

IPV4 INTERNET TOPOLOGY MAP

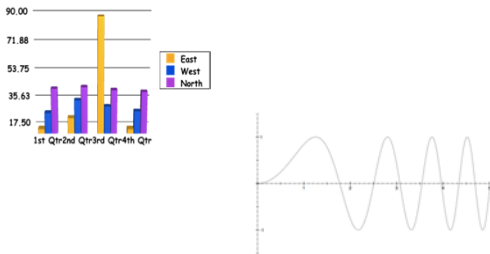
GRAPHS

Lecture 19  
CS2110 – Spring 2013

### Announcements

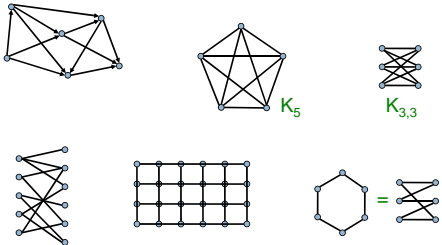
- Prelim 2: Two and a half weeks from now
  - Tuesday, April 16, 7:30-9pm, Statler
- Exam conflicts?
  - We need to hear about them and can arrange a makeup
  - It would be the same day but 5:30-7:00
- Old exams available on the course website

### These are not Graphs



...not the kind we mean, anyway

### These are Graphs



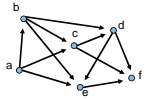
### Applications of Graphs

- Communication networks
- Routing and shortest path problems
- Commodity distribution (flow)
- Traffic control
- Resource allocation
- Geometric modeling
- ...

### Graph Definitions

- A **directed graph** (or **digraph**) is a pair  $(V, E)$  where
  - $V$  is a set
  - $E$  is a set of ordered pairs  $(u, v)$  where  $u, v \in V$ 
    - Usually require  $u \neq v$  (i.e., no self-loops)
- An element of  $V$  is called a **vertex** (pl. **vertices**) or **node**
- An element of  $E$  is called an **edge** or **arc**
- $|V|$  = size of  $V$ , often denoted  $n$
- $|E|$  = size of  $E$ , often denoted  $m$

### Example Directed Graph (Digraph)

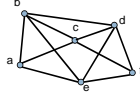


$V = \{a,b,c,d,e,f\}$   
 $E = \{(a,b), (a,c), (a,e), (b,c), (b,d), (b,e), (c,d), (c,f), (d,e), (d,f), (e,f)\}$   
 $|V| = 6, |E| = 11$

### Example Undirected Graph

An **undirected graph** is just like a directed graph, except the edges are **unordered pairs (sets)**  $\{u,v\}$

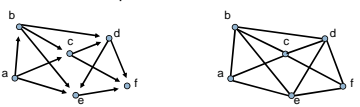
**Example:**




$V = \{a,b,c,d,e,f\}$   
 $E = \{\{a,b\}, \{a,c\}, \{a,e\}, \{b,c\}, \{b,d\}, \{b,e\}, \{c,d\}, \{c,f\}, \{d,e\}, \{d,f\}, \{e,f\}\}$

### Some Graph Terminology

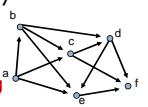
- Vertices  $u$  and  $v$  are called the **source** and **sink** of the directed edge  $(u,v)$ , respectively
- Vertices  $u$  and  $v$  are called the **endpoints** of  $(u,v)$
- Two vertices are **adjacent** if they are connected by an edge
- The **outdegree** of a vertex  $u$  in a directed graph is the number of edges for which  $u$  is the source
- The **indegree** of a vertex  $v$  in a directed graph is the number of edges for which  $v$  is the sink
- The **degree** of a vertex  $u$  in an undirected graph is the number of edges of which  $u$  is an endpoint



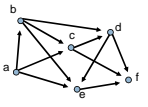
### More Graph Terminology



- A **path** is a sequence  $v_0, v_1, v_2, \dots, v_p$  of vertices such that  $(v_i, v_{i+1}) \in E, 0 \leq i \leq p-1$
- The **length of a path** is its number of edges
  - In this example, the length is 5
- A path is **simple** if it does not repeat any vertices
- A **cycle** is a path  $v_0, v_1, v_2, \dots, v_p$  such that  $v_0 = v_p$
- A cycle is **simple** if it does not repeat any vertices except the first and last
- A graph is **acyclic** if it has no cycles
- A directed acyclic graph is called a **dag**

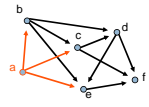


### Is This a Dag?



- **Intuition:**
  - If it's a dag, there must be a vertex with indegree zero - why?
- **This idea leads to an algorithm**
  - A digraph is a dag if and only if we can iteratively delete indegree-0 vertices until the graph disappears

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### Is This a Dag?

