

CS 3220: Introduction to Scientific Computing

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Spring 2009

scientific computing: The use of computers to solve problems that arise in science (and engineering, medicine, ...).

numerical methods: Algorithms (methods) for solving problems with real numbers by numerical (as opposed to symbolic) means.

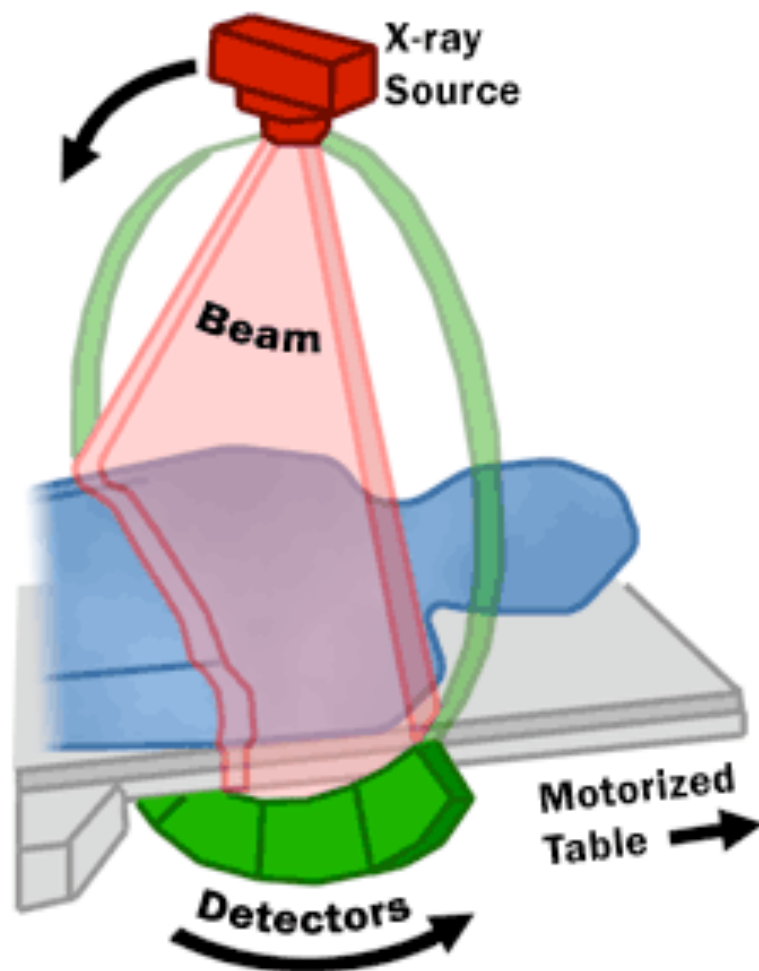
If your variables represent real-valued quantities, you're doing numerical computing. Perhaps surprising are:

- audio (stream of sound pressure samples)
- video (grids of intensity or color samples)
- computational geometry (positions in space)
- computer graphics and vision (geometry, color, light...)
- information retrieval (more on this in a moment)

with abundant computing power, more applications are using numerical methods all the time.

