CS 421: Numerical Analysis Fall 2005

Problem Set 4

Handed out: Wed., Oct. 19.

Due: Fri., Oct. 28 in lecture.

- 1. Develop an efficient algorithm for the following problem, and analyze its running time accurate to the leading terms. Given an $n \times n$ lower triangular matrix G that is the Cholesky factor of A (i.e., $A = GG^T$), and given a matrix $H \in \mathbf{R}^{n \times p}$, where p < n, find the Cholesky factor of $A + HH^T$.
 - Suggested approach: Observe that $A + HH^T = [H, G][H^T; G^T]$. If we could compute a QR factorization of $[H^T; G^T]$ efficiently, then the problem would be solved (why? consider the R-factor here). To compute this factorization efficiently, consider Householder transformations that have extra sparsity to account for the nonzero pattern of $[H^T; G^T]$.
- 2. (a) Let $\mathbf{u} \in \mathbf{R}^m$, $\mathbf{v} \in \mathbf{R}^n$ be two vectors, both nonzero. Find a formula for the singular values of the rank-one matrix $\mathbf{u}\mathbf{v}^T$.
 - (b) It was proved by Wilkinson that the backward error E for solving $A\mathbf{x} = \mathbf{b}$ using Gaussian elimination with partial pivoting in the presence of roundoff is bounded by $||E|| \leq c_n ||A|| \epsilon_{\text{mach}}$. Suppose we are given a matrix A, a vector \mathbf{b} and a computed solution $\hat{\mathbf{x}}$. Explain how to determine the backward error E such that $(A + E)\hat{\mathbf{x}} = \mathbf{b}$ and such that $||E||_2$ is minimum among all such matrices E. [Hint: Find a rank-one E such that $(A + E)\hat{\mathbf{x}} = \mathbf{b}$. This E will involve vectors such as $\mathbf{b} A\hat{\mathbf{x}}$. Use the result of part (a) to determine the 2-norm of this matrix E. Use vector norm subordination to claim that there could not be any E with a smaller norm.]
- 3. (Exercise 4.24 from Heath.) Let A be an $n \times n$ real rank-one matrix of the form $A = \mathbf{u}\mathbf{v}^T$ where $\mathbf{u}^T\mathbf{v} \neq 0$.
 - (a) Show that $\mathbf{u}^T \mathbf{v}$ is an eigenvalue of A. What is its eigenvector?
 - (b) What are the other eigenvalues of A? [Hint: normalize \mathbf{v} and extend it to an orthonormal basis.]
 - (c) Suppose the power method is applied to A. How many iterations are required for it to converge exactly to the eigenvector corresponding to the dominant eigenvalue? What assumptions must be made about the initial vector?
- 4. On the class web page is a dataset containing information from the "help" files for matrix functions in Matlab (i.e., the files accessible starting from the menu given by help matlab/matfun). Specifically, the following data items are stored in ps4q4.mat, which is downloadable and should be loaded into matlab via the statement load ps4q4.mat.

- doctitles: A cell array with the titles of the help pages (46 documents total in the corpus). To access the title of the *i*th document, you would say doctitles{i}. Note the curly braces. Cell arrays are Matlab arrays in which the entries can be arbitrary Matlab data (e.g., entire strings in this case) rather than just numbers.
- A: The term-document matrix, which is 1003 by 48. It is stored in sparse format so that the data file is not too large. Make it full with the statement A=full(A).
- finaltermlist: A cell array with the 1003 terms that appear in this corpus.

Write three functions for retrieving documents from this corpus as follows.

- function qvector = convert_query(query,finaltermlist): This function takes as input a natural language query, stored in a string called query, and converts it to a vector in term-space (which is R¹⁰⁰³ for this dataset). It does so by matching the terms in the query against the terms in finaltermlist. For this function, the Matlab string-operation primitives lower, strtok and strmatch might be helpful. To check if a token w is a word, use all(isletter(w)).
- function scores = scoredoc(qvector,U,S,V,k): This function returns a score for each document (i.e., a vector in \mathbb{R}^{48} for this corpus) for the query using the LSI operations covered in class. Here, U,S,V are the outputs of the Matlab svd function applied to A; k is the number of singular values to keep (I experimented with 15); and qvector is a query converted to a vector by the previous function.
- function topthree(doctitles, scores): This function has no return values, but prints out the top three LSI matches in the corpus for the scores computed by scoredoc. The disp(sprintf(...)) construction and sort functions may be helpful.

Hand in listings of these functions and three test runs, include a test for the query "estimate condition number":

Do you get a better result if you keep all 48 singular values?