13

```

    graph TD
      b --> c
      b --> d
      b --> e
      c --> d
      d --> f
      e --> f
    
```

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14

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15

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### Is This a Dag?

16

```

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17

```

    graph TD
      f
    
```

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18


```

    graph TD
      f
    
```

- Intuition:
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### Is This a Dag?


19



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### Is This a Dag?


20



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### Is This a Dag?

21

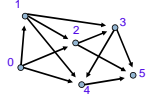


- Intuition:
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### Topological Sort

22

- We just computed a **topological sort** of the dag
  - This is a numbering of the vertices such that all edges go from lower- to higher-numbered vertices




- Useful in job scheduling with precedence constraints

### Graph Coloring

23

- A **coloring** of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color

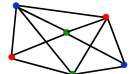


- How many colors are needed to color this graph?

### Graph Coloring

24

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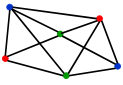


- How many colors are needed to color this graph?
  - 3

### An Application of Coloring

25


- Vertices are jobs
- Edge  $(u,v)$  is present if jobs  $u$  and  $v$  each require access to the same shared resource, and thus cannot execute simultaneously
- Colors are time slots to schedule the jobs
- Minimum number of colors needed to color the graph = minimum number of time slots required



### Planarity

26

- A graph is **planar** if it can be embedded in the plane with no edges crossing

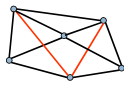


- Is this graph planar?

### Planarity

27

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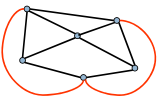


- Is this graph planar?
  - Yes

### Planarity

28

- A graph is **planar** if it can be embedded in the plane with no edges crossing





- Is this graph planar?
  - Yes

### Detecting Planarity

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- Kuratowski's Theorem





- A graph is planar if and only if it does not contain a copy of  $K_5$  or  $K_{3,3}$  (possibly with other nodes along the edges shown)

### The Four-Color Theorem

30

Every planar graph is 4-colorable  
(Appel & Haken, 1976)



### Bipartite Graphs

31

- A directed or undirected graph is **bipartite** if the vertices can be partitioned into two sets such that all edges go between the two sets

### Bipartite Graphs

32

- The following are equivalent
  - G is bipartite
  - G is 2-colorable
  - G has no cycles of odd length

### Traveling Salesperson

33

- Find a path of minimum distance that visits every city

### Representations of Graphs

34

#### Adjacency List

