Deadlocks: Detection & Avoidance

CS 4410, Operating Systems

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Rachit Agarwal Anne Bracy

See: Ch 6 in OSPP textbook

The slides are the product of many rounds of teaching CS 4410 by Professors Sirer, Bracy, Agarwal, George, and Van Renesse.



System Model

There are non-shared computer resources

- 1+ instances (printers, semaphores, CPU, etc.) Processes need access to these resources
- Acquire resource
 - If resource is available, access is granted
 - If not available, the process is blocked
- Use resource
- Release resource
- Undesirable scenario:
 - Process A acquires resource 1, waits for resource 2
 - Process B acquires resource 2, waits for resource 1
 - Deadlock!

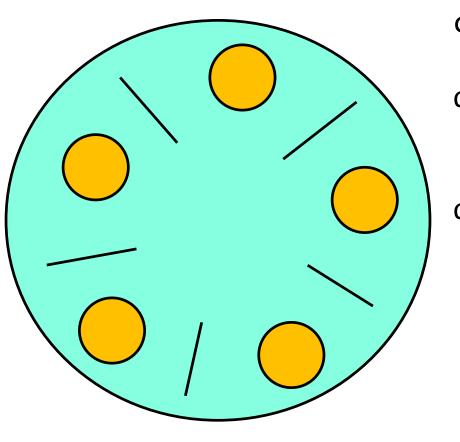
Classic Deadlock



Example 1: Semaphores

```
semaphore:
printer mutex = 1 /* protects printer resource */
                           Process B code:
Process A code:
                            {
{
  /* initial compute */
                              /* initial compute */
                              P(printer mutex)
  P(file mutex)
  P(printer mutex)
                              P(file mutex)
  /* use resources */
                              /* use resources */
  V(printer mutex)
                              V(file mutex)
  V(file mutex)
                              V(printer mutex)
                           }
```

Example 2: Dining Philosophers



class Philosopher: chopsticks[N] = [Semaphore(1),...]

def init (mynum) self.id = mynum def eat(): right = (self.id+1) % N left = (self.id-1+N) % Nwhile True: P(left) P(right) # om nom nom V(right) V(left)

- Philosophers go out for Chinese food
- Need exclusive access to 2 chopsticks to eat food

Starvation vs. Deadlock

Starvation: thread waits indefinitely

Deadlock: circular waiting for resources Deadlock => starvation, but not vice versa

Subject to deadlock ≠ will deadlock

- → Testing is not the solution
- → System must be deadlock-free by design

Four Conditions for Deadlock [Coffman 1971]

Necessary conditions for deadlock to exist:

- Mutual Exclusion / Bounded Resources
 At least one resource must be held in non-sharable mode
- Hold and wait

∃ a process holding a resource, and waiting for another

- No preemption
 - Resources cannot be preempted
- Circular wait
 - \exists a set of processes {P₁, P₂, ... P_N}, such that

 P_1 is waiting for P_2 , P_2 for P_3 , and P_N for P_1 All four conditions must hold for deadlock to occur. *Note: not just about locks!*

Is this a Deadlock?

Truck A has to wait for Truck B to move

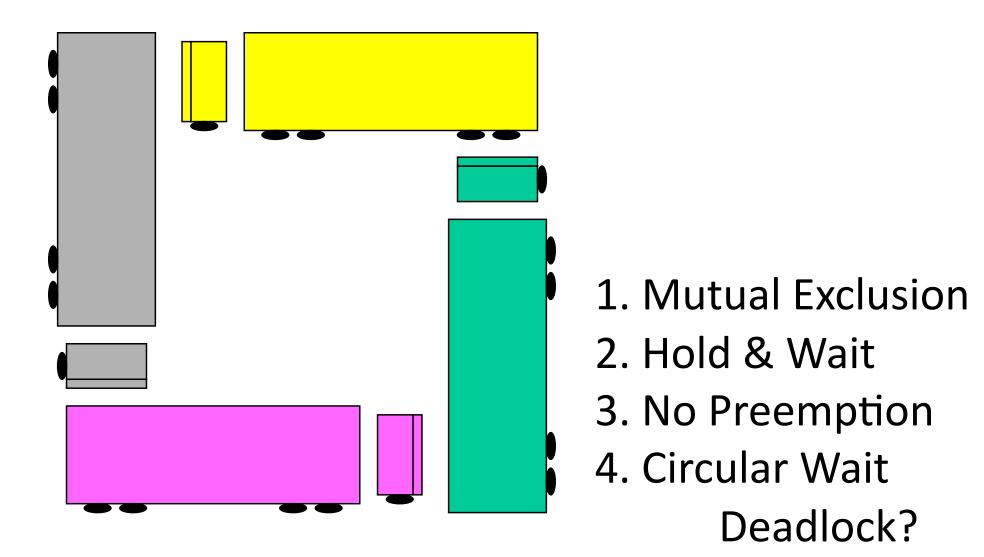


1. Mutual Exclusion

- 2. Hold & Wait
- 3. No Preemption
- 4. Circular Wait Deadlock?

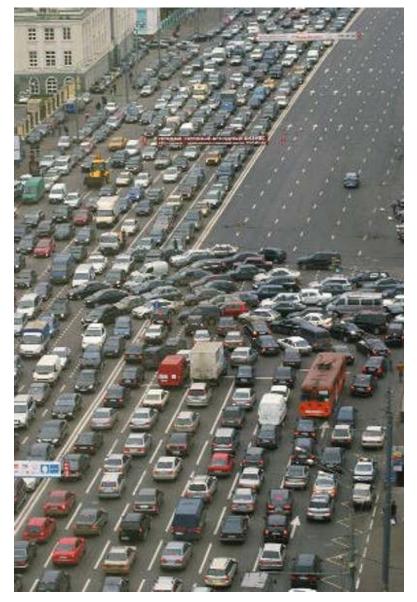


Gridlock



Is this a Deadlock?