Numerical computing in medicine: computed tomography

a linear inverse problem



U.S. FDA

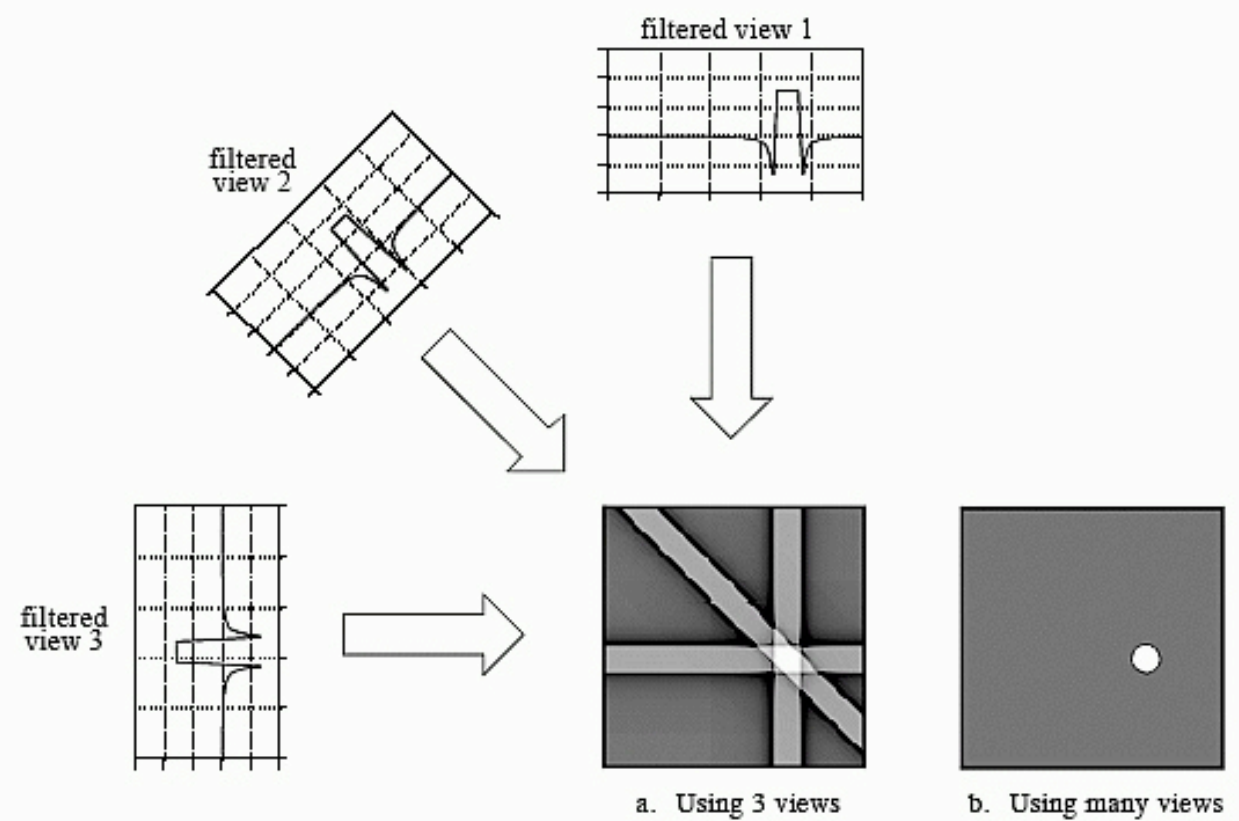


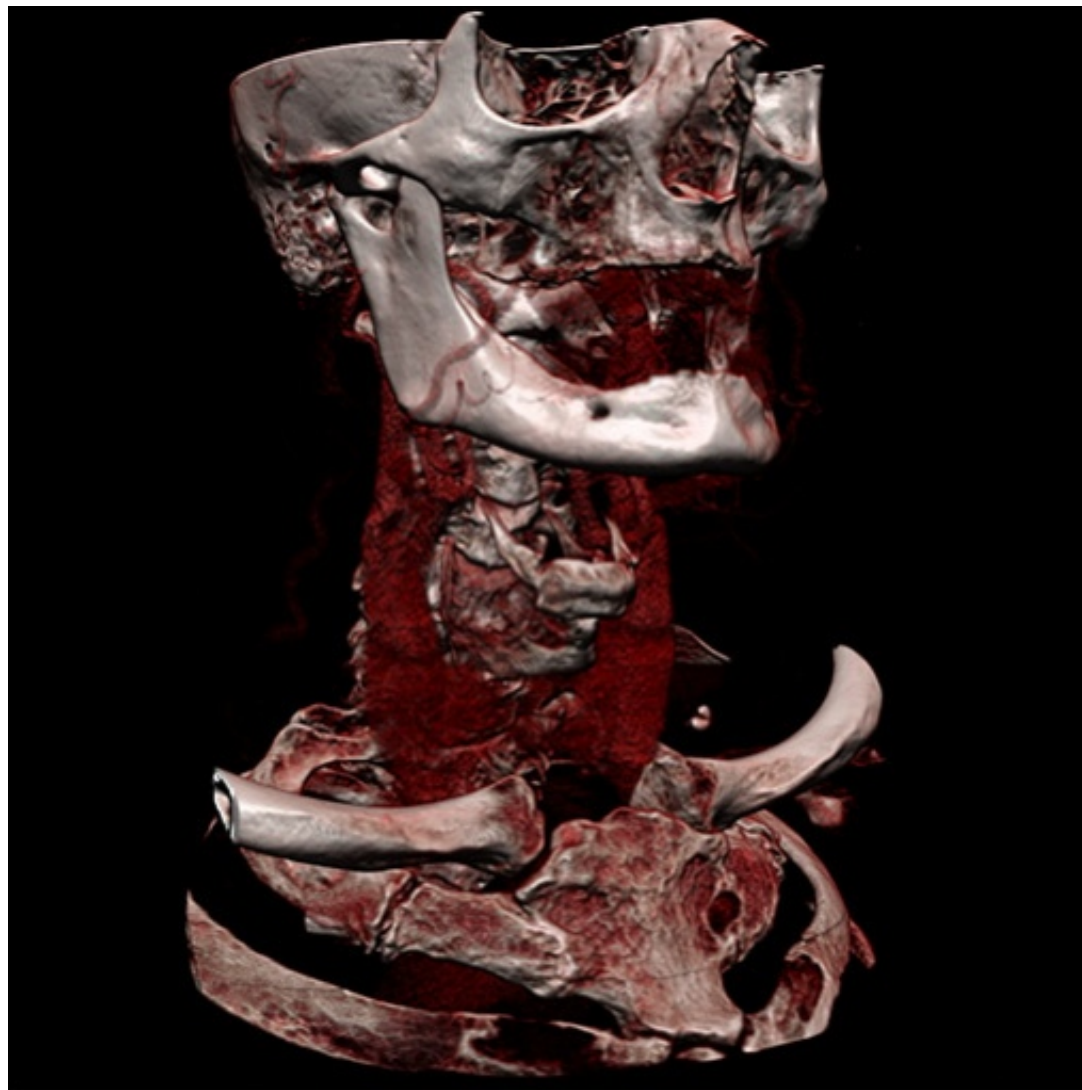
FIGURE 25-17
Filtered backprojection. Filtered backprojection reconstructs an image by filtering each view before backprojection. This removes the blurring seen in simple backprojection, and results in a mathematically exact reconstruction of the image. Filtered backprojection is the most commonly used algorithm for computed tomography systems.