```

1 → 2, 3, 4
2 → 3
3 → 4
4 → 3
                    
```

#### Adjacency Matrix

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

### Adjacency Matrix or Adjacency List?

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- $n$  = number of vertices
- $m$  = number of edges
- $d(u)$  = degree of  $u$  = number of edges leaving  $u$

- Adjacency Matrix**
  - Uses space  $O(n^2)$
  - Can iterate over all edges in time  $O(n^2)$
  - Can answer "Is there an edge from  $u$  to  $v$ ?" in  $O(1)$  time
  - Better for **dense** graphs (lots of edges)

- Adjacency List**
  - Uses space  $O(m+n)$
  - Can iterate over all edges in time  $O(m+n)$
  - Can answer "Is there an edge from  $u$  to  $v$ ?" in  $O(d(u))$  time
  - Better for **sparse** graphs (fewer edges)

### Graph Algorithms

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- Search**
  - depth-first search
  - breadth-first search
- Shortest paths**
  - Dijkstra's algorithm
- Minimum spanning trees**
  - Prim's algorithm
  - Kruskal's algorithm

### Depth-First Search

37

- Follow edges depth-first starting from an arbitrary vertex  $r$ , using a stack to remember where you came from
- When you encounter a vertex previously visited, or there are no outgoing edges, retreat and try another path
- Eventually visit all vertices reachable from  $r$
- If there are still unvisited vertices, repeat
- $O(m)$  time

### Depth-First Search

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### Depth-First Search

39

### Depth-First Search

40

### Depth-First Search

41

### Depth-First Search

42

### Depth-First Search

43