Gridlock



- 1. Mutual Exclusion
- 2. Hold & Wait
- 3. No Preemption
- 4. Circular Wait Deadlock?

Is this a Deadlock? Gridlock



- 1. Mutual Exclusion
- 2. Hold & Wait
- 3. No Preemption
- 4. Circular Wait Deadlock?

Deadlock Detection

Create a Wait-For Graph

- 1 Node per Process
- 1 Edge per Waiting Process, P (from P to the process it's waiting for)
 Note: Do this in a single instant of time, not as things change

Cycles in graph indicate deadlock

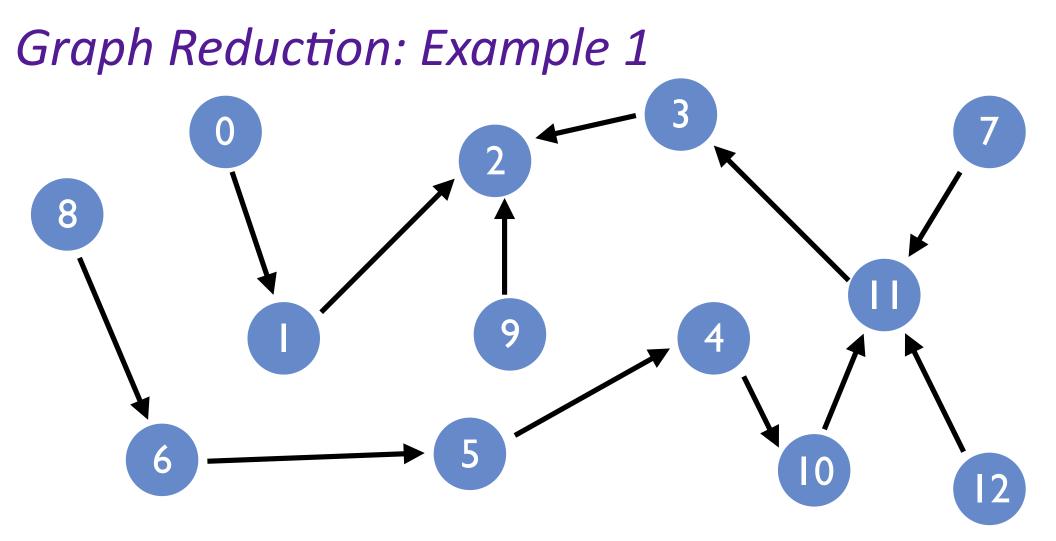
Testing for cycles (= deadlock)

Find a node with no outgoing edges

- Erase node
- Erase any edges coming into it

Intuition: this was a process waiting on nothing. It will eventually finish, and anyone waiting on it will no longer be waiting.

Erase whole graph ↔ graph has no cycles Graph remains ↔ deadlock This is a graph reduction algorithm.



Graph can be fully reduced, hence there was no deadlock at the time the graph was drawn. (Obviously, things could change later!)

Graph Reduction: Example 2

3

0

No node with no outgoing edges... Irreducible graph, contains a cycle (only some processes are in the cycle)

→ deadlock

Resource waits

Processes usually don't wait for each other

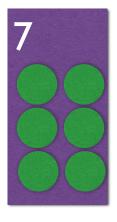
- They wait for resources used by other processes
- P1 needs access to the critical section of memory P2 is using

Can we extend our graphs to represent resource wait?

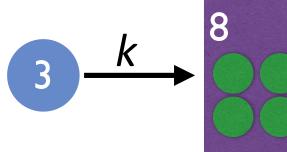
Resource Allocation Graphs

2 kinds of nodes

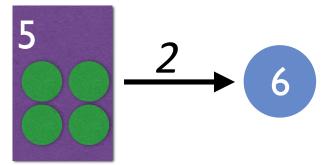
- A process: P₃ represented as 3
- A resource: R₇ represented as multiple identical units of the resource (e.g., blocks of memory) = circles in box



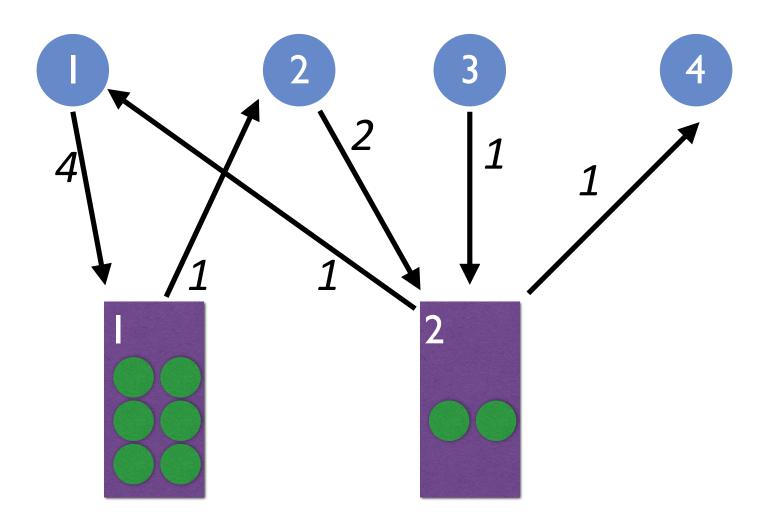
Edge from P₃ to R₈: "P₃ wants k units of R₈"



