen space)
  - pass through color
- Rasterizer
  - interpolated parameter:  $z'$  (screen  $z$ )
  - pass through color
- Fragment stage (output: color,  $z'$ )
  - write to color planes only if interpolated  $z' <$  current  $z'$

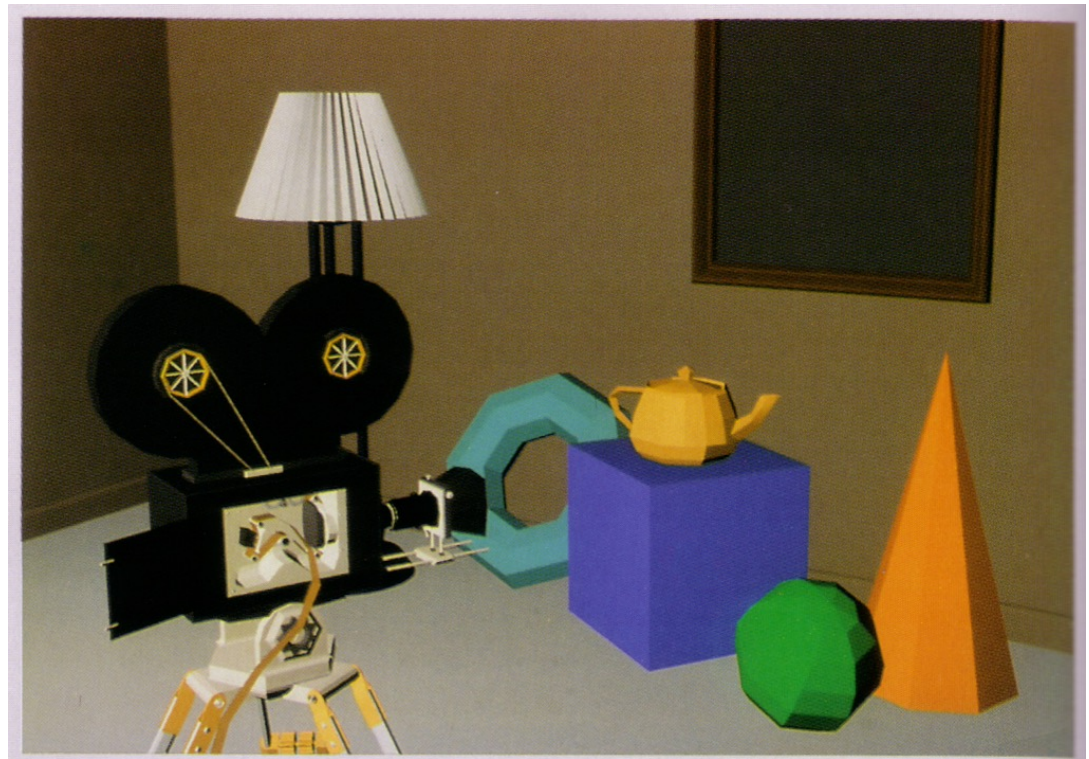


# Result of z-buffer pipeline



# Flat shading

- Shade using the real normal of the triangle
  - same result as ray tracing a bunch of triangles
- Leads to constant shading and faceted appearance
  - truest view of the mesh geometry



**Plate II.29** *Shutterbug*. Individually shaded polygons with diffuse reflection (Sections 14.4.2 and 16.2.3). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)

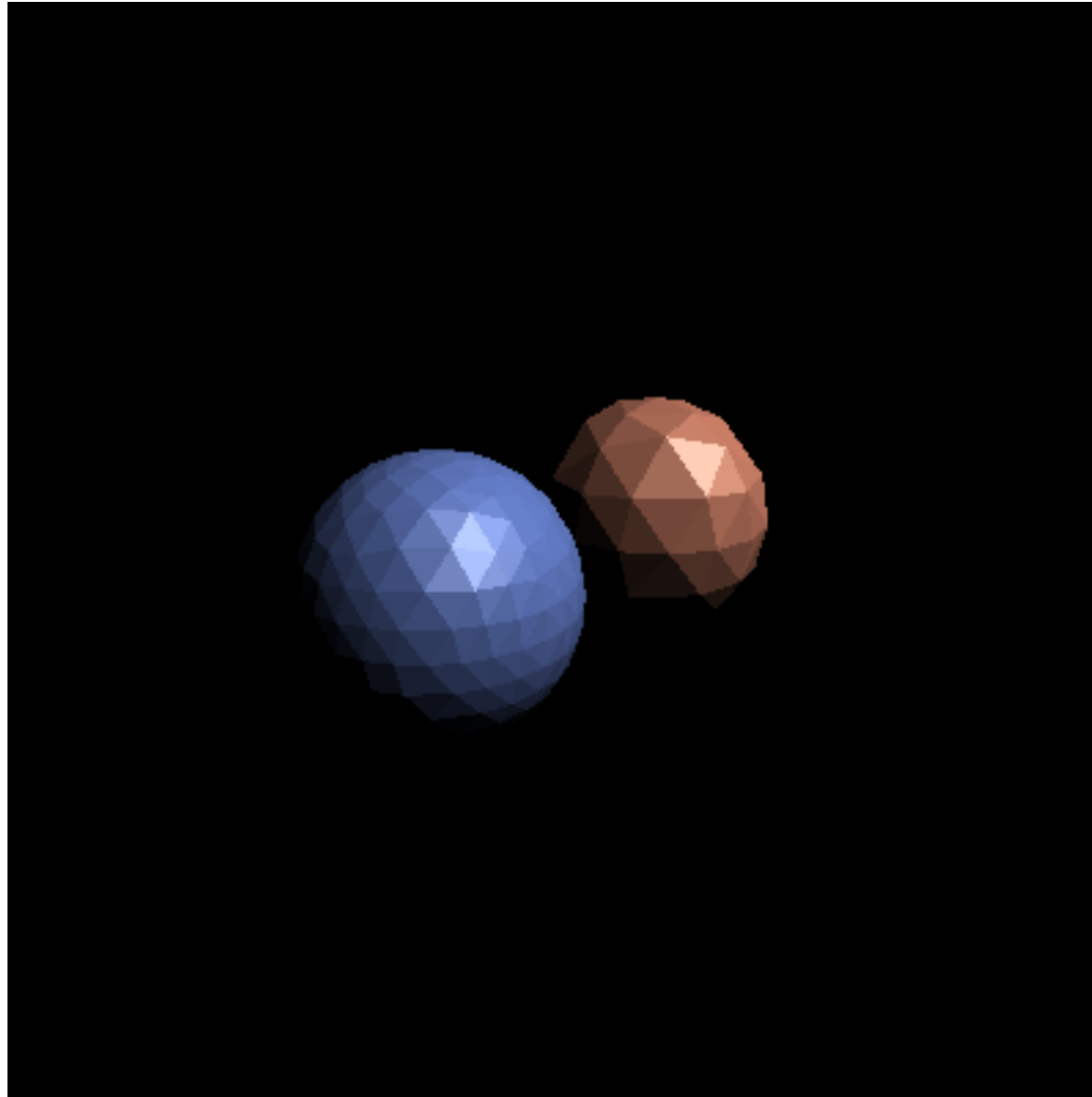
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# Pipeline for flat shading