A directed graph with 6 nodes and 8 edges. The nodes are arranged in a roughly circular pattern. The edges are: (1,2), (1,3), (2,4), (2,5), (3,6), (4,5), (5,6), and (6,1). In this slide, the path from node 1 to node 2 is highlighted in red, and the path from node 2 to node 3 is highlighted in green. All other edges are black.

### Depth-First Search

44

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### Depth-First Search

45

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### Depth-First Search

46

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### Depth-First Search

47

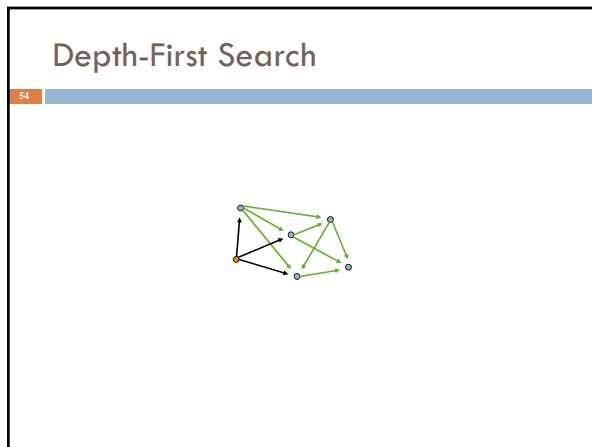
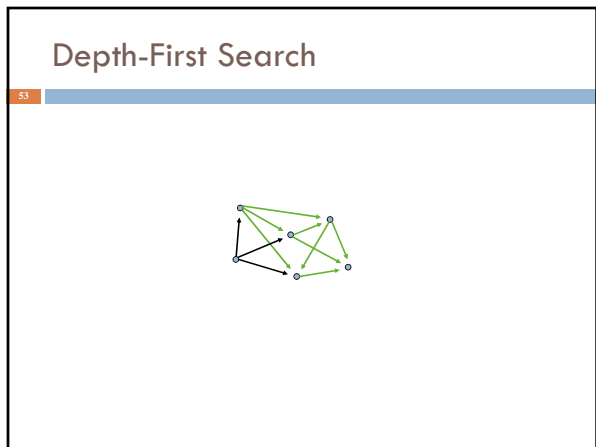
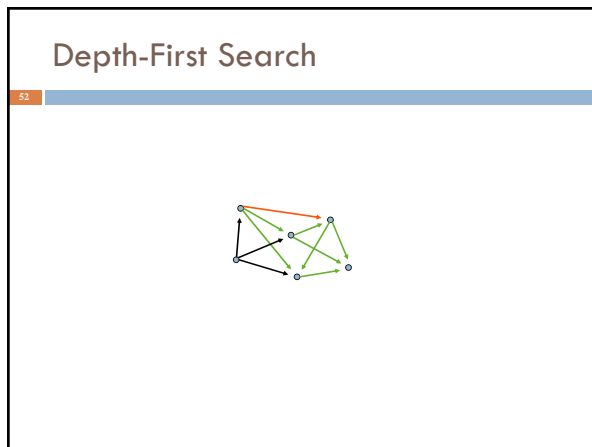
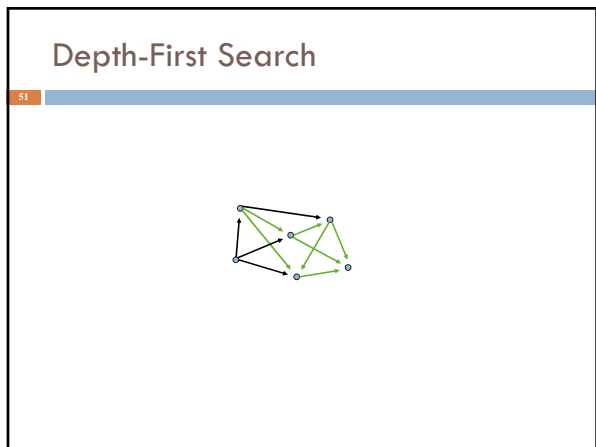
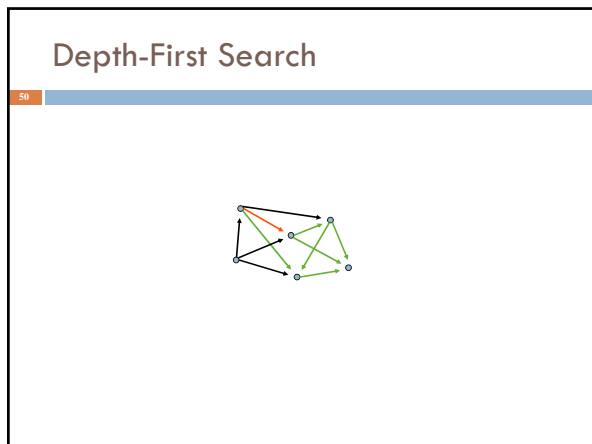
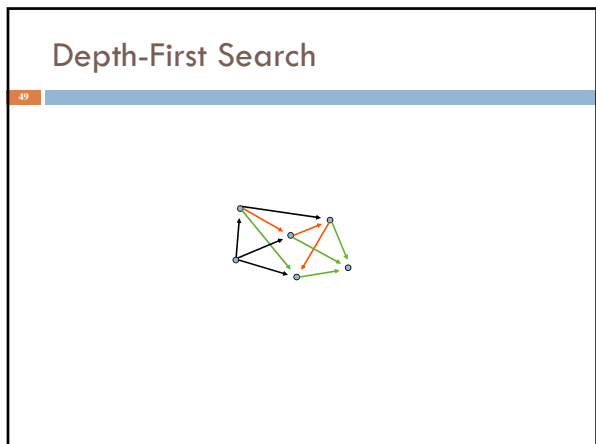
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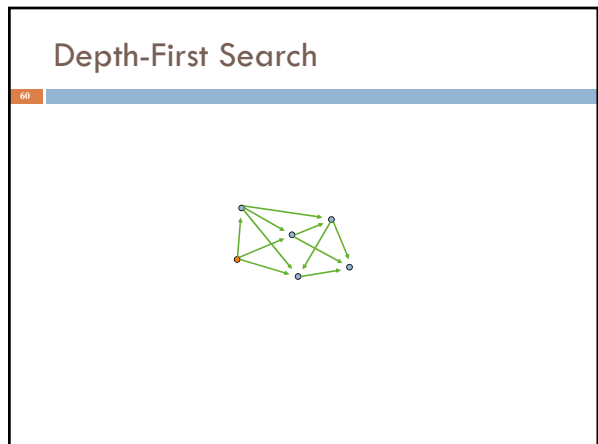
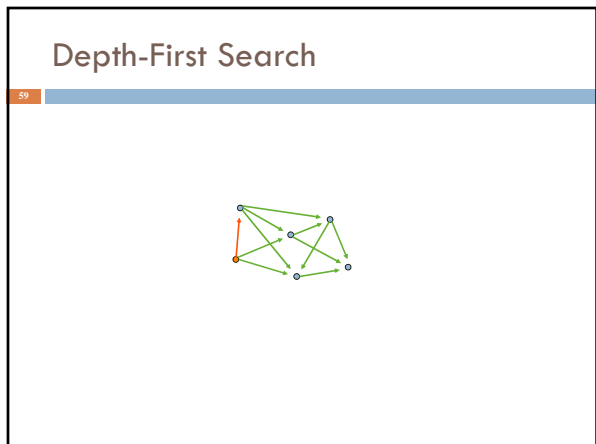
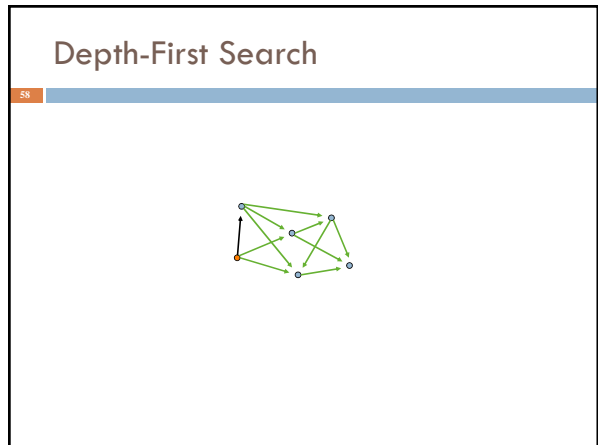
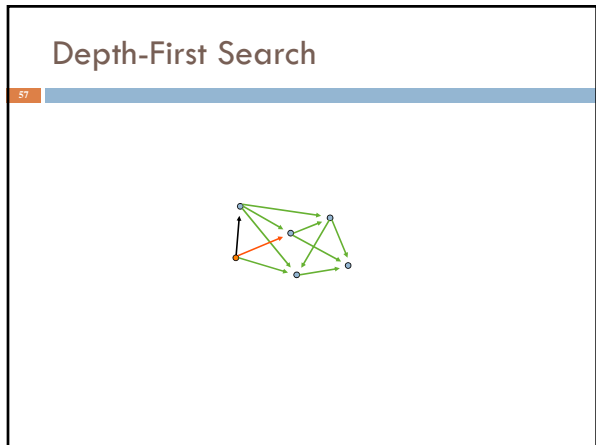
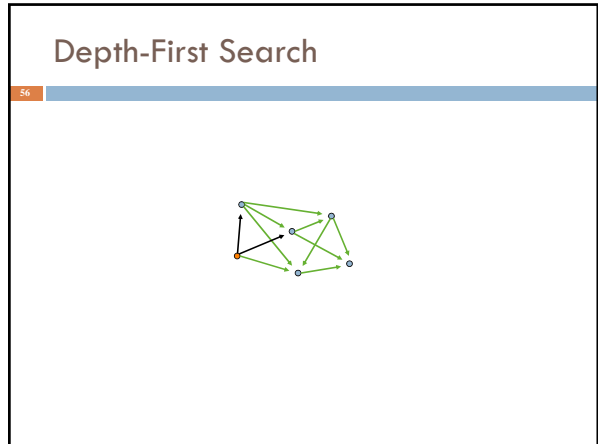
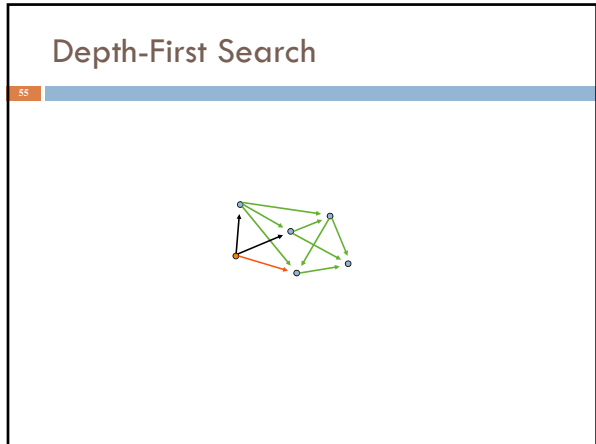
### Depth-First Search

48

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### Depth-First Search

61

### Breadth-First Search

62

- Same, except use a queue instead of a stack to determine which edge to explore next
  - ▣ Recall: A stack is last-in, first-out (LIFO)
  - ▣ A queue is first-in, first-out (FIFO)

### Breadth-First Search

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### Breadth-First Search

64

### Breadth-First Search

65

### Breadth-First Search

66

### Breadth-First Search

67