Steven W. Smith—dspguide.com

Numerical computing in medicine: computed tomography

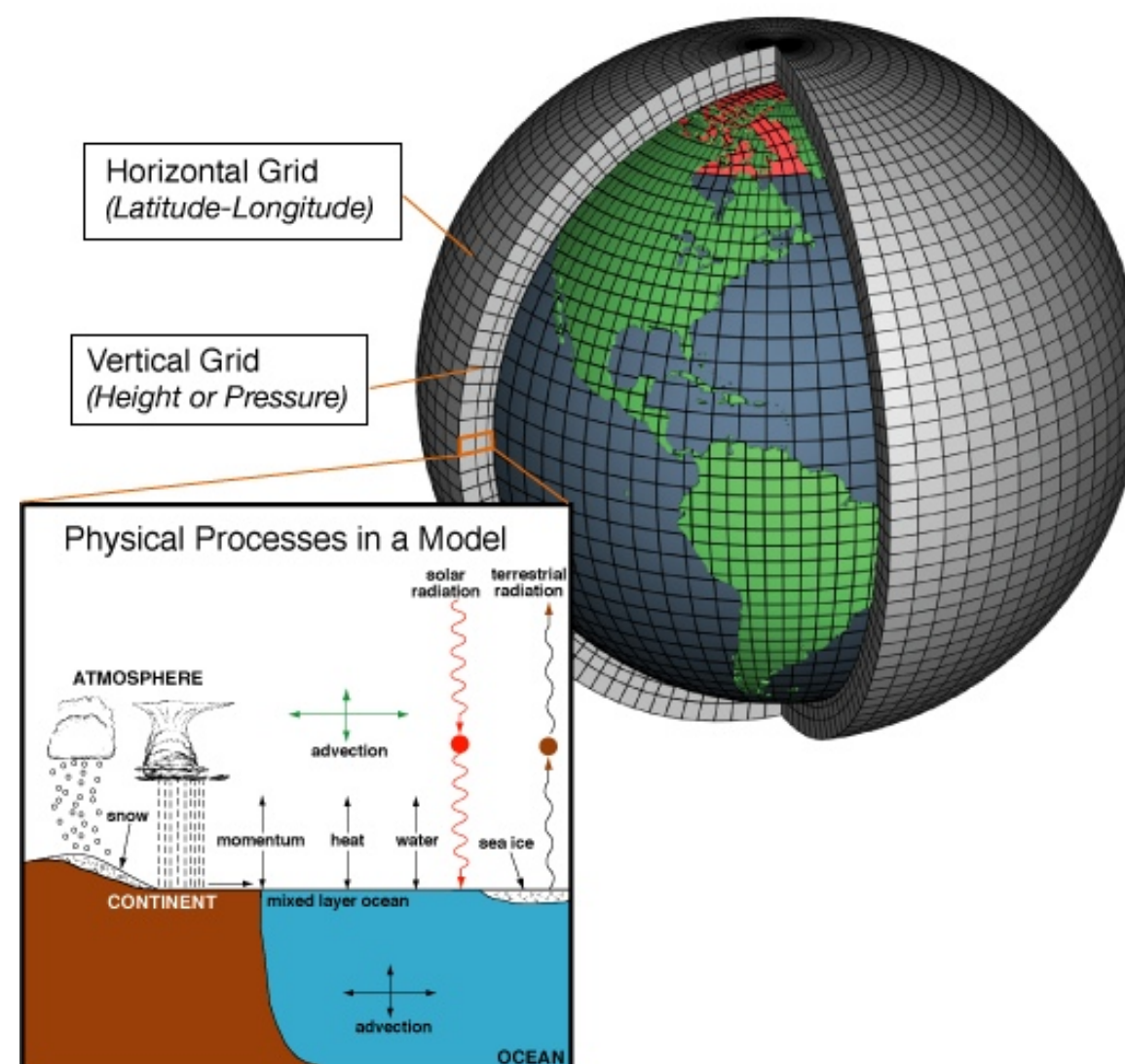


Numerical computing in medicine: computed tomography



Numerical computing in climatology: predicting global warming

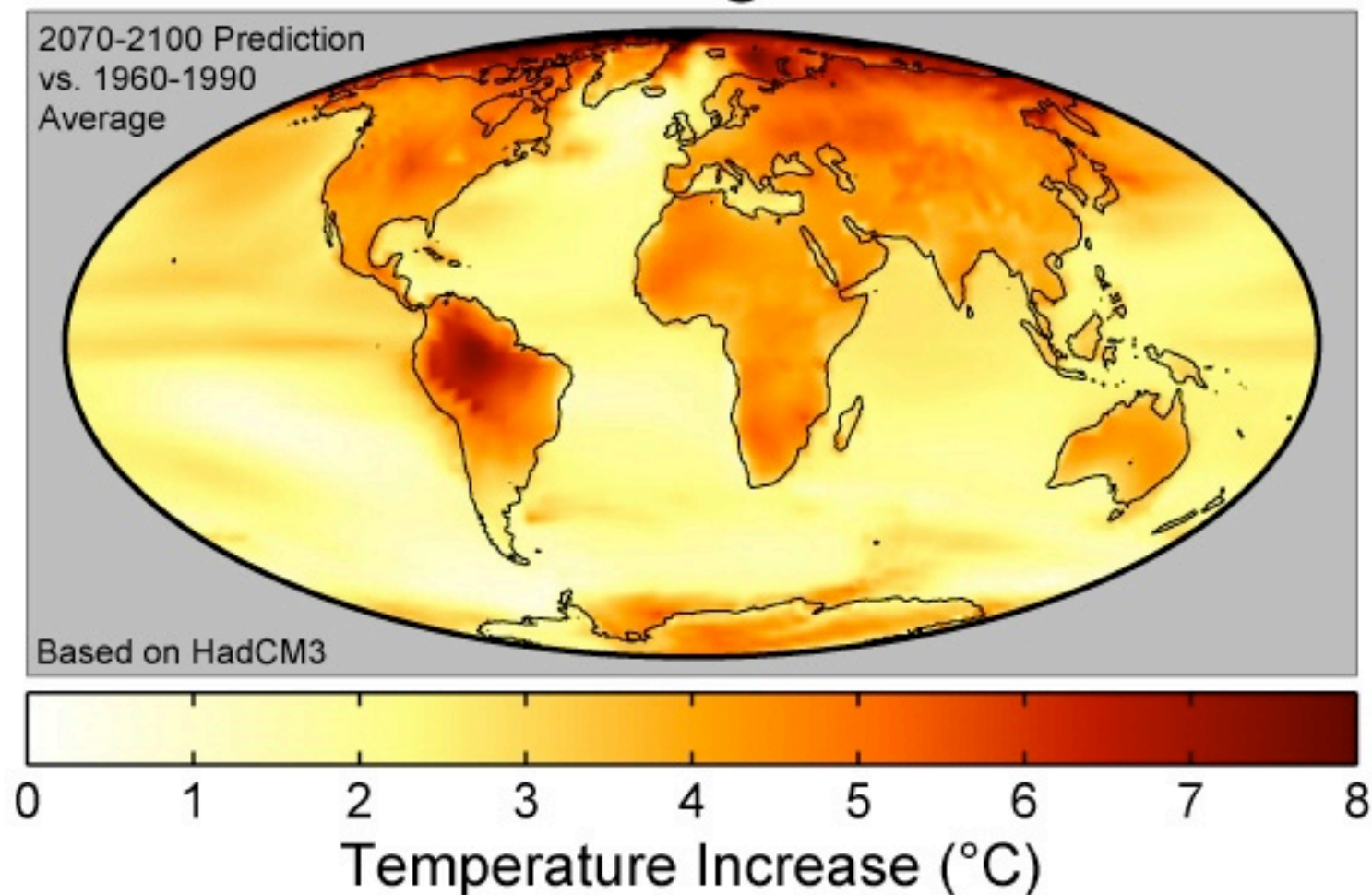
partial differential equations



NOAA

Numerical computing in climatology: predicting global warming