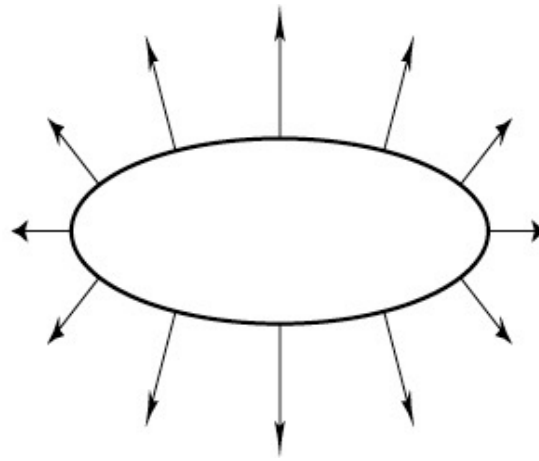
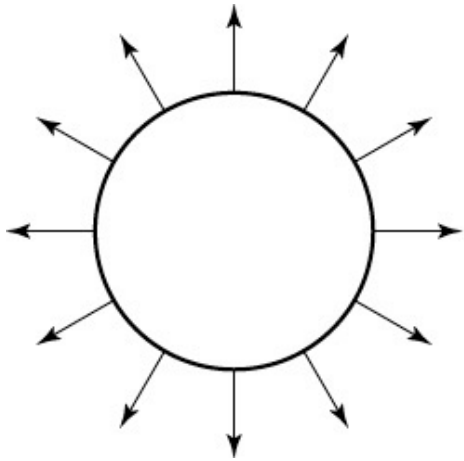
- Vertex stage (input: position / vtx; color and normal)
  - transform position and normal (object to eye space)
  - compute shaded color per triangle using normal
  - transform position (eye to screen space)
- Rasterizer
  - interpolated parameters:  $z'$  (screen  $z$ )
  - pass through color
- Fragment stage (output: color,  $z'$ )
  - write to color planes only if interpolated  $z' <$  current  $z'$

# Result of flat-shading pipeline



# Transforming normal vectors

- Transforming surface normals
  - differences of points (and therefore tangents) transform OK
  - normals do not --> use inverse transpose matrix



