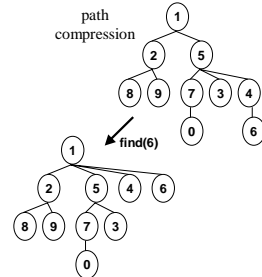


## Finish Union/Find, Finish Graph Algorithms, Quick Overview

CS211  
Fall 2000

## Union/Find

- Operations
  - Union: Combine two sets
  - Find: Given an item, determine the "name" of the set that contains it
- Use reverse trees
  - Each item points at its parent
  - The root is the "name" of the set
- Union-by-Size
  - Always make the larger tree be the root
- Path Compression
  - Every time we "find" something, we update every item we touch so that it points at the root



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## Union/Find Analysis

Theorem (Tarjan)  
Using weighted union and path compression, a sequence of  $n$  union/find operations takes time  $O(n \alpha(n))$

- Note that  $\alpha(n) \leq 4$  for any integer  $n$  that we are ever likely to encounter

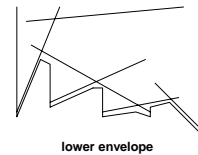
- Is the  $\alpha(n)$  factor really necessary?
  - Yes: Tarjan showed a lower bound of  $\Omega(n \alpha(n))$  for union/find
  - Claim: the inverse Ackerman's function is not just an artifact of this one problem

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## Lower Envelope of Line Segments

- Given  $n$  line segments in the plane, what is the worst-case complexity of their lower envelope?

$\Theta(n \alpha(n))$



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## Two MST Algorithms (Both Greedy)

### Kruskal's Algorithm

- Choose the shortest edge  $e$  such that
  - $e$  is not yet processed
  - $e$  does not make a cycle

### Prim's Algorithm

- Choose the shortest edge  $e$  such that
  - $e$  touches the tree
  - $e$  touches a vertex not in the tree

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## Kruskal's MST Algorithm

KruskalMST(G):  
 $E$  = edges of G;  
 forest = empty;  
 do  
    $\langle u, v \rangle$  = least cost edge of  $E$ ;  
    $E = E - \langle u, v \rangle$ ;  
   if ( $u$  and  $v$  in different trees)  
     forest = forest  $\cup \langle u, v \rangle$ ;  
 while ( $E$  is nonempty);  
 return forest

- Can sort the edges initially (or can use a PQ)
- Use Union/Find to check for different trees and to combine trees
- Total worst-case time:  $O(e \log e)$  when using adjacency lists
- Time is  $O(v^2 + e \log e)$  for adjacency matrix

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## Quick Review: Programming Topics

- Object Oriented Programming
  - Classes and Objects
    - ▲ Parameter Passing
    - ▲ Objects vs. References
    - ▲ Abstraction
    - ▲ Encapsulation
  - Inheritance
    - ▲ Polymorphism
    - ▲ Dynamic Method Binding
    - ▲ Abstract Classes
    - ▲ Interfaces
    - ▲ Upcasting vs. Downcasting
- Other Topics
  - Access-Control Modifiers
  - Packages
  - Exceptions
  - Program Design
    - ▲ UML Diagrams
    - ▲ Pseudo-code
    - ▲ Javadoc
  - GUIs
    - ▲ Layout
    - ▲ Event Handling

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## Quick Review: Data-Structure Topics

- Searching and Sorting in Arrays
  - Binary Search
  - Quick Sort
  - Merge Sort
  - Insertion Sort
  - Heap Sort
  - Sorting Lower Bound
- Data Structures for Searching (Dictionaries)
  - Hash Table
  - Binary Search Tree
  - Balanced Trees
- Data Structures for Sequencing
  - Stack
  - Queue
  - Priority Queue
- Graphs (Adj List, Adj Matrix)
  - Shortest Paths
    - ▲ Breadth First Search
    - ▲ Dijkstra's Algorithm
  - Minimum Spanning Trees
    - ▲ Prim's Alg (single tree)
    - ▲ Kruskal's Alg (forest)

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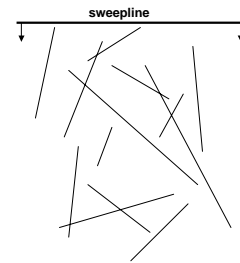
## Quick Review: Additional Topics

- Recursion
  - Recursive Descent Parsing
  - Stack Frames
  - Induction
- Algorithm Analysis
  - Big-O
  - Worst- vs. Expected-Case
- Algorithm Design Methods
  - Divide and Conquer
  - Greedy Method
- Union/Find
  - union-by-size
  - path compression
- The Java Collections Framework
  - Interfaces: Set, SortedSet, List, Map, SortedMap, Iterator
  - Classes: HashSet, TreeSet, ArrayList, LinkedList, HashMap, TreeMap
  - Utilities: java.util.Arrays, java.util.Collections
  - Comparator vs. Comparable

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## What I Do: Computational Geometry

- Using a computer to solve geometric problems
  - Get to use lots of data structure ideas
  - Example
    - ▲ Given n line segments in the plane, report all intersections
    - ▲ Uses both a PQ and a Balanced Tree
- Areas I work in
  - Motion Planning
  - Meshing
  - Shape Matching
    - ▲ computer vision
    - ▲ protein matching
  - More theoretical questions



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