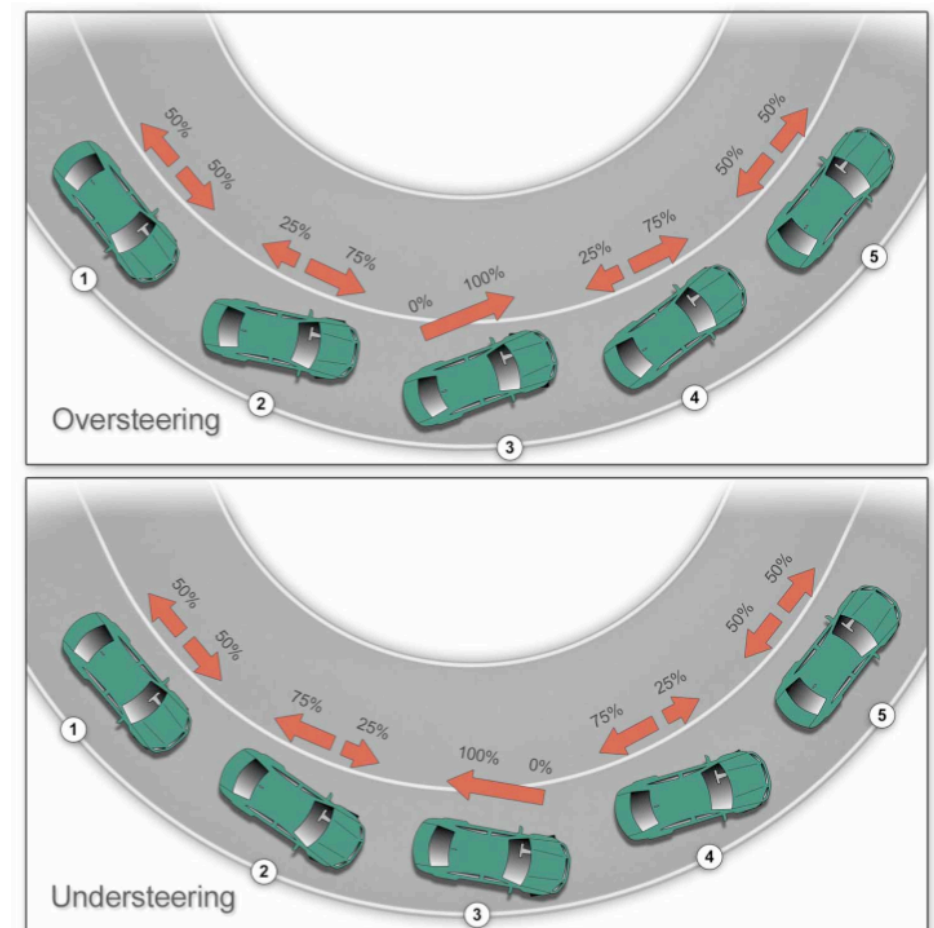
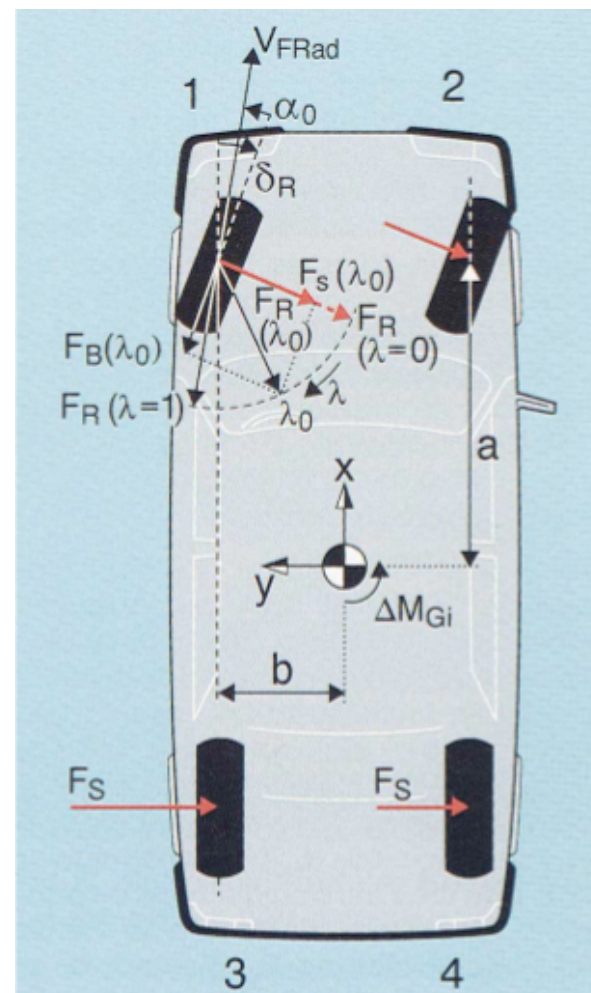
Global Warming Predictions



Robert A. Rohde

Numerical computing in cars: electronic stability control

images from:
Liebemann et al. "Safety and Performance Enhancement: The Bosch Electronic Stability Control (ESP)" in *The 19th International Technical Conference on the Enhanced Safety of Vehicles (ESV)*