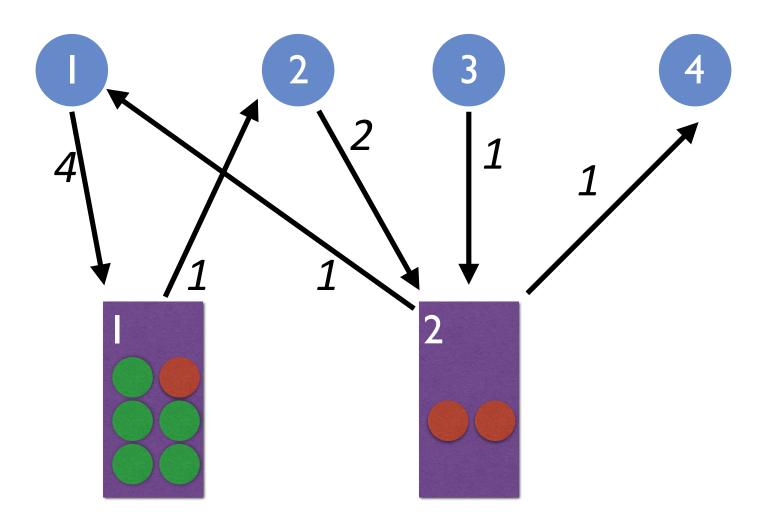
Edge from R_5 to P_6 : " P_6 has k units of R_5 "



Example Resource Allocation Graph (RAG)



Example Resource Allocation Graph (RAG)



red is optional, but we think it helps...

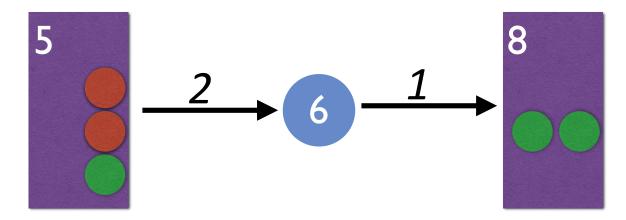
Reduction Rules

- Find satisfiable process P: available amount of resource ≥ amount requested
- Erase P

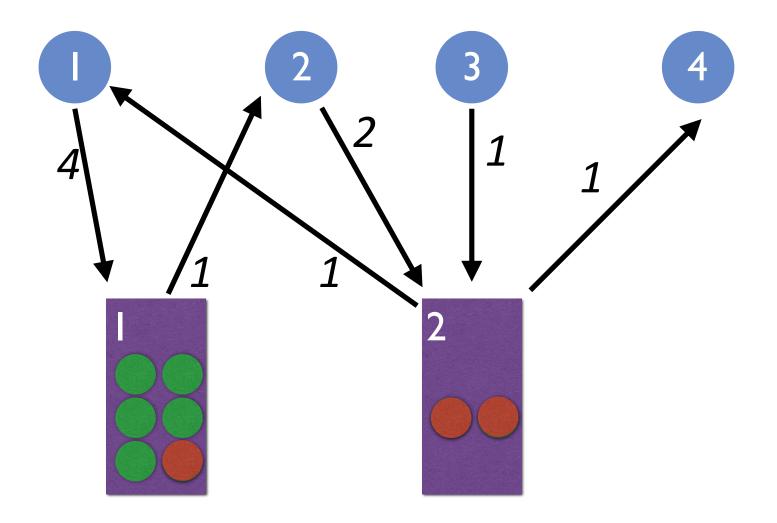
Intuition: grant the request, let it run, eventually it will release the resource

• Repeat until:

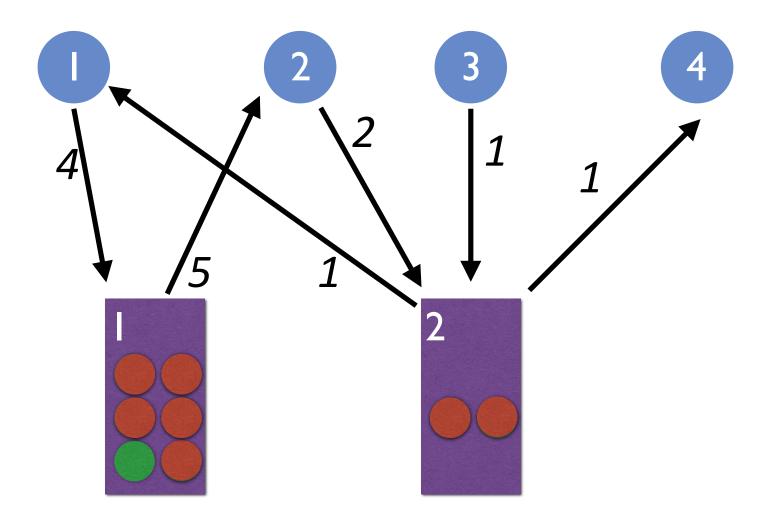
all processes gone (yay!) —or — irreducible (boo!)



Is this graph reducible?

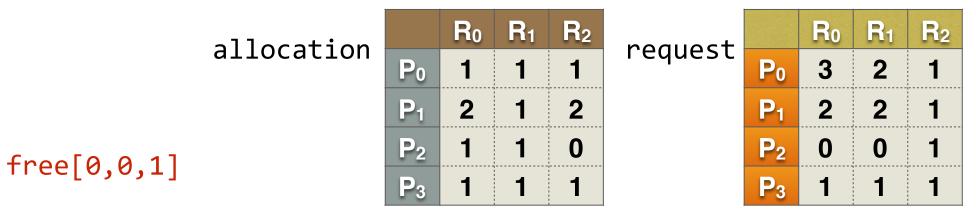


Is this graph reducible?