have:  $\mathbf{t} \cdot \mathbf{n} = \mathbf{t}^T \mathbf{n} = 0$

want:  $M\mathbf{t} \cdot X\mathbf{n} = \mathbf{t}^T M^T X\mathbf{n} = 0$

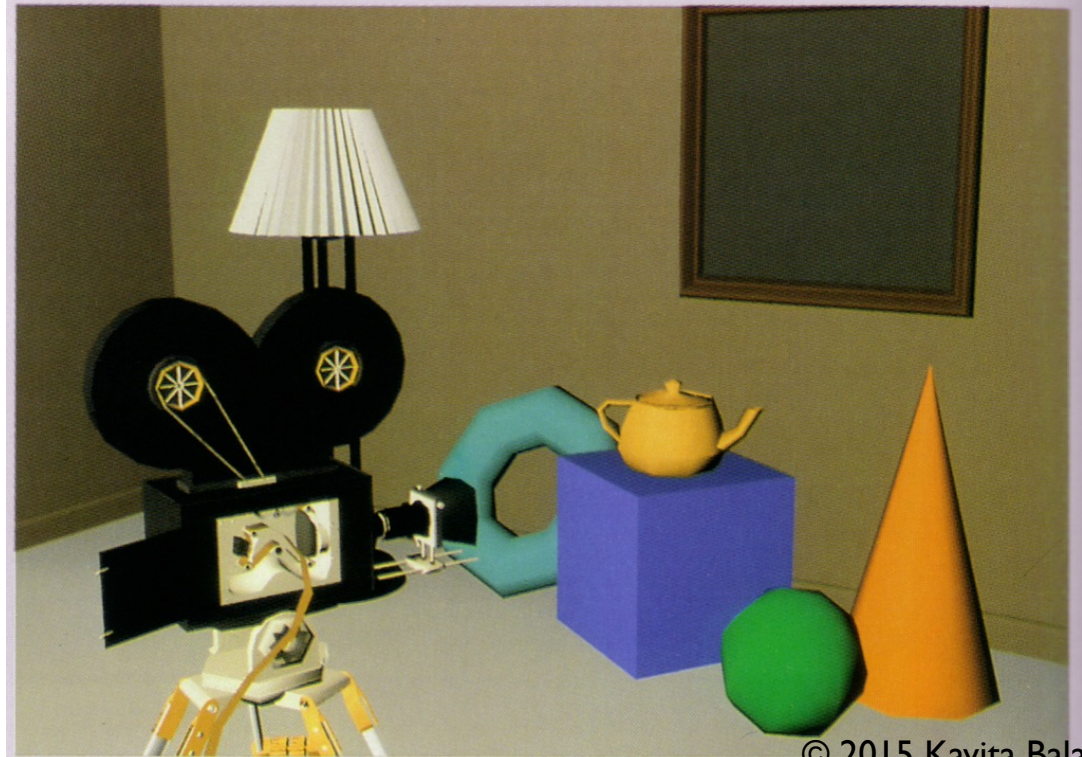
so set  $X = (M^T)^{-1}$

then:  $M\mathbf{t} \cdot X\mathbf{n} = \mathbf{t}^T M^T (M^T)^{-1} \mathbf{n} = \mathbf{t}^T \mathbf{n} = 0$

# Gouraud shading

- Often we're trying to draw smooth surfaces, so facets are an artifact
  - compute colors at vertices using vertex normals
  - interpolate colors across triangles
  - “Gouraud shading”
  - “Smooth shading”

**Plate II.30** *Shutterbug*. Gouraud shaded polygons with diffuse reflection (Sections 14.4.3 and 16.2.4). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)



[Foley et al.]

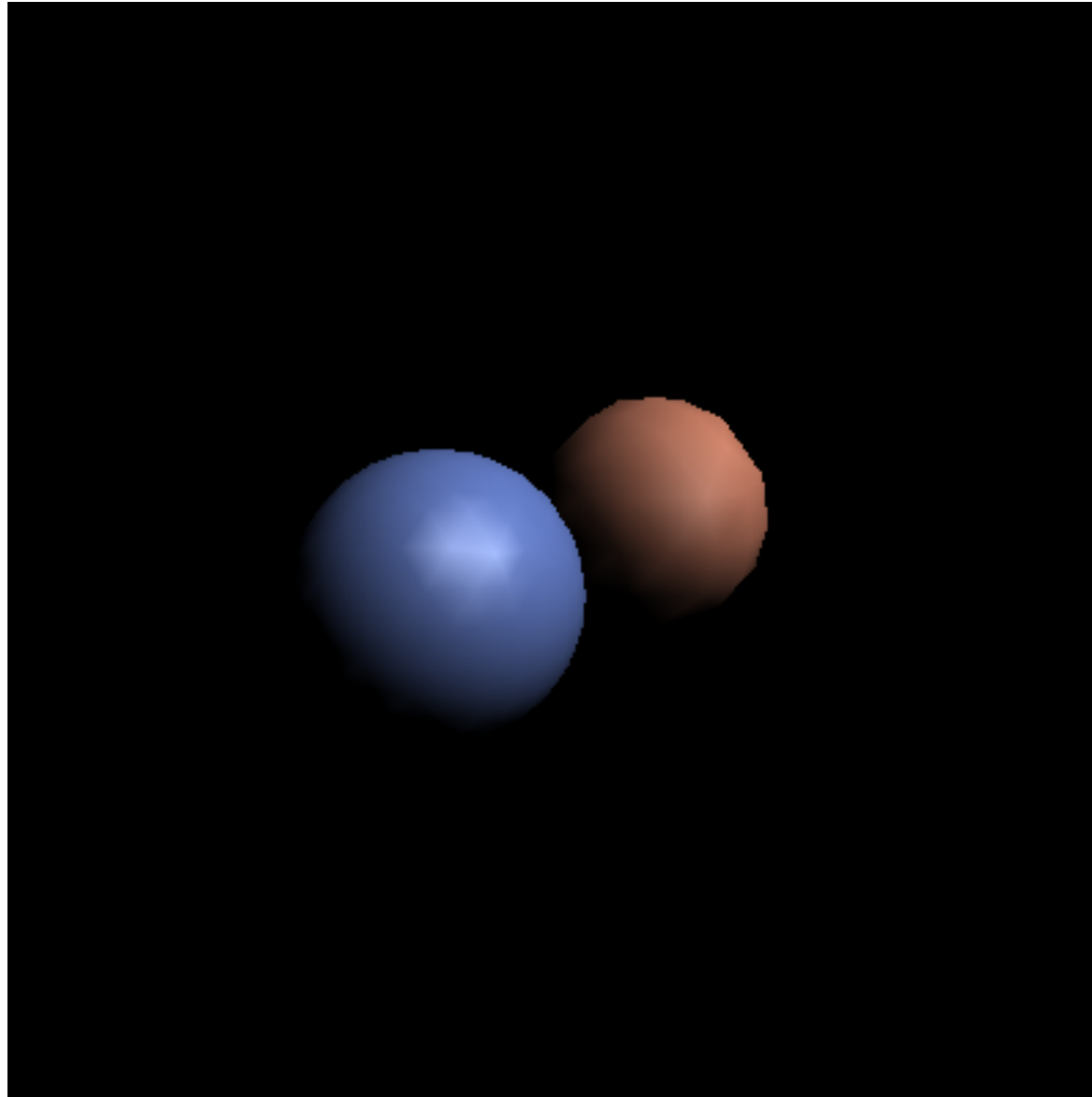
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# Pipeline for Gouraud shading

- Vertex stage (input: position, color, and normal / vtx)
  - transform position and normal (object to eye space)
  - compute shaded color per vertex
  - transform position (eye to screen space)
- Rasterizer
  - interpolated parameters:  $z'$  (screen  $z$ );  $r, g, b$  color
- Fragment stage (output: color,  $z'$ )
  - write to color planes only if interpolated  $z' <$  current  $z'$