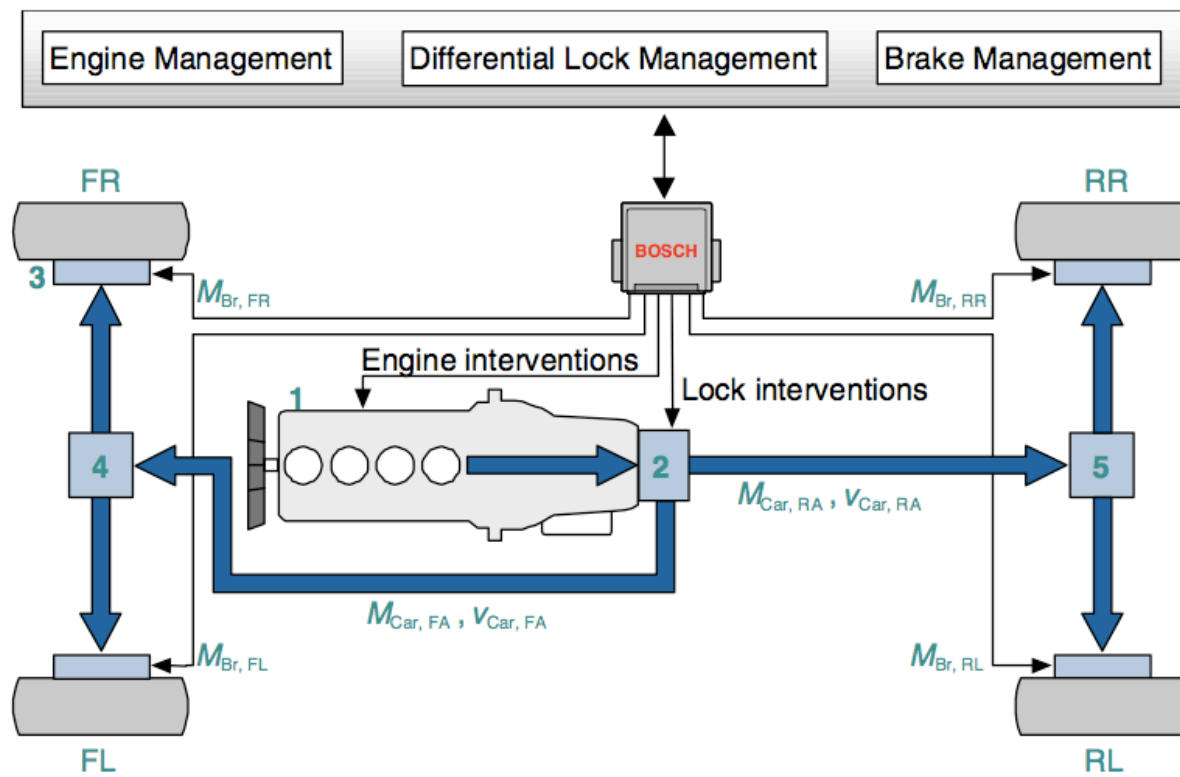
Yaw rate control at work



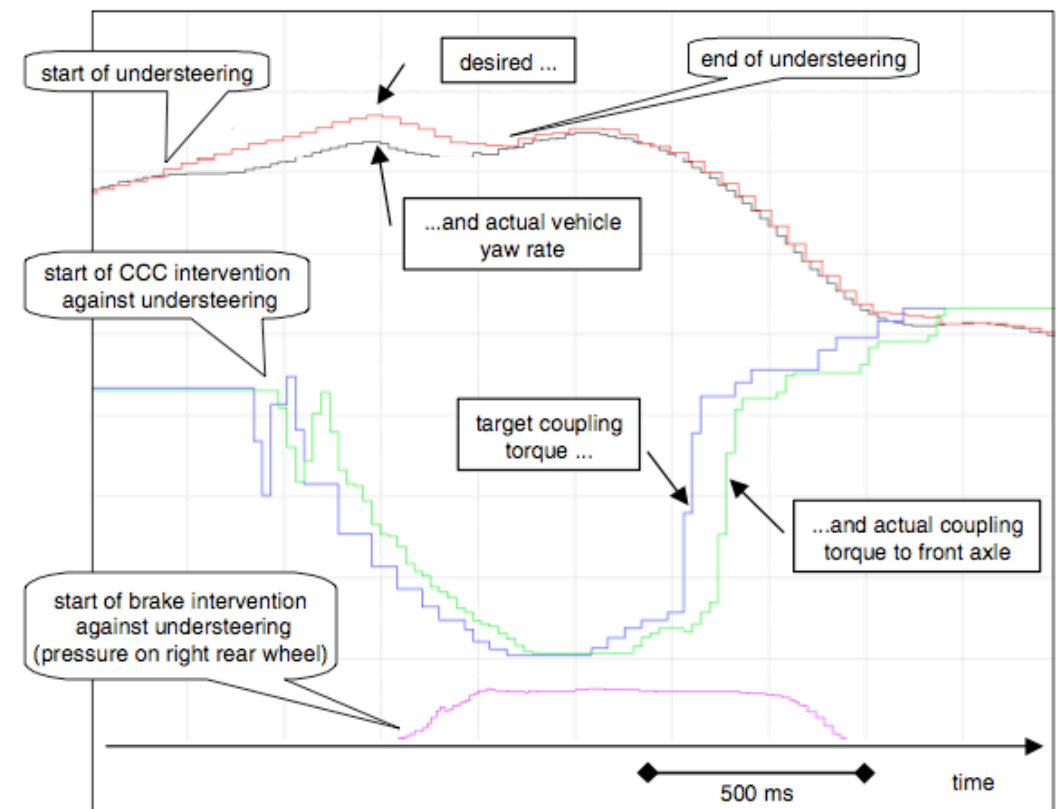
Fifth Gear—demo of Bosch ESP system

Numerical computing in cars: electronic stability control

ordinary differential equations



Liebemann et al.



Liebemann et al.

Yaw rate control by braking



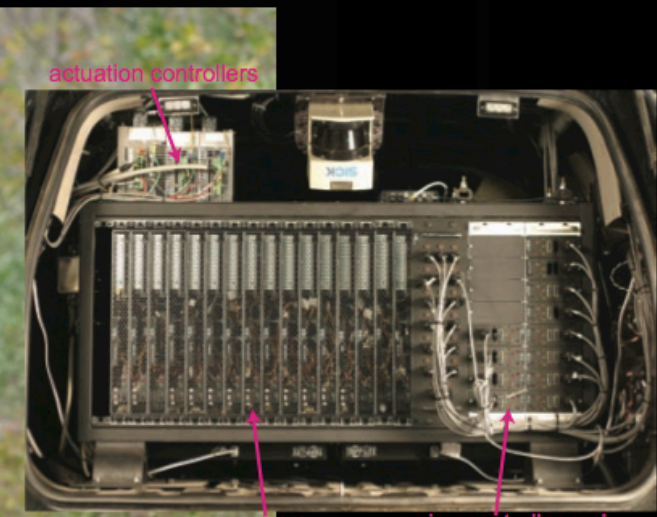
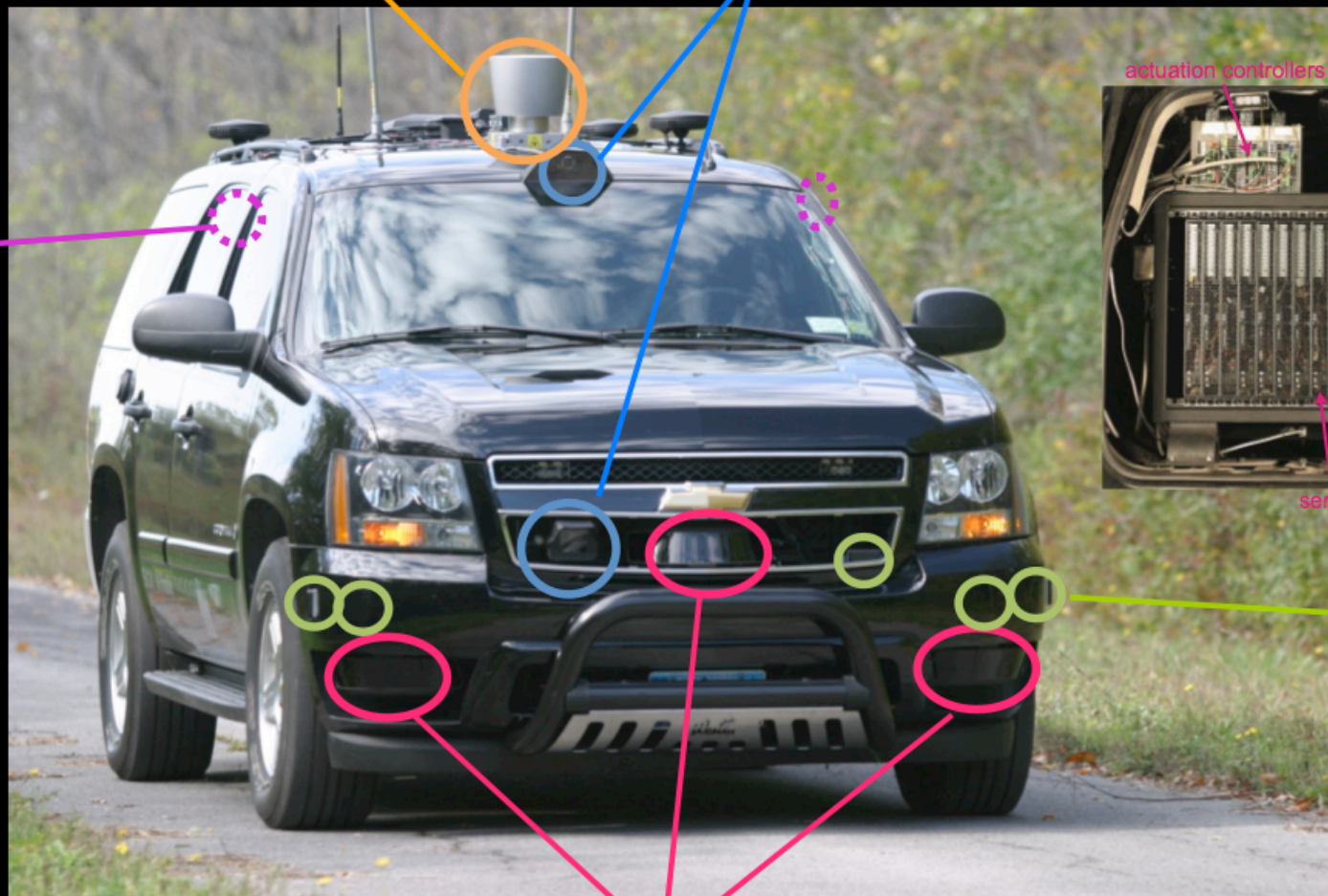
Fifth Gear—demo of Bosch ESP system

Numerical computing in autonomous vehicles: path planning

Velodyne HD LIDAR (64 lasers)

Basler cameras (lane, stop line)

SICK 1D LIDAR (mounted inside)