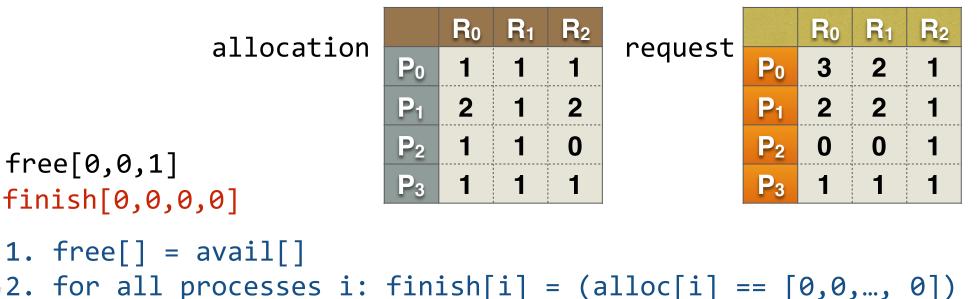


Deadlock Detection Algorithm

```
Data structures:
                  number of processes
n:
                  number of resource types
m:
avail[1..m]:
                  avail[j]: # of currently available type j resources
alloc[n][m]:
                  current allocation of resource R_i to P_i
req[n][m]:
                  current demand of each P_i for each R_i
                     (in addition to what has already been allocated)
1. free[] = avail[]
2. for all processes i: finish[i] = (alloc[i] == [0,0,...,0])
3. find process i such that finish[i] = 0 and req[i] \leq free
      if no such i exists, goto 7
4. free = free + alloc[i]
5. finish[i] = true
6. goto 3
7. system is deadlocked iff finish[i] = 0 for some process i
```



4 processes, 3 resource types,
avail[0,0,1]: 1 type-2 resource available

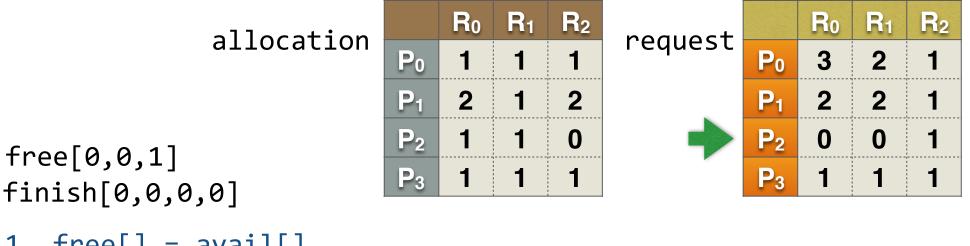


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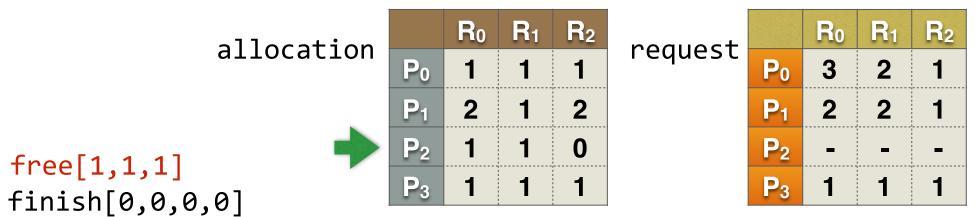
What about a process with a request that currently has nothing allocated? Since it holds no resources it will not participate in the hold-and-wait deadlock circle, so we ignore it.₂₅

4 processes, 3 resource types,
avail[0,0,1]: 1 type-2 resource available



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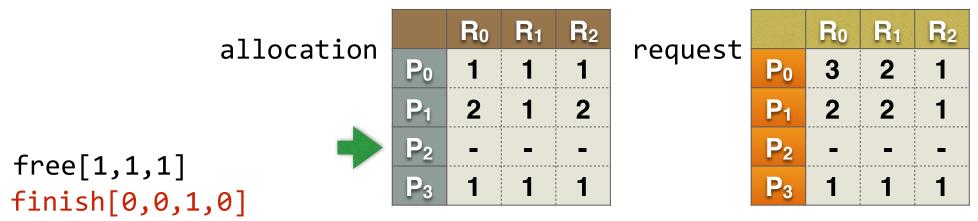
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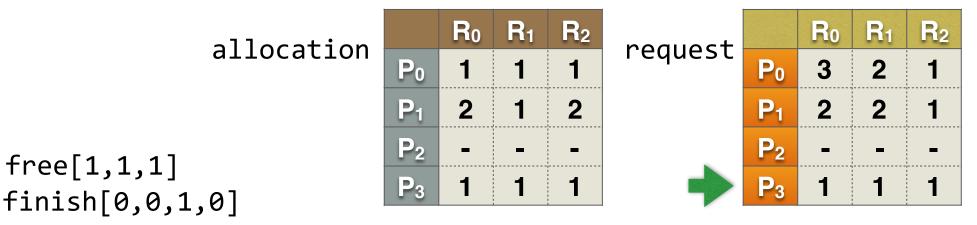
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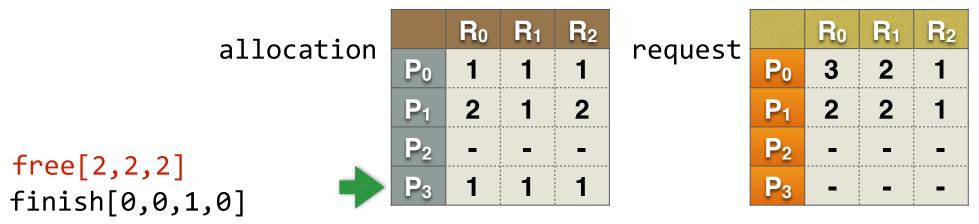
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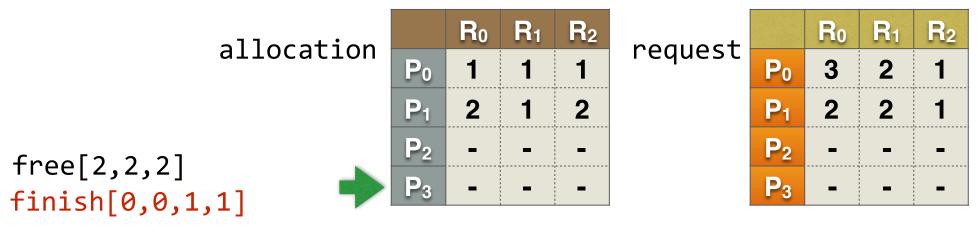