A directed graph with 6 nodes. The search process is shown with edges colored: black for the root node, green for its children, and red for the children of the green nodes. The root node is at the top left, with two children below it. The left child has two children of its own, and the right child has one child. The red edges represent the search frontier.

### Breadth-First Search

68

The graph is the same as in slide 67. The search has progressed further. The root node and its children are now green. The children of the left child are now red, indicating they are the current search frontier.

### Breadth-First Search

69

The graph is the same as in slide 68. The search has progressed further. The root node, its children, and the children of the left child are now green. The children of the right child are now red, indicating they are the current search frontier.

### Breadth-First Search

70

The graph is the same as in slide 69. The search has progressed further. The root node, its children, the children of the left child, and the children of the right child are now green. The children of the left child of the right child are now red, indicating they are the current search frontier.

### Breadth-First Search

71

The graph is the same as in slide 70. The search has completed. All nodes and edges in the search tree are now green, indicating that all nodes have been visited.

### Summary

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- We've seen an introduction to graphs and will return to this topic next week on Tuesday
  - ▣ Definitions
  - ▣ Testing for a dag
  - ▣ Depth-first and breadth-first search
  
- On Thursday Ken and David will be out of town.
  - ▣ Dexter Kozen will do a lecture on induction
  - ▣ We use induction to prove properties of graphs and graph algorithms, so the fit is good