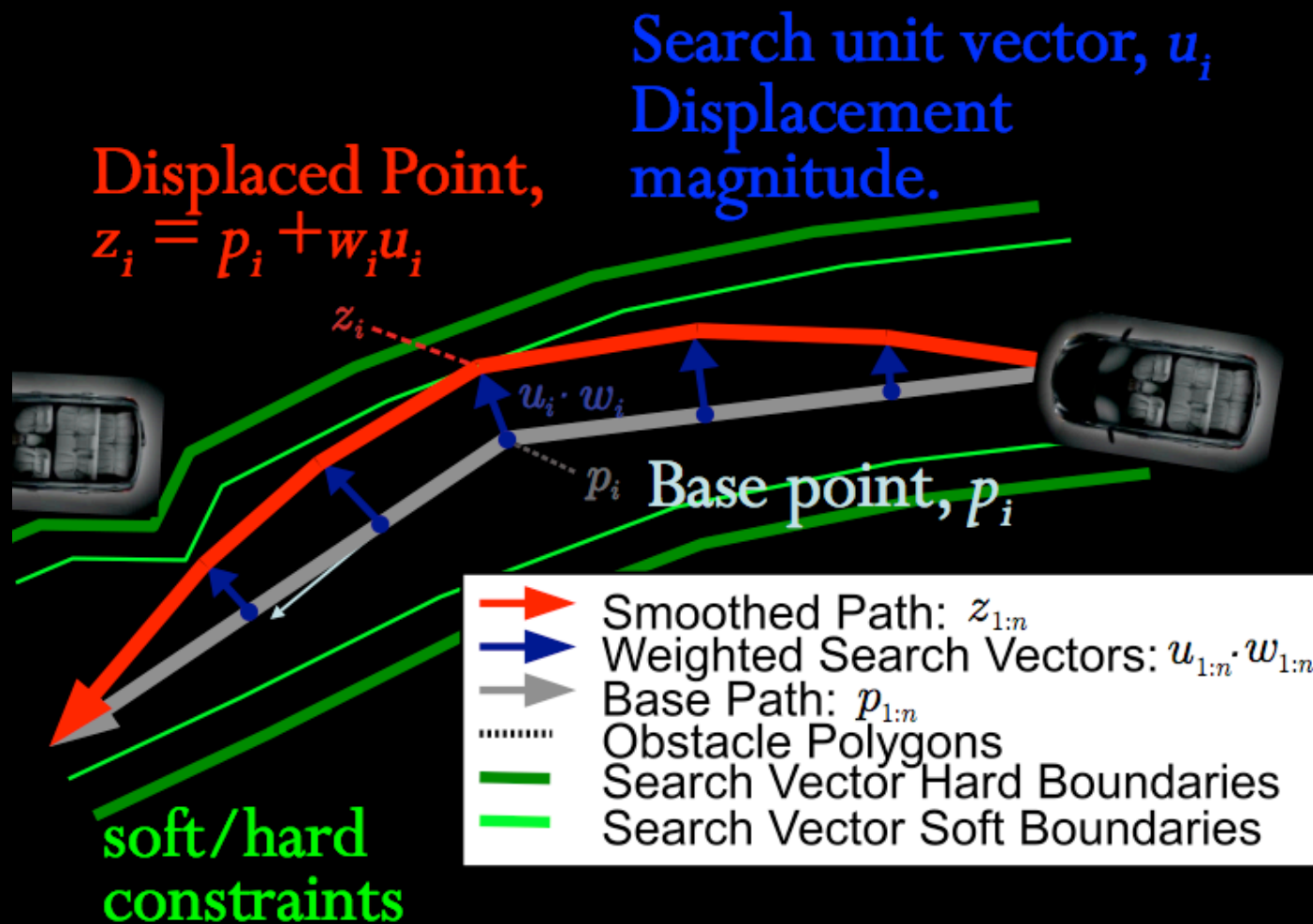
DELPHI millimeter wave RADAR

Ibeo LIDAR scanners (4 lasers)

Mark Campbell—Cornell DARPA Urban Challenge team

Numerical computing in autonomous vehicles: path planning

constrained nonlinear optimization



Individual costs:

- path curvature
- distance from base
- obstacle spacing

tuning weights

$$J(w_i) = \sum_j \alpha_j J_j$$

$$c(x) = 0$$

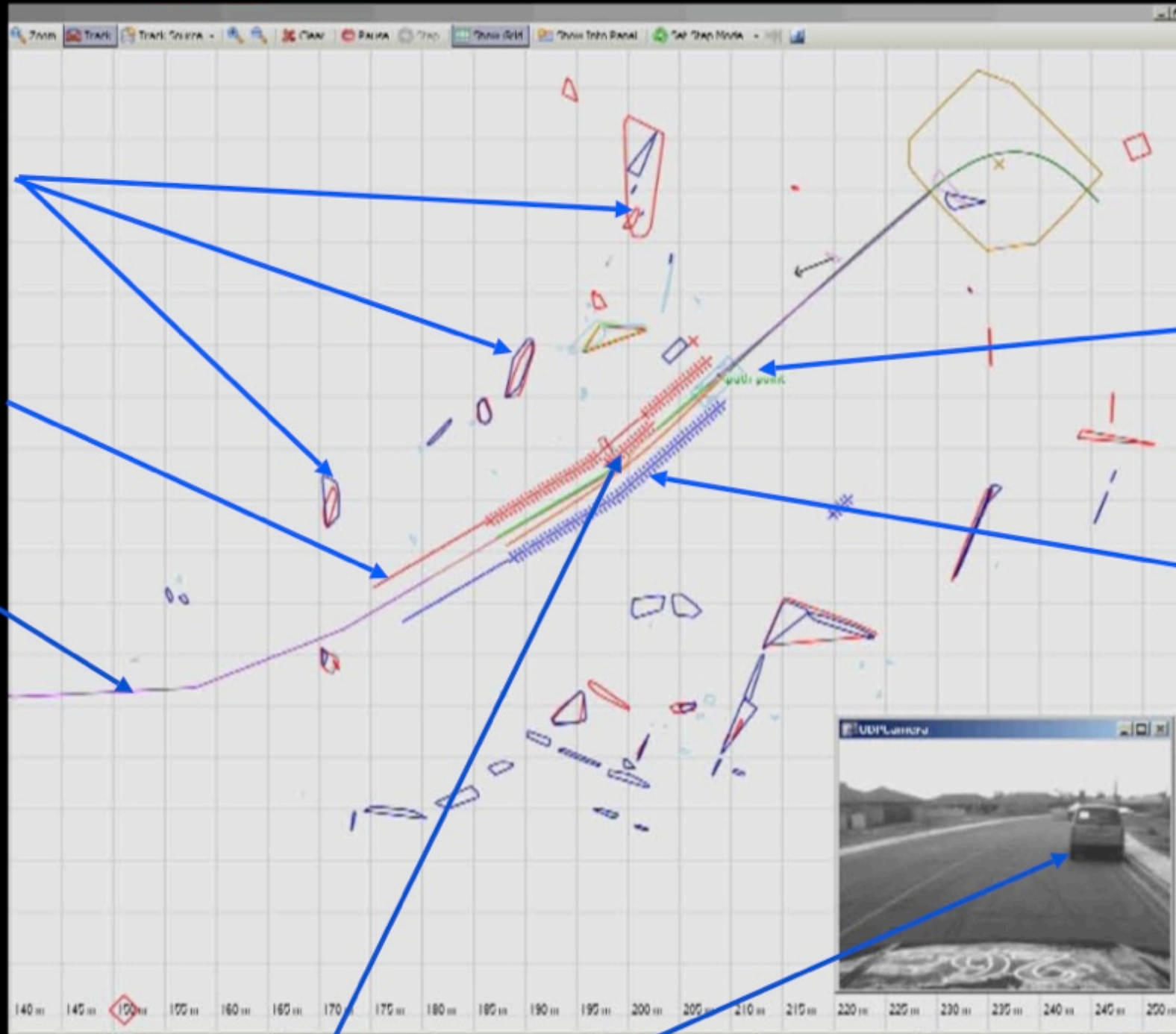
Constraints:

- lane width
- obstacle spacing

convex hulls of obstacles

lane boundaries

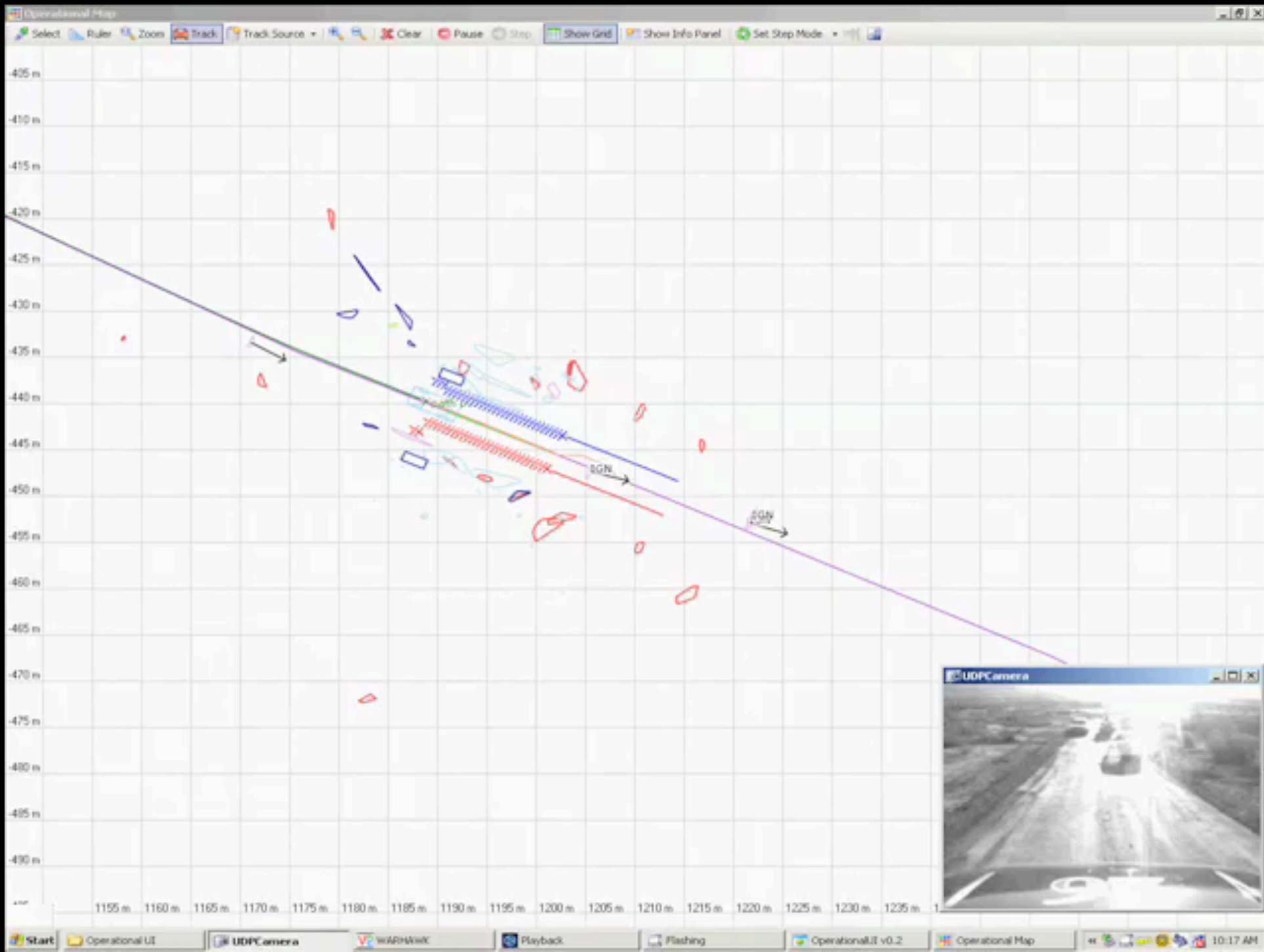
RNDF (map)



Ego-vehicle

planner constraints

constraints around parked car



Mark Campbell—Cornell DARPA Urban Challenge team

Numerical computing in games: physics engines

ordinary differential equations



Crytek GmbH—advertisement for CryEngine 2 game engine

Numerical computing in movies: realistic lighting

Hand with Reflecting Sphere. M. C. Escher, 1935. lithograph



Gene Miller & Ken Perlin, 1982

Numerical computing in movies: realistic lighting

numerical integration (quadrature)