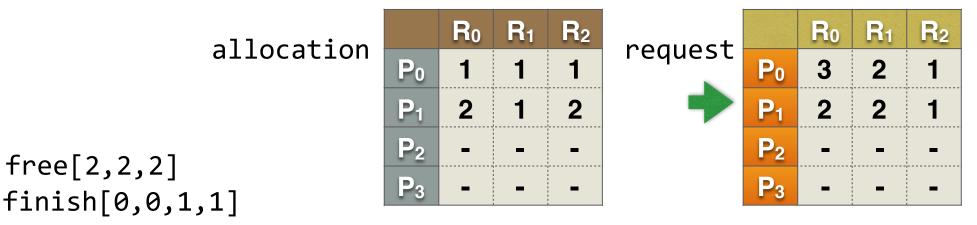
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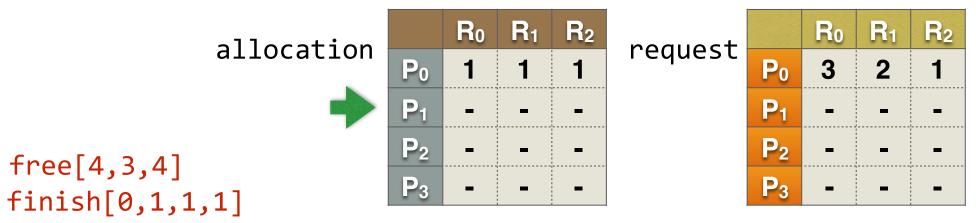
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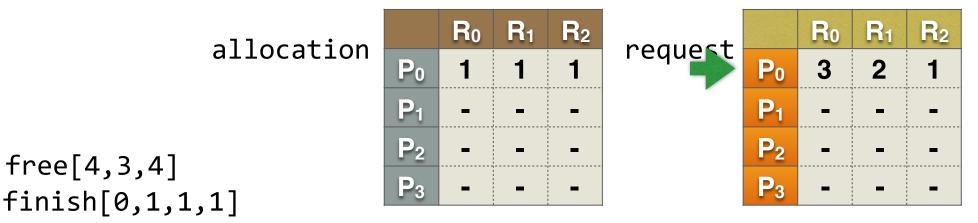


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```

Question #1

Does order of reduction matter?

Answer: No.

Explanation: an unchosen candidate at one step remains a candidate for later steps. Eventually—regardless of order—every node will be reduced.

Question #2

If a system is deadlocked, could the deadlock go away on its own?

Answer: No, unless someone kills one of the threads or something causes a process to release a resource. Explanation: Many real systems put time limits on "waiting" precisely for this reason. When a process gets a timeout exception, it gives up waiting; this can eliminate the deadlock.

Process may be forced to terminate itself because often, if a process can't get what it needs, there are no other options available!

Question #3

Suppose a system isn't deadlocked at time T. Can we assume it will still be free of deadlock at time T+1?

Answer: No Explanation: the very next thing it might do is to run some process that will request a resource... ... establishing a cyclic wait ... and causing deadlock

Dealing with Deadlocks (1)

Reactive Approaches:

- Periodically check for evidence of deadlock (graph reduction algorithm)
- Need a way to recover
 - Blue screen and reboot the computer
 - Pick a "victim" and terminate that thread (Only possible in certain kinds of applications)
 - Have threads "retry" from scratch (despite drawbacks, database systems do this)

Dealing with Deadlocks (2)

Proactive Approaches:

- Deadlock Prevention & Avoidance
 - Prevent 1 of 4 necessary conditions from arising
 - will prevent deadlock from occurring

1. Mutual exclusion / Bounded Resources:

- Make resources sharable without locks?
- Make more resources available?
- Example: reserve space in TCB for thread to be inserted into a waiting list or the ready list.
- Not always possible (e.g., printers)

2. Hold and wait

Don't hold resources when waiting for another

• re-write code:

Module:: foo() {
 lock.acquire();
 doSomeStuff();
 otherModule->bar();
 doOtherStuff();
 lock.release(); }

Module:: foo() {
 doSomeStuff();
 otherModule->bar();
 doOtherStuff();
 }
}

have these 2 fns acquire/release

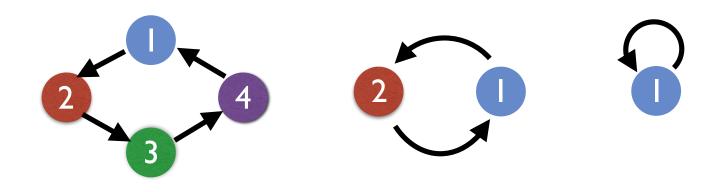
- Request all resources before execution begins
 - Processes don't know what they need ahead of time
 - Starvation (if waiting on many popular resources)
 - Low utilization (need resource only for a bit)
 Optimization: Release all resources before requesting anything new? Still has last two problems