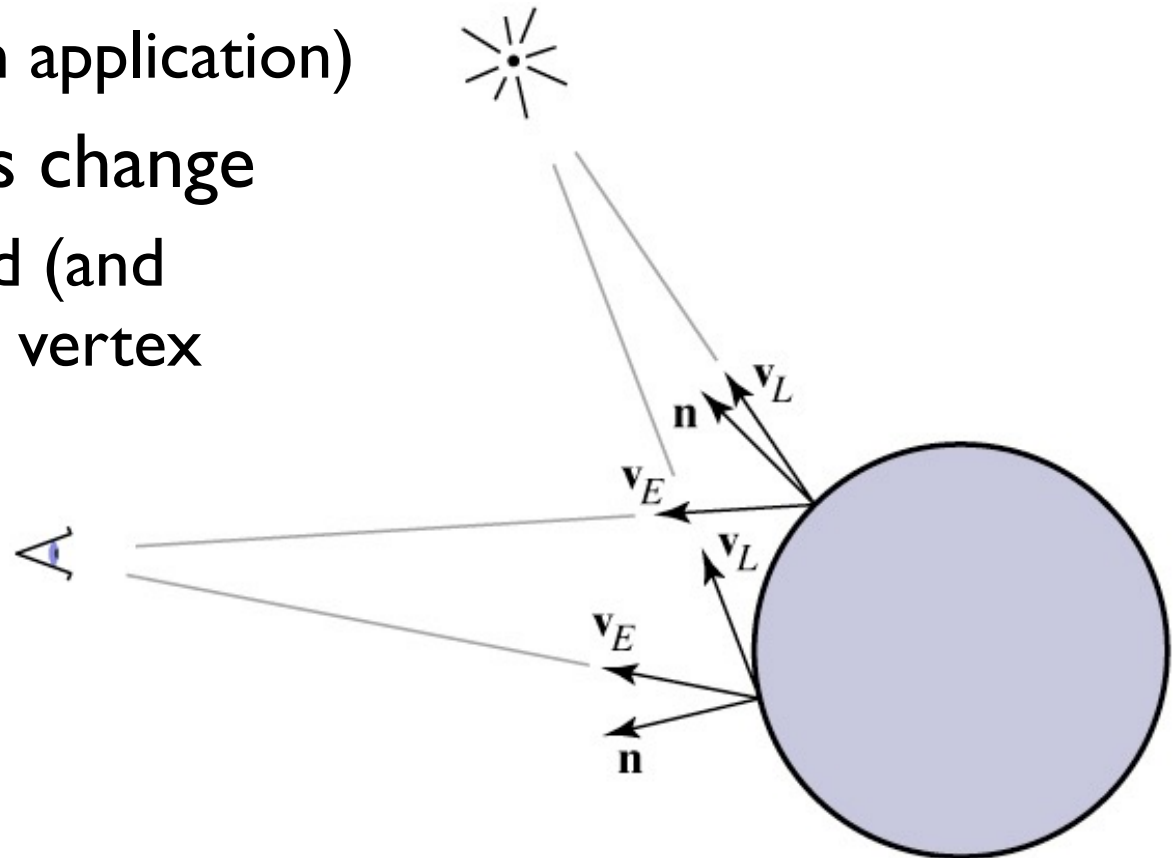
# Result of Gouraud shading pipeline





# Local vs. infinite viewer, light

- Phong illumination requires geometric information:
  - light vector (function of position)
  - eye vector (function of position)
  - surface normal (from application)
- Light and eye vectors change
  - need to be computed (and normalized) for each vertex

