

Graph Algorithms: Shortest Paths

CS211
Fall 2000

Sorting in Linear Time

There are several sorting methods that take linear time

- Counting Sort
 - sorts integers from a small range: $[0..k]$ where $k = O(n)$
- Radix Sort
 - the method used by the old card-sorters
 - sorting time $O(dn)$ where d is the number of "digits"

How do these methods get around the $\Omega(n \log n)$ lower bound?

- They don't use comparisons
- What sorting method works best?
 - QuickSort is best general-purpose sort
 - Counting Sort or Radix Sort can be best for *some* kinds of data

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Aside: An Open Question on Sorting

How long does it take to sort an n -by- n table of numbers?



- $O(n^2 \log n)$ because there are n^2 numbers in the table

What if it's an addition table?

+	1	3	5	8
2	3	5	7	10
10	11	13	15	18
12	13	15	18	20
14	15	17	19	22

- Shouldn't it be easier to sort than an arbitrary set of n^2 numbers?

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Recall Digraphs

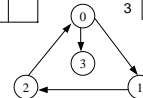
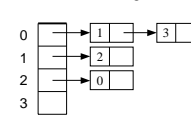
■ Adjacency Matrix

- Space $O(v^2)$
- $g[u][v]$ is true iff there is an edge from u to v

	0	1	2	3
0		T		T
1			T	
2	T			
3				

■ Adjacency List

- Space $O(e+v)$
- The list for u contains v iff there is an edge from u to v



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Recall Weighted Digraphs

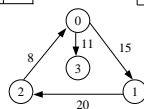
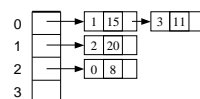
■ Adjacency Matrix

$g[u][v]$ is c iff there is an edge of cost c from u to v

	0	1	2	3
0		15		11
1			20	
2	8			
3				

■ Adjacency List

The list for u contains v, c iff there is an edge from u to v that has cost c



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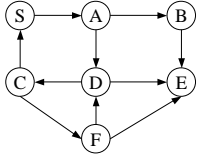
Goal: Find Shortest Path in a Graph

■ Finding the shortest (min-cost) path in a graph is a problem that occurs often

- Find the least-cost route between Ithaca and Detroit
- Result depend on our notion of cost
 - ▲ least mileage
 - ▲ least time
 - ▲ cheapest
 - ▲ least boring
- All of these "costs" can be represented as edge costs on a graph
- How do we find a shortest path?

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Shortest Paths for Unweighted Graphs



```

bfsDistance(s):
// s is the start vertex
// dist[v] is length of s-to-v path
// Initially dist[v] = ∞ for all v
dist[s] = 0;
Q.insert(s);

while (Q nonempty) {
  v = Q.get();
  for (each w adjacent to v) {
    if (dist[w] == ∞) {
      dist[w] = dist[v]+1;
      Q.insert(w);
    }
  }
}
    
```

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Analysis for bfsDistance

- How many times can a vertex be placed in the queue?
- How much time for the for-loop?
 - Depends on representation
 - Adjacency Matrix: $O(v)$
 - Adjacency List: $O(e_v)$
- Time:
 - $O(v^2)$ for adj matrix
 - $O(e+v)$ for adj list

```

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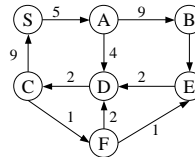
If There are Edge Costs?

- Idea #1
 - Add false nodes so that all edge costs are 1
 - But what if edge costs are large?
 - What if the costs aren't integers?
- Idea #2
 - Nothing "interesting" happens at the false nodes
 - Can't we just jump ahead to the next "real" node
 - Rule: always do the closest (real) node first
 - Use the array `dist[]` to
 - Report answers
 - Keep track of what to do next

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Dijkstra's Algorithm

- Intuition
 - Edges are threads; vertices are beads
 - Pick up at `s`; mark each node as it leave the table
- Note: Negative edge-costs are not allowed
- `s` is the start vertex
- `c(i,j)` is the cost from `i` to `j`
- Initially, vertices are unmarked
- `dist[v]` is length of `s-to-v` path
- Initially, `dist[v] = ∞`, for all `v`



```

dijkstra(s):
dist[s] = 0;
while (some vertices are unmarked) {
  v = unmarked vertex with smallest dist;
  Mark v;
  for (each w adj to v) {
    dist[w] = min [ dist[w], dist[v] + c(v,w) ];
  }
}
    
```

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Dijkstra's Algorithm using Adj Matrix

- While-loop is done v times
 - Within the loop
 - Choosing `v` takes $O(v)$ time
 - For-loop takes $O(v)$ time
 - Total time = $O(v^2)$
- ```

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 }
}

```

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## Dijkstra's Algorithm using Adj List

- Looks like we need a PQ
    - Problem: priorities are updated as algorithm runs
    - Can insert pair  $(v, dist[v])$  in PQ whenever `dist[v]` is updated
    - At most  $e$  things in PQ
  - Time  $O(v + e \log e)$
  - Using a more complicated PQ (e.g., Pairing Heap), time can be brought down to  $O(e + v \log v)$
- ```

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