3. No preemption:

- Make resources pre-emptable by runtime system
 1. Preempt requesting processes' resources if all not available
 2. Preempt resources of waiting processes to satisfy request
- Good when easy to save and restore state of resource
 - CPU registers
 - memory virtualization (page memory to disk, maybe even page tables)

4. Circular Wait

- Single lock for entire system?
- Impose partial ordering on resources, request in order *Intuition:* Cycle requires an edge from low to high, and from high to low numbered node, or to same node



Preventing Dining Philosophers Deadlock?

1. Mutual Exclusion / Bounded Resources

2. Hold and wait

3. No preemption

4. Circular wait

How do cars do it?

- Try not to block an intersection
- Don't drive into the intersection if you can see that you'll be stuck there.

Why does this work?

- Prevents a wait-for relationship
- Cars won't take up a resource if they see they won't be able to acquire the next one...

Deadlock Dynamics

Safe state:

- For any possible sequence of future resource requests, it is possible to eventually grant all requests
- May require waiting even when resources are available!

Unsafe state:

 Some sequence of resource requests can result in deadlock

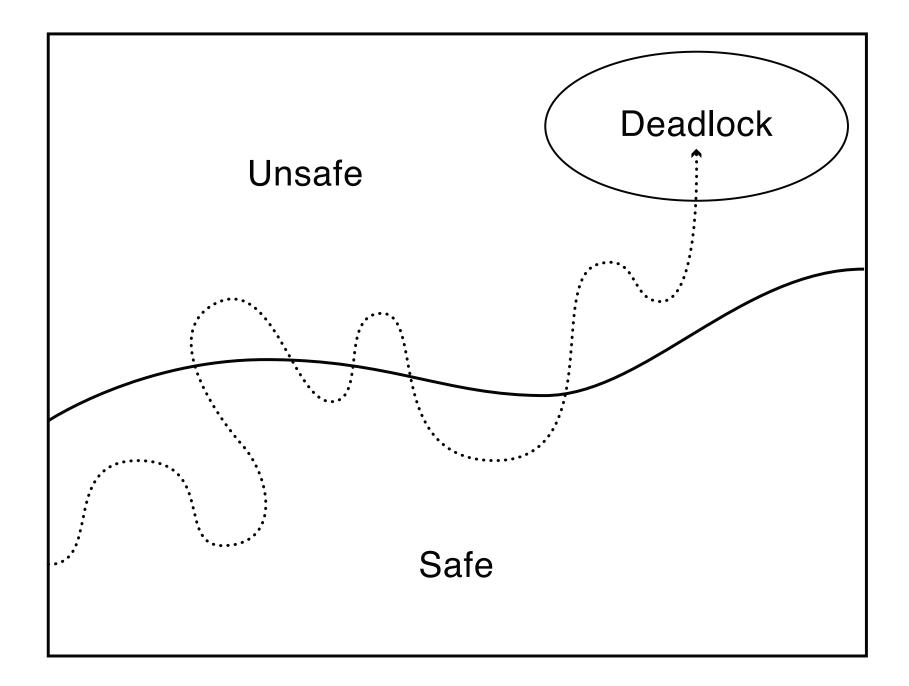
Doomed state:

• All possible computations lead to deadlock

Deadlocked state:

• System has at least one deadlock

Possible System States



Safe State

- A state is said to be safe, if there exists a sequence of processes [P₁, P₂,..., P_n] such that for each P_i the resources that P_i can still request can be satisfied by the currently available resources plus the resources held by all P_j where j < i
- State is safe b/c OS can definitely avoid deadlock
 - by blocking new requests until safe order is executed
- Avoids circular wait condition from ever happening
 - Process waits until safe state is guaranteed

Safe State Example

Suppose: 12 tape drives and 3 processes: p0, p1, and p2

	max	current	could
	need	usage	ask for
p0	10	5	5
p1	4	2	2
p2	9	2	7

3 drives remain

current state is *safe* because a safe sequence exists: [p1, p0, p2]

- p1 can complete with remaining resources
- p0 can complete with remaining+p1
- p2 can complete with remaining+p1+p0

What if p2 requests 1 drive? Grant or not?

- Suppose we know the "worst case" resource needs of processes in advance
 - A bit like knowing the credit limit on your credit cards. (This is why they call it the Banker's Algorithm)
- **Observation:** Suppose we just give some process ALL the resources it could need...
 - Then it will execute to completion.
 - After which it will give back the resources.
- Hmmm, if Visa hands you all the money your credit lines permit, at the end of the month, will you pay your entire bill?

- So...
 - A process pre-declares its worst-case needs
 - Then it asks for what it "really" needs, a little at a time
 - The algorithm decides when to grant requests
- It delays a request unless:
 - It can find a sequence of processes...
 - such that it could grant their outstanding need...
 - ... so they would terminate...
 - ... letting it collect their resources...
 - ... and in this way it can execute everything to completion!

How will it really do this?