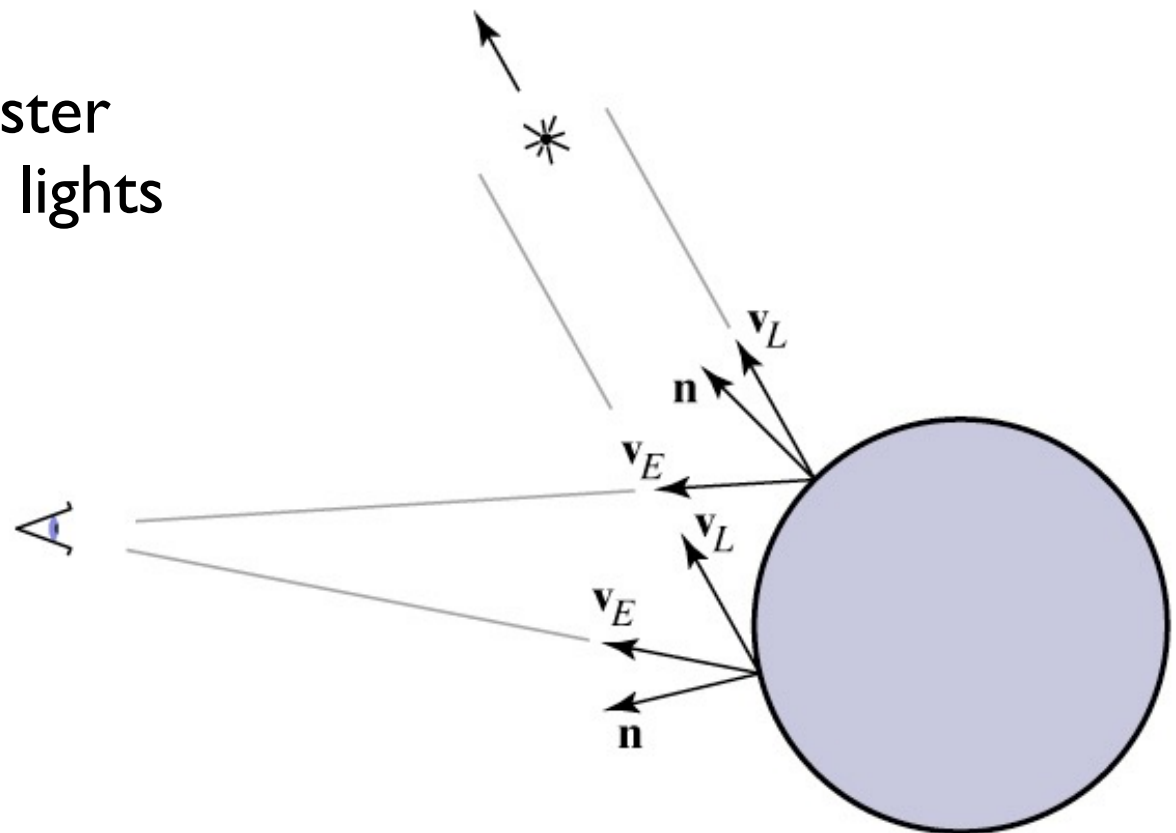


# Local vs. infinite viewer, light

- Look at case when eye or light is far away:
  - distant light source: nearly parallel illumination
  - distant eye point: nearly orthographic projection
  - in both cases, eye or light vector changes very little
- Optimization: approximate eye and/or light as infinitely far away

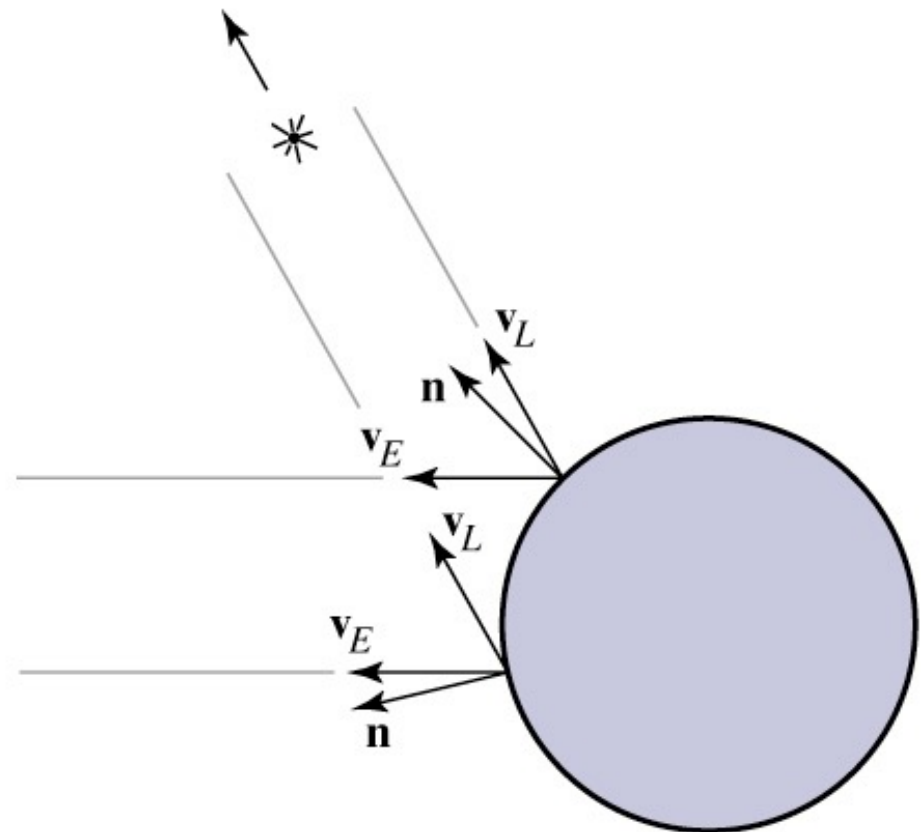
# Directional light

- Directional (infinitely distant) light source
  - light vector always points in the same direction
  - often specified by position  $[x \ y \ z \ 0]$
  - many pipelines are faster if you use directional lights



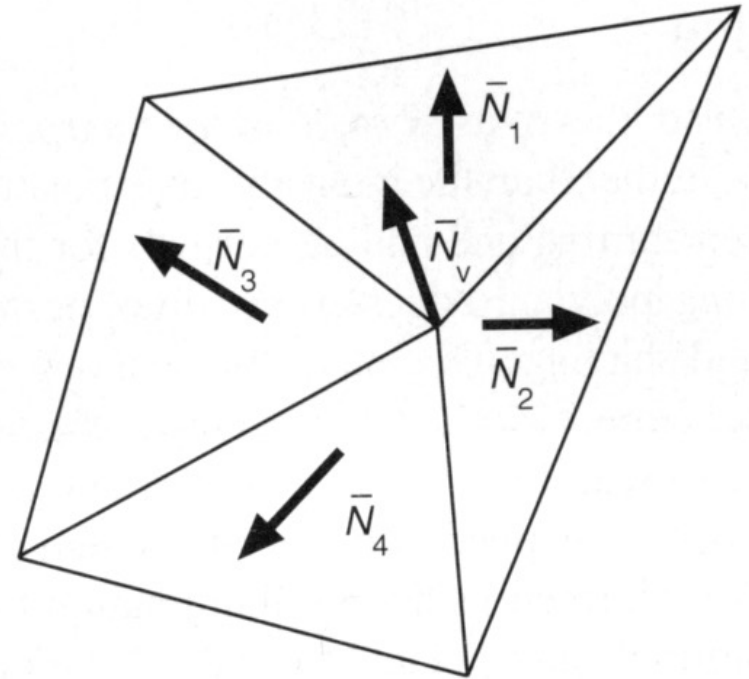
# Infinite viewer

- Orthographic camera
  - projection direction is constant
- “Infinite viewer”
  - even with perspective, can approximate eye vector using the image plane normal
  - Blinn-Phong: light, eye, half vectors all constant!