Real environment,
computed objects



Jonas Unger



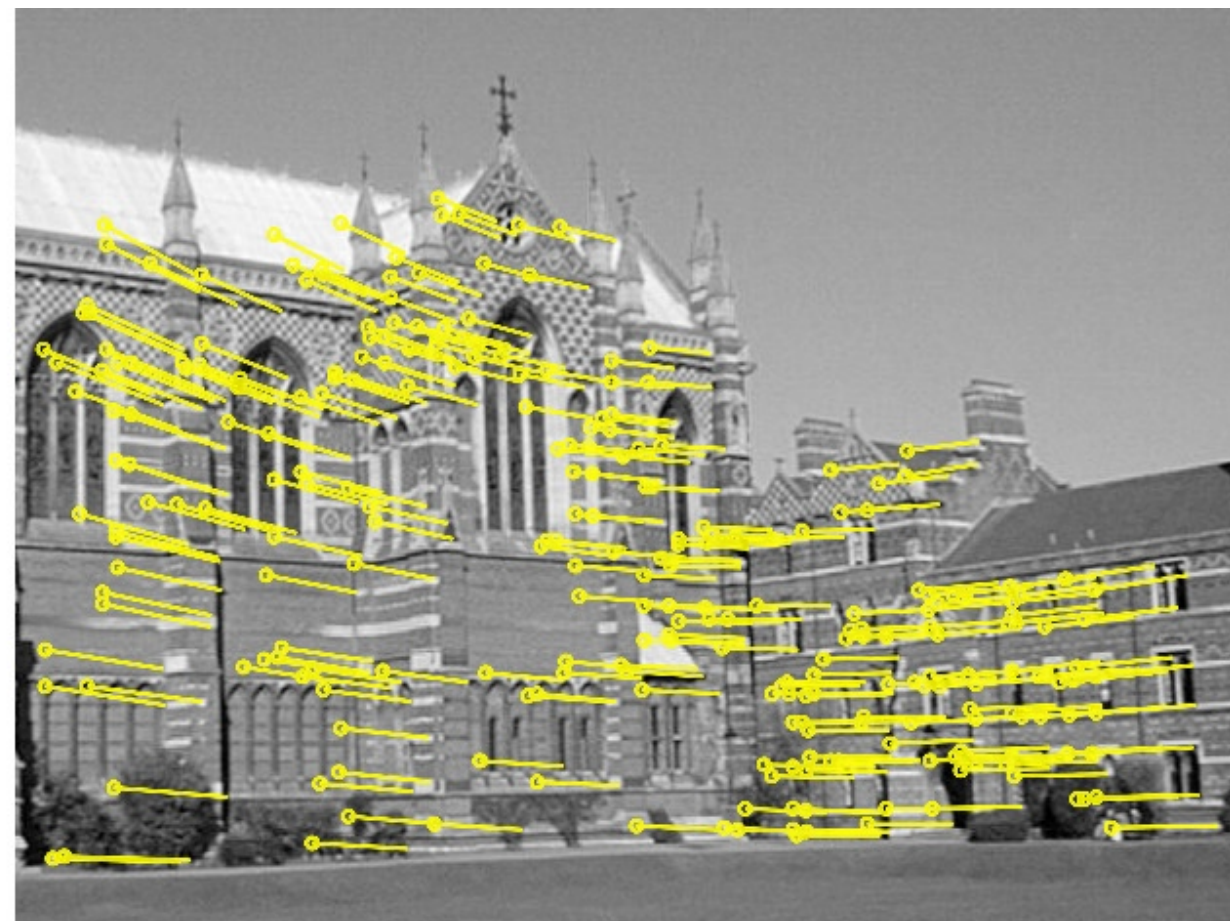
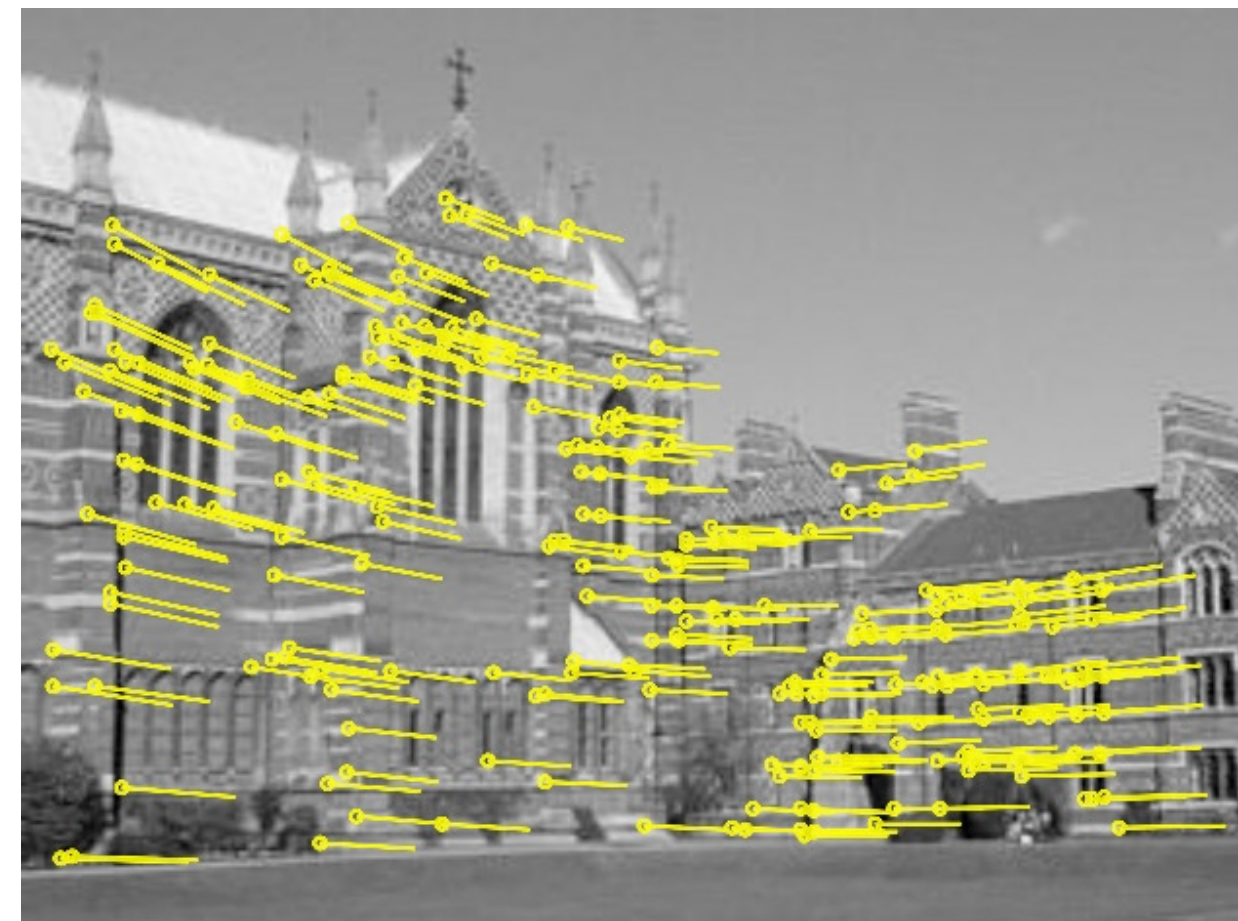
KING KONG

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Numerical computing in movies: camera tracking

numerical differentiation

nonlinear optimization



Camera footage



Rendered model added



Numerical computing in information retrieval: Google's PageRank

matrix eigenvalues

Idea 1: **importance = citation count** — simple integer exact answer

Idea 2: **importance = citation count weighted by importance** — now it is a self-referencing definition for a real-valued quantity (and it must be approximated numerically)

Computing PageRank works out to be a linear algebra problem: finding the largest eigenvalue of a matrix.

course themes

discrete — continuous

exact — approximate

accuracy, stability, and robustness

“Never in the history of mankind has it been possible
to produce so many wrong answers so quickly!”

—Carl-Erik Fröberg

prerequisites

calculus, linear algebra

some programming experience

Matlab

CS1132: Transition to Matlab

A one-credit course for students who know another language (e.g. Java) and need to map the ideas over to Matlab.

Informational meetings:

today 3:35 Hollister 307

tomorrow 4:40 Hollister 3:14

course mechanics

<http://www.cs.cornell.edu/Courses/cs3220>