- The algorithm will just implement the graph reduction method for resource graphs
- Graph reduction is "like" finding a sequence of processes that can be executed to completion
- So: given a request
 - Build a resource allocation graph assuming the request is granted
 - See if it is reducible, only grant request if so
 - Else must delay the request until someone releases some resources, at which point can test again

[Dijkstra 1977]

- Decides whether to grant a resource request.
- Data structures (similar to before):

n:	number of processes
m:	number of resource types
avail[m]:	<pre>avail[j]: # of currently available type j resources</pre>
<pre>max[n][m]:</pre>	max demand of each P_i for each R_i
alloc[n][m]:	current allocation of resource R_j to P_i
<pre>need[n][m]:</pre>	max # resource R_j that P_i may still request
	(need = max – allocation)

algorithm-internal state:
finish[n] - which processors are finished in this scenario
free[m] - which resources are available inside path

How to check safety?

free[1..m] = available /* how many resources available */
finish[1..n] = [0..0] /* none finished yet */

Step 1: Find a process i such that finish[i] = F and need[i] ≤ free If f no such i exists, go to Step 3 /* we're done */ Step 2: Found an i: finish [i] = 1 (nee i alloc[i])

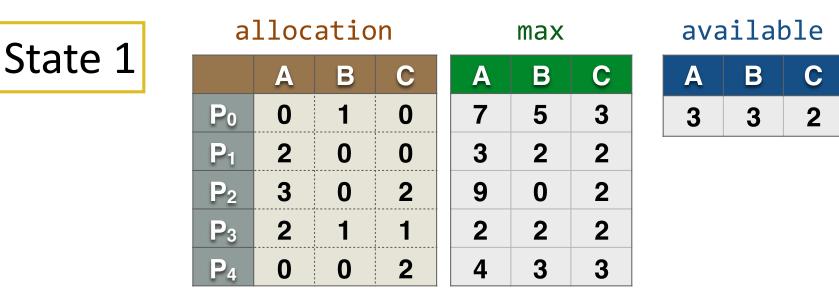
```
free = free + alloc[i]
go to Step 1
```

Step 3: The system is safe iff finish[i] = 1 for all i

Full Banker's Algorithm

Let process i be the next process that is scheduled to run Let request[i] be vector of # of resource $R_{\rm j}$ Process $P_{\rm i}$ wants in addition to the resources it already has

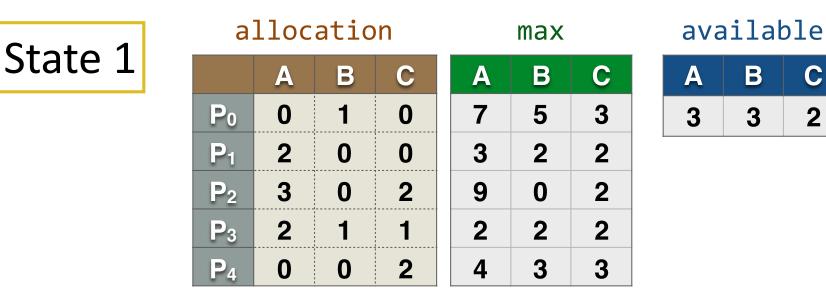
```
1. If request[i] > need[i] then error (asked for too much)
2. If request[i] > available then wait (can't supply it now)
3. Resources are currently available to satisfy the request.
Tentatively assume we satisfy the request.
Then we would have:
    available = available - request[i]
    alloc[i] = alloc[i] + request[i]
    need[i] = need[i] - request[i]
    Now, check if this would leave us in a safe state:
    if yes, grant the request,
    if no, then leave state as is & cause process to wait
```



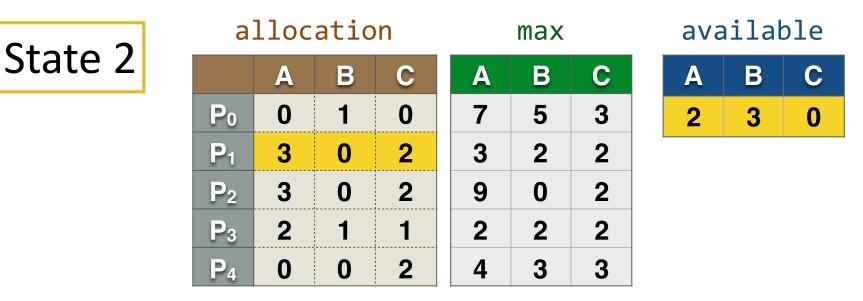
Is State 1 a safe state?

Is there a sequence of granting processors resources that satisfies everyone?





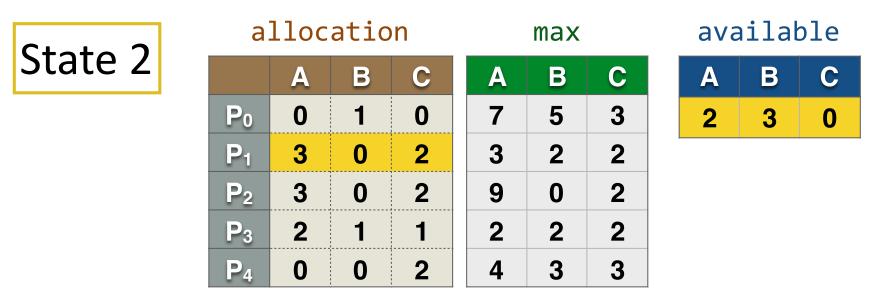
State 1 is a safe state. safe sequence: [P1, P3, P4, P2, P0] Now suppose that P1 requests (1,0,2) add it to P1's allocation subtract it from Available



Is State 2 a safe state?