# Vertex normals

- Need normals at vertices to compute Gouraud shading
- Best to get vtx. normals from the underlying geometry
  - e. g. spheres example
- Otherwise have to infer vtx. normals from triangles
  - simple scheme: average surrounding face normals



[Foley et al.]

$$N_v = \frac{\sum_i N_i}{\|\sum_i N_i\|}$$

# Non-diffuse Gouraud shading

- Can apply Gouraud shading to any illumination model
  - it's just an interpolation method
- Results are not so good with fast-varying models like specular ones
  - problems with any highlights smaller than a triangle

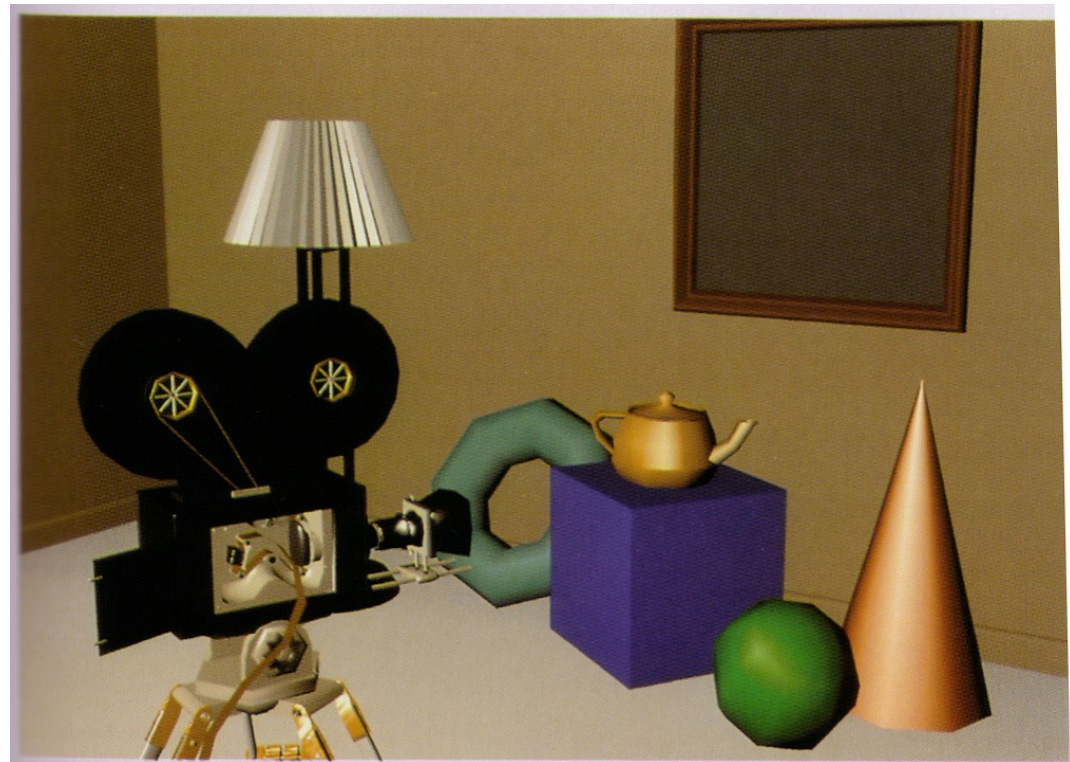


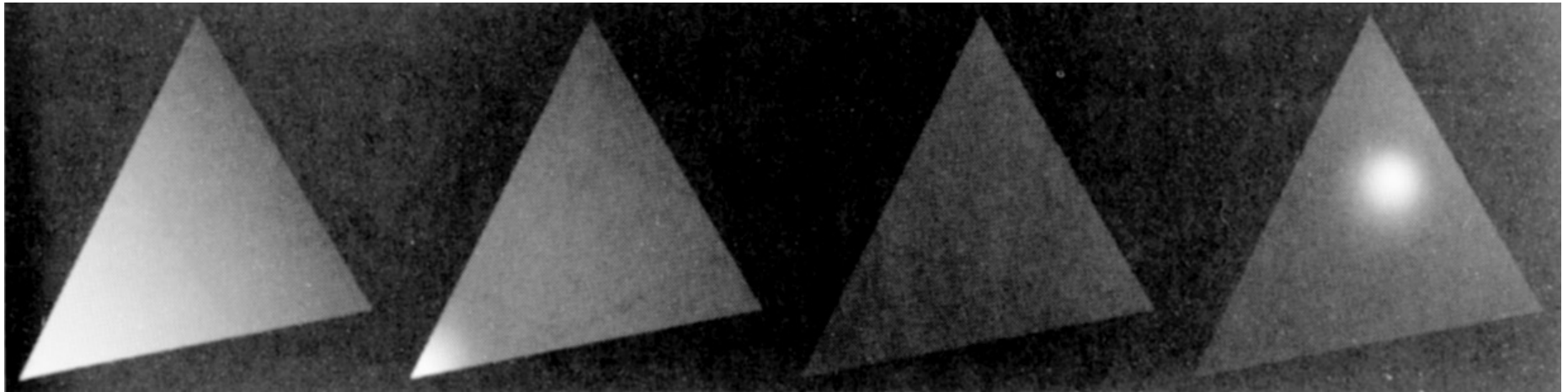
Plate II.31 *Shutterbug*. Gouraud shaded polygons with specular reflection (Sections 14.4.4 and 16.2.5). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)