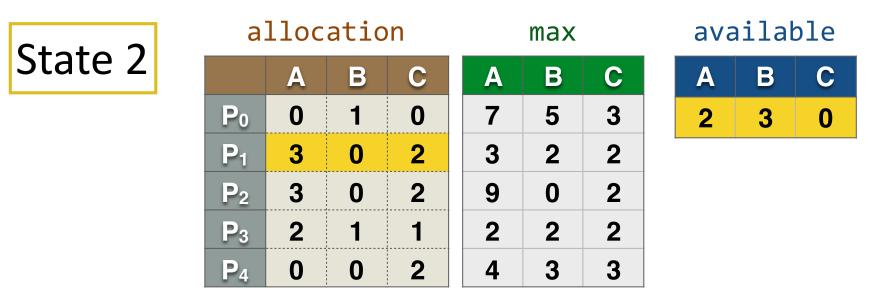
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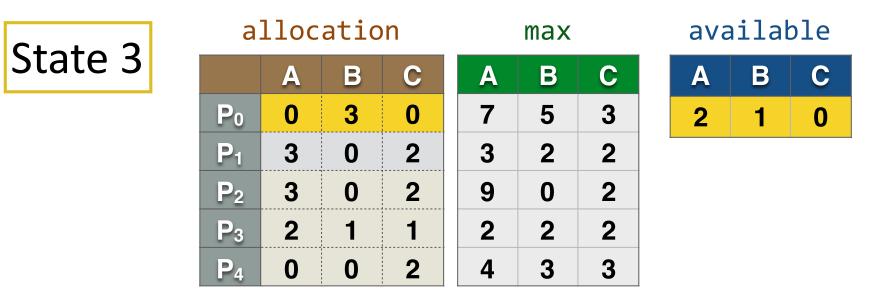
State 2 is still safe: safe seq [P1, P3, P4, P0, P2]. Now suppose P4 requests (3,3,0)

not enough available resources: has to wait



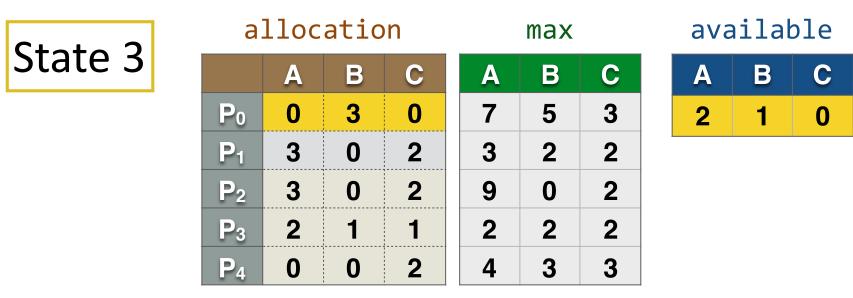
State 2 is still safe: safe seq [P1, P3, P4, P0, P2]. Now suppose P0 requests (0,2,0)

 have enough resources, but, hypothetically... add it to PO's allocation subtract it from Available



Is State 3 a safe state?

Is there a sequence of granting processors resources that satisfies everyone?



State 3 is unsafe state (why?) So PO has to wait

Problems with Bankers

- The number of processes is fixed
- Need to know how many resources each process will request ahead of time

Deadlock Detection & Recovery

- If neither avoidance or prevention is implemented, deadlocks can (and will) occur.
- Coping with this requires:
 - Detection: finding out if deadlock has occurred
 - Keep track of resource allocation (who has what)
 - Keep track of pending requests (who is waiting for what)
 - Recovery: untangle the mess.
- Expensive to detect, as well as recover

When to run the Detection Algorithm?

- For every resource request?
- For every request not immediately satisfiable?
- Once every hour?
- When CPU utilization drops below 40%?
- Some combination of the last two?

Deadlock Recovery

Killing one/all deadlocked processes

- Crude, but effective
- Keep killing processes, until deadlock broken
- Repeat the entire computation

Preempt resource/processes until deadlock broken

- Selecting a victim (# resources held, how long executed)
- Rollback (partial or total)
- Starvation (prevent a process from being executed)

The Story So Far

We saw that you can prevent deadlocks.

• By negating one of the four necessary conditions.

We saw that the OS can schedule processes in a careful way so as to avoid deadlocks.

• By preventing circular waiting to ever occur

We discussed options when deadlock has occurs.

The discussion continues...

Transactions / Transactional Memory

- Programming simplicity of coarse-grain locks
- Higher concurrency (parallelism) of fine-grain locks
- Critical sections only serialized if data is actually shared
- No lock acquisition overhead

Transactional Memory

Big idea I: no locks, just shared data **Big idea II:** optimistic (speculative) concurrency

- Execute critical section speculatively, abort on conflicts
- "Better to beg for forgiveness than to ask for permission"

Read set: set of shared addresses critical section reads Example: accts[37].bal, accts[241].bal Write set: set of shared addresses critical section writes Example: accts[37].bal, accts[241].bal

begin_transaction

- Take a local register checkpoint
- Locally track read set (remember addresses you read)
- See if anyone else is trying to write it
- Locally buffer all of your writes (invisible to other processors)
- Local actions only: no lock acquire

```
struct acct_t { int bal; };
shared struct acct_t accts[MAX_ACCT];
int id_from,id_to,amt;
```

```
begin_transaction();
if (accts[id_from].bal >= amt) {
    accts[id_from].bal -= amt;
    accts[id_to].bal += amt; }
end_transaction();
```

end_transaction

- Check read set: is data you read still valid (i.e., no writes to any)
 - Yes? Commit transactions: commit writes
 - No? Abort transaction: restore checkpoint

```
struct acct_t { int bal; };
shared struct acct_t accts[MAX_ACCT];
int id_from,id_to,amt;
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if (accts[id_from].bal >= amt) {
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