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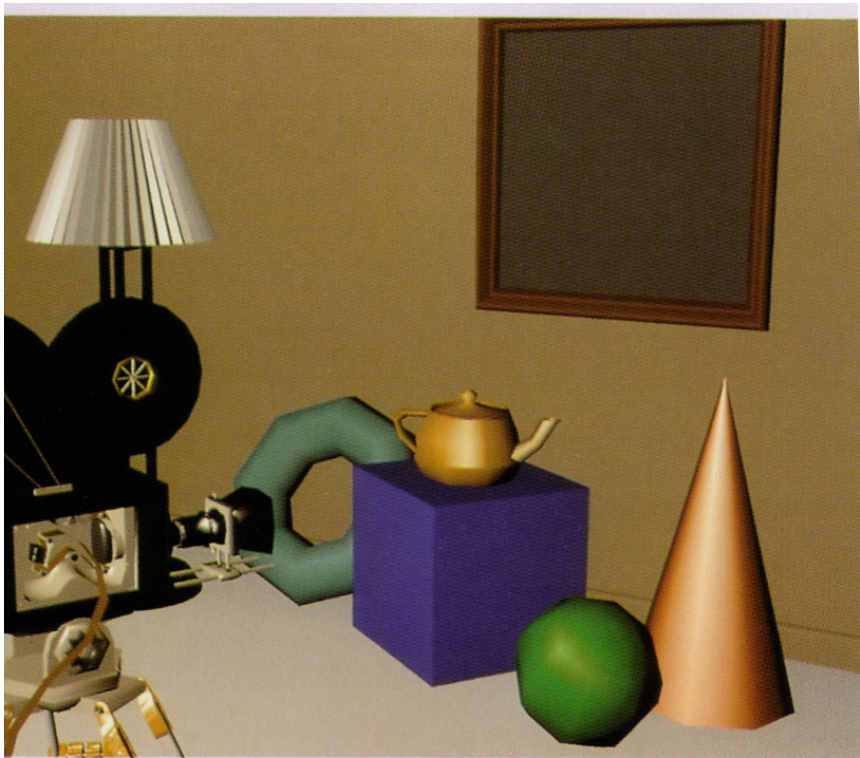
# Per-pixel (Phong) shading

- Get higher quality by interpolating the normal
  - just as easy as interpolating the color
  - but now we are evaluating the illumination model per pixel rather than per vertex (and normalizing the normal first)
  - in pipeline, this means we are moving illumination from the vertex processing stage to the fragment processing stage



# Per-pixel (Phong) shading

- Bottom line: produces much better highlights



Shutterbug. Gouraud shaded polygons with specular reflection (Sections 14.4.4 and 16.2.5). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)

Plate II.32 Shutterbug. Phong shaded polygons with specular reflection (Sections 14.4.4 and 16.2.5). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)



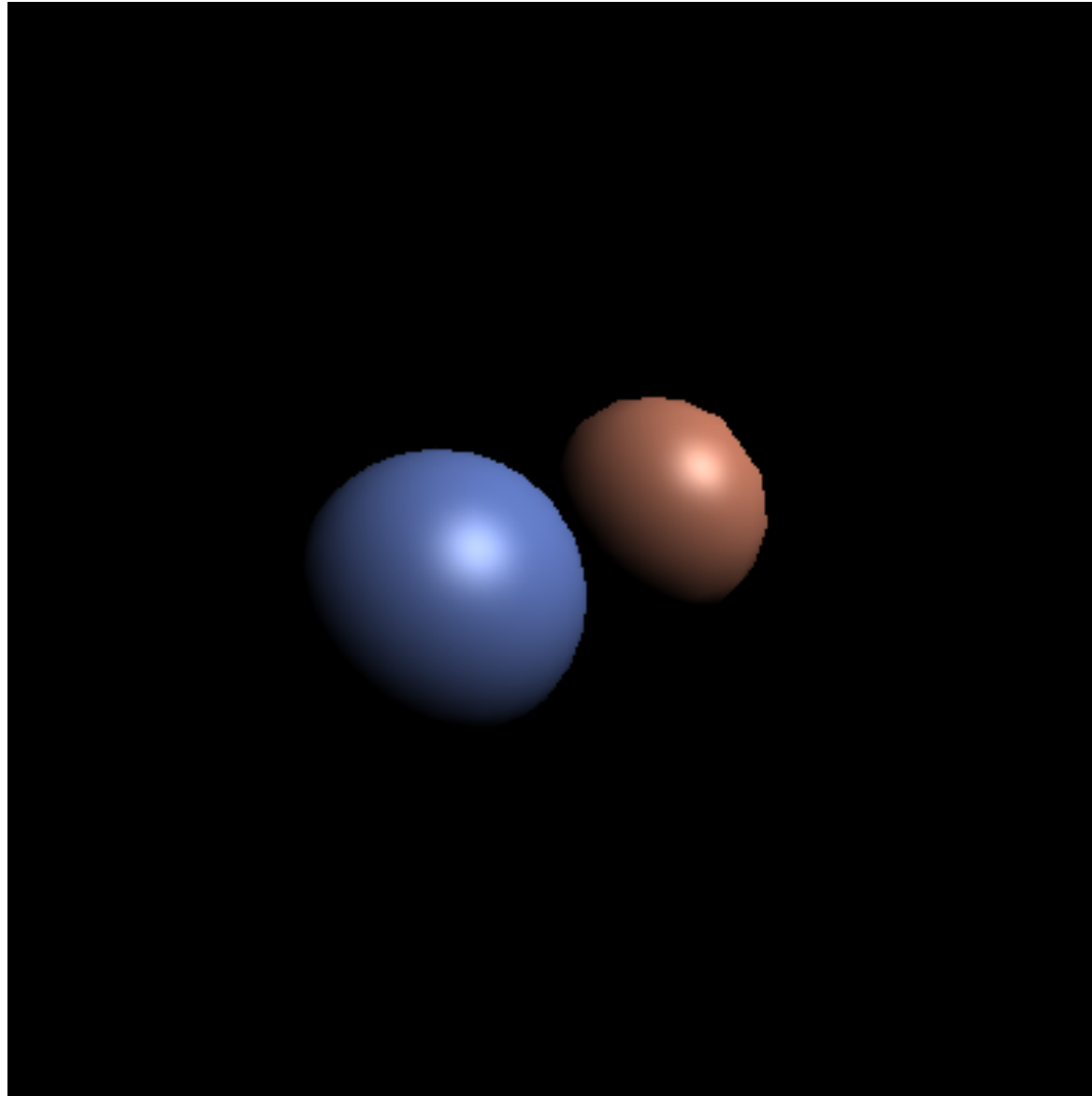
[Foley et al.]



# Pipeline for per-pixel shading

- Vertex stage (input: position, color, and normal / vtx)
  - transform position and normal (object to eye space)
  - transform position (eye to screen space)
  - pass through color
- Rasterizer
  - interpolated parameters:  $z'$  (screen  $z$ );  $r, g, b$  color;  $x, y, z$  normal
- Fragment stage (output: color,  $z'$ )
  - compute shading using interpolated color and normal
  - write to color planes only if interpolated  $z' <$  current  $z'$

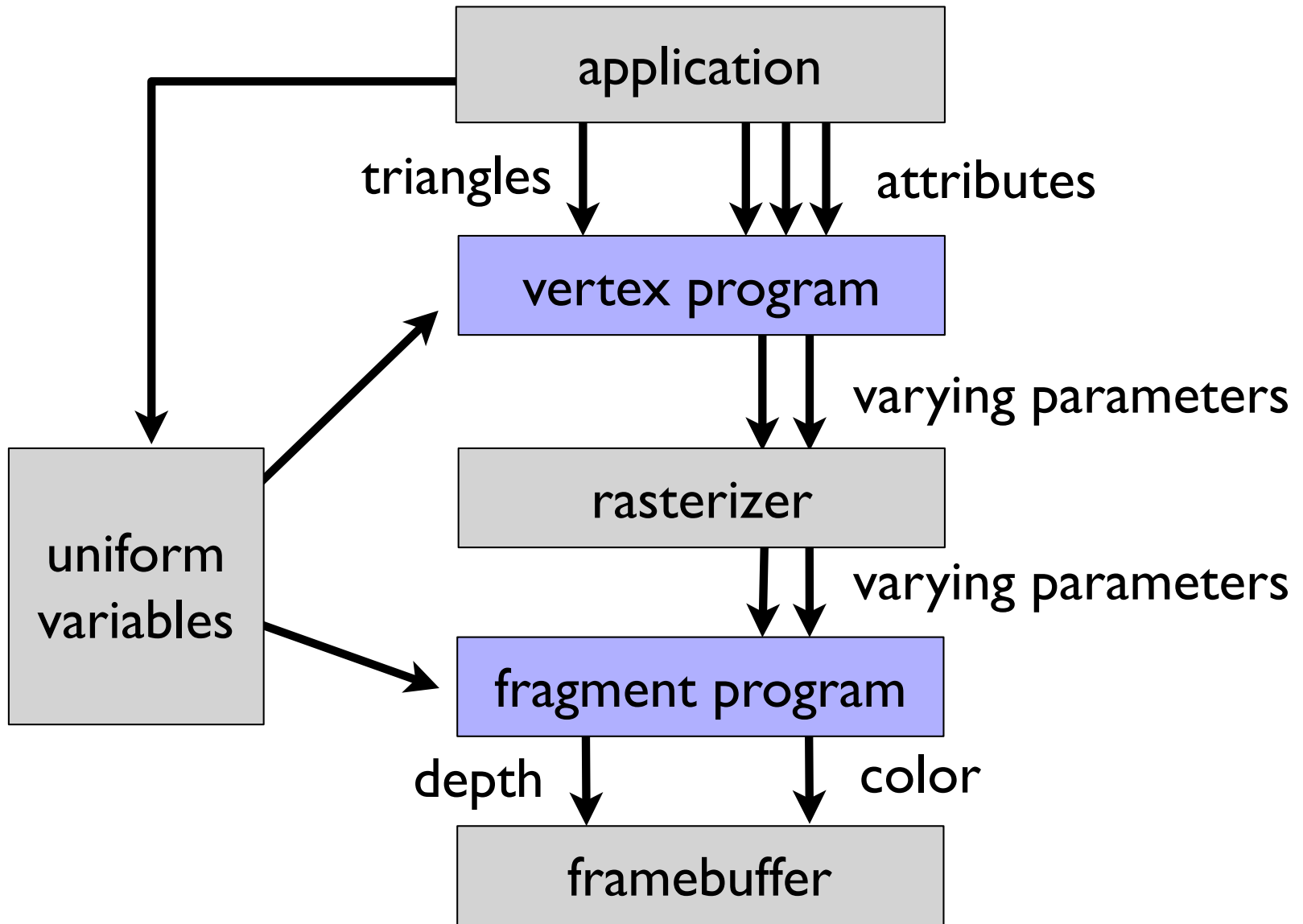
# Result of per-pixel shading pipeline



# Programming hardware pipelines

- Modern hardware graphics pipelines are flexible
  - programmer defines exactly what happens at each stage
  - do this by writing *shader programs* in domain-specific languages called *shading languages*
  - rasterization is fixed-function, as are some other operations (depth test, many data conversions, ...)
- One example: OpenGL and GLSL (**GL Shading Language**)
  - several types of shaders process primitives and vertices; most basic is the *vertex program*
  - after rasterization, fragments are processed by a *fragment program*

# GLSL Shaders



# Demos

[Shader toy](#)

<https://www.shadertoy.com/>

<http://acko.net/files/gltalks/pixelfactory/online.html>